Note: Notebook was updated July 2, 2019 with bug fixes.

If you were working on the older version:

- Please click on the "Coursera" icon in the top right to open up the folder directory.
- Navigate to the folder: Week 3/ Planar data classification with one hidden layer. You can see your prior work in version 5: Planar data classification with one hidden layer v5.ipynb

List of bug fixes and enhancements

- Clarifies that the classifier will learn to classify regions as either red or blue.
- · compute_cost function fixes np.squeeze by casting it as a float.
- compute_cost instructions clarify the purpose of np.squeeze.
- compute_cost clarifies that "parameters" parameter is not needed, but is kept in the function definition until the auto-grader is also updated.
- nn_model removes extraction of parameter values, as the entire parameter dictionary is passed to the invoked functions.

Planar data classification with one hidden layer

Welcome to your week 3 programming assignment. It's time to build your first neural network, which will have a hidden layer. You will see a big difference between this model and the one you implemented using logistic regression.

You will learn how to:

- Implement a 2-class classification neural network with a single hidden layer
- · Use units with a non-linear activation function, such as tanh
- · Compute the cross entropy loss
- Implement forward and backward propagation

1 - Packages

Let's first import all the packages that you will need during this assignment.

- numpy (https://www.numpy.org/) is the fundamental package for scientific computing with Python.
- sklearn (http://scikit-learn.org/stable/) provides simple and efficient tools for data mining and data analysis.
- matplotlib (http://matplotlib.org) is a library for plotting graphs in Python.
- testCases provides some test examples to assess the correctness of your functions
- planar_utils provide various useful functions used in this assignment

```
In [1]:
        # Package imports
        import numpy as np
        import matplotlib.pyplot as plt
        from testCases_v2 import *
        import sklearn
        import sklearn.datasets
        import sklearn.linear model
        from planar_utils import plot_decision_boundary, sigmoid, load_planar datase
        %matplotlib inline
        np.random.seed(1) # set a seed so that the results are consistent
```

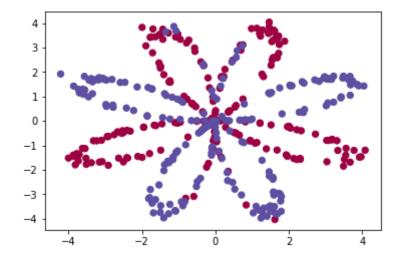
2 - Dataset

First, let's get the dataset you will work on. The following code will load a "flower" 2-class dataset into variables x and y.

```
In [2]: X, Y = load_planar_dataset()
```

Visualize the dataset using matplotlib. The data looks like a "flower" with some red (label y=0) and some blue (y=1) points. Your goal is to build a model to fit this data. In other words, we want the classifier to define regions as either red or blue.

```
In [3]: # Visualize the data:
        plt.scatter(X[0, :], X[1, :], c=Y, s=40, cmap=plt.cm.Spectral);
```



You have:

```
- a numpy-array (matrix) X that contains your features (x1, x2)
- a numpy-array (vector) Y that contains your labels (red:0, blue:
1).
```

Lets first get a better sense of what our data is like.

Exercise: How many training examples do you have? In addition, what is the shape of the variables x and y?

Hint: How do you get the shape of a numpy array? (help) (https://docs.scipy.org/doc/numpy/reference/generated/numpy.ndarray.shape.html)

```
In [4]: ### START CODE HERE ### (≈ 3 lines of code)
        shape_X = None
        shape Y = None
        m = X.shape[1] # training set size
        ### END CODE HERE ###
        print ('The shape of X is: ' + str(shape_X))
        print ('The shape of Y is: ' + str(shape_Y))
        print ('I have m = %d training examples!' % (m))
        The shape of X is: (2, 400)
        The shape of Y is: (1, 400)
        I have m = 400 training examples!
```

Expected Output:

```
shape of
             (2, 400)
shape of
             (1, 400)
                400
```

3 - Simple Logistic Regression

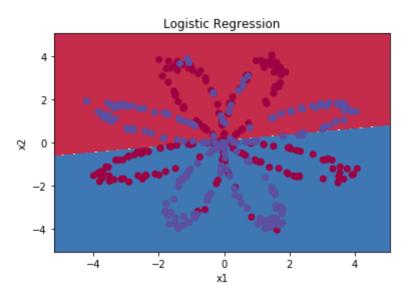
Before building a full neural network, lets first see how logistic regression performs on this problem. You can use sklearn's built-in functions to do that. Run the code below to train a logistic regression classifier on the dataset.

```
In [5]: # Train the logistic regression classifier
        clf = sklearn.linear model.LogisticRegressionCV();
        clf.fit(X.T, Y.T);
```

