Deep Neural Network for Image Classification: Application

When you finish this, you will have finished the last programming assignment of Week 4, and also the last programming assignment of this course!

You will use use the functions you'd implemented in the previous assignment to build a deep network, and apply it to cat vs non-cat classification. Hopefully, you will see an improvement in accuracy relative to your previous logistic regression implementation.

After this assignment you will be able to:

Build and apply a deep neural network to supervised learning.

Let's get started!

1 - Packages

Let's first import all the packages that you will need during this assignment.

- numpy (www.numpy.org) is the fundamental package for scientific computing with Python.
- matplotlib (http://matplotlib.org) is a library to plot graphs in Python.
- h5py (http://www.h5py.org) is a common package to interact with a dataset that is stored on an H5 file.
- PIL (http://www.pythonware.com/products/pil/) and scipy (https://www.scipy.org/) are used here to test your model with your own picture at the end.
- dnn_app_utils provides the functions implemented in the "Building your Deep Neural Network: Step by Step" assignment to this notebook.
- np.random.seed(1) is used to keep all the random function calls consistent. It will help us grade your work.

```
In [1]:
        import time
        import numpy as np
        import h5py
        import matplotlib.pyplot as plt
        import scipy
        from PIL import Image
        from scipy import ndimage
        from dnn_app_utils_v3 import *
        %matplotlib inline
        plt.rcParams['figure.figsize'] = (5.0, 4.0) # set default size of plots
        plt.rcParams['image.interpolation'] = 'nearest'
        plt.rcParams['image.cmap'] = 'gray'
        %load ext autoreload
        %autoreload 2
        np.random.seed(1)
```

2 - Dataset

You will use the same "Cat vs non-Cat" dataset as in "Logistic Regression as a Neural Network" (Assignment 2). The model you had built had 70% test accuracy on classifying cats vs non-cats images. Hopefully, your new model will perform a better!

Problem Statement: You are given a dataset ("data.h5") containing:

```
- a training set of m train images labelled as cat (1) or non-cat
 (0)
- a test set of m_test images labelled as cat and non-cat
- each image is of shape (num px, num px, 3) where 3 is for the 3 ch
annels (RGB).
```

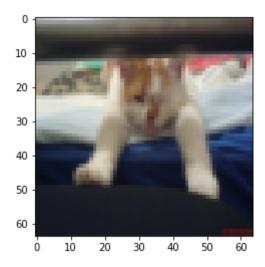
Let's get more familiar with the dataset. Load the data by running the cell below.

```
In [2]: train x orig, train y, test x orig, test y, classes = load data()
```

The following code will show you an image in the dataset. Feel free to change the index and re-run the cell multiple times to see other images.

```
In [4]:
        # Example of a picture
        index = 29
        plt.imshow(train_x_orig[index])
        print ("y = " + str(train_y[0,index]) + ". It's a " + classes[train_y[0,index]]
```

y = 1. It's a cat picture.



```
In [5]:
        # Explore your dataset
        m_train = train_x_orig.shape[0]
        num px = train x orig.shape[1]
        m_test = test_x_orig.shape[0]
        print ("Number of training examples: " + str(m_train))
        print ("Number of testing examples: " + str(m_test))
        print ("Each image is of size: (" + str(num_px) + ", " + str(num_px)
        print ("train_x_orig shape: " + str(train_x_orig.shape))
        print ("train y shape: " + str(train y.shape))
        print ("test_x_orig shape: " + str(test_x_orig.shape))
        print ("test_y shape: " + str(test_y.shape))
```

```
Number of training examples: 209
Number of testing examples: 50
Each image is of size: (64, 64, 3)
train_x_orig shape: (209, 64, 64, 3)
train y shape: (1, 209)
test_x_orig shape: (50, 64, 64, 3)
test_y shape: (1, 50)
```

As usual, you reshape and standardize the images before feeding them to the network. The code is given in the cell below.

