

Fundamentals of GIS

Emphasizing GIS Use for
Natural Resource Management



BSRSI

Produced for:

Basic Science and Remote Sensing Initiative

Department of Geography

Michigan State University

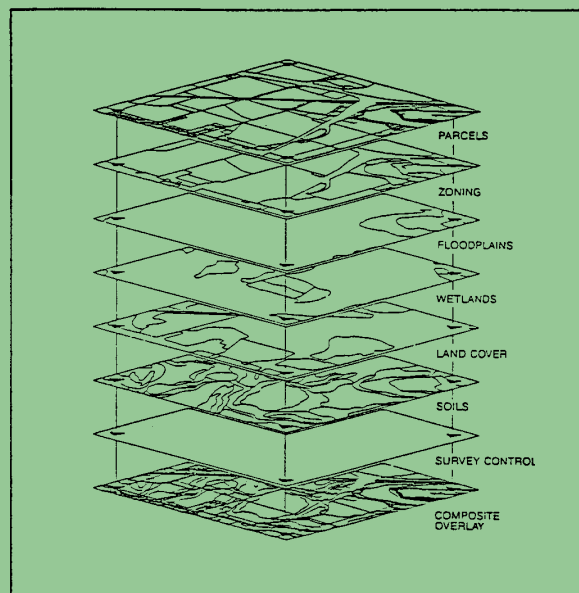
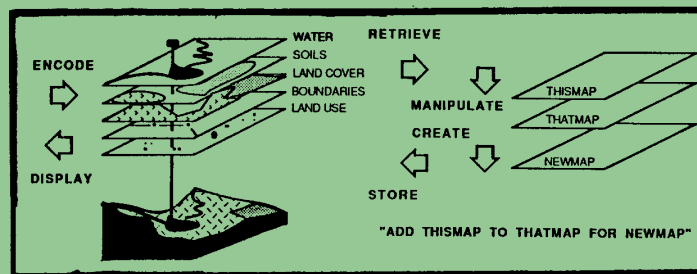
FUNDAMENTALS OF GIS

EMPHASIZING GIS USE FOR NATURAL RESOURCE MANAGEMENT

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*Center For Remote Sensing and Geographic Information Science
Michigan State University*



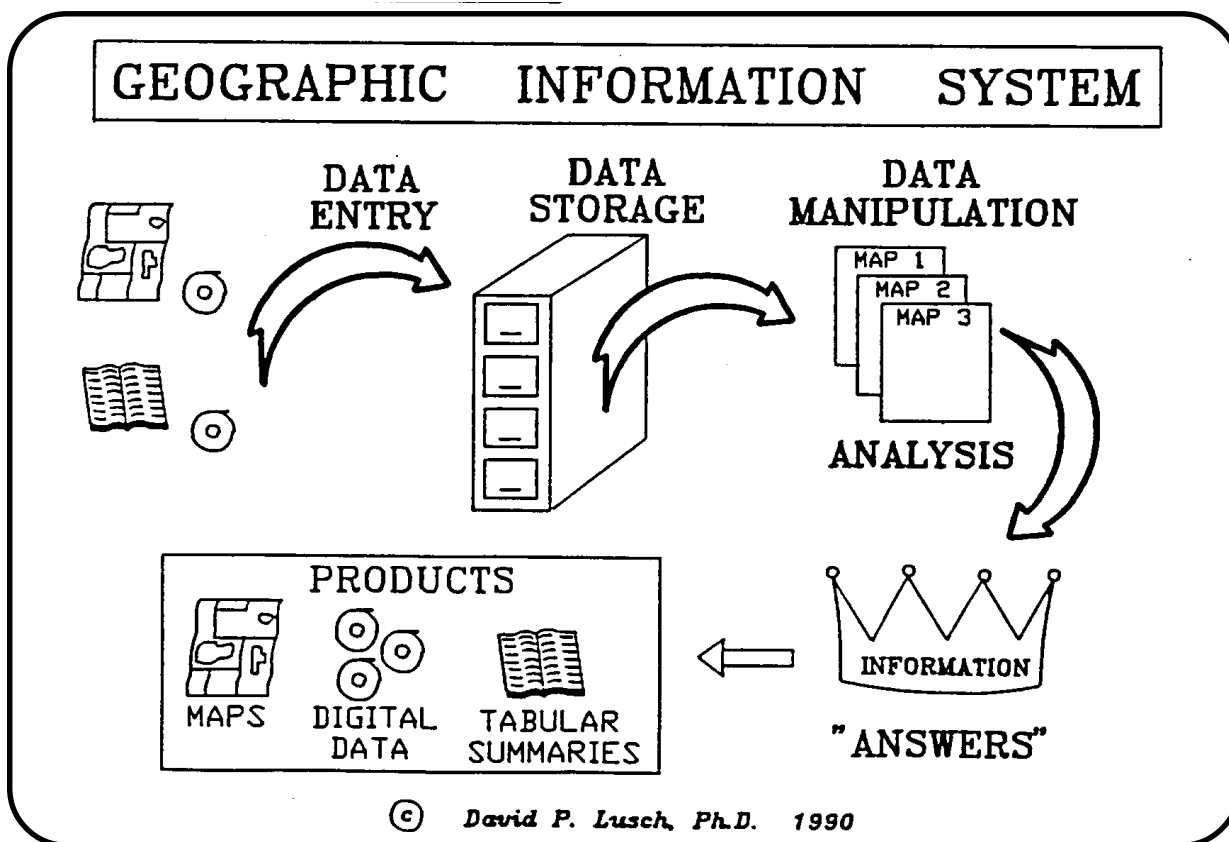
November, 1999

OVERVIEW OF GIS

G I S

Geographic Information Systems

An INTEGRATED SYSTEM of COMPUTER HARDWARE and SOFTWARE coupled with **PROCEDURES** and a **HUMAN ANALYST** which together support the CAPTURE, MANAGEMENT, MANIPULATION, ANALYSIS, MODELLING, and DISPLAY of SPATIALLY REFERENCED DATA



G I S Capabilities:

☐ **QUERY FOR LOCATION**

"Show me all the countries of South America that have a population greater than 20,000,000. "

☐ **QUERY FOR CONDITION**

"Display the population of each country I point to on the map."

☐ **TREND ANALYSIS**

"Show me where the census blocks are that have experienced more than a 50% population change between 1980 and 1990."

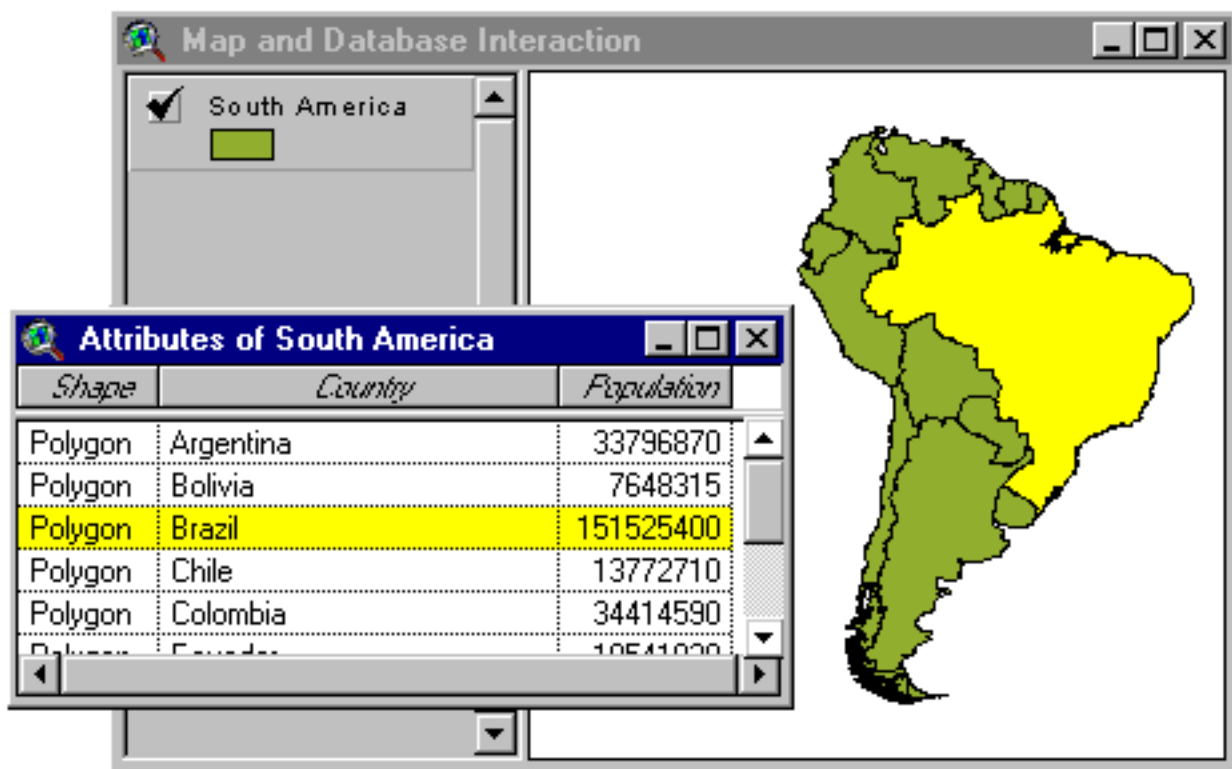
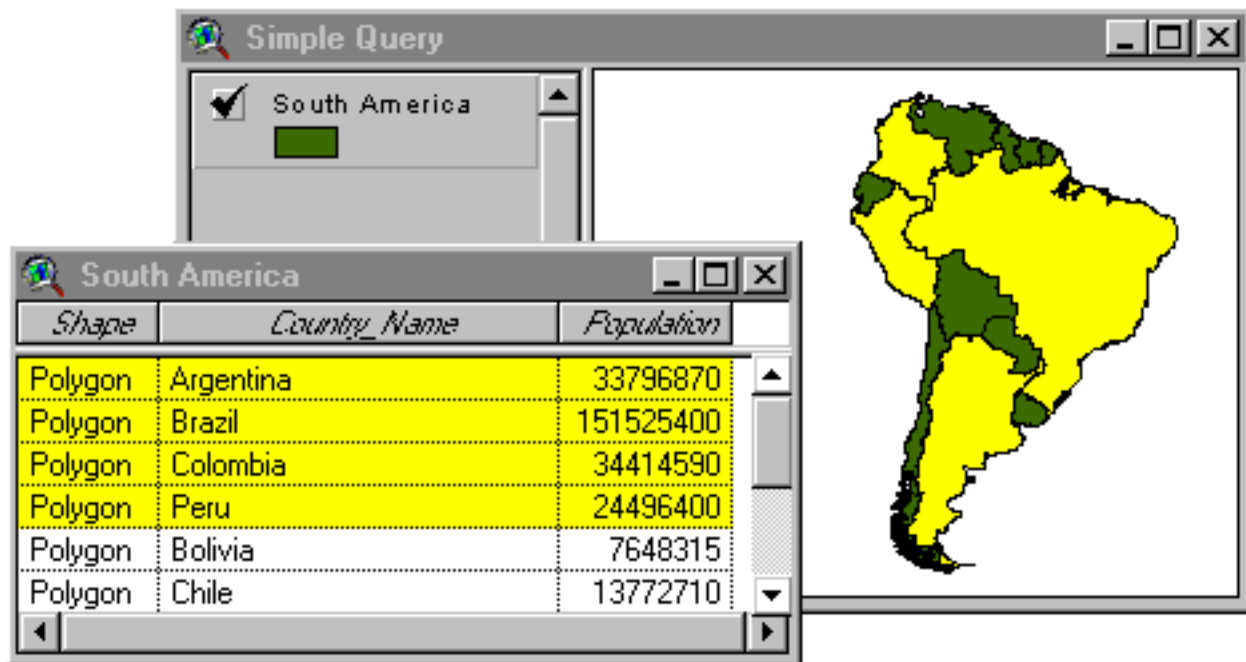
☐ **PATTERNS ANALYSIS**




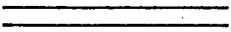

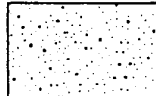
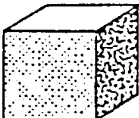

"Calculate the fragmentation index for all the forest patches in the municipio."