You can now plot the decision boundary of these models. Run the code below.

```
# Plot the decision boundary for logistic regression
plot decision boundary(lambda x: clf.predict(x), X, Y)
plt.title("Logistic Regression")
# Print accuracy
LR predictions = clf.predict(X.T)
print ('Accuracy of logistic regression: %d ' % float((np.dot(Y,LR_prediction)))
       '% ' + "(percentage of correctly labelled datapoints)")
```

Accuracy of logistic regression: 47 % (percentage of correctly labelled d atapoints)



Expected Output:

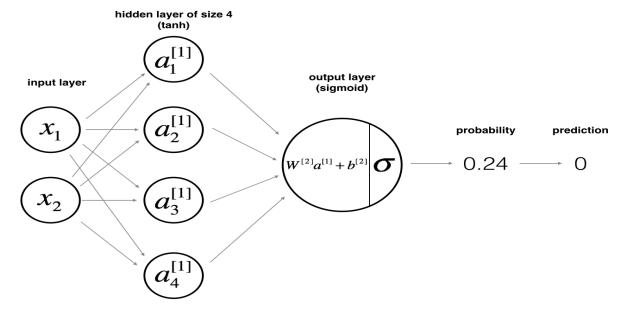
Accuracy 47%

Interpretation: The dataset is not linearly separable, so logistic regression doesn't perform well. Hopefully a neural network will do better. Let's try this now!

4 - Neural Network model

Logistic regression did not work well on the "flower dataset". You are going to train a Neural Network with a single hidden layer.

Here is our model:



Mathematically:

For one example $x^{(i)}$:

$$z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$$
 (1)

$$a^{[1](i)} = \tanh(z^{[1](i)}) \tag{2}$$

$$z^{[2](i)} = W^{[2]} a^{[1](i)} + b^{[2]}$$
(3)

$$\hat{\mathbf{y}}^{(i)} = a^{[2](i)} = \sigma(z^{[2](i)}) \tag{4}$$

$$\hat{y}^{(i)} = a^{[2](i)} = \sigma(z^{[2](i)})$$

$$y_{prediction}^{(i)} = \begin{cases} 1 & \text{if } a^{[2](i)} > 0.5 \\ 0 & \text{otherwise} \end{cases}$$
(5)

Given the predictions on all the examples, you can also compute the cost J as follows:

$$J = -\frac{1}{m} \sum_{i=0}^{m} \left(y^{(i)} \log(a^{[2](i)}) + (1 - y^{(i)}) \log(1 - a^{[2](i)}) \right)$$
 (6)

Reminder: The general methodology to build a Neural Network is to:

- 1. Define the neural network structure (# of input units, # of hid den units, etc).
- 2. Initialize the model's parameters
- 3. Loop:
 - Implement forward propagation
 - Compute loss
 - Implement backward propagation to get the gradients
 - Update parameters (gradient descent)

You often build helper functions to compute steps 1-3 and then merge them into one function we call nn model(). Once you've built nn model() and learnt the right parameters, you can make predictions on new data.

4.1 - Defining the neural network structure

Exercise: Define three variables:

```
- n x: the size of the input layer
- n h: the size of the hidden layer (set this to 4)
- n_y: the size of the output layer
```

Hint: Use shapes of X and Y to find n_x and n_y. Also, hard code the hidden layer size to be 4.

```
In [7]: # GRADED FUNCTION: layer sizes
        def layer sizes(X, Y):
            Arguments:
            X -- input dataset of shape (input size, number of examples)
            Y -- labels of shape (output size, number of examples)
            Returns:
            n x -- the size of the input layer
            n_h -- the size of the hidden layer
            n_y -- the size of the output layer
            ### START CODE HERE ### (≈ 3 lines of code)
            n x = None # size of input layer
            n h = None
            n y = None # size of output layer
            ### END CODE HERE ###
            return (n_x, n_h, n_y)
```

```
In [8]: X_assess, Y_assess = layer_sizes_test_case()
        (n x, n h, n y) = layer sizes(X assess, Y assess)
        print("The size of the input layer is: n_x = " + str(n_x))
        print("The size of the hidden layer is: n_h = " + str(n_h))
        print("The size of the output layer is: n_y = " + str(n_y))
        The size of the input layer is: n \times = 5
        The size of the hidden layer is: n_h = 4
        The size of the output layer is: n_y = 2
```

Expected Output (these are not the sizes you will use for your network, they are just used to assess the function you've just coded).

