

Balancing

Balancing Criteria

1. Balancing Criteria:

- The difference between the left side weight, and the right side weight is no more than 10%
- If there is only 1 container, it's balanced
- **Balanced** = $\max(\text{weight}(\text{right_side}), \text{weight}(\text{left_side})) / \min(\text{weight}(\text{right_side}), \text{weight}(\text{left_side})) < 1.1$
Assume x represents the weight of the heavier side, and y represents the weight of the lighter side, and T

represents the total weight $x+y$

$$x/y < 1.1,$$

$$x < 1.1y,$$

$T - y < 1.1y$ we can get

$$y > T/2.1 \text{ and } x < ((1.1)/(2.1))T$$

$$\mathbf{W_min = (total\ weight)/2.1}$$

$$\mathbf{W_max = (1.1 / 2.1) * (total\ weight)}$$

When we explore the states, we don't have to recalculate both side, only need to consider one side.

Moving Criteria

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	1	unused	unused	9	2
NAN	NAN	unused	unused	NAN	NAN

2. What can be moved in a grid:

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	9	2
NAN	NAN	unused	1	NAN	NAN

What can we move in a grid:
the topmost container in its column

3. A container can be moved to:

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	9	2
NAN	NAN	unused	1	NAN	NAN

A container **can be moved to**:

- (1) An unused spot that is :
 - (a) Directly above a NAN slot, or
 - (b) On the first row, or
 - (c) Directly above other container

Can't be moved to its own column

The **Cost** of each move is the **Manhattan distance** between, for example, moving the container with weight 5 (at [1,4]) to unused space [4,2] would be $|(4-1)| + |(2-4)| = 5$

Note: haven't consider:

- (a) the 9th and 10th rows that we can stack temporarily
- (b) buffer

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	9	2
NAN	NAN	unused	1	NAN	NAN

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	9	2
NAN	NAN	unused	1	NAN	NAN

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	9	2
NAN	NAN	unused	1	NAN	NAN

4.1 Cost:

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	9	2
NAN	NAN	unused	1	NAN	NAN

The **Cost** of each move is the **Manhattan distance** between, for example, moving the container with weight 5 (at [1,4]) to unused space [4,2] would be $|4-1| + |2-4| = 5$

4.2 Cost:

	1	2	3	4	5	6
4	5 ↓	unused	unused	unused	unused	unused
3	10	unused	unused	unused	unused	unused
2	7	1 ↑	unused	unused	9	2
1	NAN	NAN	unused	unused	NAN	NAN

We have to consider the **initial crane move cost**:

- At the first round, the cost will be the time the crane move to the slot position

Starting position is (5,1)

For example,

starting from slot (4,1) the cost is 1 $// (4,1) - (5,1) - 1$

Starting from slot (2,2) the cost is 4 $// (2,2) - (5,1) = 4$

4.2 Cost:

	1	2	3	4	5	6
4	unused	unused	unused	unused	unused	unused
3	10	unused	unused	unused	unused	unused
2	7	1	unused	unused	9	2
1	NAN	NAN	unused	5	NAN	NAN

(?) We have to consider the **last crane move**:

For example,
 starting from slot (1,4) the cost is 7 $\| (1,4) - (5,1) \| = 7$
 Starting from slot (2,2) the cost is 4 $\| (2,2) - (5,1) \| = 4$

Thought

5.1 Thought: Methods

- **Side_min = (total weight)/2.1**

Side_max = (1.1 / 2.1) * (total weight)

When we explore the states, we don't have to recalculate both side, only need to consider one side.

-

Method1(current search)	Method2 (heuristic)
<ul style="list-style-type: none">● Find the movable containers in the gird● For each movable containers, we find the valid destination to move to● Move them, push the new gridstate and cost into the frontier	<ul style="list-style-type: none">● We have a goal side weight range.● Pick the containers that can fulfill the weight range to the otherside.● Find the best route for moving these container to the other side

5 Thought: tracing back

- In GridState:
- Attribute ParentGrid
- Attribute CranePosition
- Tracing back from destination gridstate to the root gridstate to
 - show path : CranePosition
 - show cost: Each step's cost = current grid cost - parent's grid cost

Heuristic

- Method 1 : Weight difference ($\text{left_weight} - \text{right_weight}$)
 - Pro: fast to compute, easy to understand
 - Con: less specific, doesn't guide the search toward the feasible goal states.
- **Method 2: Valid Combinations weight (used for the software)**
 - **Goal_combination: `can_balance()` returns the list of combinations that matches goal weights range**
 - Each item has a “ container combination”
- Method 3: Misplaced Containers
 - Use the number of misplaced containers
-