☐ **MODELLING**

"Which route for the new highway has the lowest cost in terms of losses of housing, prime farmland, and wetlands, while minimizing the needs for cutting and filling."

Query: Population > 20,000,000



Point	Line	Area	Volume
 	 	 	 
Well or Town	Stream or Road	City or Field	Fertilizer or Yield

Geometric Classes of Data

DATA TYPES

VECTOR

Point = Position, no area

Line = Length, no width

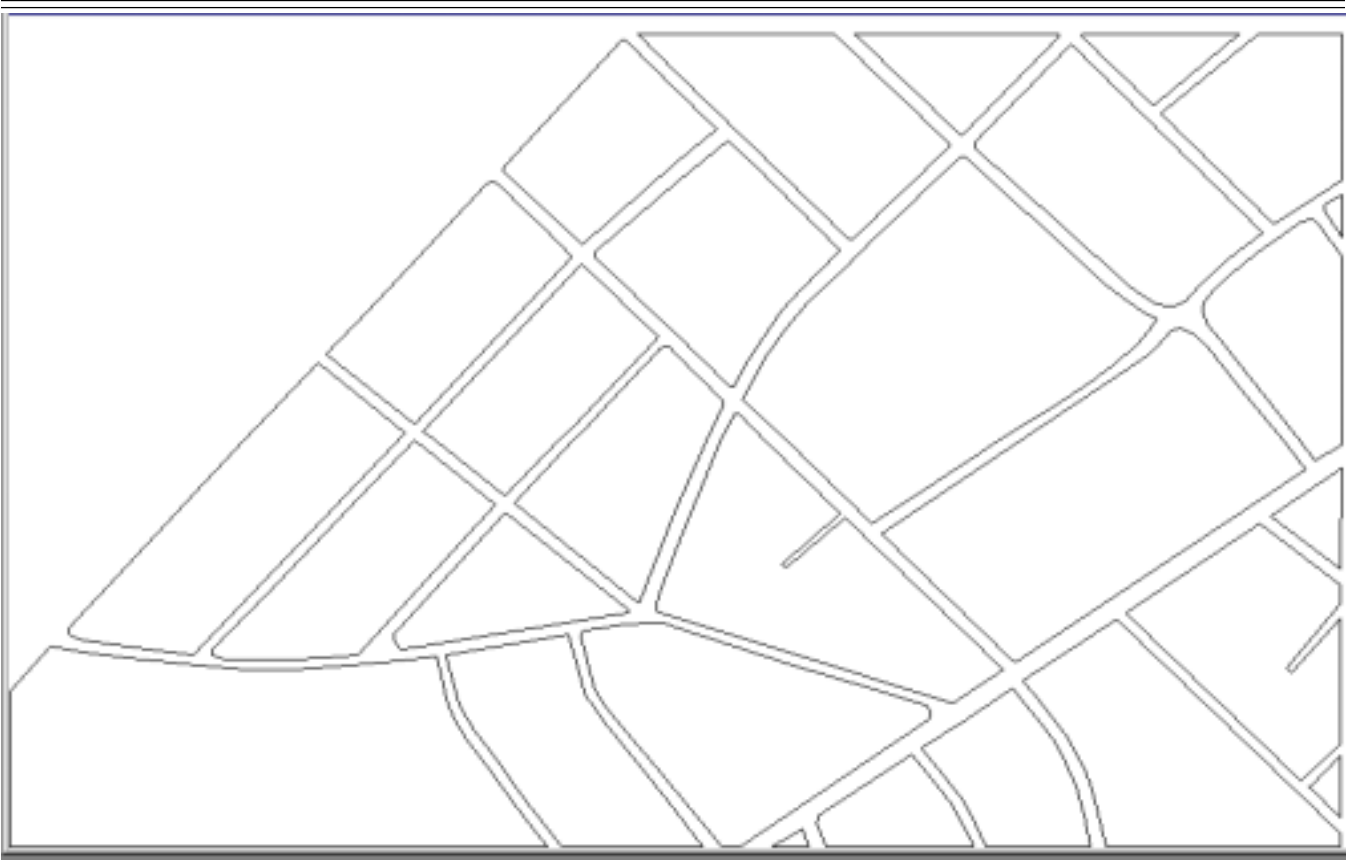
Polygon = Area and perimeter

RASTER

Point = 1 cell

Line = Multiple cells joined at edges or corners, usually with only 1 or 2 neighbors

Polygon = Group of contiguous cells joined at edges or corners



VECTOR STRUCTURE

Advantages

- Good representation of the landscape being mapped
- Topology can be completely described, including network linkages
- Great looking graphics ("Looks like a map is supposed to")
- Generalization of the graphics is possible while still maintaining the great look ("What the map reader doesn't know won't hurt them")

RASTER STRUCTURE

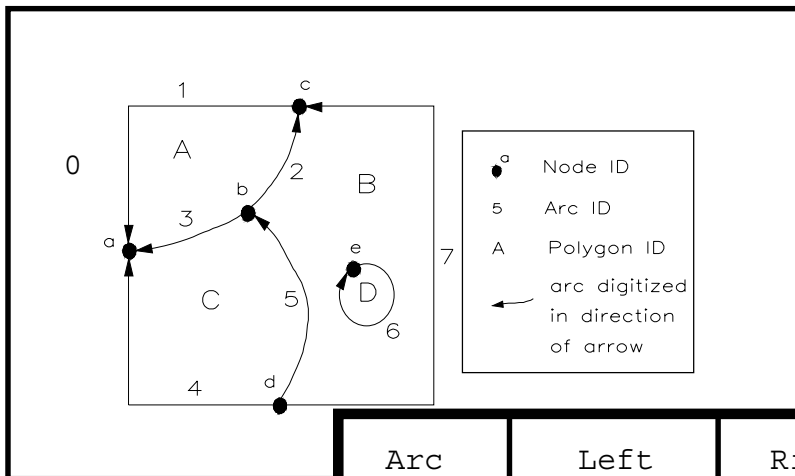
Advantages

- Overlaying maps is easy and "perfect" (i.e. no possibility of sliver polygons developing since all raster cell borders are coincident)
- Integration of remotely sensed imagery (satellite images or scanned airphotos) is straight-forward
- A huge variety of complex spatial analyses are supported
- Software is generally cheaper and easier to learn compared to vector GISs

TOPOLOGY

Geometrical relationships between spatial objects (Points, Lines, and Areas), such as adjacency, that are not altered by distortion, as long as the surface is not torn

Example of "Built" Topology (from Arc/Info)



Arc ID	Left Poly	Right Poly	From Node	To Node
1	A	0	c	a
2	A	0	b	c
3	C	A	b	a
4	0	C	d	a
5	C	B	d	b
6	B	D	e	e
	B	0	d	c

Polygon ID	Number of arcs	List of arcs
A	3	-1, -2, 3
B	4	2, -7, 5, 0, -6
C	3	-3, -5, 4
D	1	6

Vector GIS ATTRIBUTE DATABASE

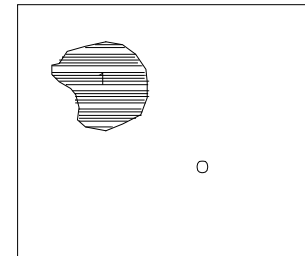
ID	Name	Quality	...
0	N/A		
1	Fir Lake	High	

ID	Species	Size	...
0	N/A		
1	Jack Pine	Pole	
2	Spruce	Sapling	
3	Jack Pine	Sapling	

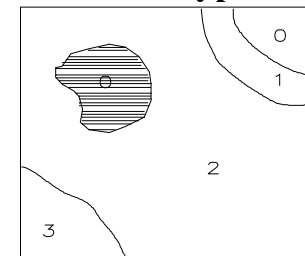
ID	Type	Depth	...
0	N/A		
1	B		
2	A		
3	B		
4	C		
5	C		
6	A		
7	R		

Type	Drainage	...
A	Fair	
B	Poor	
C	Good	
R	Rock	

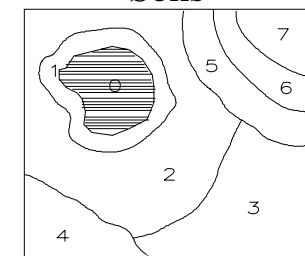
Lakes



Forest Types



Soils



Related Table
"Type" is
KEY FIELD

ENTITY RELATIONSHIPS

Point - Point **Is nearest to ...**
Interacts with ...

Point - Line **Is on ...**
Is nearest to ...

Point - Area **Is within ...**
Is adjacent to ...

Line - Line **Intersects ...**
Is upstream of ...

Line - Area **Crosses ...**
Is contained within ...
Is nearest to ...

Area - Area **Is adjacent to ...**
Overlaps ...
Is enclosed by ...

A Classification of GIS Functions

□ **Analysis of Spatial and Attribute Data**

- Non-spatial analyses

Attribute query and display

Map retrieval and display

Attribute classification

Map measurements (distance, direction, area, etc.)

- Spatial analyses

Overlay operations

Neighborhood functions

Distance and Connectivity functions

Contiguity measures

Proximity analysis

Network analysis

Spread functions

Seek operands

Intervisibility analysis

Solar illumination calculation

Perspective view

Search operations

Line-in-polygon; Point-in-polygon

Topographic functions

Thiessen polygons

Interpolation

Contour generation

This classification has been adapted from:

Aronoff, Stan. 1989. Geographic Information Systems: A Management Approach. Ottawa, Ontario, Canada: WDL Publications. 294p.

A Classification of GIS Functions

□ Maintenance of Attribute Data

**Format conversions
Database error checking
Database editing**

□ Maintenance of Spatial Data

**Format conversions
Geometric transformations
Projection conversions
Conflation
Edge matching
Editing of graphic elements
Line coordinate thinning**

□ Output functions

**Map annotation
Text labels
Texture patterns and line styles
Graphic symbols
Plotting
Printing (laser printers, color inkjet printers, etc.)**

This classification has been adapted from:

Aronoff, Stan. 1989. Geographic Information Systems: A Management Approach. Ottawa, Ontario, Canada: WDL Publications. 294p.