> 5 n_x n_h 2 n_y

4.2 - Initialize the model's parameters

Exercise: Implement the function initialize_parameters().

Instructions:

Make sure your parameters' sizes are right. Refer to the neural network figure above if needed.

```
    You will initialize the weights matrices with random values.
```

Typesetting math: 100% Use: np.random.randn(a,b) * 0.01 to randomly initialize a matrix of shape (a,b).

- You will initialize the bias vectors as zeros.
 - Use: np.zeros((a,b)) to initialize a matrix of shape (a,b) with zeros.

```
In [9]: # GRADED FUNCTION: initialize_parameters
        def initialize parameters(n_x, n_h, n_y):
            Argument:
            n x -- size of the input layer
            n_h -- size of the hidden layer
            n_y -- size of the output layer
            Returns:
            params -- python dictionary containing your parameters:
                             W1 -- weight matrix of shape (n_h, n_x)
                             b1 -- bias vector of shape (n_h, 1)
                             W2 -- weight matrix of shape (n_y, n_h)
                             b2 -- bias vector of shape (n_y, 1)
            .....
            np.random.seed(2) # we set up a seed so that your output matches ours a
            ### START CODE HERE ### (≈ 4 lines of code)
            W1 = None
            b1 = None
            W2 = None
            b2 = None
            ### END CODE HERE ###
            assert (W1.shape == (n h, n x))
            assert (b1.shape == (n_h, 1))
            assert (W2.shape == (n_y, n_h))
            assert (b2.shape == (n_y, 1))
            parameters = {"W1": W1,
                           "b1": b1,
                           "W2": W2,
                           "b2": b2}
            return parameters
```

```
In [10]: n_x, n_h, n_y = initialize parameters_test_case()
         parameters = initialize parameters(n_x, n_h, n_y)
         print("W1 = " + str(parameters["W1"]))
         print("b1 = " + str(parameters["b1"]))
         print("W2 = " + str(parameters["W2"]))
         print("b2 = " + str(parameters["b2"]))
         W1 = [[-0.00416758 -0.00056267]]
          [-0.02136196 \quad 0.01640271]
          [-0.01793436 -0.00841747]
          [ 0.00502881 -0.01245288]]
         b1 = [[0.]]
          [ 0.]
          [ 0.]
          [ 0.]]
         W2 = [[-0.01057952 -0.00909008 \ 0.00551454 \ 0.02292208]]
         b2 = [[0.]]
```

```
[[-0.00416758 -0.00056267] [-0.02136196
W1
             0.01640271] [-0.01793436 -0.00841747] [
                            0.00502881 -0.01245288]]
                                    [[0][0.][0.][0.]]
b1
               [[-0.01057952 -0.00909008 0.00551454
W2
                                        0.02292208]]
                                                [[.0]]
b2
```

4.3 - The Loop

Question: Implement forward propagation().

Instructions:

- Look above at the mathematical representation of your classifier.
- You can use the function sigmoid(). It is built-in (imported) in the notebook.
- You can use the function np.tanh(). It is part of the numpy library.
- The steps you have to implement are:
 - 1. Retrieve each parameter from the dictionary "parameters" (which is the output of initialize parameters()) by using parameters[".."].
 - Implement Forward Propagation. Compute \$Z^{[1]}, A^{[1]}, Z^{[2]}\$ and \$A^{[2]}\$ (the vector of all your predictions on all the examples in the training set).
- Values needed in the backpropagation are stored in "cache". The cache will be given as an input to the backpropagation function.

```
In [11]: # GRADED FUNCTION: forward propagation
         def forward propagation(X, parameters):
             Argument:
             X -- input data of size (n_x, m)
             parameters -- python dictionary containing your parameters (output of in
             Returns:
             A2 -- The sigmoid output of the second activation
             cache -- a dictionary containing "Z1", "A1", "Z2" and "A2"
             # Retrieve each parameter from the dictionary "parameters"
             ### START CODE HERE ### (≈ 4 lines of code)
             W1 = None
             b1 = None
             W2 = None
             b2 = None
             ### END CODE HERE ###
             # Implement Forward Propagation to calculate A2 (probabilities)
             ### START CODE HERE ### (≈ 4 lines of code)
             Z1 = None
             A1 = None
             Z2 = None
             A2 = None
             ### END CODE HERE ###
             assert(A2.shape == (1, X.shape[1]))
             cache = {"Z1": Z1,}
                       "A1": A1,
                       "Z2": Z2,
                       "A2": A2}
             return A2, cache
```

```
In [12]:
         X_assess, parameters = forward_propagation_test_case()
         A2, cache = forward propagation(X assess, parameters)
         # Note: we use the mean here just to make sure that your output matches our
         print(np.mean(cache['Z1']) ,np.mean(cache['A1']),np.mean(cache['Z2']),np.mea
         0.262818640198 0.091999045227 -1.30766601287 0.212877681719
```