- When receiving a balancing quest, check if it can be balanced by solving the subset sum (using bitmask dp)
 - Return a list of combinations
 - ShipCase3 Balanceable! Combinations: [
 - ([600, 9041, 10], [10001, 500, 100]),
 - ([600, 100, 9041], [10001, 500, 10]),
 - ([600, 100, 9041, 10], [10001, 500]),
 - ([10001], [500, 600, 100, 9041, 10]),
 - ([10001, 10], [500, 600, 100, 9041]),
 - ([10001, 100], [500, 600, 9041, 10]),
 - ([10001, 100, 10], [500, 600, 9041]),
 - ([500, 600, 9041], [10001, 100, 10]),
 - ([500, 600, 9041, 10], [10001, 100]),
 - ([500, 600, 100, 9041], [10001, 10]),
 - ([500, 600, 100, 9041, 10], [10001]),
 - ([10001, 500], [600, 100, 9041, 10]),
 - ([10001, 500, 10], [600, 100, 9041]),
 - ([10001, 600], [500, 100, 9041, 10])]
 - ShipCase4 [
 - ([2000, 2007, 2011, 2020, 3044], [10000, 1100]), //left side, right side combination
 - ([10000, 1100], [2000, 2007, 2011, 2020, 3044]) //left side, right side combination

State 1

	300			20	200
	100			70	30

State 1 (300,100), (20, 70, 200, 30)

Possible Goal Combinations are

- a. (300,20,30), (200,100,70)
- b. (300,70),(200,20,30,100)

Calculate the Heuristic from State 1 to state a (300,20,30), (200,100,70)

Heuristic = move 20 to left,
move 30 to left and
move 100 to right
 $2+3+2 = 7$

Ignore obstacles and stacking requirements.
Calculate the Manhattan distance directly between the current position of the target container and the nearest available slot on the other side.

	300			20	200
	100			70	30

	300	20			200
		30	100	70	

Calculate the Heuristic from State 1 to state b (300,70), (200,100,20,30)

Heuristic = move 70 to left,
move 100 to right
 $2+2 = 4$

	300			20	200
	100			70	30

	300			20	200
		70	100		30

● Method 3: Misplaced Container (not selected)

State 1

	300			20	200
	100			70	30

State 1 (300,100), (20, 70, 200, 30)
Possible Goal Combinations are

- a. (300,20,30), (200,100,70)
- b. (300,70),(200,20,30,100)

Calculate the Heuristic from State 1 to state a (300,20,30), (200,100,70)
Misplaced Container = 3

Calculate the Heuristic from State 1 to state b (300,70), (200,100,20,30)
Misplaced Container = 2

	300			20	200
	100			70	30

Diagram illustrating the heuristic calculation for state a. Red arrows show the movement of containers 20 and 70 from the right side to the left side. A purple arrow shows the movement of container 100 from the left side to the right side.

	300			20	200
	100			70	30

Diagram illustrating the heuristic calculation for state b. A purple arrow shows the movement of container 100 from the left side to the right side. A red arrow shows the movement of container 70 from the right side to the left side.

	300	20			200
		30	100	70	

Diagram illustrating the heuristic calculation for state a. The containers are now in their goal positions: 300, 20, and 30 on the left; 100, 70, and 200 on the right.

	300			20	200
		70	100		30

Diagram illustrating the heuristic calculation for state b. The containers are now in their goal positions: 300, 20, and 30 on the right; 100, 70, and 200 on the left.

SIFT

take everything out and put them back in weight order

BUFFER

5. Goal:

- balanced ship with the minimum cost

Frontier.py - Using a heapq to store nodes and a set to track explored states**class Frontier**

def init

def insert(state):

- Add a state to the frontier with priority based on its cost
- Track the explored set to avoid re-visiting

def pop(state):

- Remove and return the state with the lowest cost from the heap

def contains(state): check if a specific state is already in the frontier

def is_empty:

def max_queue_size: track the max size of the frontier for testing purposes

Balance.py	
class BalanceProblem	def Init: <ul style="list-style-type: none">- set up initial grid, desired balanced weight range- Create frontier
	def solve: <ul style="list-style-type: none">- A star procedure- Loop the

Grid_state_balance.py (1)**class Grid**

def Init:

