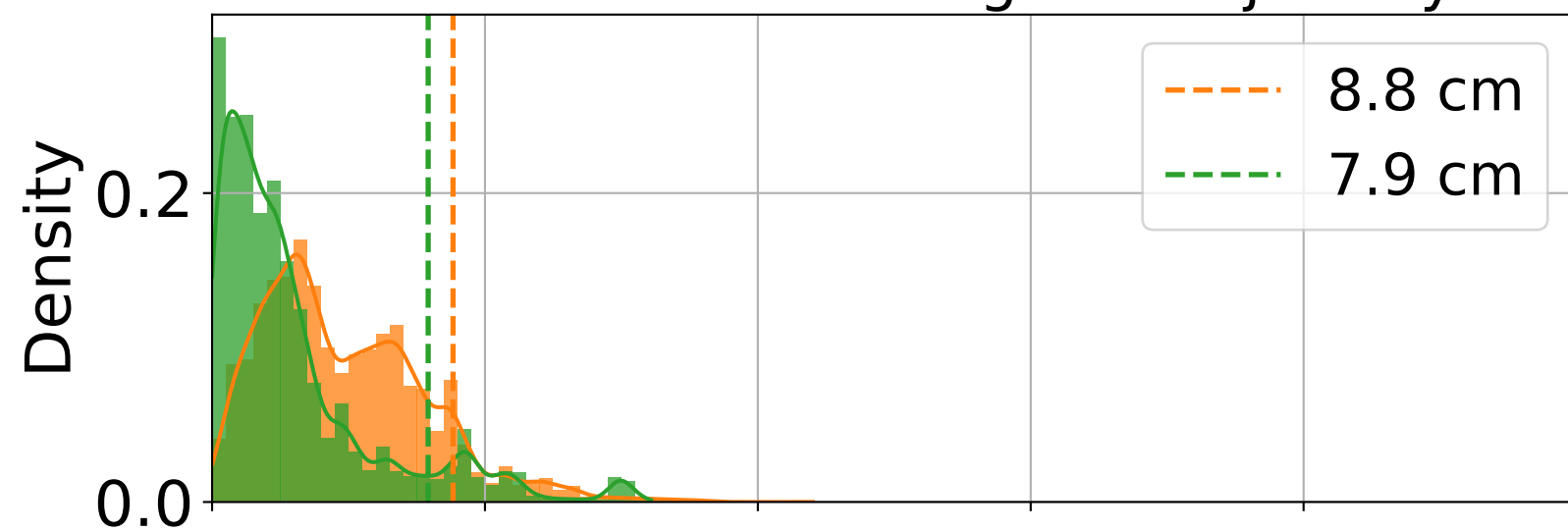
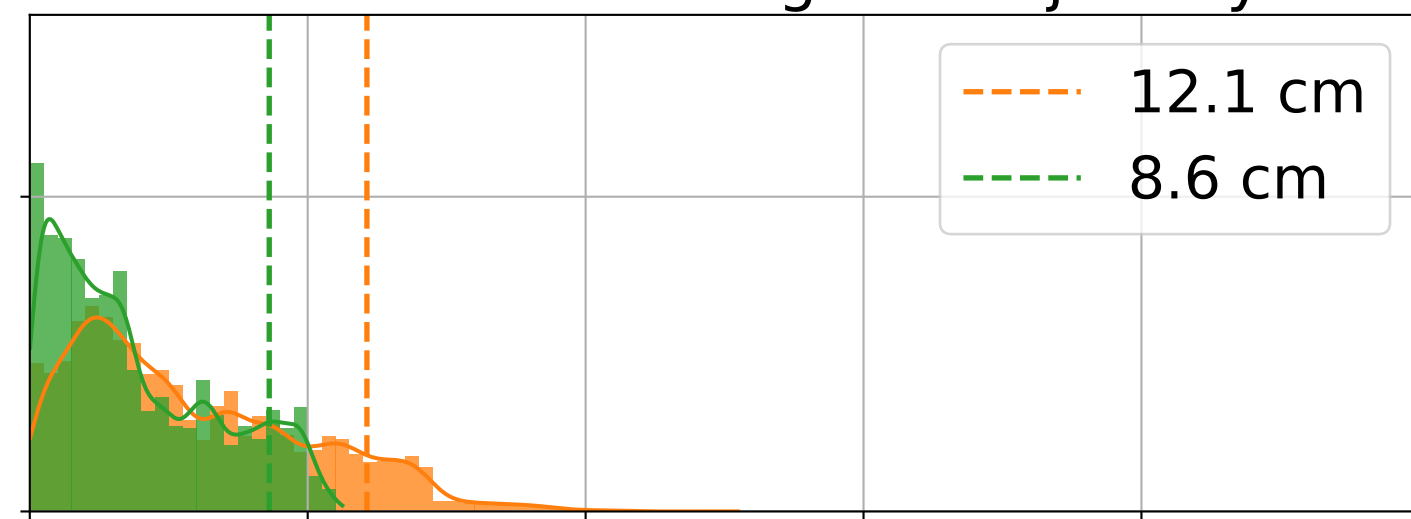