reshaped image vector

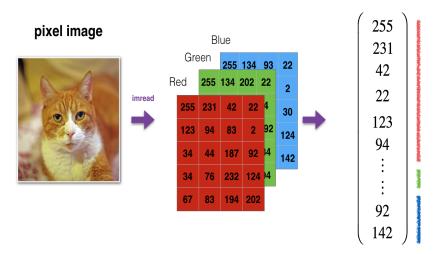


Figure 1: Image to vector conversion.

```
In [6]:
        # Reshape the training and test examples
        train x flatten = train x orig.reshape(train x orig.shape[0], -1).T
                                                                                # The
        test x flatten = test x orig.reshape(test x orig.shape[0], -1).T
        # Standardize data to have feature values between 0 and 1.
        train_x = train_x_flatten/255.
        test_x = test_x_flatten/255.
        print ("train_x's shape: " + str(train_x.shape))
        print ("test_x's shape: " + str(test_x.shape))
        train_x's shape: (12288, 209)
        test_x's shape: (12288, 50)
```

12, 288 equals $64 \times 64 \times 3$ which is the size of one reshaped image vector.

3 - Architecture of your model

Now that you are familiar with the dataset, it is time to build a deep neural network to distinguish cat images from non-cat images.

You will build two different models:

- A 2-layer neural network
- An L-layer deep neural network

You will then compare the performance of these models, and also try out different values for L.

Let's look at the two architectures.

3.1 - 2-layer neural network

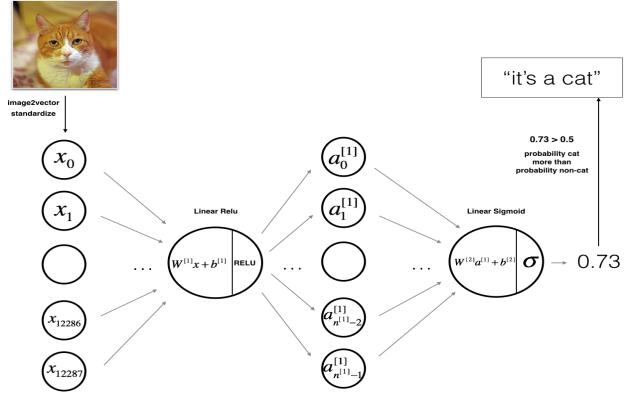


Figure 2: 2-layer neural network.

The model can be summarized as: INPUT -> LINEAR -> RELU -> LINEAR -> SIGMOID -> **OUTPUT.**

Detailed Architecture of figure 2:

- The input is a (64,64,3) image which is flattened to a vector of size (12288, 1).
- The corresponding vector: $[x_0, x_1, \dots, x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ of size $(n^{[1]}, 12288)$.
- You then add a bias term and take its relu to get the following vector: $[a_0^{[1]}, a_1^{[1]}, \dots, a_{n^{[1]}-1}^{[1]}]^T$.
- You then repeat the same process.
- You multiply the resulting vector by $W^{[2]}$ and add your intercept (bias).
- Finally, you take the sigmoid of the result. If it is greater than 0.5, you classify it to be a cat.

3.2 - L-layer deep neural network

It is hard to represent an L-layer deep neural network with the above representation. However, here is a simplified network representation:

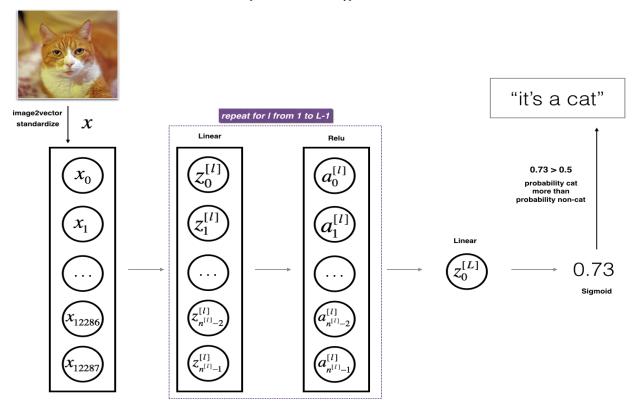


Figure 3: L-layer neural network.