- Initialize the grid with slots, based on manifest
- Left weight, Right Weight, Total weight

def get_balance: calculate and return the left and right side weights

class Slot

Represent individual slot in the grid

Attributes:

- position
- state
- container

class Container

Represent a container

Attributes:

- weight
- name
- position

Grid_state_balance.py (2)	
def manhattan_distance(pos1, pos2)	<ul style="list-style-type: none">- Compute the Manhattan distance between two positions
def move(container, target_position)	<ul style="list-style-type: none">- Move a container to a specified target position if it's a valid move- Update attributes: grid slot, container position, left and right weights
def expand	<ul style="list-style-type: none">- Generate all possible moves for the current grid state- For each container that can be moved, create a new grid state with the container moved to each valid target position- Return a list of new grid states (children)
print_path	Traverse back to the root to print the sequence of move

Test and Debug

sample_manifest_children_test_1

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	1	unused	unused	unused	2
NAN	NAN	unused	unused	NAN	NAN

Result for sample_manifest_children_test_1

Total states expanded:149

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	unused	2
NAN	NAN	unused	1	NAN	NAN

Result for sample_manifest_children_test_1

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	unused	unused	unused	unused	2
NAN	NAN	unused	1	NAN	NAN

What can we move in a grid:

If in the slot, there is a container:

No other container is above it (topmost container in its column)

Valid slots position to move to

7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
4	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
2	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
1	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
0	NAN	Cat 99	Dog1 00	unused	unused	unused	unused	unused	unused	unused	unused	NAN
	0	1	2	3	4	5	6	7	8	9	10	11

Test1

Test1

Balance Moves: [Move container from position (1, 3) to position (1, 7)]

Test2

Balance Moves: [Move container from position (1, 4) to position (1, 7), Move container from position (1, 9) to position (1, 6)]

Test3

Balance Moves: [Move container from position (2, 1) to position (1, 7), Move container from position (1, 3) to position (2, 7), Move container from position (1, 4) to position (1, 8)]

Test4

Infinite

Test5

infinite

SilverQueen

Balance Moves: [Move container from position (1, 4) to position (1, 7), Move container from position (2, 2) to position (2, 7), Move container from position (1, 3) to position (1, 8)]

Test2

	Crane Starting point											
7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
4	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
2	Cat 40	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
1	NAN	Dog 50	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
0	NAN	NAN	NAN	unused	unused	Owl 35	Ram 120	unused	unused	unused	unused	NAN
row/col	0	1	2	3	4	5	6	7	8	9	10	11

(0, 0), 0, NAN, 0

(0, 1), 0, NAN, 0

(0, 2), 0, NAN, 0

(0, 3), 2, Ram, 120

(0, 4), 1, UNUSED, 0

(0, 5), 1, UNUSED, 0

(0, 6), 1, UNUSED, 0

(0, 7), 1, UNUSED, 0

(0, 8), 2, Owl, 35

(0, 9), 0, NAN, 0

(0, 10), 0, NAN, 0

(0, 11), 0, NAN, 0

(1, 0), 0, NAN, 0

(1, 1), 2, Dog, 50

(1, 2), 1, UNUSED, 0

(1, 3), 1, UNUSED, 0

(1, 4), 1, UNUSED, 0

(1, 5), 1, UNUSED, 0

Test4 Debug

[illegible]