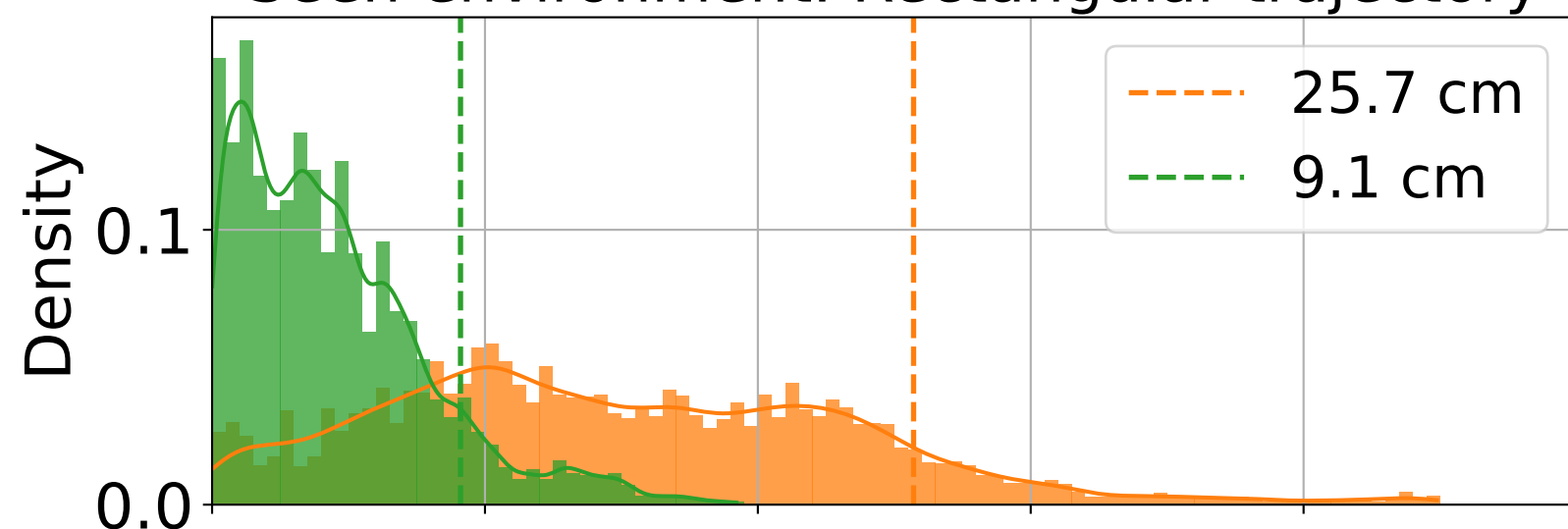
No obstacles. Rectangular trajectory



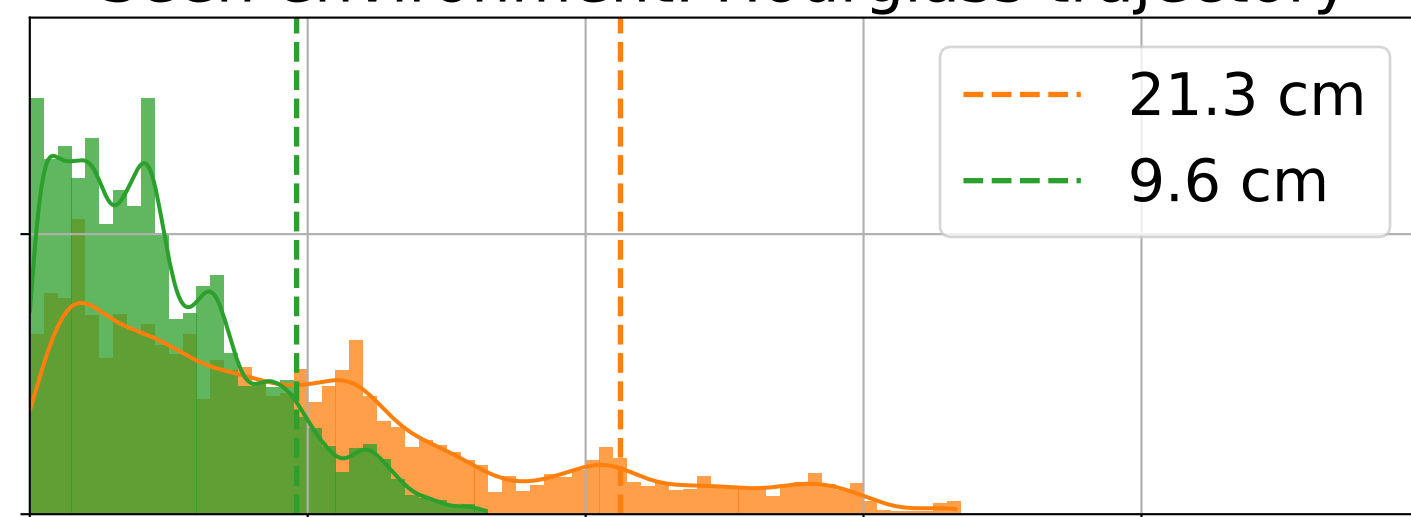