The model can be summarized as: [LINEAR -> RELU] × (L-1) -> LINEAR -> SIGMOID

Detailed Architecture of figure 3:

- The input is a (64,64,3) image which is flattened to a vector of size (12288,1).
- The corresponding vector: $[x_0, x_1, \dots, x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ and then you add the intercept $b^{[1]}$. The result is called the linear unit.
- · Next, you take the relu of the linear unit. This process could be repeated several times for each $(W^{[l]}, b^{[l]})$ depending on the model architecture.
- Finally, you take the sigmoid of the final linear unit. If it is greater than 0.5, you classify it to be a cat.

3.3 - General methodology

As usual you will follow the Deep Learning methodology to build the model:

- 1. Initialize parameters / Define hyperparameters
- 2. Loop for num_iterations:
 - a. Forward propagation
 - b. Compute cost function
 - c. Backward propagation
 - d. Update parameters (using parameters, and grads from backprop)
- 4. Use trained parameters to predict labels

Let's now implement those two models!

4 - Two-layer neural network

Question: Use the helper functions you have implemented in the previous assignment to build a 2layer neural network with the following structure: LINEAR -> RELU -> LINEAR -> SIGMOID. The functions you may need and their inputs are:

```
def initialize parameters(n_x, n_h, n_y):
    return parameters
def linear_activation_forward(A_prev, W, b, activation):
    return A, cache
def compute_cost(AL, Y):
    . . .
    return cost
def linear_activation_backward(dA, cache, activation):
    return dA_prev, dW, db
def update parameters(parameters, grads, learning rate):
    return parameters
```

```
In [7]: ### CONSTANTS DEFINING THE MODEL ####
        n_x = 12288 # num px * num px * 3
        n h = 7
        n_y = 1
        layers_dims = (n_x, n_h, n_y)
```

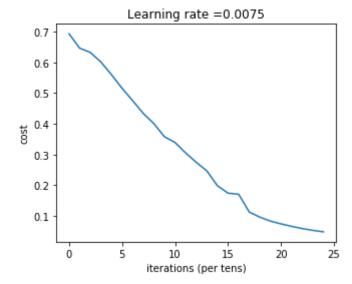
```
In [8]: # GRADED FUNCTION: two layer model
        def two_layer_model(X, Y, layers_dims, learning_rate = 0.0075, num_iteration
            Implements a two-layer neural network: LINEAR->RELU->LINEAR->SIGMOID.
            Arguments:
            X -- input data, of shape (n x, number of examples)
            Y -- true "label" vector (containing 0 if cat, 1 if non-cat), of shape
            layers dims -- dimensions of the layers (n_x, n_h, n_y)
            num iterations -- number of iterations of the optimization loop
            learning rate -- learning rate of the gradient descent update rule
            print cost -- If set to True, this will print the cost every 100 iterat:
            Returns:
            parameters -- a dictionary containing W1, W2, b1, and b2
            np.random.seed(1)
            grads = {}
            costs = []
                                                     # to keep track of the cost
            m = X.shape[1]
                                                      # number of examples
            (n_x, n_h, n_y) = layers_dims
            # Initialize parameters dictionary, by calling one of the functions you
            ### START CODE HERE ### (≈ 1 line of code)
            parameters = initialize parameters(n x, n h, n y)
            ### END CODE HERE ###
            # Get W1, b1, W2 and b2 from the dictionary parameters.
            W1 = parameters["W1"]
            b1 = parameters["b1"]
            W2 = parameters["W2"]
            b2 = parameters["b2"]
            # Loop (gradient descent)
            for i in range(0, num_iterations):
                # Forward propagation: LINEAR -> RELU -> LINEAR -> SIGMOID. Inputs:
                ### START CODE HERE ### (≈ 2 lines of code)
                A1, cache1 = linear activation forward(X, W1, b1, "relu")
                A2, cache2 = linear activation forward(A1, W2, b2, "sigmoid")
                ### END CODE HERE ###
                # Compute cost
                ### START CODE HERE ### (≈ 1 line of code)
                cost = compute_cost(A2, Y)
                ### END CODE HERE ###
                # Initializing backward propagation
                dA2 = - (np.divide(Y, A2) - np.divide(1 - Y, 1 - A2))
                # Backward propagation. Inputs: "dA2, cache2, cache1". Outputs: "dA.
                ### START CODE HERE ### (≈ 2 lines of code)
                dA1, dW2, db2 = linear activation backward(dA2, cache2, "sigmoid")
                dA0, dW1, db1 = linear_activation_backward(dA1, cache1, "relu")
```

```
### END CODE HERE ###
    # Set grads['dWl'] to dW1, grads['db1'] to db1, grads['dW2'] to dW2
    grads['dW1'] = dW1
    grads['db1'] = db1
    grads['dW2'] = dW2
    grads['db2'] = db2
    # Update parameters.
    ### START CODE HERE ### (approx. 1 line of code)
    parameters = update parameters(parameters, grads, learning_rate)
    ### END CODE HERE ###
    # Retrieve W1, b1, W2, b2 from parameters
    W1 = parameters["W1"]
    b1 = parameters["b1"]
    W2 = parameters["W2"]
    b2 = parameters["b2"]
    # Print the cost every 100 training example
    if print cost and i % 100 == 0:
        print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
    if print cost and i % 100 == 0:
        costs.append(cost)
# plot the cost
plt.plot(np.squeeze(costs))
plt.ylabel('cost')
plt.xlabel('iterations (per tens)')
plt.title("Learning rate =" + str(learning_rate))
plt.show()
return parameters
```

