

Convolutional Neural

Networks (CNNs)

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Data pre-processing

• Local mean subtraction: subtract the mean from original data
•  $X = X - \mu$ • Normalization: scale original data to a specific range
•  $X = \frac{X - \mu}{\sigma}$ • ...

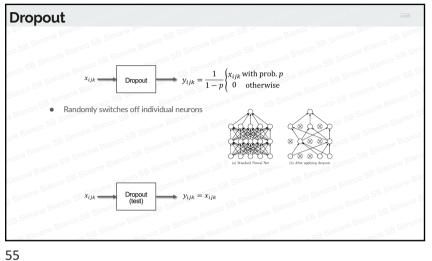
original data

zero-centered data

normalized data

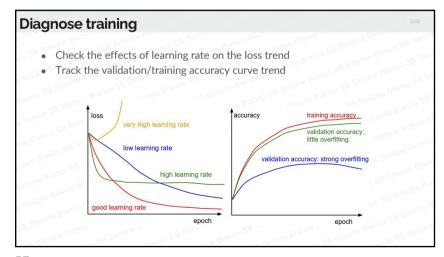
Overfitting is a problem since CNNs have many parameters
 Forms of regularization approaches
 Weight decay (Penalizes weight magnitudes)
 Dropout
 Data augmentation

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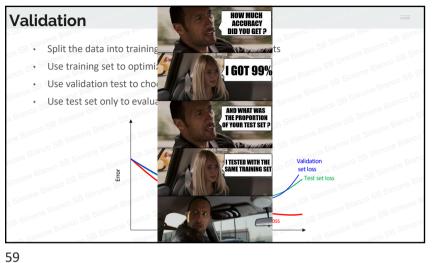


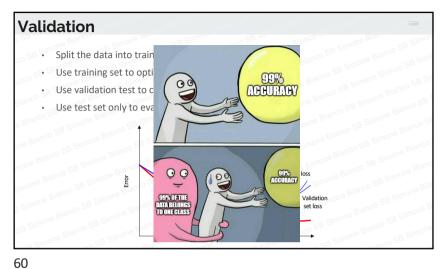
Data augmentation • Augment the training set by "jittering" samples • Label preserving image transformations: ■ Horizontal flip Random crop Color casting ■ Geometric distortion

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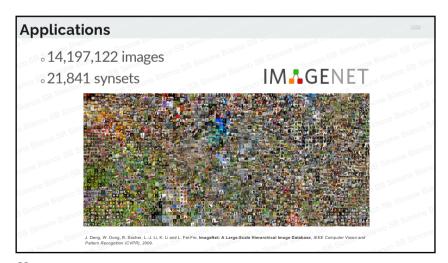


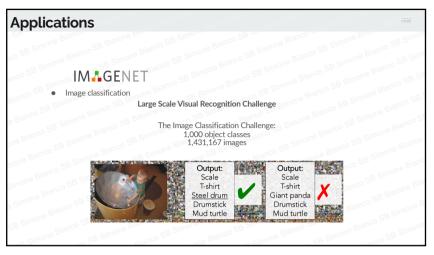
**Validation** · Split the data into training, validation, and test subsets • Use training set to optimize model parameters · Use validation test to choose the best model Use test set only to evaluate performance Training set loss