Spatial Analyses

Basic Functional Classes

□ **Reclassifying Maps**

Vector and Raster

□ **Overlaying Maps**

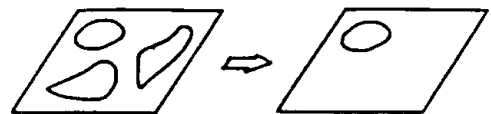
□ **Measuring Distance and Connectivity**

□ **Characterizing Neighborhoods**

Position

Vector and Raster

"only those in the NW"



Value

Vector and Raster

"change feet to meters"



"elevations between 20 & 40 feet"

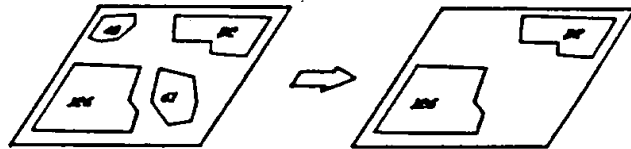


RECLASSIFYING MAPS

Size

Vector and Raster

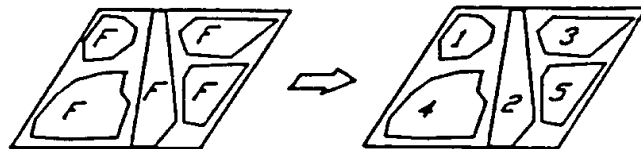
"larger than 80 acres"



Contiguity

Raster Only

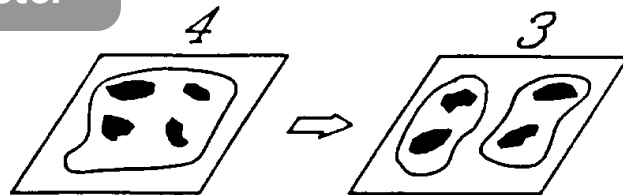
"work with individual members rather than the class as a whole"



Shape

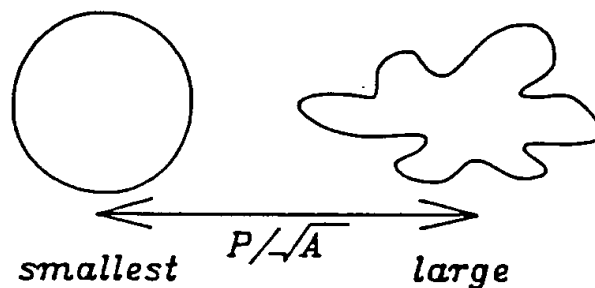
Vector and Raster

- Spatial Integrity



$$[\# \text{ Holes} - (\# \text{ Fragments} - 1)]$$

- Boundary Configuration



SPATIAL ANALYSES

Basic Functional Classes

- Reclassifying Maps

- Overlaying Maps

Vector and Raster

- Measuring Distance and Connectivity

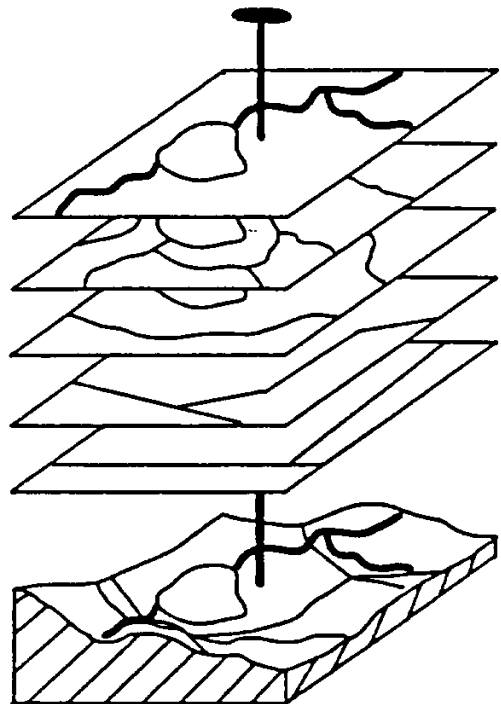
- Characterizing Neighborhoods

Point by Point

Vector and Raster

*"piercing – needle"
approach*

All locations in the coverage or grid
are evaluated. The results extend
to the spatial limits of the input maps.



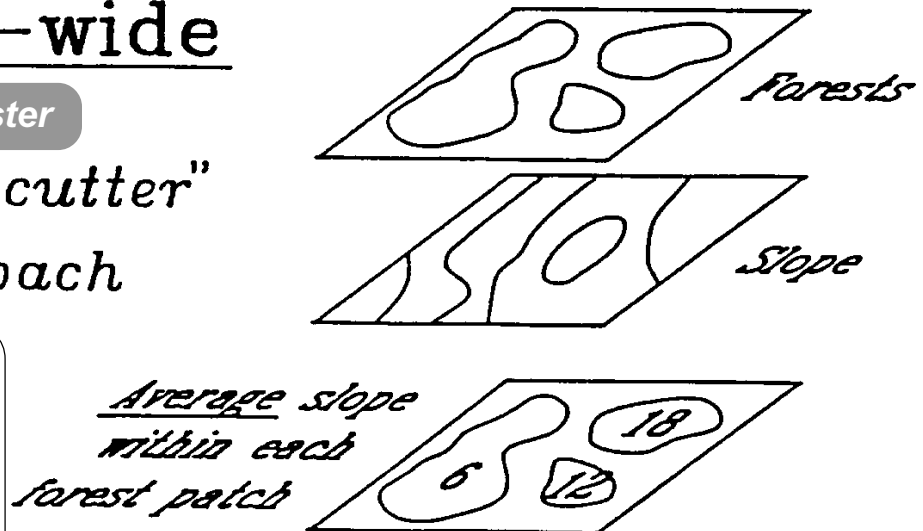
OVERLAYING MAPS

Region-wide

Vector and Raster

"cookie-cutter"
approach

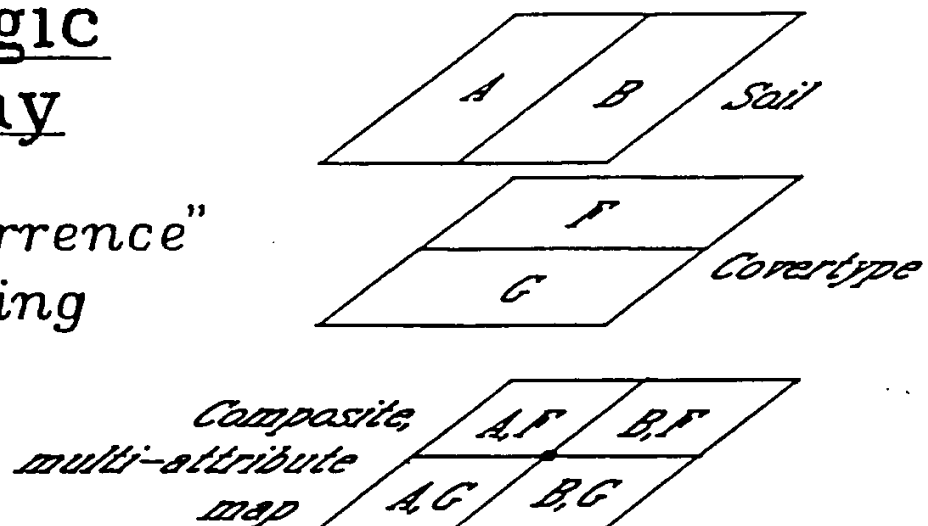
All locations in the coverage or grid are not necessarily evaluated. The results are constrained to the spatial nature of the reference map.



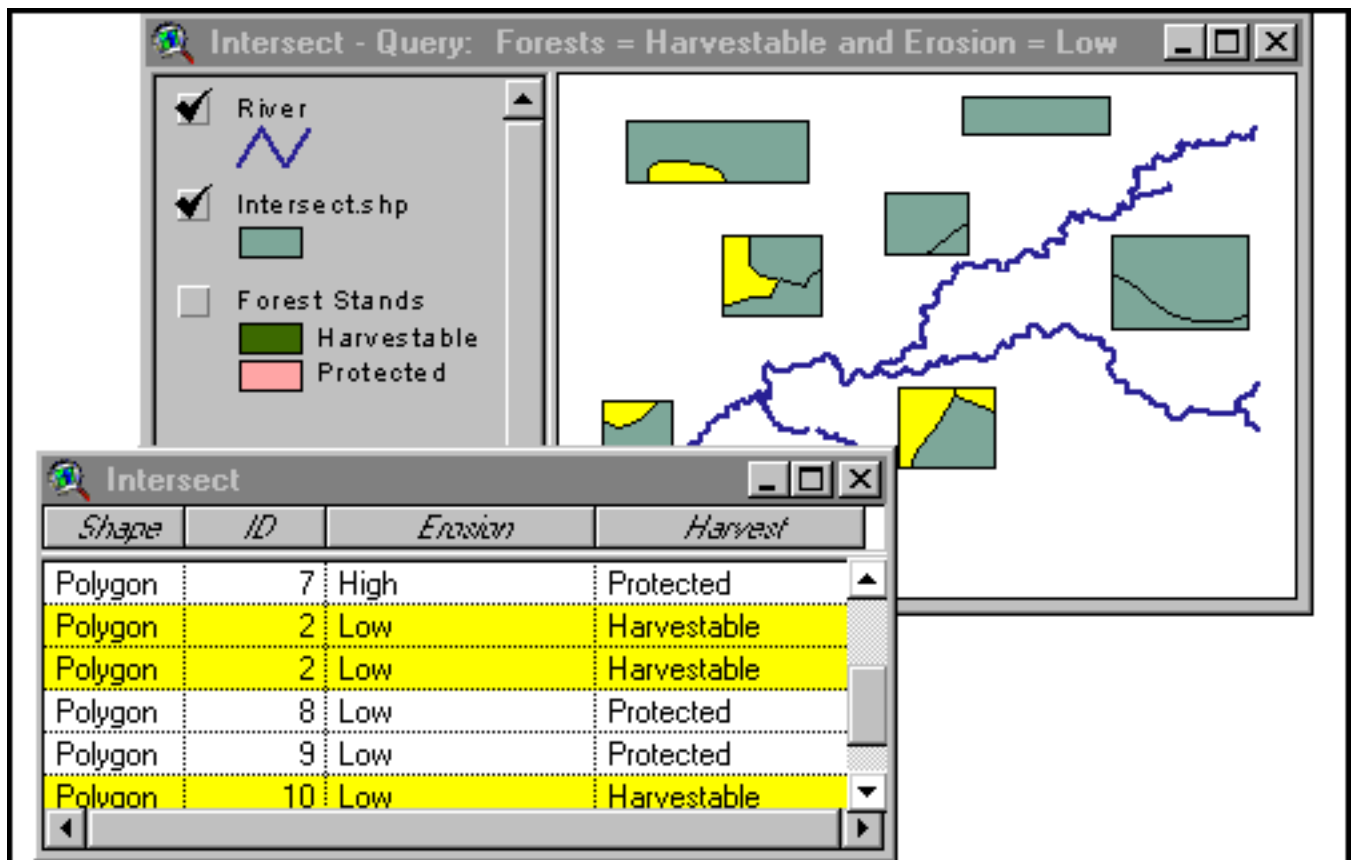
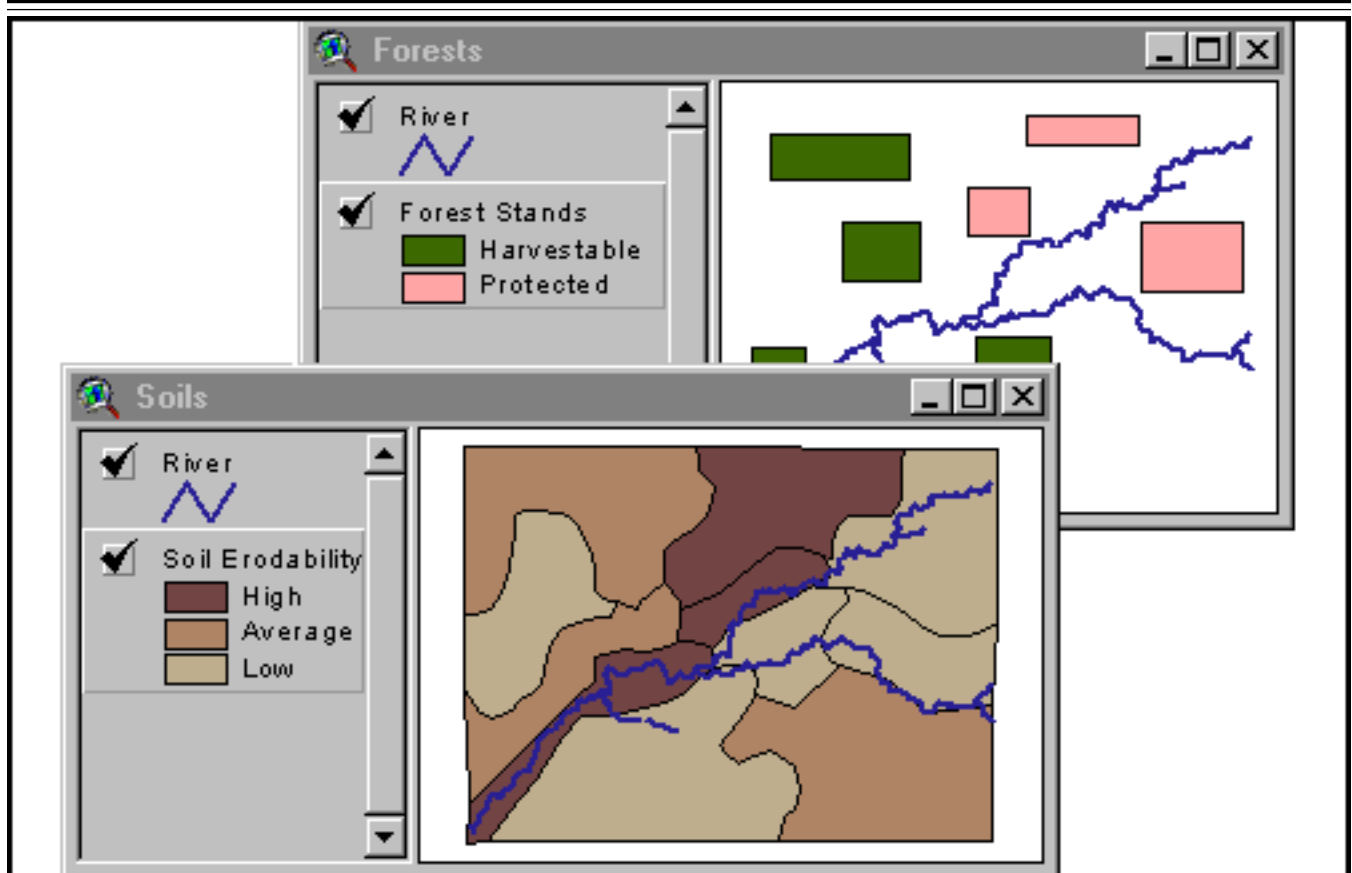
Vector Only

