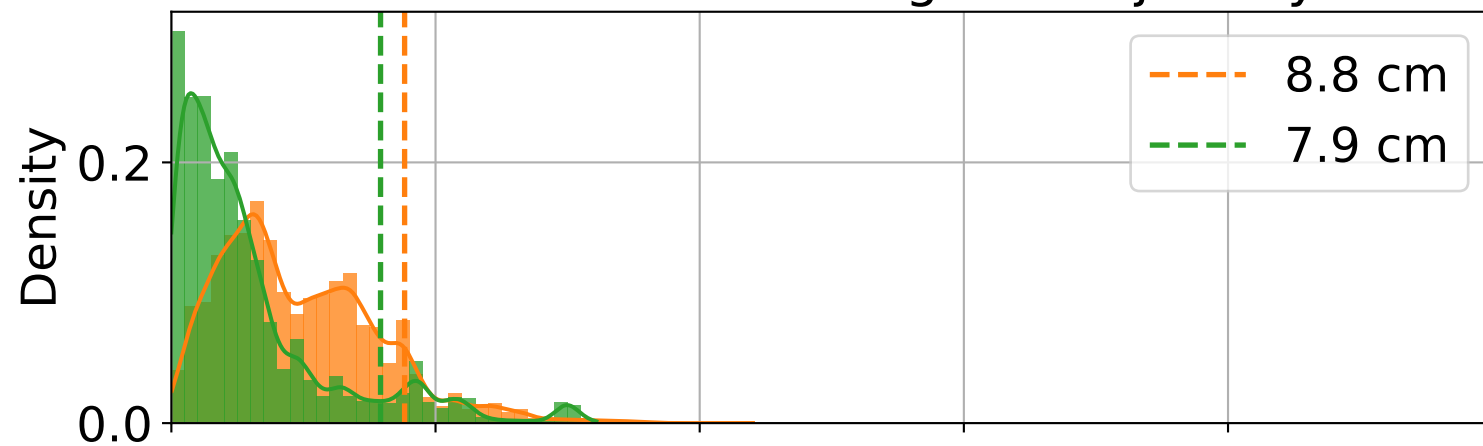
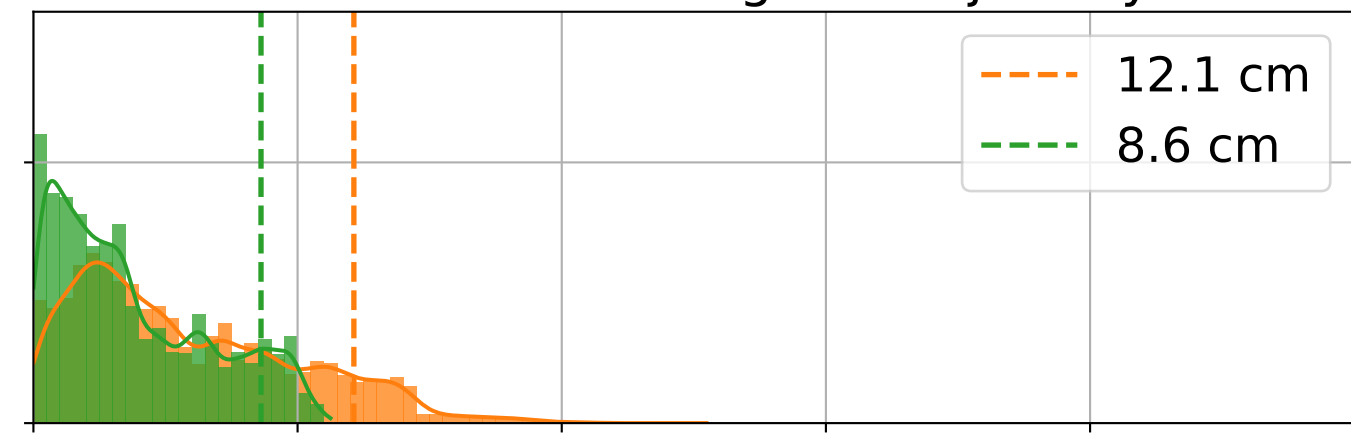