[illegible]

```
for child_state, move in state.getPossibleStatesMoves():
    if child_state not in self.closed_set:
```

```
✓ closed_set = {(0, 0), 0, NAN, 0}
```

```
> function variables
```

```
✓ 4391026352 = (0, 0), 0, NAN, 0
```

```
> special variables
```

```
> function variables
```

```
columns = 12
```

```
> goal_weight = (10563, 11619)
```

```
✓ grid = [(0, 0), 0, NAN, 0]
```

```
> special variables
```

```
> function variables
```

```
> 0 = [(0, 0), 0, NAN, 0]
```

```
> 1 = [(1, 0), 0, NAN, 0]
```

```
> 2 = [(2, 0), 1, UNUSED, 0]
```

```
> 3 = [(3, 0), 1, UNUSED, 0]
```

```
> 4 = [(4, 0), 1, UNUSED, 0]
```

```
> 5 = [(5, 0), 1, UNUSED, 0]
```

```
> 6 = [(6, 0), 1, UNUSED, 0]
```

```
> 7 = [(7, 0), 1, UNUSED, 0]
```

```
len() = 8
```

```
> id = UUID('2a54651b-25a6-4ca7-bdf4-1e7987918f73')
```

```
left_weight = 22182
```

```
right_weight = 0
```

```
rows = 8
```

```
✓ child_state = (0, 0), 0, NAN, 0
```

```
> special variables
```

```
> function variables
```

```
columns = 12
```

```
> goal_weight = (10563, 11619)
```

```
✓ grid = [(0, 0), 0, NAN, 0]
```

```
> special variables
```

```
> function variables
```

```
> 0 = [(0, 0), 0, NAN, 0]
```

```
> 1 = [(1, 0), 0, NAN, 0]
```

```
> 2 = [(2, 0), 1, UNUSED, 0]
```

```
> 3 = [(3, 0), 1, UNUSED, 0]
```

```
> 4 = [(4, 0), 1, UNUSED, 0]
```

```
> 5 = [(5, 0), 1, UNUSED, 0]
```

```
> 6 = [(6, 0), 1, UNUSED, 0]
```

```
> 7 = [(7, 0), 1, UNUSED, 0]
```

```
len() = 8
```

```
> id = UUID('2a54651b-25a6-4ca7-bdf4-1e7987918f73')
```

```
left_weight = 22182
```

```
right_weight = 0
```

```
> move = Move container from position (7, 4) to position (1, 3)
```

```
> neighbor_states_moves = [(0, 0), 0, NAN, 0
```

```
  new_grid = (0, 0), 0, NAN, 0
```

```
> special variables
```

```
> function variables
```

```
  columns = 12
```

```
> goal_weight = (10563, 11619)
```

```
> grid = [(0, 0), 0, NAN, 0
```

```
> id = UUID('2a54651b-25a6-4ca7-bdf4-1e7987918f73')
```

```
  left_weight = 22182
```

```
  right_weight = 0
```

```
  rows = 8
```

```
  total_weight = 22182
```

Test5

	Crane Starting point											
7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused	unused	Doe 1100	unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused	Owl 2020	unused	unused	unused	unused	unused	unused	unused
4	unused	unused	unused	unused	Ewe 10000	unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused	Cow 2011	unused	unused	unused	unused	unused	unused	unused
2	unused	unused	unused	unused	Dog 2007	unused	unused	unused	unused	unused	unused	unused
1	NAN	unused	unused	Pig 3044	Cat 2000	unused	unused	unused	unused	unused	unused	NAN
0	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN
row/col	0	1	2	3	4	5	6	7	8	9	10	11

Test5

	Crane Starting point											
7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused	unused		unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused		unused	unused	unused	unused	unused	unused	unused
4	unused	unused		unused		unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused		unused	Cat 2011	unused	unused	unused	unused	unused
2	unused	unused	unused	unused	Ewe 10000	unused	Owl 2020	unused	unused	unused	unused	unused
1	NAN	unused			Doe 1100	unused	Pig 3044	Dog 2007	Cat 2000	unused	unused	NAN
0	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN
row/col	0	1	2	3	4	5	6	7	8	9	10	11


```
> function variables
> 0 = [(0, 0), 0, NAN, 0
> 1 = [(1, 0), 0, NAN, 0
> 2 = [(2, 0), 1, UNUSED, 0
> 3 = [(3, 0), 1, UNUSED, 0
> 4 = [(4, 0), 1, UNUSED, 0
> 5 = [(5, 0), 1, UNUSED, 0
> 6 = [(6, 0), 1, UNUSED, 0
> 7 = [(7, 0), 1, UNUSED, 0
  len() = 8
> id = UUID('ef9c4643-7524-4165-ac8d-59e3e8248d73')
  left_weight = 22182
  right_weight = 0
  rows = 8
  total_weight = 22182
```

```
✓ 08 = ((0, 0), 0, NAN, 0)
  > special variables
  > function variables
✓ 0 = (0, 0), 0, NAN, 0
  > special variables
  > function variables
    columns = 12
  > goal_weight = (10563, 11619)
  > grid = [[(0, 0), 0, NAN, 0]
  > id = UUID('d13d0e20-7dc3-4637-96a7-935218896cbe')
    left_weight = 22182
    right_weight = 0
    rows = 8
    total_weight = 22182
  > 1 = Move container from position (7, 4) to position (1, 9)
```