Topologic Overlay

"co-occurrence"
mapping



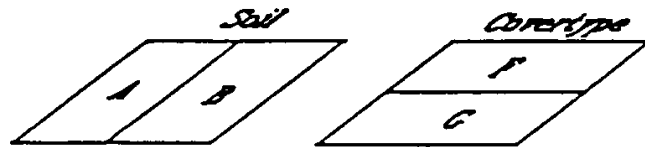
Note the new NODE - topologically correct areas were created



OVERLAYING MAPS

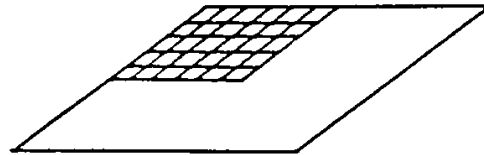
Boolean Overlay

Vector and Raster



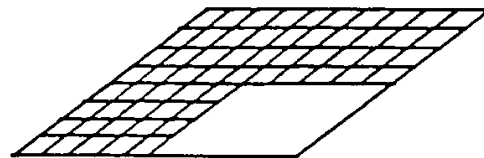
- Intersection

"Forest AND Soil A"



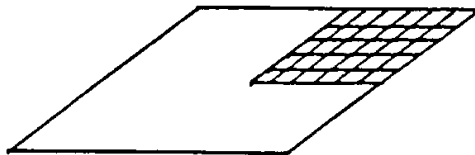
- Union

"Forest OR Soil A"



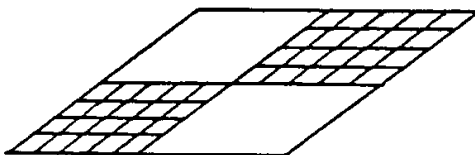
- Negate

"Forest, but NOT on
Soil A"

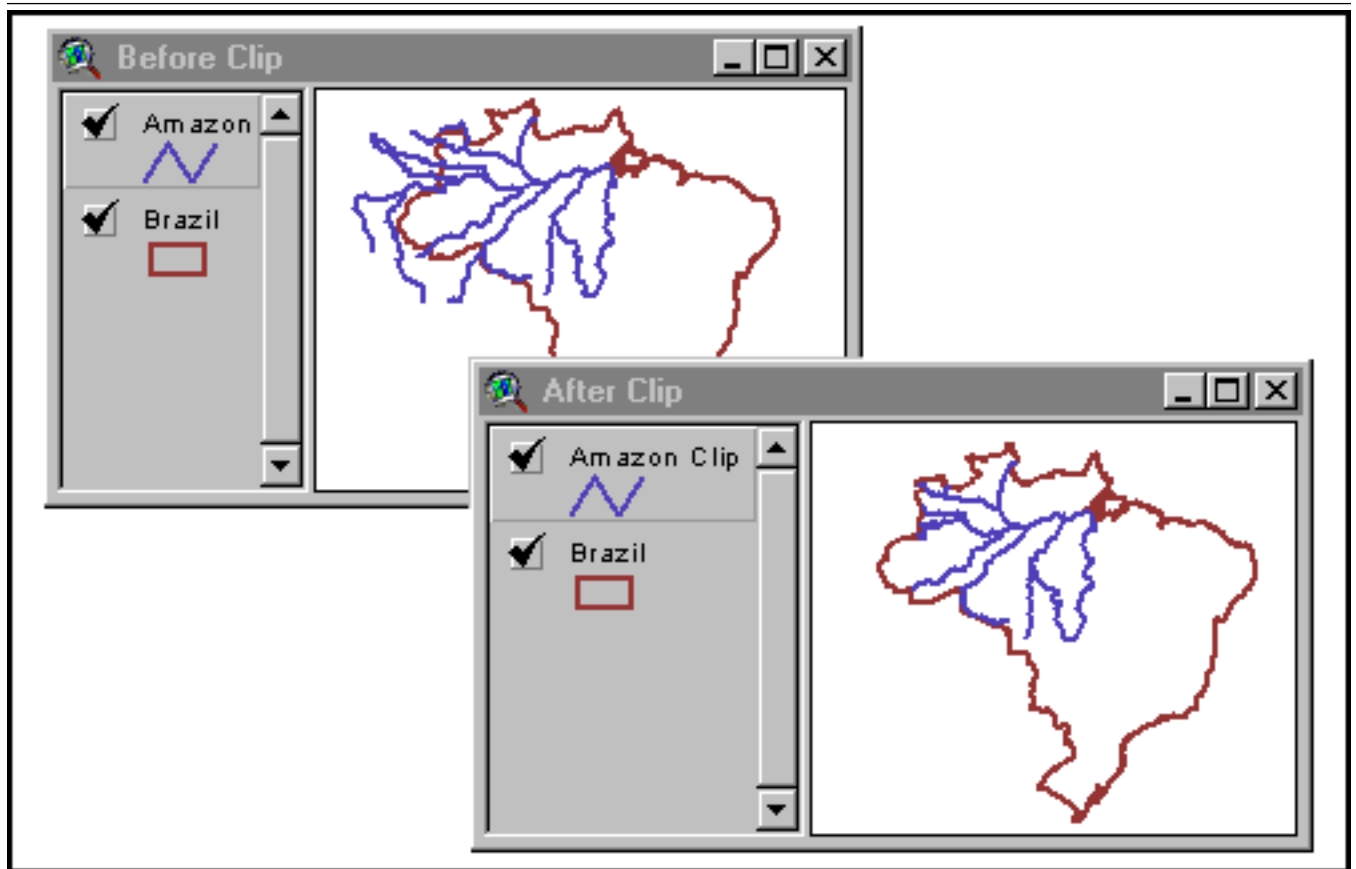


- Exclusive Or

"Forest XOR Soil A"



Note: Most relational database management systems support a "SWAP" function which selects the *currently unselected* items in the database. In the example above, the "SWAP" function would return the white areas after the hatched areas had initially been selected.



SPATIAL ANALYSES

Basic Functional Classes

- Reclassifying Maps
- Overlaying Maps
- Measuring Distance and Connectivity
- Characterizing Neighborhoods

DISTANCE MEASURES

Point to Point

Vector and Raster

"How far is it from A to B?"

USEFUL, BUT LIMITED

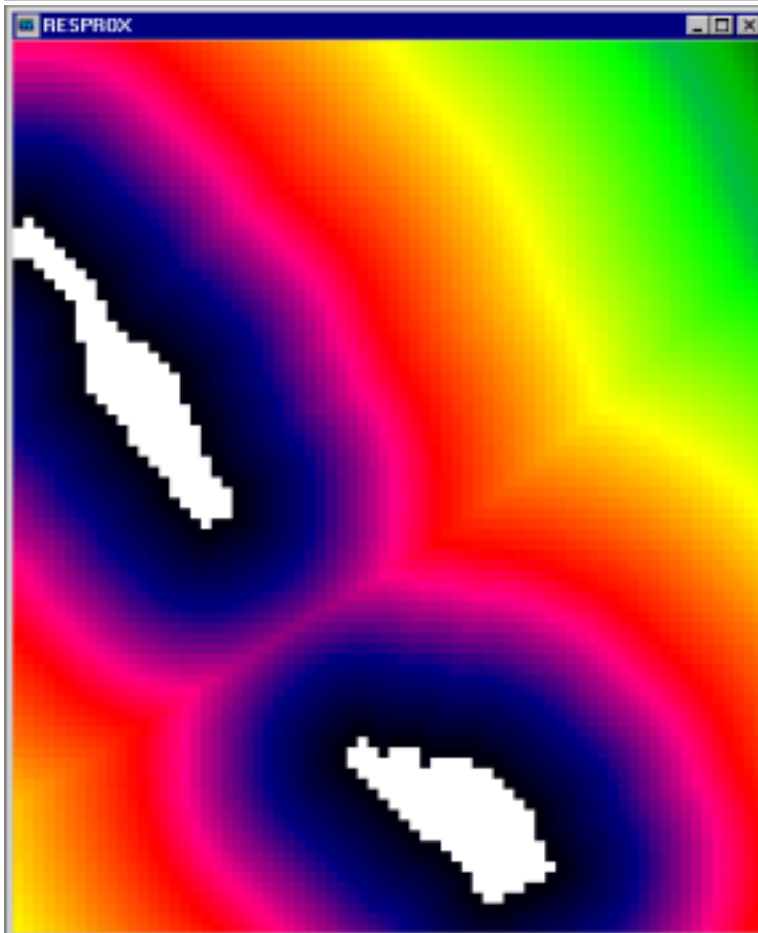
Proximity

Raster Only

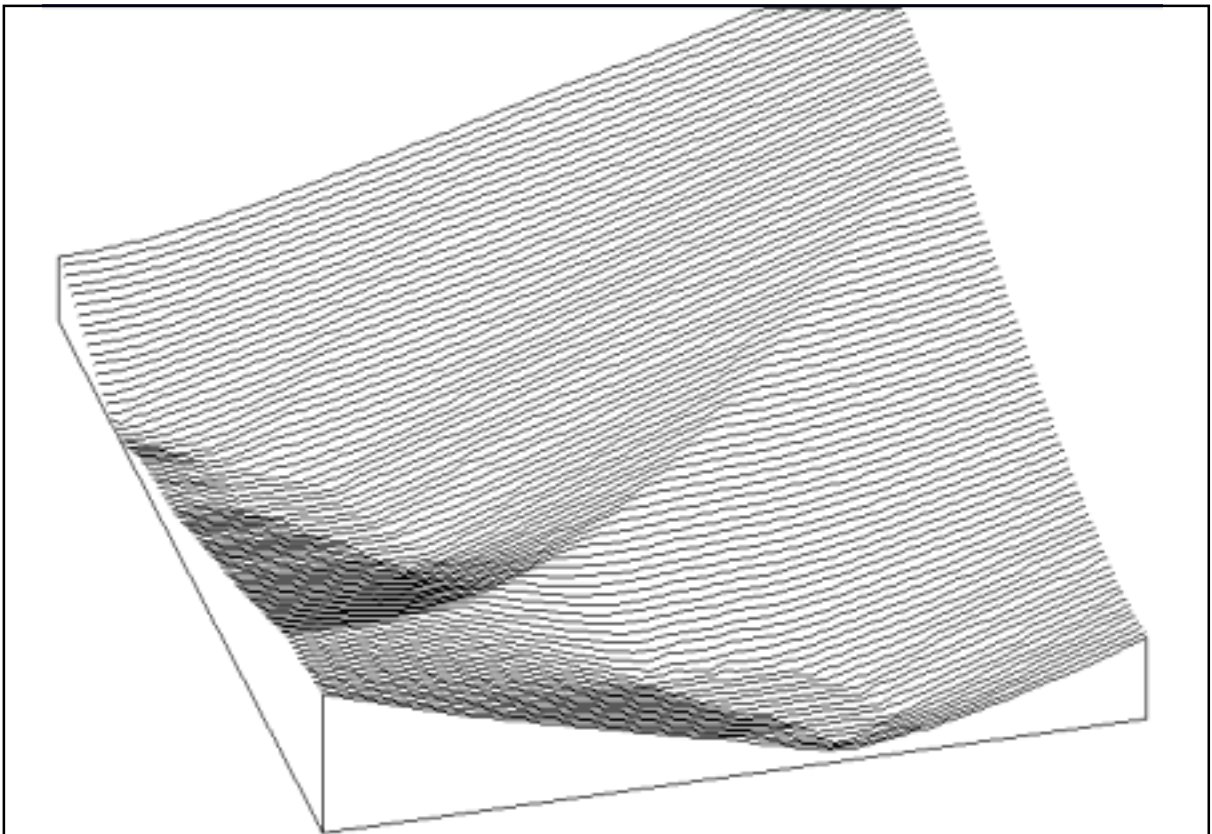
"How far from the forest is every location on the map?"

