



嵌入式軟體聯盟  
Embedded Software Consortium



# Exception

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# Exceptions

- ❖ Exceptions are usually used to handle **unexpected events** which arise during the execution of a program

# Exception in Linux

- ❖ When an exception is generated, a function: **vector\_swi()** is called.
- ❖ vector\_swi() is defined in `<kernel source code/arch/arm/kernel/entry-common.S>`.
- ❖ vector\_swi() gets the system call number in the **R7 register** and finds the system call address in the `sys_call_table` and invokes it.
- ❖ Registers R0-R6 are used to send arguments to the system calls.

# Outline

## ❖ Environment

## ❖ Goal

## ❖ Steps

- Initialization
- Operation a system call
- Write a system call

## ❖ Reference

# Environment

## ❖ PC x 1

### ➤ Linux Ubuntu

- Editor, arm cross compiler

## ❖ Raspberry Pi

# Goal

- ❖ Observe the initialization of exception.
- ❖ Observe the implementation of system calls.
- ❖ Add a new system call.

# Initialization

## ❖ System boot

- Start kernel

## ❖ Lab. steps

- Download kernel
- Compile kernel

# Observation of a system call (1)

- ❖ In general, a **user level process** is not supposed to access kernel.
- ❖ Linux uses **software interrupt** to generate exception to implement system calls.
- ❖ The user-level calling process fills the registers with the appropriate values and then **calls a special instruction** which jumps to a previously defined location in the kernel.



# Observation of a system call (2)

❖ I/O is conducted by the system

➤ Use a `printf` program to investigate its assembly

❖ Cross-compile with static link

```
$arm-linux-gnueabihf-gcc -g -static -o  
test.exe test.c
```

❖ Disassemble the executable code: test.exe

```
$arm-linux-gnueabihf-objdump -d test.exe  
> assembly
```

# Observation of a system call (3)

## ❖ Find an svc(swi) instruction for the system call

```
pschen@SmallTurtleLinux1: ~/RaspberryPi3/test
2726c: e49d7004 pop {r7} ; (ldr r7, [sp], #4)
27270: e3700a01 cmn r0, #4096 ; 0x1000
27274: 312fff1e bxcc lr
27278: ea000e18 b 2aae0 <__syscall_error>
2727c: e1a00000 nop ; (mov r0, r0)

00027280 <__libc_open>:
27280: e59fc060 ldr ip, [pc, #96] ; 272e8 <__libc_open+0x68>
27284: e79fc00c ldr ip, [pc, ip]
27288: e33c0000 teq ip, #0
2728c: e52d7004 push {r7} ; (str r7, [sp, #-4]!)
27290: 1a000005 bne 272ac <__libc_open+0x2c>
27294: e3a07005 mov r7, #5
27298: ef000000 svc 0x00000000
2729c: e49d7004 pop {r7} ; (ldr r7, [sp], #4)
272a0: e3700a01 cmn r0, #4096 ; 0x1000
272a4: 312fff1e bxcc lr
272a8: ea000e0c b 2aae0 <__syscall_error>
272ac: e92d400f push {r0, r1, r2, r3, lr}
272b0: eb000816 bl 29310 <__libc_enable_asynccancel>
272b4: e1a0c000 mov ip, r0
272b8: e8bd000f pop {r0, r1, r2, r3}
```

# Write a system call (1)

## ❖ Define a system call

- <Linux kernel source code>/arch/arm/kernel/calls.S

## ❖ You also need to generate a system call "stub" so that an ordinary user program can invoke your system call.

- <Linux kernel source code>/arch/arm/include/uapi/asm/unistd.h

## ❖ Write your system call

- Find the place suitable for your system call
- Add **asmlinkage** in front of the function and **sys\_** in front of the call
- include <linux/linkage.h> and <linux/kernel.h>

# Write a system call (2)

## ❖ Define a system call

```
CALL(sys_pkey_mprotect)
/* 395 */ CALL(sys_pkey_alloc)
CALL(sys_pkey_free)
CALL(sys_mysyscall)
```

## ❖ Establish a “stub”

```
#define __NR_pkey_mprotect    (__NR_SYSCALL_BASE+394)
#define __NR_pkey_alloc      (__NR_SYSCALL_BASE+395)
#define __NR_pkey_free       (__NR_SYSCALL_BASE+396)
#define __NR_mysyscall       (__NR_SYSCALL_BASE+397)
```

# Write a system call (3)

❖ Add **mysyscall.c** for the system call

```
➤ #include <linux/linkage.h>
#include <linux/kernel.h>
asmlinkage void sys_mysyscall(int a, char *b)
{
    printk("system call ...\n");
    printk("int1:%d, staring:%s in kernel\n",a,b);
}
```

# Write a system call (4)

❖ User applications use the system call

➤ **mytestsys.c**

```
#include <sys/syscall.h>
#include <linux/unistd.h>
#define __NR_mysyscall (__NR_SYSCALL_BASE+397)
#define mysyscall(a,b) syscall(__NR_mysyscall, (a), (b))
int main()
{
    mysyscall(14, "system_call_lab");
    return 0;
}
```

# Write a system call (5)

## ❖ Compilation and verification

- Modify makefile under <linux source>/arch/arm/kernel for the system call
  - Add obj-y += ..... **mysyscall.o**
- Re-compile the kernel
- Compile mytestsys.c for the target, ARM-Linux
  - Cross compile
  - arm-linux-gnueabi-gcc -I<Linux Source Code>/include/ -g mytestsys.c -o mytestsys.exe
- Execute the user program(ex: ./mytestsys.exe) in Raspberry Pi
  - type **dmesg** in terminal and the system call message will be displayed.

## ❖ Q1: asmlinkage的描述是什麼意義？

**For example:**

```
asmlinkage int sys_myservice (...)  
{  
    ...  
}
```

請在實驗報告裡回答。