Right_weight not updated

```
> function variables
  columns = 12
> goal_weight = (10563, 11619)
> grid = [(0, 0), 0, NAN, 0]
> id = UUID('1416946e-8157-41fd-8f2c-39ad334b2fa1')
  left_weight = 22182
  right_weight = 0
  rows = 8
  total_weight = 22182
  f_cost = 7
  g_cost = 7
  h_cost = 0
> initial_crane_position = (8, 0)
> move = Move container from position (1, 3) to position (7, 4)
```

```
def balance_heuristic(self, state):  
    left_w, right_w, total_w = state.calculate_weights()  
    return abs(left_w - right_w)
```

Weight is not updated immediately after move but recalculate again during search, i think it's not the most efficient way

```
for child_state, move in state.getPossibleStatesMove:  
    if child_state not in self.closed_set:  
        new_g_cost = g_cost + move.get_cost()  
        h_cost = self.balance_heuristic(child_state)  
        new_f_cost = new_g_cost + h_cost  
        new_path = path + [move]  
  
        heapq.heappush(self.open_set, (new_f_cost, n
```

Todo

- 1. We need to consider the cost between moves
 - The cost is stored at the movement now
- 2. Heuristic

[illegible]

Cost Debug

Isabel Chen

	Crane Starting point											
7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused			unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused	Owl 2020	unused	unused	unused	unused	unused	unused	unused
4	unused	unused	unused	unused	Ewe 10000	unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused	Cow 2011	unused	unused	unused	unused	unused	unused	unused
2	unused	unused	unused	unused	Dog 2007	unused	unused	unused	unused	unused	unused	unused
1	NAN	unused	unused	Pig 3044	Cat 2000	Doe 1100	unused	unused	unused	unused	unused	NAN
0	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN
row/col	0	1	2	3	4	5	6	7	8	9	10	11


```

✓ open_set = [(7, 7, [...], (0, 0), 0, NAN, 0

```

```

> special variables

```

```

> function variables

```

```

> 00 = (7, 7, [Move container from position (7, 4) to position (1, 3)], (0, 0), 0, NAN, 0
> 01 = (7, 7, [Move container from position (7, 4) to position (1, 5)], (0, 0), 0, NAN, 0
> 02 = (8, 8, [Move container from position (7, 4) to position (1, 6)], (0, 0), 0, NAN, 0
> 03 = (9, 9, [Move container from position (7, 4) to position (1, 1)], (0, 0), 0, NAN, 0
> 04 = (8, 8, [Move container from position (7, 4) to position (1, 2)], (0, 0), 0, NAN, 0
> 05 = (9, 9, [Move container from position (7, 4) to position (2, 0)], (0, 0), 0, NAN, 0
> 06 = (9, 9, [Move container from position (7, 4) to position (1, 7)], (0, 0), 0, NAN, 0
> 07 = (10, 10, [Move container from position (7, 4) to position (1, 8)], (0, 0), 0, NAN, 0
> 08 = (11, 11, [Move container from position (7, 4) to position (1, 9)], (0, 0), 0, NAN, 0
> 09 = (12, 12, [Move container from position (7, 4) to position (1, 10)], (0, 0), 0, NAN, 0
> 10 = (12, 12, [Move container from position (7, 4) to position (2, 11)], (0, 0), 0, NAN, 0
len() = 11

```

```

23
24     while self.open_set:
25         f_cost, g_cost, path, state = heapq.heappop(self.open_set)
26
27         if state.isBalanced():

```

```

def __lt__(self, other):
    return self.get_cost() < other.get_cost()

```

The problem is, now it only consider from point A to B, not the accumulated cost

[illegible]

```

> move = Move container from position (6, 4) to position (2, 11)
✓ possible_moves = [Move container from position (1, 3) to position (2, 0)
> special variables
> function variables
> 00 = Move container from position (1, 3) to position (2, 0)
> 01 = Move container from position (1, 3) to position (1, 1)
> 02 = Move container from position (1, 3) to position (1, 2)
> 03 = Move container from position (1, 3) to position (7, 4)
> 04 = Move container from position (1, 3) to position (1, 5)
> 05 = Move container from position (1, 3) to position (1, 6)
> 06 = Move container from position (1, 3) to position (1, 7)
> 07 = Move container from position (1, 3) to position (1, 8)
> 08 = Move container from position (1, 3) to position (1, 9)
> 09 = Move container from position (1, 3) to position (1, 10)
> 10 = Move container from position (1, 3) to position (2, 11)
> 11 = Move container from position (6, 4) to position (2, 0)
> 12 = Move container from position (6, 4) to position (1, 1)
> 13 = Move container from position (6, 4) to position (1, 2)
> 14 = Move container from position (6, 4) to position (2, 3)
> 15 = Move container from position (6, 4) to position (1, 5)
> 16 = Move container from position (6, 4) to position (1, 6)
> 17 = Move container from position (6, 4) to position (1, 7)
> 18 = Move container from position (6, 4) to position (1, 8)
> 19 = Move container from position (6, 4) to position (1, 9)
> 20 = Move container from position (6, 4) to position (1, 10)
> 21 = Move container from position (6, 4) to position (2, 11)
len() = 22
\ self = (0 0) 0 NaN 0

