

Open Command-oriented Geometric Graphics Generator

OpenCG³ Specification Version 0.2.12

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Regular Expressions

$\mathbb{N} := \{ \alpha \mid \alpha \in [0-9]^+ \}$

$\mathbb{R} := \{ \alpha \mid \alpha \in [+ \backslash -]^? ([0-9]^* [.])^? [0-9]^+ \}$

$\Rightarrow \mathbb{R} \supset \mathbb{N}$

$\mathbb{S} := \{ \alpha \mid \alpha \in '(. * ?)' \mid [. 0-9 A-Z a-z + \backslash -]^+ \}$

$\Rightarrow \mathbb{S} \supset \mathbb{R}$

$\mathbb{W} := \{ \alpha \mid \alpha \in [\backslash t]^* \}$

whitespace

Descriptions

- The matching mechanism abides by the maximal munch rule.
- Each command is whitespace-insensitive except being quoted by a pair of single quotation marks (').

Context-Free Expansions

$$\mathbf{C} \rightarrow \mathbf{AC} \mid ; \mid \text{EOL}$$

$$\mathbf{A} \rightarrow \mathbf{T(A)} \mid \mathbf{V(A)} \mid \mathbf{S(A)} \mid \mathbf{L(A)} \mid \mathbf{L(A, A, \dots, A)} \mid \mathbf{N} \mid \mathbf{R} \mid \mathbf{S}$$

$$\begin{array}{l} \mathbf{T(\Pi)} \equiv \Pi : n \rangle \rightarrow (\Sigma(\Pi, n)) \\ \mathbf{V(\Pi)} \equiv \Pi : n \rangle \rightarrow < \Sigma(\Pi, n) > \\ \mathbf{S(\Pi)} \equiv \Pi : n \} \rightarrow \{ \Sigma(\Pi, n) \} \\ \mathbf{L(\Pi_1, \Pi_2, \dots, \Pi_{n-1}, \Pi_n)} \equiv \mathbb{L} [\Pi_1 \Pi_2 \dots \Pi_{n-1} \Pi_n] \rightarrow [\Pi_1 \dots \Pi_n] \end{array} \quad \left\| \quad \begin{array}{l} \Sigma(\Pi, n) \rightarrow \overbrace{\Pi \dots \Pi}^{n \text{ items}} \quad (\text{identical}) \\ \mathbf{L(\Pi)} \equiv \mathbb{L} [\Pi : n] \rightarrow [\Sigma(\Pi, n)] \end{array} \right.$$

Descriptions

- Each command starts from \mathbf{C} and ends with a $;$ or an EOL.
- Non-terminal symbol expansions are prior than function expansions.

Escape Sequence

- `\x` is an escape sequence.
- If `x` is `\`, then it is treated as a single backslash.
- If `x` is EOL which may vary from platforms, then the sequence is omitted.
- Otherwise, the sequence is ignored and triggers a warning by default.

Error Handling

- Physical lines are separated by an EOL.
- Logical lines are separated by either a semicolon or an unescaped EOL.
- If the command cannot be parsed by the grammar, then all the characters on the same logical line will be discarded.

Definitions

- The whole system are divided into four fields and several classes:
 - ① field e-(nviron.): includes class window and class camera.
 - ② field p-(rimitive): includes class point, class circle, etc.
 - ③ field c-(ompound): includes class line, class triangle, class polygon, etc.
 - ④ field a-(uxiliary): includes class attrib and class group.

Notations

- class^x denotes the name of the class in the field x .
- label^x denotes the unique name of the object from the class in the field x .

Prototypes

- Argument prototypes are written in a mixture of types and names with underlines.
- Each type with an asterisk indicates that the brackets are used for cross-referencing.
- Cross-reference is a feature for manipulating multiple objects in a single command.
- Each name with a plus/minus/ampersand implies that the given name is used for creating new objects/deleting existed objects/cross-referencing among objects, etc.