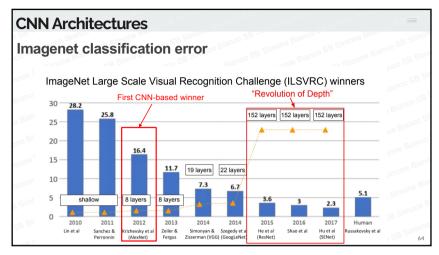


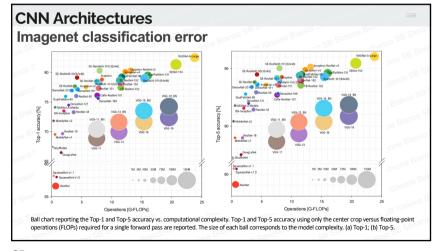


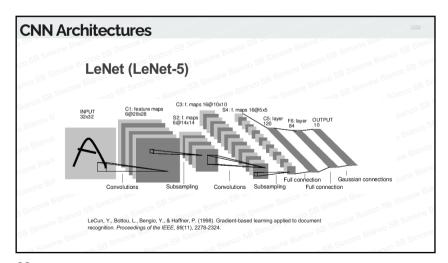


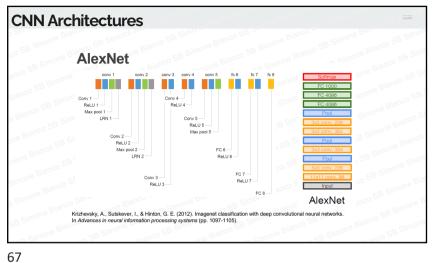


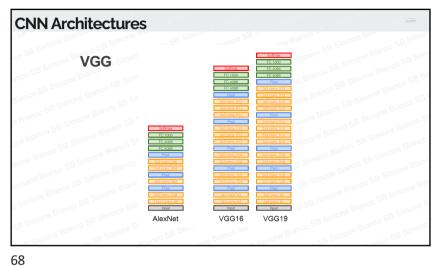


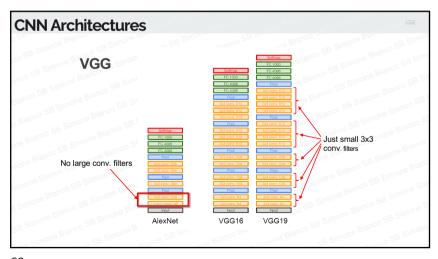






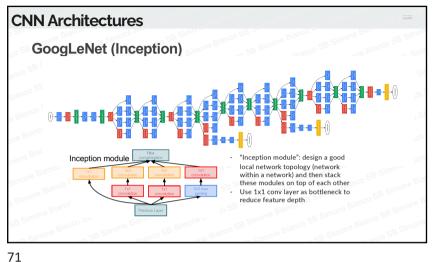


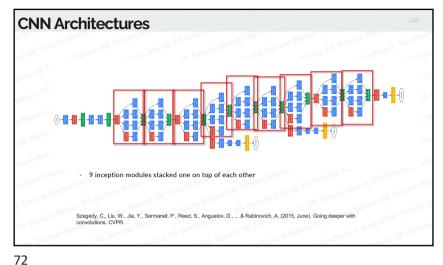


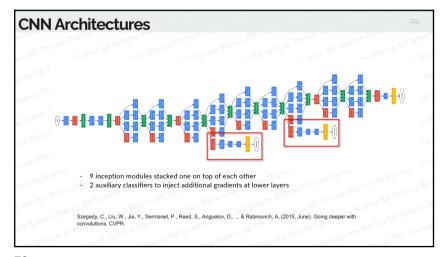


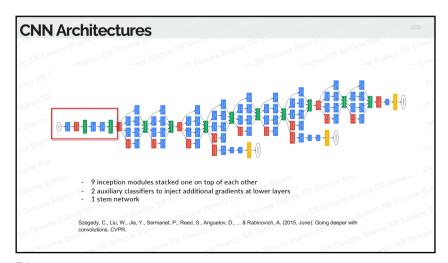
**CNN Architectures VGG** Why use smaller filters? Stack of 3x3 conv filters has the same receptive field as one 7x7 But makes the CNN deeper, with more nonlinearities And fewer parameters

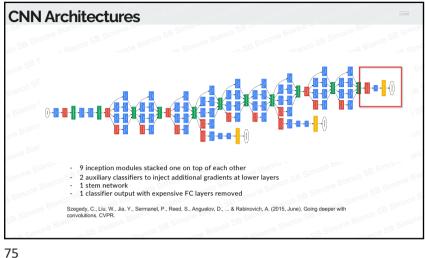
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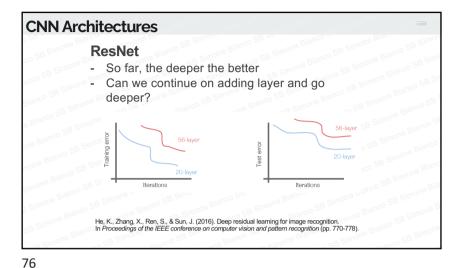








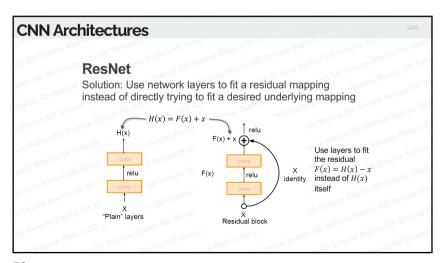


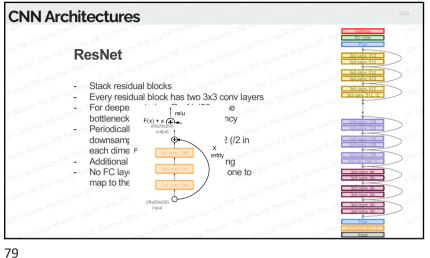


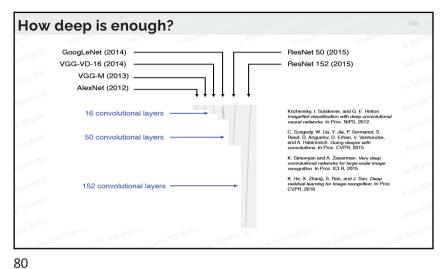
## **CNN Architectures**

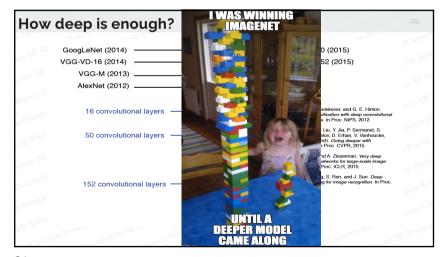
## ResNet

- So far, the deeper the better
- Can we continue on adding layer and go deeper?
- Unfortunately no
- Hypothesis: the problem is an optimization problem, deeper models are harder to optimize (e.g. vanishing gradients)