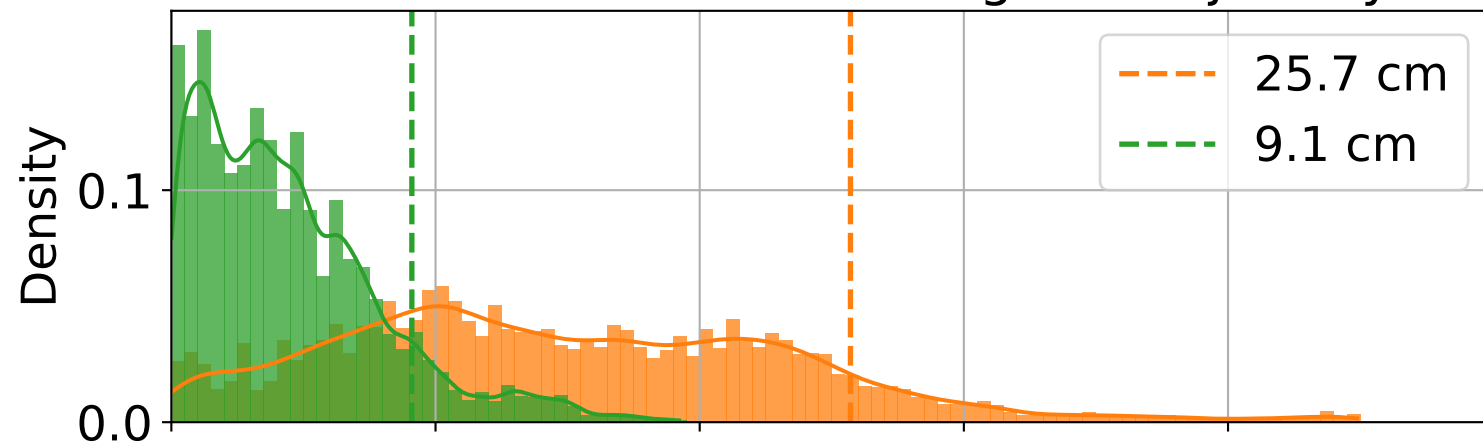
No obstacles. Rectangular trajectory



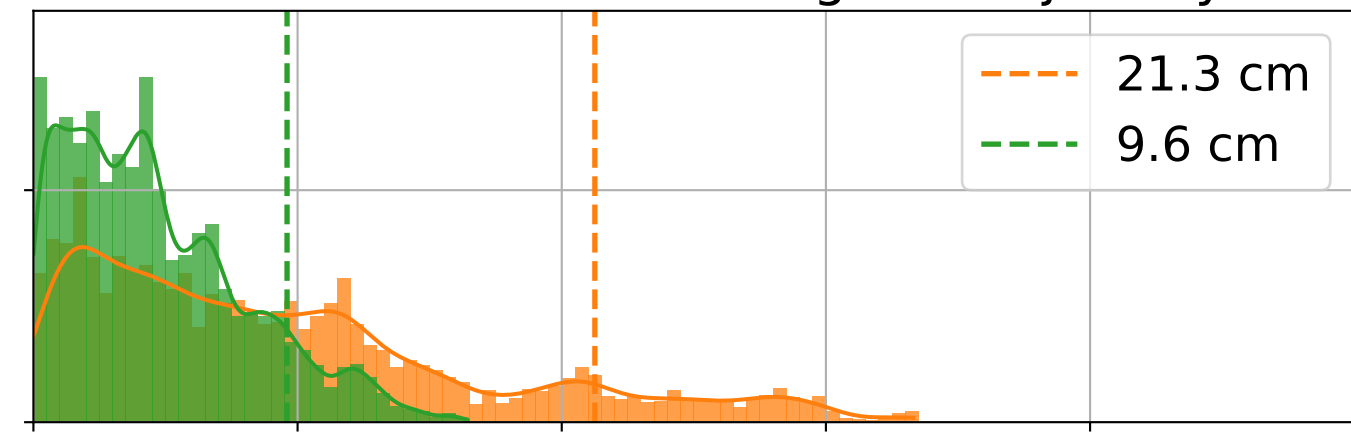
No obstacles. Hourglass trajectory



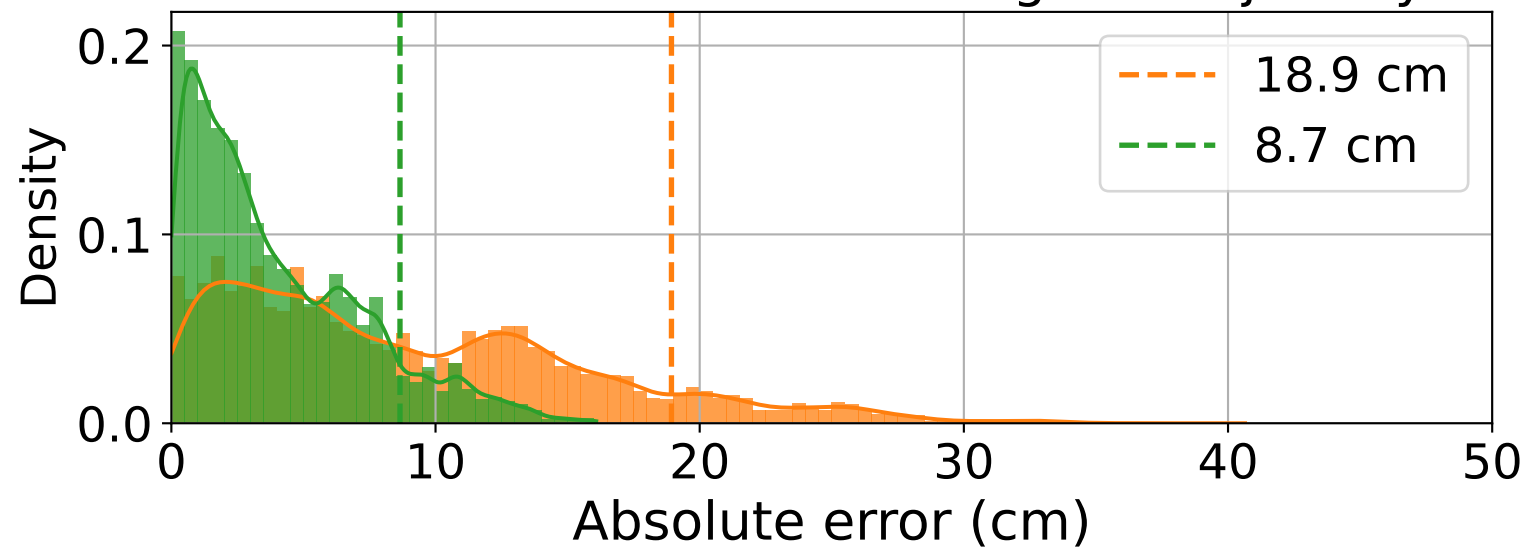
Seen environment. Rectangular trajectory