0.262818640198 0.091999045227 -1.30766601287 0.212877681719

Now that you have computed \$A^{[2]}\$ (in the Python variable "A2"), which contains \$a^{[2](i)}\$ for every example, you can compute the cost function as follows:

```
\overline{\text{Typesetting math:}} \frac{1}{\sqrt{m}} \cdot \frac{1}{m} \cdot \frac{1}{m}
                                                                                                                                                                                                                                                                                                     y^{(i)}\\log\left(1-a^{[2](i)}\right) \
```

Exercise: Implement compute cost() to compute the value of the cost \$J\$.

Instructions:

 There are many ways to implement the cross-entropy loss. To help you, we give you how we would have implemented $-\sum_{i=0}^{m} y^{(i)}\log(a^{[2](i)})$:

```
logprobs = np.multiply(np.log(A2),Y)
cost = - np.sum(logprobs)
                                          # no need to use a for
 loop!
```

(you can use either np.multiply() and then np.sum() or directly np.dot()). Note that if you use np.multiply followed by np.sum the end result will be a type float, whereas if you use np.dot, the result will be a 2D numpy array. We can use np.squeeze() to remove redundant dimensions (in the case of single float, this will be reduced to a zero-dimension array). We can cast the array as a type float using float().

```
In [13]: # GRADED FUNCTION: compute cost
         def compute_cost(A2, Y, parameters):
             Computes the cross-entropy cost given in equation (13)
             Arguments:
             A2 -- The sigmoid output of the second activation, of shape (1, number of
             Y -- "true" labels vector of shape (1, number of examples)
             parameters -- python dictionary containing your parameters W1, b1, W2 at
             [Note that the parameters argument is not used in this function,
             but the auto-grader currently expects this parameter.
             Future version of this notebook will fix both the notebook
             and the auto-grader so that `parameters` is not needed.
             For now, please include `parameters` in the function signature,
             and also when invoking this function.]
             Returns:
             cost -- cross-entropy cost given equation (13)
             .....
             m = Y.shape[1] # number of example
             # Compute the cross-entropy cost
             ### START CODE HERE ### (≈ 2 lines of code)
             logprobs = None
             cost = None
             ### END CODE HERE ###
             cost = float(np.squeeze(cost)) # makes sure cost is the dimension we ex
                                              # E.g., turns [[17]] into 17
             assert(isinstance(cost, float))
             return cost
```

cost 0.693058761...

Using the cache computed during forward propagation, you can now implement backward propagation.

Question: Implement the function backward propagation().

Instructions: Backpropagation is usually the hardest (most mathematical) part in deep learning. To help you, here again is the slide from the lecture on backpropagation. You'll want to use the six equations on the right of this slide, since you are building a vectorized implementation.

Summary of gradient descent

$$\begin{split} dz^{[2]} &= a^{[2]} - y \\ dW^{[2]} &= dz^{[2]}a^{[1]^T} \\ db^{[2]} &= dz^{[2]} \\ dz^{[2]} &= \frac{1}{m}dZ^{[2]}A^{[1]^T} \\ dz^{[2]} &= \frac{1}{m}np. sum(dZ^{[2]}, axis = 1, keepdims = True) \\ dz^{[1]} &= W^{[2]T}dz^{[2]} * g^{[1]'}(z^{[1]}) \\ dW^{[1]} &= dz^{[1]}x^T \\ db^{[1]} &= dz^{[1]} \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axis = 1, keepdims = True) \\ db^{[1]} &= \frac{1}{m}np. sum(dZ^{[1]}, axi$$