Run the cell below to train your parameters. See if your model runs. The cost should be decreasing. It may take up to 5 minutes to run 2500 iterations. Check if the "Cost after iteration 0" matches the expected output below, if not click on the square () on the upper bar of the notebook to stop the cell and try to find your error.

```
parameters = two layer model(train x, train y, layers dims = (n x, n h, n y
```

```
Cost after iteration 0: 0.6930497356599888
Cost after iteration 100: 0.6464320953428849
Cost after iteration 200: 0.6325140647912677
Cost after iteration 300: 0.6015024920354665
Cost after iteration 400: 0.5601966311605747
Cost after iteration 500: 0.515830477276473
Cost after iteration 600: 0.4754901313943325
Cost after iteration 700: 0.4339163151225749
Cost after iteration 800: 0.4007977536203887
Cost after iteration 900: 0.3580705011323798
Cost after iteration 1000: 0.3394281538366412
Cost after iteration 1100: 0.3052753636196264
Cost after iteration 1200: 0.27491377282130164
Cost after iteration 1300: 0.24681768210614846
Cost after iteration 1400: 0.19850735037466116
Cost after iteration 1500: 0.1744831811255664
Cost after iteration 1600: 0.17080762978096148
Cost after iteration 1700: 0.11306524562164734
Cost after iteration 1800: 0.09629426845937152
Cost after iteration 1900: 0.08342617959726863
Cost after iteration 2000: 0.07439078704319081
Cost after iteration 2100: 0.0663074813226793
Cost after iteration 2200: 0.0591932950103817
Cost after iteration 2300: 0.053361403485605585
Cost after iteration 2400: 0.04855478562877016
```



Expected Output:

Cost after iteration 0 0.6930497356599888

0.6464320953428849 Cost after iteration 100

Cost after iteration 2400 0.048554785628770206

Good thing you built a vectorized implementation! Otherwise it might have taken 10 times longer to

train this.