```

```

> 05 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(0, 5), state=0, container=NAN, 0)
> 06 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(0, 6), state=0, container=NAN, 0)
> 07 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(0, 7), state=0, container=NAN, 0)
> 08 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(0, 8), state=0, container=NAN, 0)
> 09 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(0, 9), state=0, container=NAN, 0)
> 10 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(0, 10), state=0, container=NAN, 0)
> 11 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(0, 11), state=0, container=NAN, 0)

len() = 12

```

```

1 = [Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(1, 0), state=0, container=NAN, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(2, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(3, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(4, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(5, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(6, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(8, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(9, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(10, 0), state=1, container=UNUSED, 0), Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(11, 0), state=1, container=UNUSED, 0)]

```

> special variables

> function variables

```

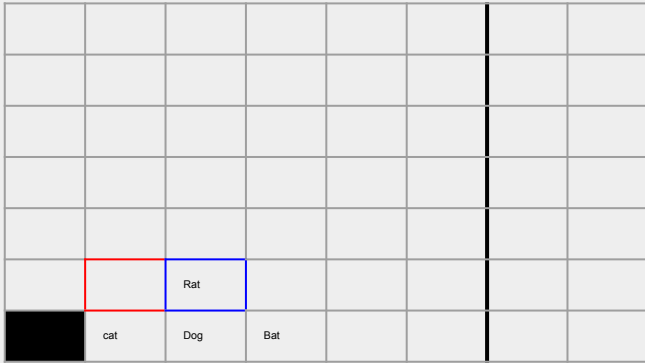
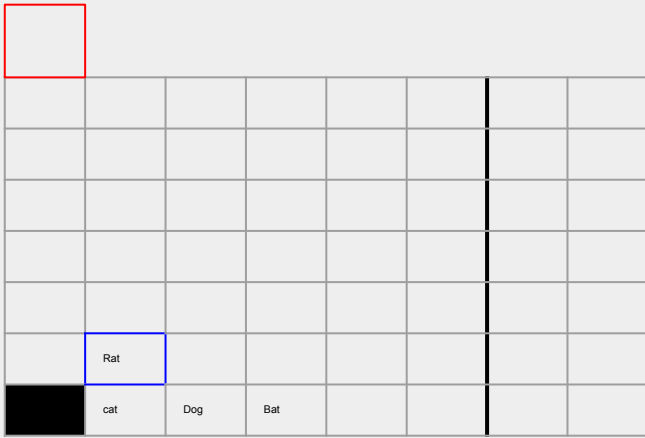
> 00 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 0), state=1, container=UNUSED, 0)
> 01 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 1), state=1, container=UNUSED, 0)
> 02 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 2), state=1, container=UNUSED, 0)
> 03 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 3), state=1, container=UNUSED, 0)
> 04 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 4), state=1, container=None)
> 05 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 5), state=1, container=UNUSED, 0)
> 06 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 6), state=1, container=UNUSED, 0)
> 07 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 7), state=1, container=UNUSED, 0)
> 08 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 8), state=1, container=UNUSED, 0)
> 09 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 9), state=1, container=UNUSED, 0)
> 10 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 10), state=1, container=UNUSED, 0)
> 11 = Slot(grid_id=80172891-8fba-4981-90e0-970e0d1b7c8b, position=(7, 11), state=1, container=UNUSED, 0)

```

Cost Debug

	Crane Starting point											
7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
4	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused	Cow 2011	Owl 2020	unused	unused	unused	unused	unused	unused
2	unused	unused	unused	unused	Dog 2007	Doe 1100	Ewe 10000	unused	unused	unused	unused	unused
1	NAN	unused	unused	unused	Cat 2000	Pig 3044	Doe 1100	unused	unused	unused	unused	NAN
0	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN	NAN
row/col	0	1	2	3	4	5	6	7	8	9	10	11