No obstacles. Hourglass trajectory



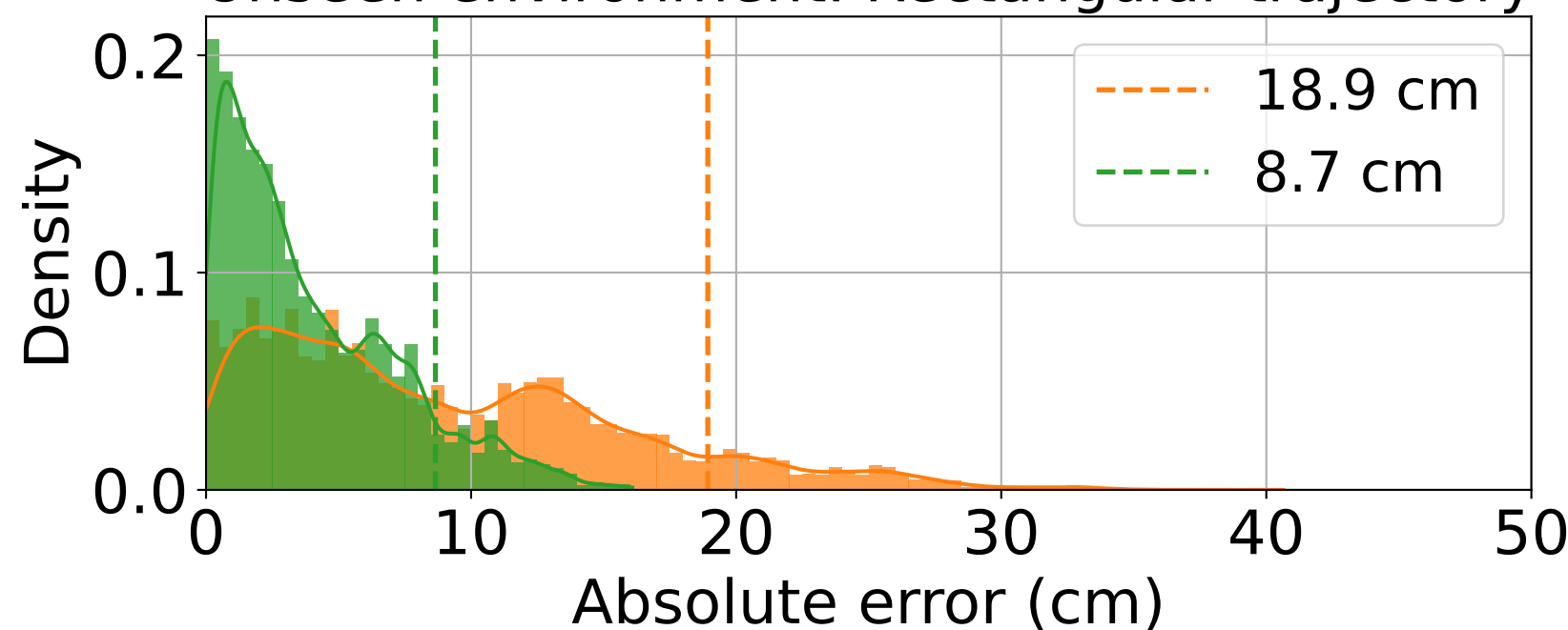
Seen environment. Rectangular trajectory