Now, you can use the trained parameters to classify images from the dataset. To see your predictions on the training and test sets, run the cell below.

```
In [10]: predictions_train = predict(train_x, train_y, parameters)
```

Accuracy: 1.0

Expected Output:

Accuracy 1.0

```
In [11]: predictions_test = predict(test_x, test_y, parameters)
```

Accuracy: 0.72

Expected Output:

Accuracy 0.72

Note: You may notice that running the model on fewer iterations (say 1500) gives better accuracy on the test set. This is called "early stopping" and we will talk about it in the next course. Early stopping is a way to prevent overfitting.

Congratulations! It seems that your 2-layer neural network has better performance (72%) than the logistic regression implementation (70%, assignment week 2). Let's see if you can do even better with an L-layer model.

5 - L-layer Neural Network

Question: Use the helper functions you have implemented previously to build an L-layer neural network with the following structure: [LINEAR -> RELU]×(L-1) -> LINEAR -> SIGMOID. The functions you may need and their inputs are:

```
def initialize parameters_deep(layers_dims):
    return parameters
def L_model_forward(X, parameters):
    return AL, caches
def compute_cost(AL, Y):
    return cost
def L_model_backward(AL, Y, caches):
    return grads
def update_parameters(parameters, grads, learning_rate):
    return parameters
```

```
In [12]: ### CONSTANTS ###
         layers_dims = [12288, 20, 7, 5, 1] # 4-layer model
```

```
In [13]: # GRADED FUNCTION: L layer model
         def L layer model(X, Y, layers dims, learning rate = 0.0075, num_iterations
             Implements a L-layer neural network: [LINEAR->RELU]*(L-1)->LINEAR->SIGM(
             Arguments:
             X -- data, numpy array of shape (number of examples, num px * num px *
             Y -- true "label" vector (containing 0 if cat, 1 if non-cat), of shape
             layers_dims -- list containing the input size and each layer size, of le
             learning rate -- learning rate of the gradient descent update rule
             num iterations -- number of iterations of the optimization loop
             print_cost -- if True, it prints the cost every 100 steps
             Returns:
             parameters -- parameters learnt by the model. They can then be used to
             np.random.seed(1)
             costs = []
                                                 # keep track of cost
             # Parameters initialization. (≈ 1 line of code)
             ### START CODE HERE ###
             parameters = initialize parameters deep(layers dims)
             ### END CODE HERE ###
             # Loop (gradient descent)
             for i in range(0, num_iterations):
                 # Forward propagation: [LINEAR -> RELU]*(L-1) -> LINEAR -> SIGMOID.
                 ### START CODE HERE ### (≈ 1 line of code)
                 AL, caches = L_model_forward(X, parameters)
                 ### END CODE HERE ###
                 # Compute cost.
                 ### START CODE HERE ### (≈ 1 line of code)
                 cost = compute cost(AL, Y)
                 ### END CODE HERE ###
                 # Backward propagation.
                 ### START CODE HERE ### (≈ 1 line of code)
                 grads = L model backward(AL, Y, caches)
                 ### END CODE HERE ###
                 # Update parameters.
                 ### START CODE HERE ### (\approx 1 line of code)
                 parameters = update parameters(parameters, grads, learning_rate)
                 ### END CODE HERE ###
                 # Print the cost every 100 training example
                 if print_cost and i % 100 == 0:
                     print ("Cost after iteration %i: %f" %(i, cost))
                 if print cost and i % 100 == 0:
                     costs.append(cost)
             # plot the cost
             plt.plot(np.squeeze(costs))
```

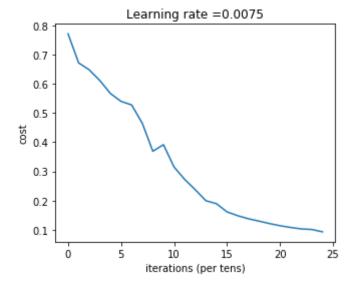
```
plt.ylabel('cost')
plt.xlabel('iterations (per tens)')
plt.title("Learning rate =" + str(learning_rate))
plt.show()
return parameters
```

You will now train the model as a 4-layer neural network.