Time cost for operator



```
=====
Balancing job selected.
```

```
Balanceable! Combinations: [[[60], [20, 20, 20]]]
```

```
Balanced path found
```

```
Balance Moves:
```

```
Move container from position (1, 1) to position (1, 2)
```

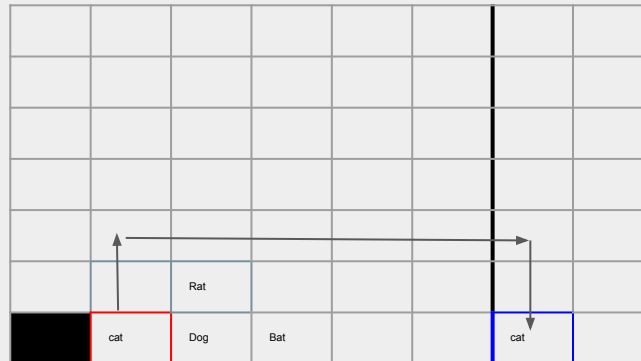
```
Move container from position (0, 1) to position (0, 6)
```

Actual Crane Path and Cost:

1. Move container from (1,1) to (1,2)
 - a. (7,0) to (1,1) = 7
 - b. (1,1) to (1,2) = 1

2. Move container from (0,1) to (0,6)

There is an obstacle in the way, so the cost is move up, right, then down. The cost is 9. NOT 5.



	Crane Starting point											
7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
4	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
2	Cat	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
1	NAN	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	NAN
0	NAN	NAN	NAN	unused	unused	unused	unused	unused	Owl	NAN	NAN	NAN
row/col	0	1	2	3	4	5	6	7	8	9	10	11

e)

38

-

new_f_cost = new_g_cost + h_cost

39

new_path

= path + [move]

e)

39

+

new_f_cost += new_g_cost + h_cost

40

new_path

= path + [move]

Transfer

Loading

- move container from truck to the nearest unused slot

Unloading

Unloading scenario 1

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	1	unused	unused	9	2
NAN	NAN	unused	unused	NAN	NAN

1. If the container is the topmost in its column, just unload it

Unloading scenario 2-1

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7	1	unused	unused	9	2
NAN	NAN	unused	unused	NAN	NAN

1. If the container is the topmost in its column, just unload it
2. If the container below some container
 - a. Move the above container(s) away
 - i. To the nearest valid slot
 - b. Take the container out

Unloading scenario 2-2

5	unused	unused	unused	unused	unused
10	5	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	9	2
NAN	NAN	unused	unused	NAN	NAN

unused	10	unused	unused	unused	unused
10	5	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	9	2
NAN	NAN	unused	unused	NAN	NAN

For example

- **Unload 7, cost = 16**
 - Move 5 away, now the crane is at (3,2), cost $1+2 = 3$
 - Move 10 away, cost $= 1 + 2 = 3$
 - Unload 7, cost $= 3 + 3 + 4$ (to car)

unused	10	unused	unused	unused	unused
unused	5	unused	unused	unused	4
unused	1	unused	unused	9	2
NAN	NAN	unused	unused	NAN	NAN

Loading and Unloading

Load item1

Load Item2

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	9	2 <small>unload</small>
NAN	NAN	unused	unused	NAN	NAN

1. How do we know to Load or Unload first?

Load item1

Load Item2

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	unused	unused
NAN	NAN	unused	unused	NAN	NAN

1. How do we know to Load or Unload first?
 - a. Based on the cost.
2. For example
 - a. For each state, we expand all the possible next moves,
 - Unload 7 cost = 16
 - Unload 2 cost = 22
 - Load item1
 - Load item2

Load Item2

5	unused	unused	unused	unused	unused
10	item1	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	unused	2 <small>unload</small>
NAN	NAN	unused	unused	NAN	NAN

1. How do we know to Load or Unload first?
 - a. Based on the cost.
2. For example
 - a. For each state, we expand all the possible next moves,
 - Unload 7 cost = 16
 - Unload 2 cost = 22
 - Load item1 cost = 7
 - Load item2

Load Item1

5	unused	unused	unused	unused	unused
10	item2	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	unused	2 <small>unload</small>
NAN	NAN	unused	unused	NAN	NAN

1. How do we know to Load or Unload first?
 - a. Based on the cost.
2. For example
 - a. For each state, we expand all the possible next moves,
 - Unload 7 cost = 16
 - Unload 2 cost = 22
 - Load item1 cost = 7
 - Load item2 cost = 7

Load item1

Load Item2

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	9	2 <small>unload</small>
NAN	NAN	unused	unused	NAN	NAN