POWERFUL AND VERY DIFFICULT TO DO BY HAND





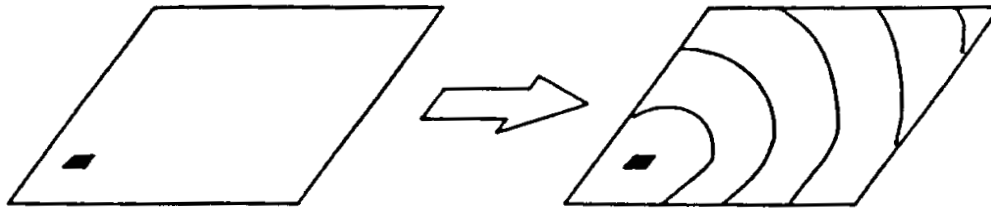
Simple (i.e. unweighted)
PROXIMITY SURFACE



DISTANCE MEASURES

^I Movement

Raster Only

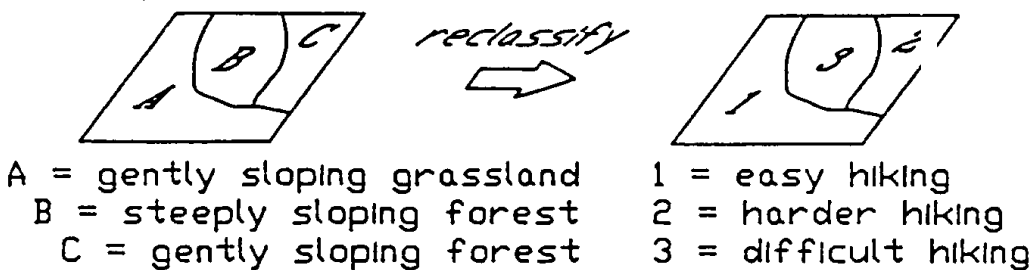


Start Location

Travel Time
(Impedance = 0)

^{II} Movement

Raster Only

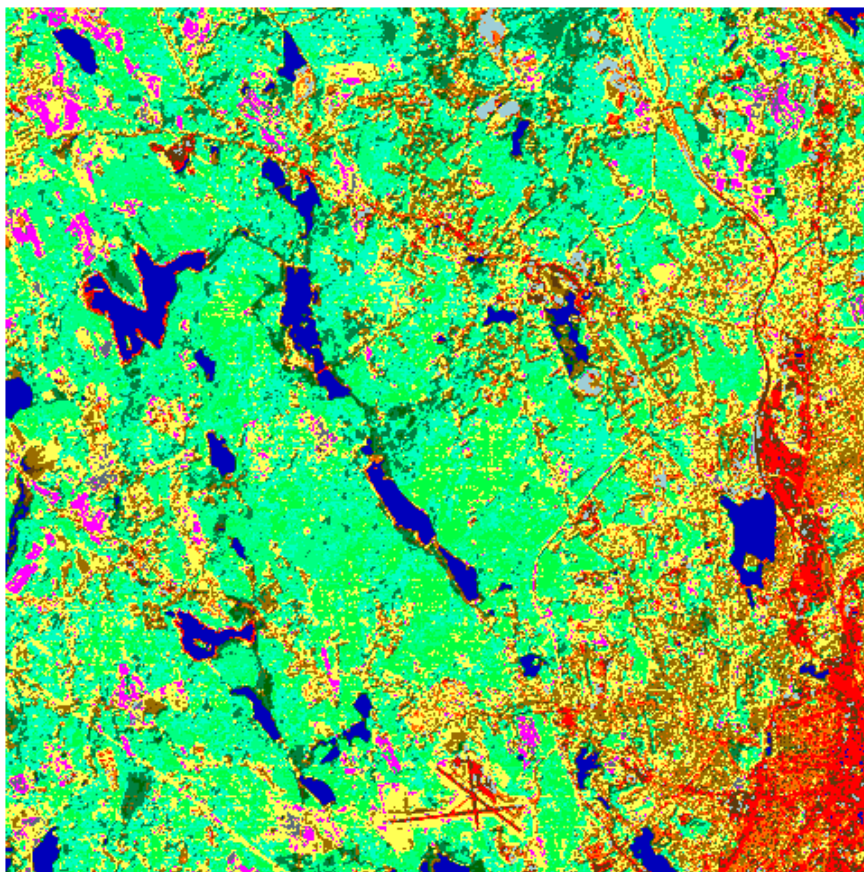


Start Location

Travel Time
(with variable impedances)

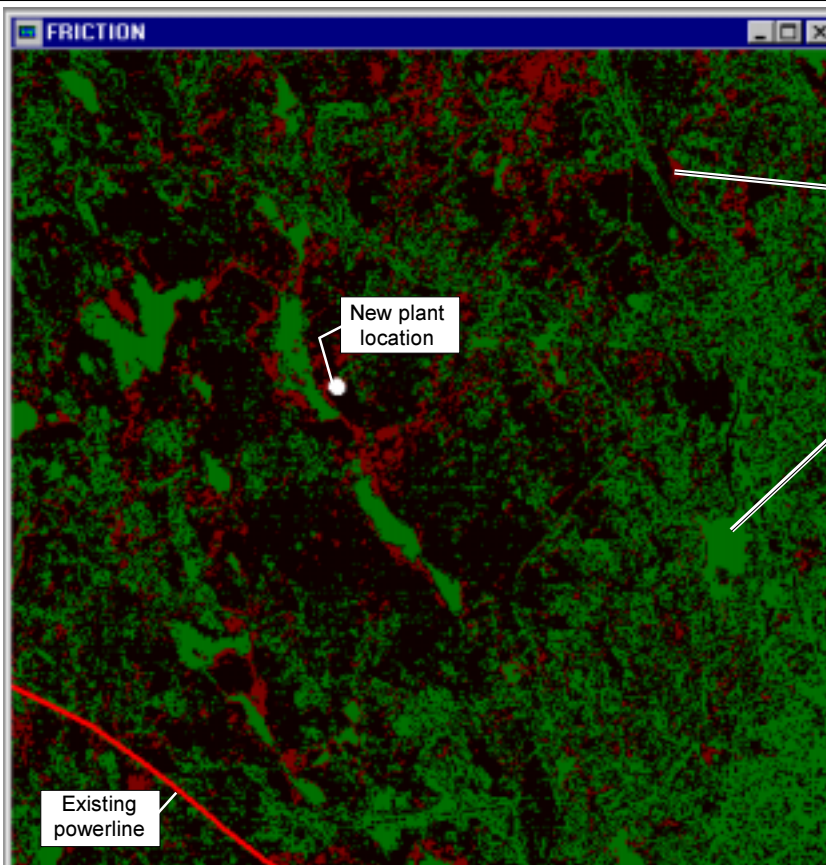
Least-Cost Pathway Analyses

- Create a **FRICTION** map from one or more existing coverages
- Create a **COST SURFACE** map by executing the **PROXIMITY** analysis *WEIGHTED BY* the **FRICTION** map
- Execute the **LEAST-COST PATHWAY** module from one or more starter entities (points, lines or areas) to a destination. It will **FIND** the one (or more) routes that **ACCUMULATE** the least cost.



- Water
- Deciduous 1
- Deciduous 2
- Deciduous 3
- Conifer 1
- Conifer 2
- Grass/Suburb
- Agriculture
- Urban Resid.
- Urban Comm.
- Pavement 1
- Pavement 2
- Gravel
- Barren

Land Use
(classified from Landsat
TM imagery)



Base cost

Base cost x 4

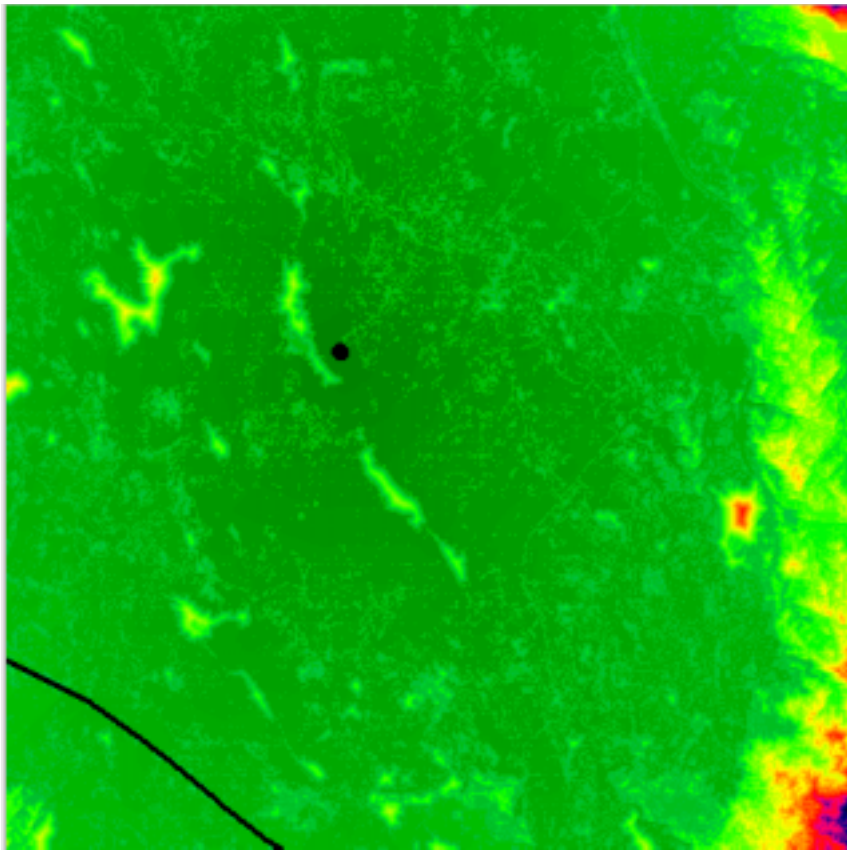
Base cost x 5

Base cost x 1000

New plant
location

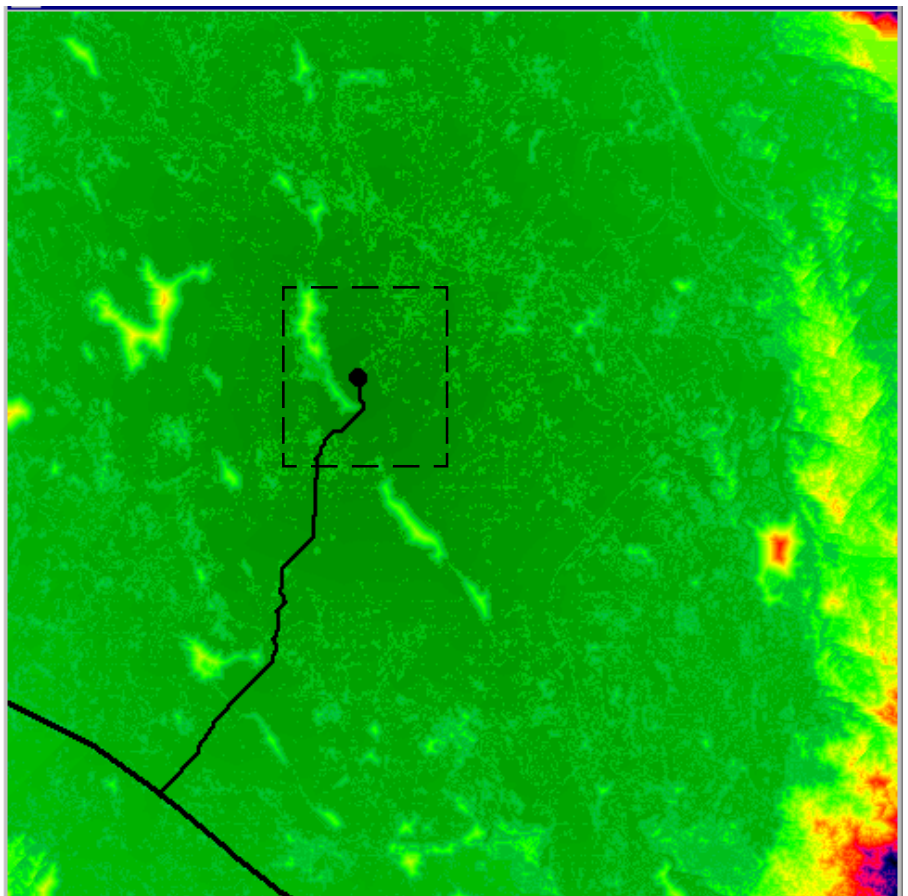
Existing
powerline

Friction Surface
(reclassified from the
Land Use map)