Run the cell below to train your model. The cost should decrease on every iteration. It may take up to 5 minutes to run 2500 iterations. Check if the "Cost after iteration 0" matches the expected output below, if not click on the square () on the upper bar of the notebook to stop the cell and try to find your error.

In [14]: parameters = L_layer_model(train_x, train_y, layers_dims, num_iterations =

```
Cost after iteration 0: 0.771749
Cost after iteration 100: 0.672053
Cost after iteration 200: 0.648263
Cost after iteration 300: 0.611507
Cost after iteration 400: 0.567047
Cost after iteration 500: 0.540138
Cost after iteration 600: 0.527930
Cost after iteration 700: 0.465477
Cost after iteration 800: 0.369126
Cost after iteration 900: 0.391747
Cost after iteration 1000: 0.315187
Cost after iteration 1100: 0.272700
Cost after iteration 1200: 0.237419
Cost after iteration 1300: 0.199601
Cost after iteration 1400: 0.189263
Cost after iteration 1500: 0.161189
Cost after iteration 1600: 0.148214
Cost after iteration 1700: 0.137775
Cost after iteration 1800: 0.129740
Cost after iteration 1900: 0.121225
Cost after iteration 2000: 0.113821
Cost after iteration 2100: 0.107839
Cost after iteration 2200: 0.102855
Cost after iteration 2300: 0.100897
Cost after iteration 2400: 0.092878
```



Expected Output:

Cost after iteration 0 0.771749

0.672053 Cost after iteration 100

Cost after iteration 2400 0.092878

```
In [15]: pred_train = predict(train_x, train_y, parameters)
```

Accuracy: 0.985645933014

Train Accuracy 0.985645933014

```
In [16]: pred_test = predict(test_x, test_y, parameters)
```

Accuracy: 0.8

Expected Output:

Test Accuracy 0.8

Congrats! It seems that your 4-layer neural network has better performance (80%) than your 2-layer neural network (72%) on the same test set.

This is good performance for this task. Nice job!

Though in the next course on "Improving deep neural networks" you will learn how to obtain even higher accuracy by systematically searching for better hyperparameters (learning_rate, layers_dims, num_iterations, and others you'll also learn in the next course).

6) Results Analysis

First, let's take a look at some images the L-layer model labeled incorrectly. This will show a few mislabeled images.

In [17]: print mislabeled images(classes, test x, test y, pred test)





















A few types of images the model tends to do poorly on include:

- Cat body in an unusual position
- Cat appears against a background of a similar color
- Unusual cat color and species
- Camera Angle
- Brightness of the picture
- Scale variation (cat is very large or small in image)

7) Test with your own image (optional/ungraded exercise)

Congratulations on finishing this assignment. You can use your own image and see the output of your model. To do that:

- 1. Click on "File" in the upper bar of this notebook, then click "Op en" to go on your Coursera Hub.
- 2. Add your image to this Jupyter Notebook's directory, in the "imag
- 3. Change your image's name in the following code
- 4. Run the code and check if the algorithm is right (1 = cat, 0 = non-cat)!

```
In [ ]: ## START CODE HERE ##
        my image = "my image.jpg" # change this to the name of your image file
        my_label_y = [1] # the true class of your image (1 -> cat, 0 -> non-cat)
        ## END CODE HERE ##
        fname = "images/" + my_image
        image = np.array(ndimage.imread(fname, flatten=False))
        my image = scipy.misc.imresize(image, size=(num px,num px)).reshape((num px
        my_image = my_image/255.
        my predicted image = predict(my image, my label y, parameters)
        plt.imshow(image)
        print ("y = " + str(np.squeeze(my_predicted_image)) + ", your L-layer model
```

References:

• for auto-reloading external module: http://stackoverflow.com/questions/1907993/autoreload-ofmodules-in-ipython (http://stackoverflow.com/questions/1907993/autoreload-of-modules-inipython)