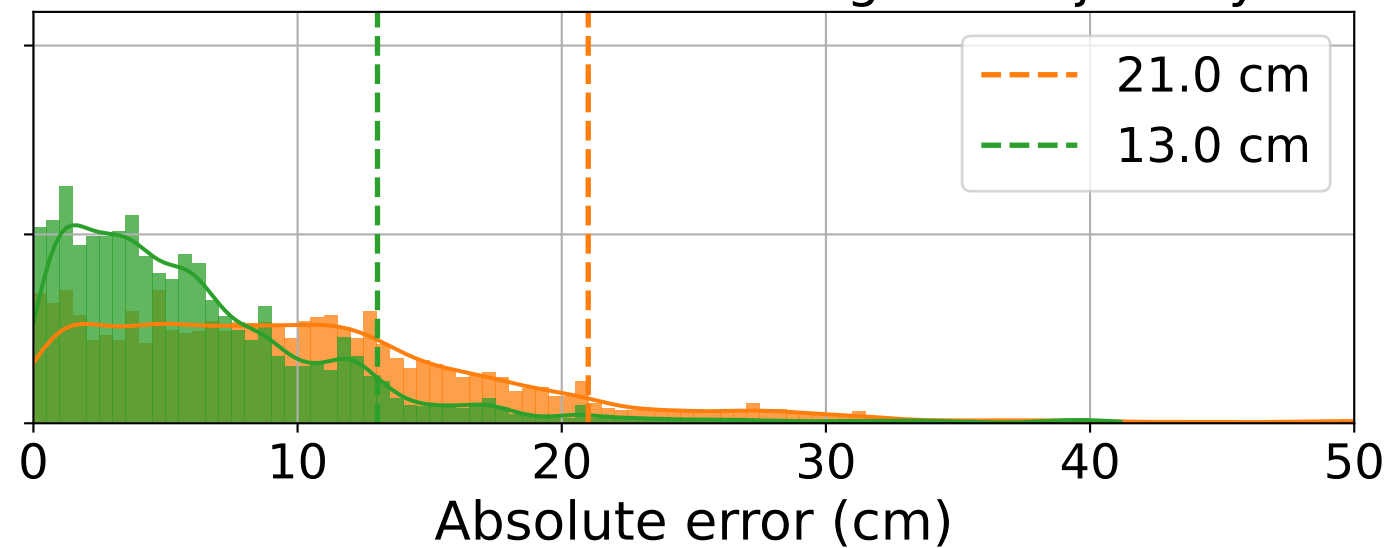
Seen environment. Hourglass trajectory



Unseen environment. Rectangular trajectory



Unseen environment. Hourglass trajectory



■ Raw
 ■ Mitigated
 --- 90th percentile (Raw)
 --- 90th percentile (Mitigated)