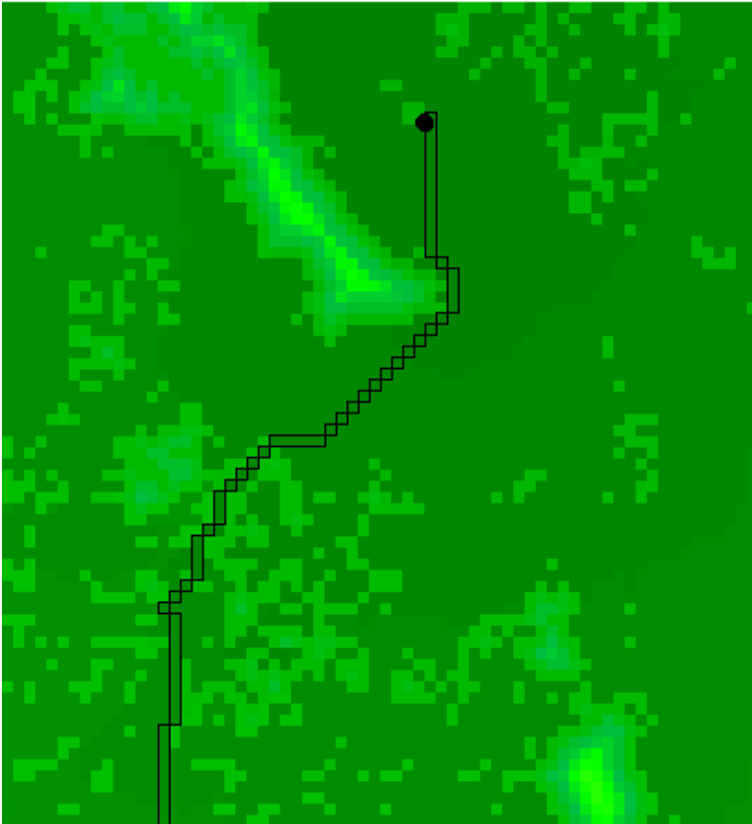


Cost Surface
(Proximity x Friction)

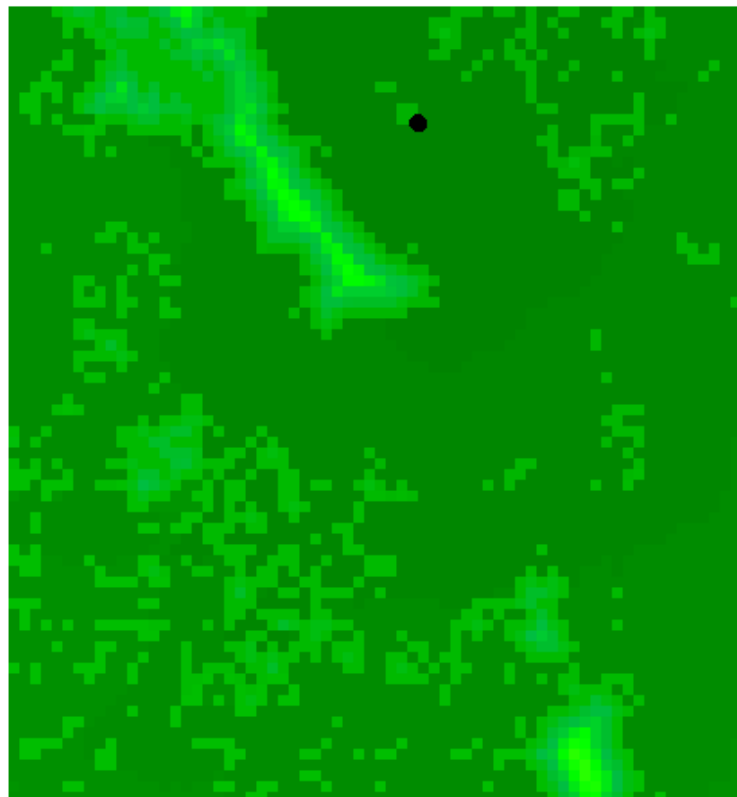
Least-Cost
Pathway



Least-Cost Pathway



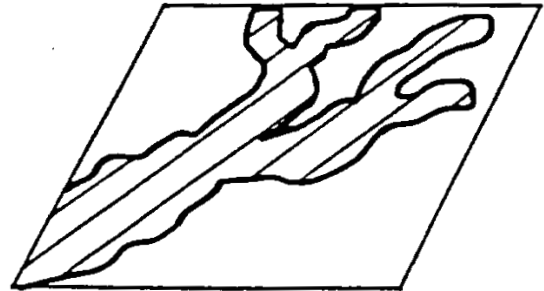
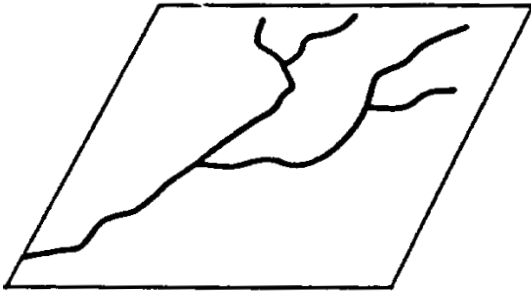
Least-Cost Pathway