Perspective Projection

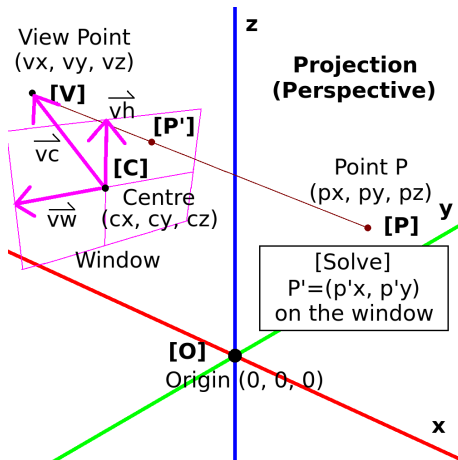


Figure: Projection in Euclidean \mathbb{R}^3 Space

Command

`create window § +labele` (1)

Parametres

- label^e : the name of the object instantiated from the class window

Examples

`create window main`

Delete a Window

Command

```
delete window $ -labele $ string (2)
```

Parametres

- label^e : the name of the object instantiated from the class window
- string : the text printed right after exiting the session

Examples

```
delete window main  
delete window main 'Have a nice day.'
```


Command

create camera S +label^e $\mathbb{R} : 3$) centre $\mathbb{R} : 3$: 2) plane $\mathbb{R} : 3$ > sight (3)

Parametres

- label^e : the name of the object instantiated from the class camera
- centre : the world coordinate (c_x, c_y, c_z) of the centre of the viewport
- plane : the horizontal and the vertical vectors (\vec{v}_w, \vec{v}_h) of the viewport
- sight : the reverse line of sight \vec{v}_c from centre to the camera

Examples

create camera z-top (0 0 1) (<1 0 0> <0 1 0>) <0 0 1>

Command

```
select camera S &label1e S &label2e (4)
```

Parametres

- label₁^e : the name of the object instantiated from the class camera
- label₂^e : the name of the object instantiated from the class window

Examples

```
select camera z-top main
```

Command

`create point` $\frac{\mathbb{S} \text{ +label}^P : \{ \}^*}{\mathbb{R} : 3} \underline{\text{coord}}$ (5)

`create point` $\frac{\mathbb{S} \text{ +label}^P : \geq n)^*}{\mathbb{R} : 3} \underline{\text{coord} : n)^*}$ (6)

Parametres

- label^P : the name of the object instantiated from the class point
- coord : the world coordinate (p_x, p_y, p_z) of the object named label^P

Examples

```
create point 'origin'    (0 0 0)
create point {X-1 X-2}   (1 0 0)
create point (Y-1 Z-1) ((0 1 0)(0 0 1))
```

Command

`delete point` \S -label^P : }^{*} (7)

Parametres

- label^P : the name of the object instantiated from the class point

Examples

```
delete point origin  
delete point {origin 'random-point'}
```

Command

`create attrib $ +labela : }* L [L [$ classp,c L [$ prop $ value :]] :]* (8)`

`create attrib $ +labela : }* L [L [$ classp,c L [$ prop $ value :]] :]* (9)`

Parametres

- label^a : the name of the object instantiated from the class `attrib`
- class^{p,c} : the name of a class in the field primitive or compound
- prop : the property of the object of class^{p,c}
- value : the value of prop in designated format

Examples

```
create attrib (magenta dashed-and-translucent-line) \  
[[point fill-hsv '(300 1.0 1.0)'] \  
 [line [style dashed] [fill-rgba '[(0 255 0) 0.5]']]]
```

Command

`attach attrib \S &labela :)* \S &labelp,c : }*` (10)

`attach attrib \S &labela :)* \S &labelp,c : }*` (11)

Parameters

- label^a : the name of the object instantiated from the class attrib
- label^{p,c} : the name of the object instantiated from a class in the field p or c

Examples

```
attach attrib red point-0
attach attrib (red large) point-1
attach attrib blue {point-2 rect-0}
attach attrib (5px black) {point-3 circ-0}
attach attrib (red thick) (point-4 line-0 triangle-0)
```

Command

`assign operat S action S class N repeat [= ∞]` (12)

Parametres

- action : the name of the corresponding action of class
- class : the name of a class
- repeat : the amount of the commands emitting operation names

Examples

```
assign operat create point 2
x-axis (1 0 0)
y-axis (0 1 0)
// Back To Normal
```