- Tips:
 - To compute dZ1 you'll need to compute \$g^{[1]'}(Z^{[1]})\$. Since \$g^{[1]}(.)\$ is the tanh activation function, if $a = g^{[1]}(z)$ then $g^{[1]}(z) = 1-a^2$. So you can compute $g^{[1]'}(Z^{[1]})$ using (1 - np.power(A1, 2)).

```
In [15]: # GRADED FUNCTION: backward propagation
          def backward_propagation(parameters, cache, X, Y):
              Implement the backward propagation using the instructions above.
              Arguments:
              parameters -- python dictionary containing our parameters
              cache -- a dictionary containing "Z1", "A1", "Z2" and "A2".
              X -- input data of shape (2, number of examples)
              Y -- "true" labels vector of shape (1, number of examples)
              Returns:
              grads -- python dictionary containing your gradients with respect to different gradients with respect to different gradients.
              m = X.shape[1]
              # First, retrieve W1 and W2 from the dictionary "parameters".
              ### START CODE HERE ### (≈ 2 lines of code)
              W1 = None
              W2 = None
              ### END CODE HERE ###
              # Retrieve also A1 and A2 from dictionary "cache".
              ### START CODE HERE ### (≈ 2 lines of code)
              A1 = None
              A2 = None
              ### END CODE HERE ###
              # Backward propagation: calculate dW1, db1, dW2, db2.
              ### START CODE HERE ### (≈ 6 lines of code, corresponding to 6 equations
              dZ2 = None
              dW2 = None
              db2 = None
              dZ1 = None
              dW1 = None
              db1 = None
              ### END CODE HERE ###
              grads = {"dW1": dW1,}
                        "db1": db1,
                        "dW2": dW2,
                        "db2": db2}
              return grads
```

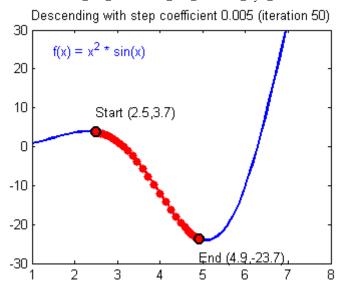
```
In [16]:
         parameters, cache, X_assess, Y_assess = backward_propagation_test_case()
         grads = backward_propagation(parameters, cache, X_assess, Y_assess)
         print ("dW1 = "+ str(grads["dW1"]))
         print ("db1 = "+ str(grads["db1"]))
         print ("dW2 = "+ str(grads["dW2"]))
         print ("db2 = "+ str(grads["db2"]))
         dW1 = [[ 0.00301023 -0.00747267]
          [ 0.00257968 -0.00641288]
          [-0.00156892 \quad 0.003893
          [-0.00652037 0.01618243]]
         db1 = [[ 0.00176201]
          [ 0.00150995]
          [-0.00091736]
          [-0.00381422]]
         dW2 = [[0.00078841 \ 0.01765429 \ -0.00084166 \ -0.01022527]]
         db2 = [[-0.16655712]]
```

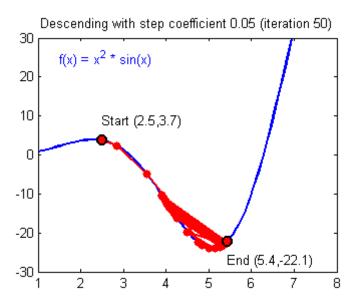
```
[[ 0.00301023 -0.00747267] [ 0.00257968
dW1
            -0.00641288] [-0.00156892 0.003893 ]
                       [-0.00652037 0.01618243]]
        [[ 0.00176201] [ 0.00150995] [-0.00091736]
db1
                                   [-0.00381422]]
           [[ 0.00078841 0.01765429 -0.00084166
dW2
                                   -0.01022527]]
                                  [[-0.16655712]]
db2
```

Question: Implement the update rule. Use gradient descent. You have to use (dW1, db1, dW2, db2) in order to update (W1, b1, W2, b2).

General gradient descent rule: \$ \theta = \theta - \alpha \frac{\partial J }{ \partial \theta }\$ where \$\alpha\$ is the learning rate and \$\theta\$ represents a parameter.

