

Continuous Distributions

Given a random variable X , which takes on values in $[0, \omega]$, we define its cumulative *distribution function* $F: [0, \omega] \rightarrow [0, 1]$ by¹

$$F(x) = \text{Prob}[X \leq x] \tag{A.1}$$

the probability that X takes on a value not exceeding x . By definition, the function F is nondecreasing and satisfies $F(0) = 0$ and $F(\omega) = 1$ (if $\omega = \infty$, then $\lim_{x \rightarrow \infty} F(x) = 1$). In this book we always suppose that F is increasing and continuously differentiable.

The derivative of F is called the associated probability *density function* and is usually denoted by the corresponding lowercase letter $f \equiv F'$. By assumption, f is continuous and we will suppose, in addition, that for all $x \in (0, \omega)$, $f(x)$ is positive. The interval $[0, \omega]$ is called the *support* of the distribution. When (A.1) holds we will say that X is distributed according to the distribution F or, equivalently, according to the density f .

If X is distributed according to F , then the *expectation* of X is

$$E[X] = \int_0^{\omega} xf(x) dx$$

and if $\gamma: [0, \omega] \rightarrow \mathbb{R}$ is some arbitrary function, then the expectation of $\gamma(X)$ is analogously defined as

$$E[\gamma(X)] = \int_0^{\omega} \gamma(x)f(x) dx$$

¹We will allow for the possibility that X can take on any nonnegative real value. In that case, with a slight abuse of notation, we will write $\omega = \infty$.

Sometimes the expectation of $\gamma(X)$ is also written as

$$E[\gamma(X)] = \int_0^{\omega} \gamma(x) dF(x)$$

The *conditional expectation* of X given that $X < x$ is

$$E[X | X < x] = \frac{1}{F(x)} \int_0^x tf(t) dt$$

and so

$$\begin{aligned} F(x)E[X | X < x] &= \int_0^x tf(t) dt \\ &= xF(x) - \int_0^x F(t) dt \end{aligned} \quad (\text{A.2})$$

which is obtained by integrating the right-hand side of the first equality by parts. The formula in (A.2) shows that $F(x)E[X | X < x]$ is the shaded area lying above the curve F in Figure A.1.

HAZARD RATES

Let F be a distribution function with support $[0, \omega]$. The *hazard rate* of F is the function $\lambda : [0, \omega) \rightarrow \mathbb{R}_+$ defined by

$$\lambda(x) \equiv \frac{f(x)}{1 - F(x)}$$

If F represents the probability that some event will happen before time x , then the hazard rate at x represents the instantaneous probability that the event will happen at x , given that it has not happened until time x . The event may be the

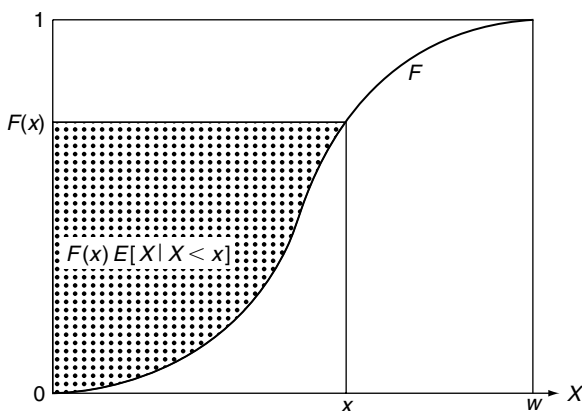


FIGURE A.1 Conditional expectation.

failure of some component—a lightbulb, for instance—and so it is sometimes also known as the “failure rate.” Notice that as $x \rightarrow \omega$, $\lambda(x) \rightarrow \infty$.