## Transfer learning

- All the best performing architectures have millions of parameters to learn
- In order to tune them, very large databases are needed (e.g., rule of 10: 10x samples wrt number of parameters to train)



• What if we do not have such amount of data? Can we still use deep learning?

In practice, very few people train an entire CNN from scratch, because it is relatively rare to have a dataset of sufficient size.

It is common to pretrain a CNN on a very large dataset (e.g., ImageNet which contains 1.2 million images with 1000 categories)

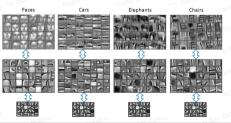
and then use the CNN either for fine-tuning or as a fixed feature extractor for the task of interest.

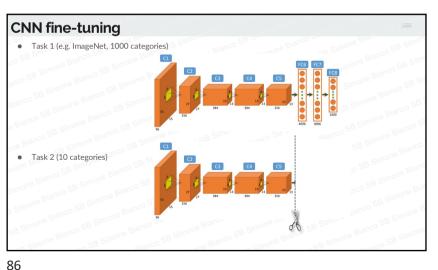
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## Transfer learning

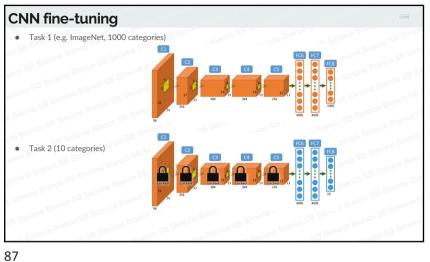
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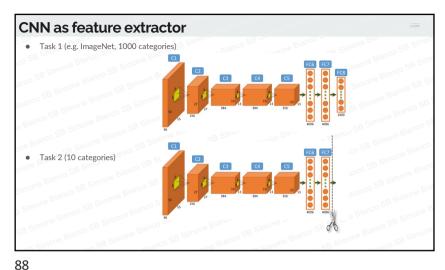
- Why does it work?
- Motivated by the observation that the earlier features of a CNN contain more generic features (e.g., edge detectors or color blob detectors) that should be useful to many tasks
- Later layers of the CNN becomes progressively more specific to the details of the classes contained in the original dataset.

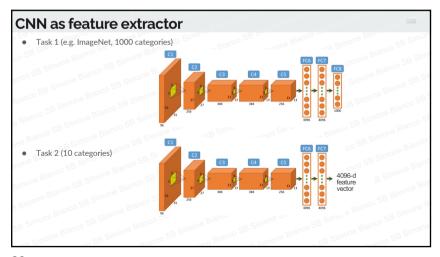




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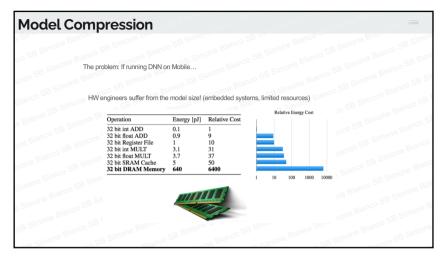


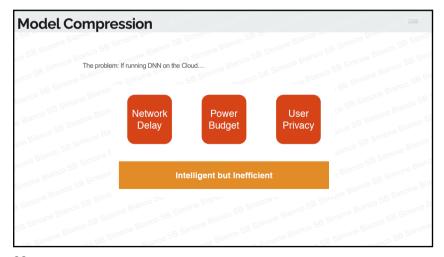


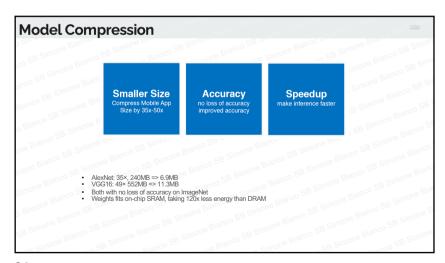


How to decide what type of TL you should perform? New dataset is small and similar to original dataset: → Train a linear classifier on CNN features from higher layers → Fine-tune the CNN New dataset is small but very different from original dataset → Train a linear classifier on CNN features from lower layers • New dataset is large and very different from original dataset → Train CNN from scratch or fine-tune it









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