1. How do we know to Load or Unload first?
 - a. Based on the cost.
2. For example
 - a. For each state, we expand all the possible next moves,
 - Unload 7 cost = 16
 - Unload 2 cost = 22
 - Load item1 cost = 7
 - Load item2 cost = 7

Load item1

Load Item2

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	9	2 <small>unload</small>
NAN	NAN	unused	unused	NAN	NAN

1. How do we know to Load or Unload first?
 - a. Based on the cost.
2. For example
 - a. For each state, we expand all the possible next moves,
 - *Unload 7 cost = 16 ←not correct*
 - *Unload 2 cost = 22 ←not correct*
 - Load item1 cost = 7
 - Load item2 cost = 7

Now the question is, during unloading, there are multiple steps, for each step, we should consider it as a new state and consider our sequence again.

Load item1

Load Item2

5	unused	unused	unused	unused	unused
10	unused	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	9	2 <small>unload</small>
NAN	NAN	unused	unused	NAN	NAN

5	unused	unused	unused	unused	unused
10	5	unused	unused	unused	4
7 <small>unload</small>	1	unused	unused	9	2 <small>unload</small>
NAN	NAN	unused	unused	NAN	NAN

Now the question is, during unloading, there are multiple steps, for each step, we should consider it as a new state and consider our sequence again.

1. For example, to **Unload 7**
 - a. Move 5 away, cost: $1 + 2 = 3$, at this point, it's a new grid. We expand the state
 - Unload 7 cost
 - Unload 2 cost
 - Load item1 cost
 - Load item2 cost

Grid representation

Unload list = [] (include names of the unloading container)

Load list = [] (include names and weights of the loading containers)

Container= [] (keep track of containers on the ship for manifest)

Process

If a problem is transfer,

Initial the the problem with the grid state with: (a) manifest, (b) unload list, (c) load list, (d) initial crane position

(a) Cannot be empty

(b) Or (c) could be empty, but not both. One of them must be not empty list

(d) initial/end crance position (8,0)

Begin solving the problem

1. Let's define which containers can be moved and where to be moved:
 - a. Search for unload list. If we can unload that item(no blocking), that item can be moved. And the destination is the truck
 - b. Search for unload list, if the item has containers above it, we can remove that container to other slots available (move to other column) in the grid.
 - c. Search for load list, move a container from the truck into the grid. The start position is truck and the end position is inside the grid.

Crane Position Representation:

- Use the crane position as a simple attribute ("truck" or (row, col) for the grid).

Cost Calculation:

- The crane_position is only used to calculate the cost of moving the crane:
 - From the truck to the grid
 - From the grid to the truck
 - Between slots within the grid
 -

A State Representation*:

- The grid state (Grid) remains the same as before, with crane_position simply stored for cost evaluation.
- The crane position doesn't add additional complexity to the A* search itself.. it's just used for cost computations.

Loading

If the crane starts at $(8,0)$:

Takes 2 minutes to move to the truck;

If the crane starts at other positions in the grid:

Move to $(8,0)$ then + 2 minutes to the truck;

If the crane starts at the truck: the cost of crane to start is 0

Load Bat

	Crane Starting point											
7	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
6	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
5	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
4	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
3	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
2	Cat	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused	unused
1	NAN	Dog	unused	unused	unused	unused	unused	unused	unused	unused	unused	NAN
0	NAN	NAN	NAN	Ram	unused	unused	unused	unused	Owl	NAN	NAN	NAN
row/col	0	1	2	3	4	5	6	7	8	9	10	11

Debug Load unload

```
1  unload,Dog
2  load,Bat,431
```

```

✓ state = Position: (0, 0), State: 0, Container Name: NAN, Container Weight: 0
> special variables
> function variables
  columns = 12
> crane_position = (-1, -1)
  goal_weight = 0
> id = UUID('a1a399c5-2da8-46e1-b74c-d7e729e5b869')
> left_containers = {Cat, 99, Dog, 100}
  left_weight = 199
> load_list = [('Bat', 431)]
> right_containers = {}
  right_weight = 0
  rows = 8
> slot = [[Slot(grid_id=a1a399c5-2da8-46e1-b74c-d7e729e5b869, position=(0, 0), state=0...
  total_weight = 199
> unload_list = [Dog, 100]
  _ = 4529941648
> Globals

```



A 10x10 grid with a red 'Cat Dog' label in the bottom-left cell and a black square in the bottom-right cell.