Since

$$-\lambda(x) = \frac{d}{dx} \ln(1 - F(x))$$

if we write

$$F(x) = 1 - \exp\left(-\int_0^x \lambda(t) dt\right) \quad (\text{A.3})$$

then this shows that any arbitrary function $\lambda : [0, \omega) \rightarrow \mathbb{R}_+$ such that for all $x < \omega$,

$$\int_0^x \lambda(t) dt < \infty$$

and

$$\lim_{x \rightarrow \omega} \int_0^x \lambda(t) dt = \infty \quad (\text{A.4})$$

is the hazard rate of some distribution; in particular, that defined by (A.3). The fact that $\lambda(x) \geq 0$ ensures that F is nondecreasing and (A.4) ensures that $F(\omega) = 1$. Using the formula in (A.2), it may be verified that $E[X] = E[1/\lambda(X)]$.

If for all $x \geq 0$, $\lambda(x)$ is a constant, say $\lambda(x) \equiv \lambda > 0$, then (A.3) results in the *exponential distribution*

$$F(x) = 1 - \exp(-\lambda x)$$

whose expectation $E[X] = 1/\lambda$.

Closely related to the hazard rate is the function $\sigma : (0, \omega] \rightarrow \mathbb{R}_+$ defined by

$$\sigma(x) \equiv \frac{f(x)}{F(x)}$$

sometimes known as the *reverse hazard rate*.² Since

$$\sigma(x) = \frac{d}{dx} \ln F(x)$$

if we write

$$F(x) = \exp\left(-\int_x^\omega \sigma(t) dt\right) \quad (\text{A.5})$$

²In some applications this is also referred to as the inverse of the *Mills' ratio*.

then this shows that any arbitrary function $\sigma : (0, \omega) \rightarrow \mathbb{R}_+$ such that for all $x > 0$,

$$\int_x^\omega \sigma(t) dt < \infty$$

and

$$\lim_{x \rightarrow 0} \int_x^\omega \sigma(t) dt = \infty \quad (\text{A.6})$$

is the reverse hazard rate of some distribution; in particular, that defined by (A.5). The fact that $\sigma(x) \geq 0$ ensures that F is nondecreasing and (A.6) ensures that $F(0) = 0$.

JOINTLY DISTRIBUTED RANDOM VARIABLES

Let X and Y be two random variables taking on values in $[0, \omega_X]$ and $[0, \omega_Y]$, respectively. We will say that X and Y have the *joint density* $f : [0, \omega_X] \times [0, \omega_Y] \rightarrow \mathbb{R}_+$ if for all $x' < x''$ and $y' < y''$

$$\text{Prob}[x' \leq X \leq x'' \text{ and } y' \leq Y \leq y''] = \int_{y'}^{y''} \int_{x'}^{x''} f(x, y) dx dy$$

We will then say that X and Y are jointly distributed according to f . We will assume that f is continuous and positive on $(0, \omega_X) \times (0, \omega_Y)$.

The *marginal density* of X is

$$f_X(x) = \int_0^{\omega_Y} f(x, y) dy$$

and the marginal density of Y is similarly defined. The random variables X and Y are *independent* if and only if

$$f(x, y) = f_X(x) \times f_Y(y)$$

For any $x > 0$, the *conditional density* of Y given that $X = x$ is

$$f_Y(y | X = x) = \frac{f(x, y)}{f_X(x)}$$

and for any $x > 0$, the *conditional expectation* of Y given that $X = x$ is defined as

$$E[Y | X = x] = \int_0^{\omega_Y} y f_Y(y | X = x) dy$$

Let us denote by $E[Y | X] : [0, \omega_X] \rightarrow \mathbb{R}_+$ the function of X whose value at $X = x$ is $E[Y | X = x]$. The function $E[Y | X]$ is then also a random variable and it is meaningful to speak of its expectation. Using the preceding definitions, it can be verified that

$$E_X[E_Y[Y | X]] = E_Y[Y]$$

This identity is sometimes known as the “law of iterated expectation.”

Extensions to an arbitrary finite number of random variables are straightforward.

NOTES ON APPENDIX A

The material on continuous random variables is quite standard and can be found in any reasonable book on probability theory. Ross (1989) has presented a concise treatment of the relevant concepts and results.