CONNECTIVITY

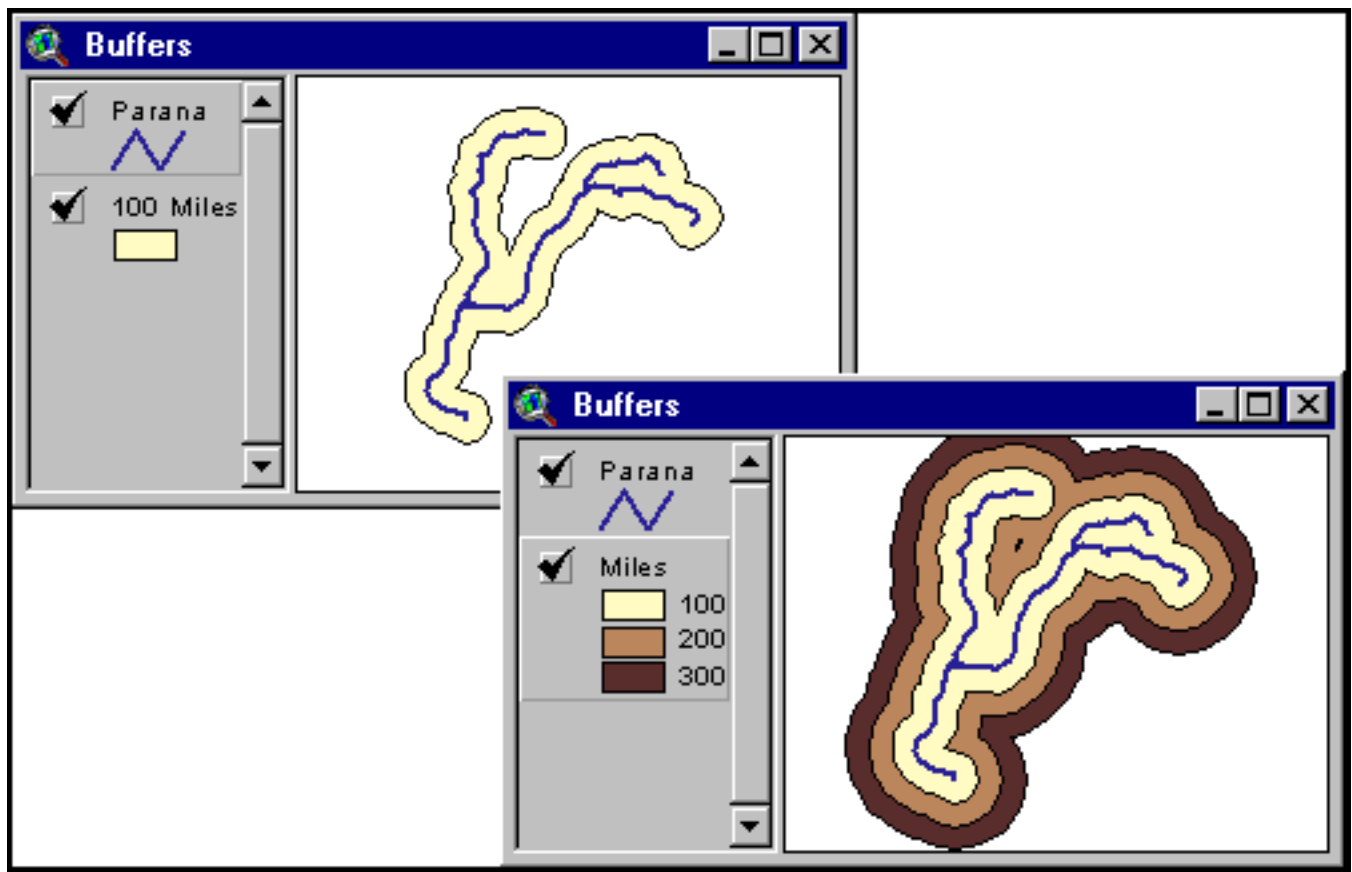
Buffering

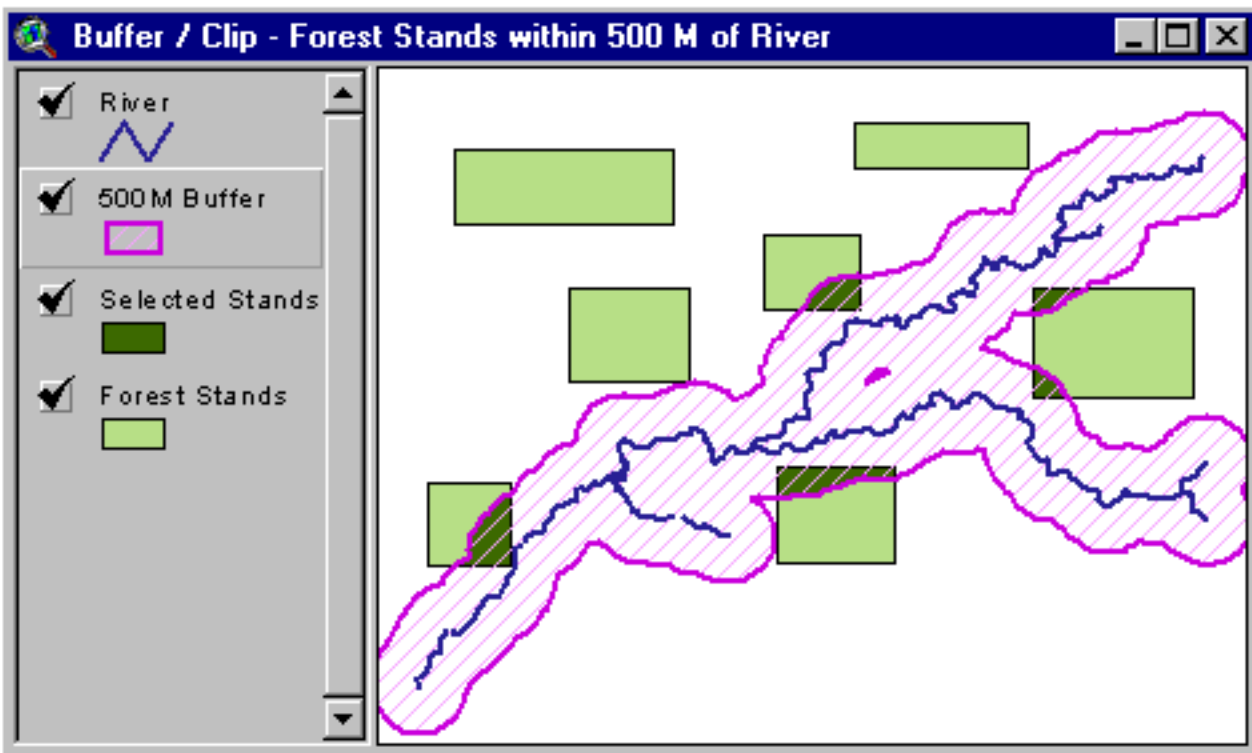
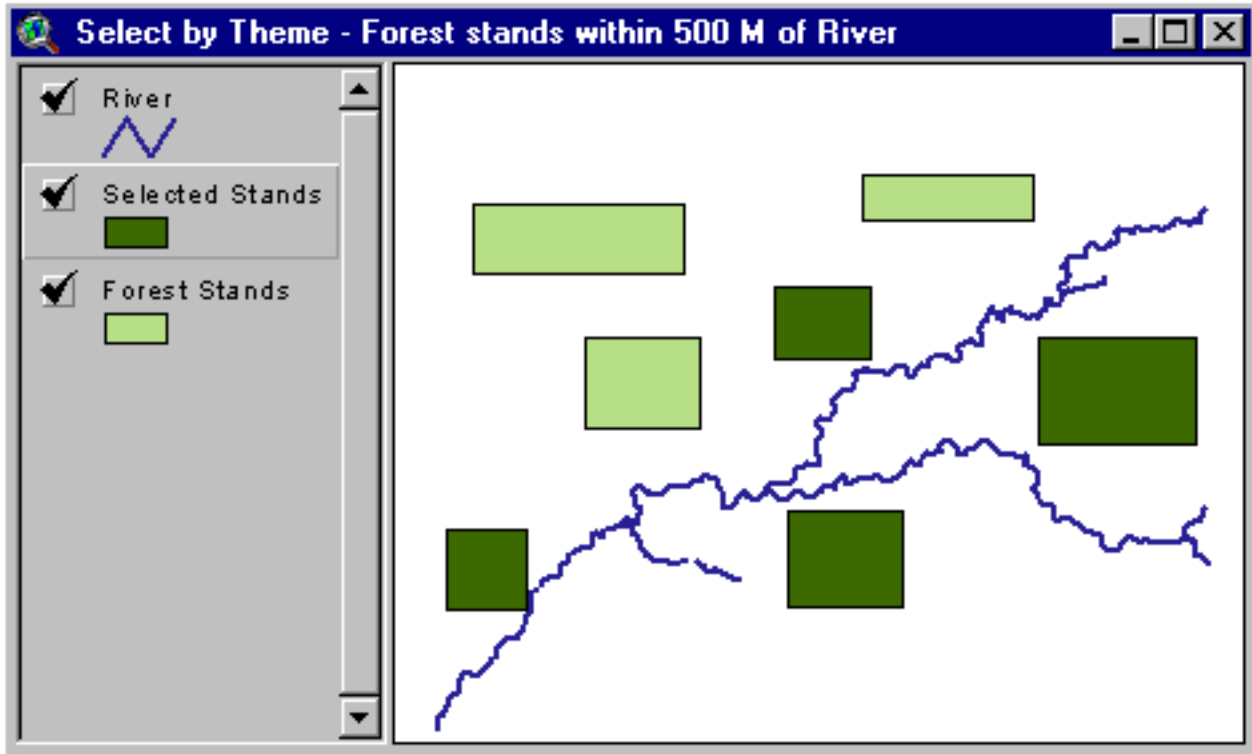
Vector and Raster

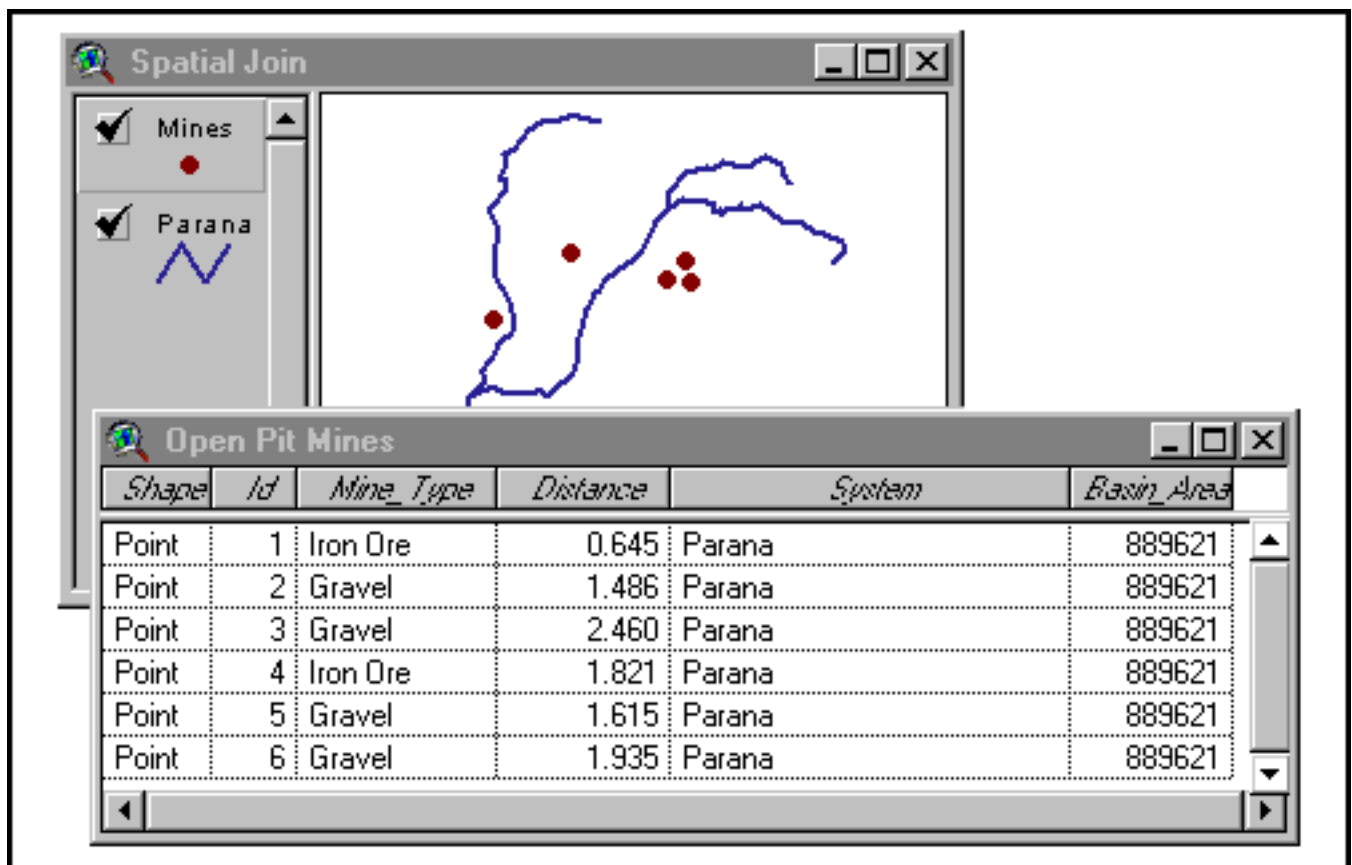
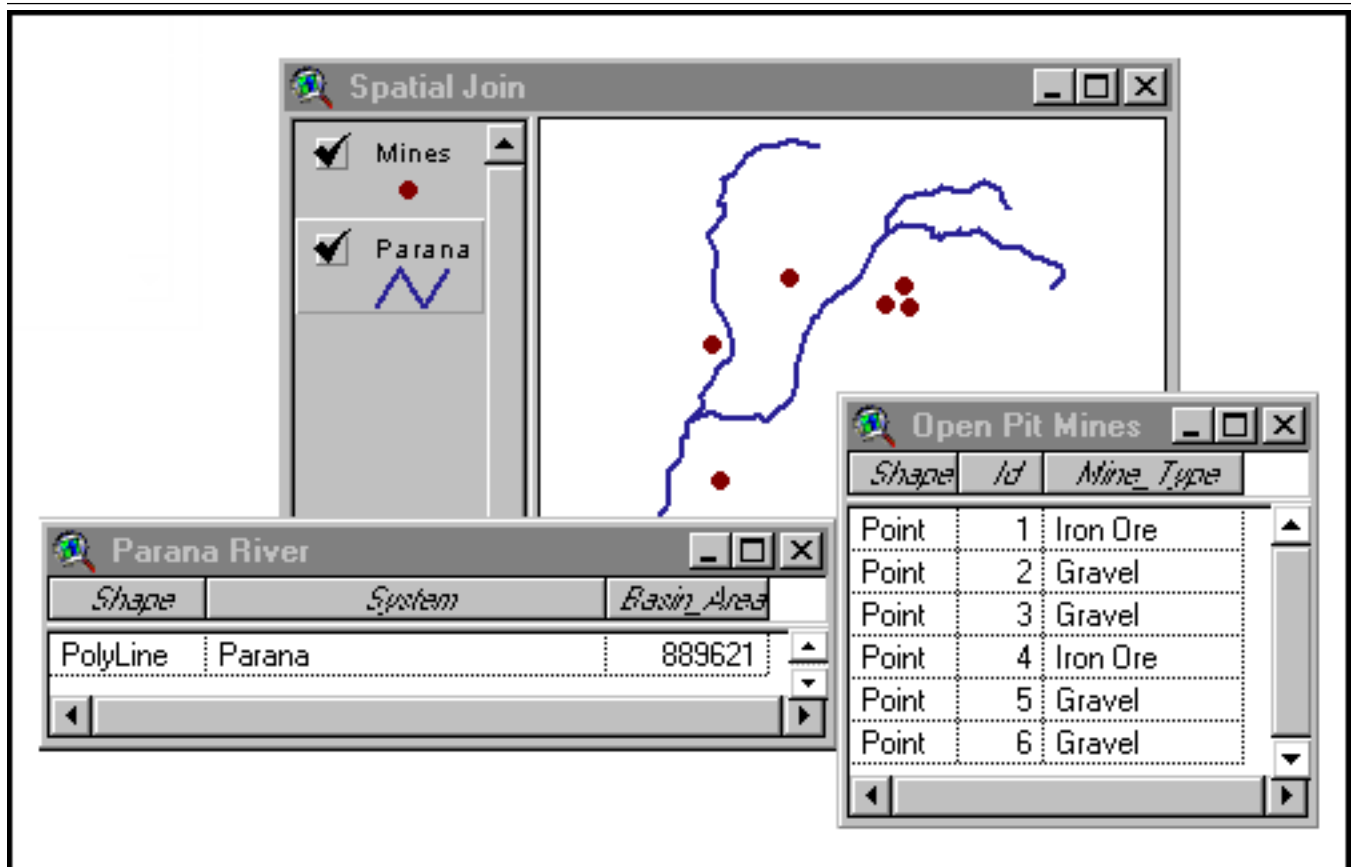


establish limited use zones

100 m	1st-order streams
200 m	2nd-order streams
500 m	3rd-order streams







SPATIAL ANALYSES

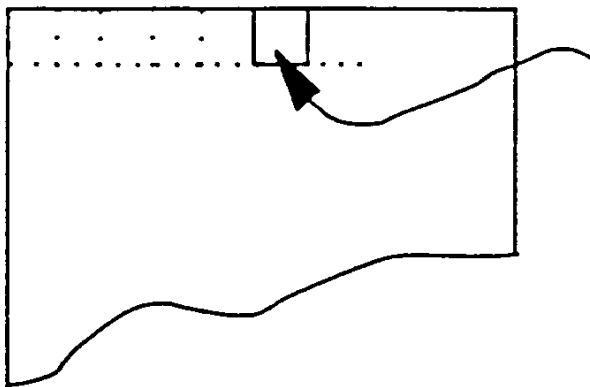
Basic Functional Classes

- Reclassifying Maps
- Overlaying Maps
- Measuring Distance and Connectivity

□ Characterizing Neighborhoods

Raster Only

CHARACTERIZING NEIGHBORHOODS



Neighborhood =
User-Defined Area
of Scrutiny

"Roving Window"