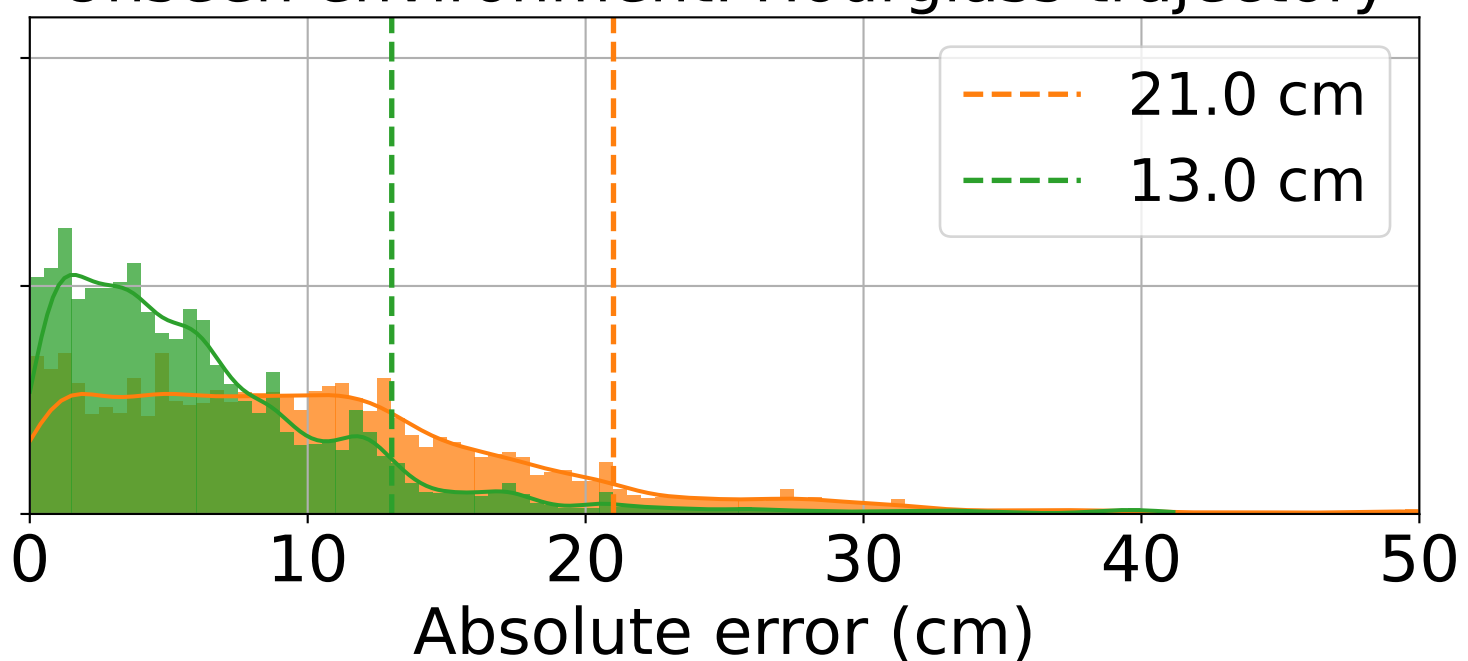
Seen environment. Hourglass trajectory



Unseen environment. Rectangular trajectory



Unseen environment. Hourglass trajectory



Raw Mitigated 90th percentile (raw) 90th percentile (mitigated)