Illustration: The gradient descent algorithm with a good learning rate (converging) and a bad learning rate (diverging). Images courtesy of Adam Harley.





```
In [31]: # GRADED FUNCTION: update parameters
         def update parameters(parameters, grads, learning rate = 1.2):
             Updates parameters using the gradient descent update rule given above
             Arguments:
             parameters -- python dictionary containing your parameters
             grads -- python dictionary containing your gradients
             Returns:
             parameters -- python dictionary containing your updated parameters
             # Retrieve each parameter from the dictionary "parameters"
             ### START CODE HERE ### (≈ 4 lines of code)
             W1 = None
             b1 = None
             W2 = None
             b2 = None
             ### END CODE HERE ###
             # Retrieve each gradient from the dictionary "grads"
             ### START CODE HERE ### (≈ 4 lines of code)
             dW1 = None
             db1 = None
             dW2 = None
             db2 = None
             ## END CODE HERE ###
             # Update rule for each parameter
             ### START CODE HERE ### (≈ 4 lines of code)
             W1 = None
             b1 = None
             W2 = None
             b2 = None
             ### END CODE HERE ###
             parameters = {"W1": W1,
                            "b1": b1,
                            "W2": W2,
                            "b2": b2}
             return parameters
```

```
In [32]:
         parameters, grads = update_parameters_test_case()
         parameters = update_parameters(parameters, grads)
         print("W1 = " + str(parameters["W1"]))
         print("b1 = " + str(parameters["b1"]))
         print("W2 = " + str(parameters["W2"]))
         print("b2 = " + str(parameters["b2"]))
         W1 = [[-0.00643025 \quad 0.01936718]]
          [-0.02410458 \quad 0.03978052]
          [-0.01653973 - 0.02096177]
          [ 0.01046864 -0.05990141]]
         b1 = [[ 1.21732533e-05]
            2.12263977e-05]
             1.36755874e-05]
             1.05251698e-05]]
         W2 = [[-0.01041081 -0.04463285 0.01758031 0.04747113]]
         b2 = [[ 0.00010457]]
```

```
[[-0.00643025 0.01936718] [-0.02410458
W1
        0.03978052] [-0.01653973 -0.02096177] [
                      0.01046864 -0.05990141]]
          [[-1.02420756e-06] [ 1.27373948e-05] [
b1
            8.32996807e-07] [ -3.20136836e-06]]
         [[-0.01041081 -0.04463285 0.01758031
W2
                                  0.04747113]]
                                 [[ 0.00010457]]
b2
```

4.4 - Integrate parts 4.1, 4.2 and 4.3 in nn_model()

Question: Build your neural network model in nn_model().

Instructions: The neural network model has to use the previous functions in the right order.

```
In [19]: # GRADED FUNCTION: nn model
         def nn model(X, Y, n h, num iterations = 10000, print cost=False):
             Arguments:
             X -- dataset of shape (2, number of examples)
             Y -- labels of shape (1, number of examples)
             n h -- size of the hidden layer
             num_iterations -- Number of iterations in gradient descent loop
             print_cost -- if True, print the cost every 1000 iterations
             Returns:
             parameters -- parameters learnt by the model. They can then be used to
             np.random.seed(3)
             n_x = layer_sizes(X, Y)[0]
             n_y = layer_sizes(X, Y)[2]
             # Initialize parameters
             ### START CODE HERE ### (≈ 1 line of code)
             parameters = None
             ### END CODE HERE ###
             # Loop (gradient descent)
             for i in range(0, num_iterations):
                 ### START CODE HERE ### (≈ 4 lines of code)
                 # Forward propagation. Inputs: "X, parameters". Outputs: "A2, cache
                 A2, cache = None
                 # Cost function. Inputs: "A2, Y, parameters". Outputs: "cost".
                 cost = None
                 # Backpropagation. Inputs: "parameters, cache, X, Y". Outputs: "grad
                 grads = None
                 # Gradient descent parameter update. Inputs: "parameters, grads". O
                 parameters = None
                 ### END CODE HERE ###
                 # Print the cost every 1000 iterations
                 if print_cost and i % 1000 == 0:
                     print ("Cost after iteration %i: %f" %(i, cost))
             return parameters
```

```
In [20]:
         X_assess, Y_assess = nn_model_test_case()
         parameters = nn model(X assess, Y assess, 4, num iterations=10000, print cos
         print("W1 = " + str(parameters["W1"]))
         print("b1 = " + str(parameters["b1"]))
         print("W2 = " + str(parameters["W2"]))
         print("b2 = " + str(parameters["b2"]))
         Cost after iteration 0: 0.692739
         Cost after iteration 1000: 0.000218
         Cost after iteration 2000: 0.000107
         Cost after iteration 3000: 0.000071
         Cost after iteration 4000: 0.000053
         Cost after iteration 5000: 0.000042
         Cost after iteration 6000: 0.000035
         Cost after iteration 7000: 0.000030
         Cost after iteration 8000: 0.000026
         Cost after iteration 9000: 0.000023
         W1 = [[-0.65848169 \ 1.21866811]]
          [-0.76204273 \quad 1.39377573]
          [0.5792005 -1.10397703]
          [0.76773391 - 1.41477129]]
         b1 = [[ 0.287592 ]
          [ 0.3511264 ]
          [-0.2431246]
          [-0.35772805]
         W2 = [[-2.45566237 -3.27042274 2.00784958 3.36773273]]
         b2 = [[0.20459656]]
```

0.692739	cost after iteration 0
\$\vdots\$	\$\vdots\$
[[-0.65848169 1.21866811] [-0.76204273 1.39377573] [0.5792005 -1.10397703] [0.76773391 -1.41477129]]	W1
[[0.287592] [0.3511264] [-0.2431246] [-0.35772805]]	b1
[[-2.45566237 -3.27042274 2.00784958 3.36773273]]	W2
[[0.20459656]]	h2

4.5 Predictions

Question: Use your model to predict by building predict(). Use forward propagation to predict results.