(e.g. ... per square mile; ... per hectare)

WINDOW OPERATIONS

Raster Only

Slope

Slope Aspect

Maximum, Minimum

Mean, Median, Mode

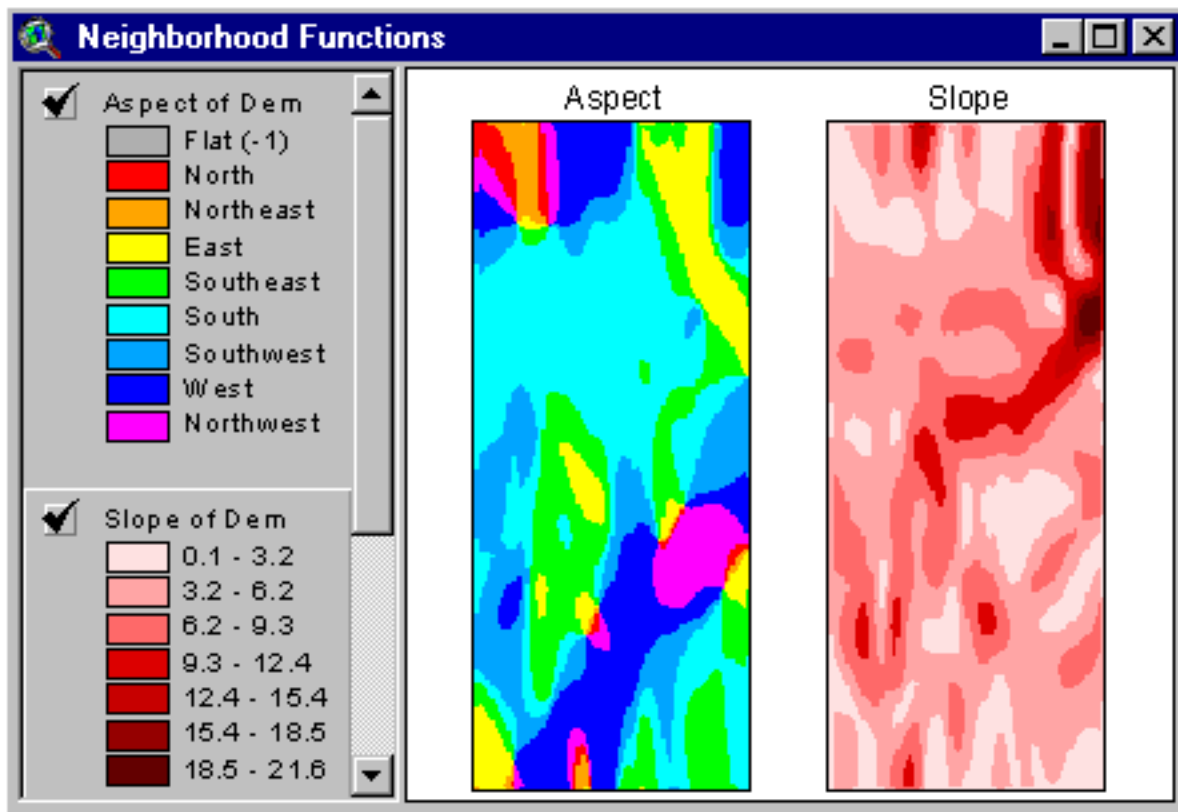
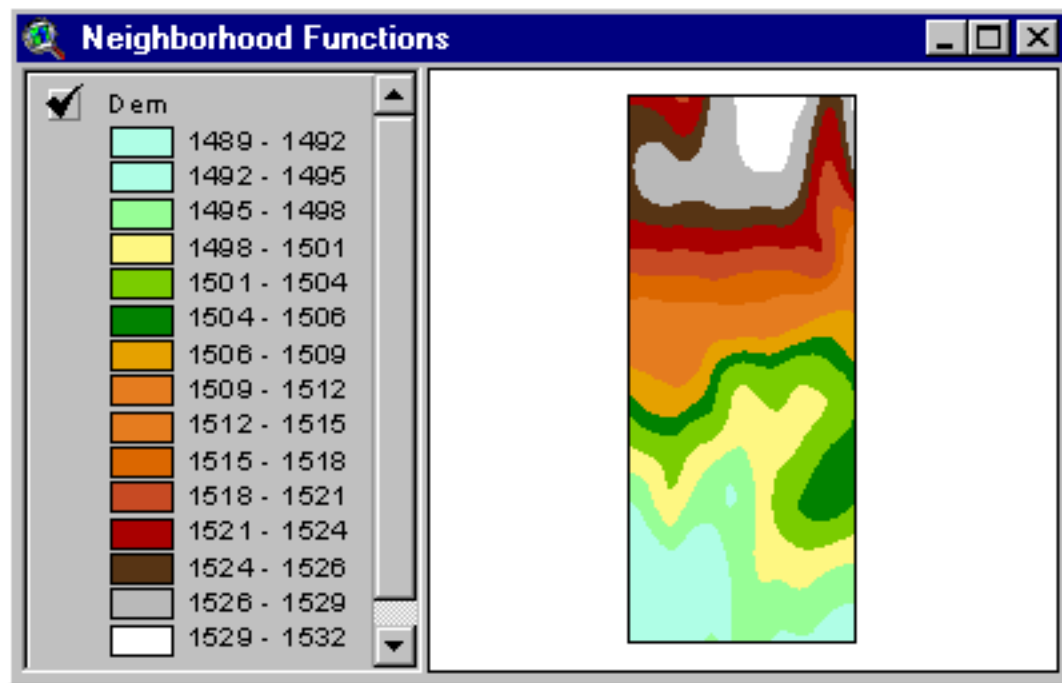
Standard Deviation

Majority, Minority

Total Count

Diversity

**Large number of Spatial Pattern
or Texture Indexes
(e.g. Dominance Index, Relative Richness, etc.)**



Examples of Neighborhood Operations to Determine Spatial Pattern

Each of the following measures are calculated within a **3 x 3 pixel window** which systematically roves throught the data set. The outcome calculation is assigned to the center cell in the window (in the output file), then the window moves over one pixel along a row and recalculates a new value for that center-pixel location, etc.

$$\text{Relative Richness} = n / (n_{\max}) \times 100$$

where n = number of different classes present

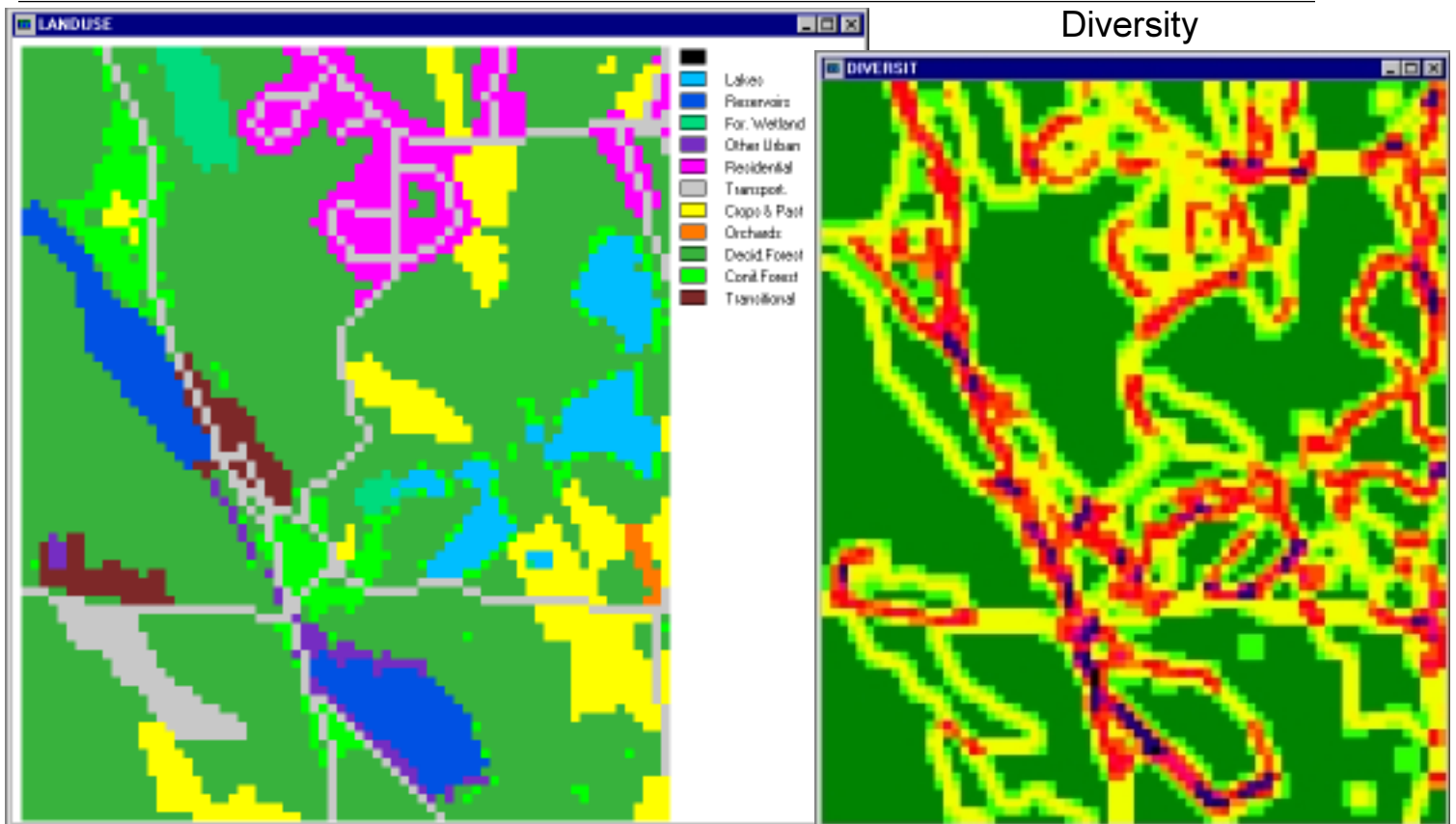
$$\text{Diversity} = -\sum[(p) \times \ln(p)]$$

where sum = the sum over all classes; p = proportion of the footprint in each class; ln = natural logarithm

$$\text{Dominance} = H_{\max} - H$$

where H = Diversity; H_{\max} = maximum diversity = $\ln(n)$; n = number of different classes present;
ln = natural logarithm

from: Turner, M.G. 1989. Landscape Ecology: The Effect of Pattern on Process, *Annu. Rev. Ecol. Syst.*, 20, 171-197.



Dominance Index

Relative Richness