Reminder: predictions = \$y_{prediction} = \mathbb 1 \text{{activation > 0.5}} = \begin{cases} 1 & \text{if}\ activation > 0.5 \\ 0 & \text{otherwise} \end{cases}\$

As an example, if you would like to set the entries of a matrix X to 0 and 1 based on a threshold you

```
\frac{\text{would do: } X_{\text{new}} = (X > \text{threshold})}{\text{Typesetting math: } 100\%}
```

```
In [21]: # GRADED FUNCTION: predict
         def predict(parameters, X):
             Using the learned parameters, predicts a class for each example in X
             Arguments:
             parameters -- python dictionary containing your parameters
             X -- input data of size (n_x, m)
             Returns
             predictions -- vector of predictions of our model (red: 0 / blue: 1)
             # Computes probabilities using forward propagation, and classifies to 0
             ### START CODE HERE ### (≈ 2 lines of code)
             A2, cache = None
             predictions = None
             ### END CODE HERE ###
             return predictions
```

```
In [22]:
         parameters, X_assess = predict_test_case()
         predictions = predict(parameters, X_assess)
         print("predictions mean = " + str(np.mean(predictions)))
```

predictions mean = 0.666666666667

Expected Output:

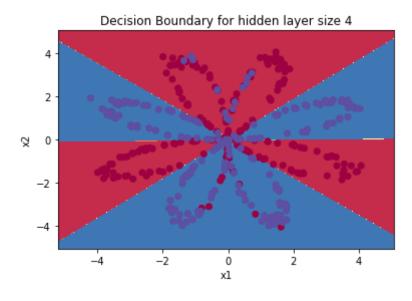
0.66666666667 predictions mean

It is time to run the model and see how it performs on a planar dataset. Run the following code to test your model with a single hidden layer of \$n_h\$ hidden units.

```
In [23]:
         # Build a model with a n h-dimensional hidden layer
         parameters = nn_model(X, Y, n_h = 4, num_iterations = 10000, print_cost=True
         # Plot the decision boundary
         plot_decision_boundary(lambda x: predict(parameters, x.T), X, Y)
         plt.title("Decision Boundary for hidden layer size " + str(4))
```

```
Cost after iteration 0: 0.693048
Cost after iteration 1000: 0.288083
Cost after iteration 2000: 0.254385
Cost after iteration 3000: 0.233864
Cost after iteration 4000: 0.226792
Cost after iteration 5000: 0.222644
Cost after iteration 6000: 0.219731
Cost after iteration 7000: 0.217504
Cost after iteration 8000: 0.219471
Cost after iteration 9000: 0.218612
```

Out[23]: <matplotlib.text.Text at 0x7f6109aee470>



Cost after iteration 0.218607 9000

```
In [24]: # Print accuracy
          predictions = predict(parameters, X)
          print ('Accuracy: %d' % float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))
```

Accuracy: 90%

Expected Output:

Accuracy 90%

Accuracy is really high compared to Logistic Regression. The model has learnt the leaf patterns of Typesetting math the flower! Neural networks are able to learn even highly non-linear decision boundaries, unlike

logistic regression.

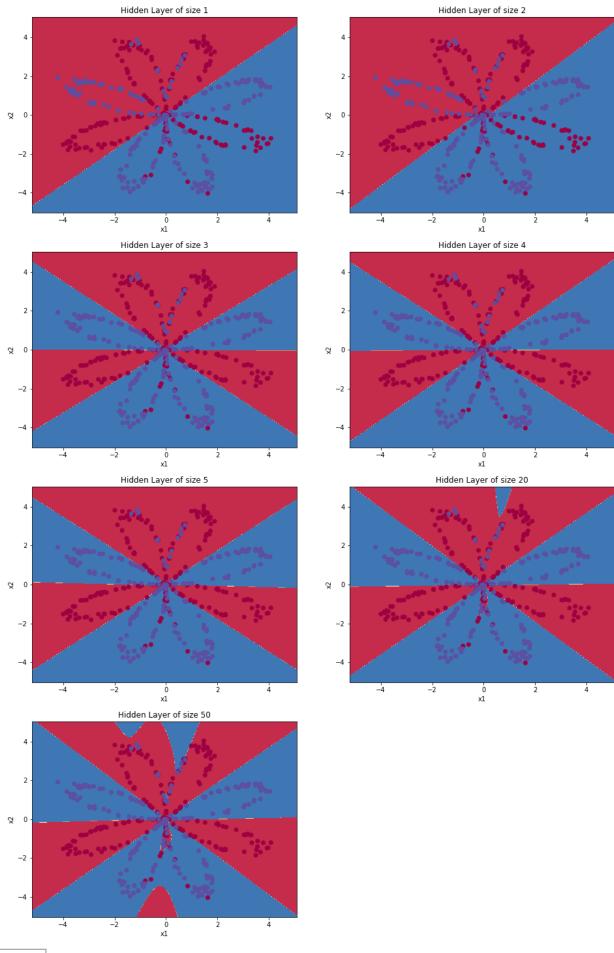
Now, let's try out several hidden layer sizes.

4.6 - Tuning hidden layer size (optional/ungraded exercise)

Run the following code. It may take 1-2 minutes. You will observe different behaviors of the model for various hidden layer sizes.

```
In [25]: # This may take about 2 minutes to run
         plt.figure(figsize=(16, 32))
         hidden_layer_sizes = [1, 2, 3, 4, 5, 20, 50]
         for i, n_h in enumerate(hidden_layer_sizes):
             plt.subplot(5, 2, i+1)
             plt.title('Hidden Layer of size %d' % n_h)
             parameters = nn model(X, Y, n h, num iterations = 5000)
             plot_decision_boundary(lambda x: predict(parameters, x.T), X, Y)
             predictions = predict(parameters, X)
             accuracy = float((np.dot(Y,predictions.T) + np.dot(1-Y,1-predictions.T))
             print ("Accuracy for {} hidden units: {} %".format(n_h, accuracy))
```

```
Accuracy for 1 hidden units: 67.5 %
Accuracy for 2 hidden units: 67.25 %
Accuracy for 3 hidden units: 90.75 %
Accuracy for 4 hidden units: 90.5 %
Accuracy for 5 hidden units: 91.25 %
Accuracy for 20 hidden units: 90.0 %
Accuracy for 50 hidden units: 90.25 %
```



Interpretation:

- The larger models (with more hidden units) are able to fit the training set better, until eventually the largest models overfit the data.
- The best hidden layer size seems to be around n_h = 5. Indeed, a value around here seems to fits the data well without also incurring noticeable overfitting.
- You will also learn later about regularization, which lets you use very large models (such as n_h = 50) without much overfitting.

Optional questions:

Note: Remember to submit the assignment by clicking the blue "Submit Assignment" button at the upper-right.

Some optional/ungraded questions that you can explore if you wish:

- What happens when you change the tanh activation for a sigmoid activation or a ReLU activation?
- Play with the learning_rate. What happens?
- What if we change the dataset? (See part 5 below!)

You've learnt to:

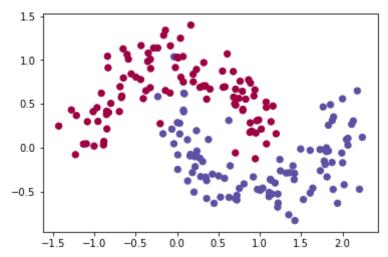
- · Build a complete neural network with a hidden layer
- · Make a good use of a non-linear unit
- Implemented forward propagation and backpropagation, and trained a neural network
- See the impact of varying the hidden layer size, including overfitting.

Nice work!

5) Performance on other datasets

If you want, you can rerun the whole notebook (minus the dataset part) for each of the following datasets.

```
In [26]:
         # Datasets
         noisy circles, noisy moons, blobs, gaussian quantiles, no structure = load
         datasets = {"noisy_circles": noisy_circles,
                      "noisy_moons": noisy_moons,
                      "blobs": blobs,
                      "gaussian quantiles": gaussian quantiles}
         ### START CODE HERE ### (choose your dataset)
         dataset = "noisy_moons"
         ### END CODE HERE ###
         X, Y = datasets[dataset]
         X, Y = X.T, Y.reshape(1, Y.shape[0])
         # make blobs binary
         if dataset == "blobs":
             Y = Y%2
         # Visualize the data
         plt.scatter(X[0, :], X[1, :], c=Y, s=40, cmap=plt.cm.Spectral);
```



Congrats on finishing this Programming Assignment!

Reference:

- http://scs.ryerson.ca/~aharley/neural-networks/_(http://scs.ryerson.ca/~aharley/neuralnetworks/)
- http://cs231n.github.io/neural-networks-case-study/ (http://cs231n.github.io/neural-networkscase-study/)