

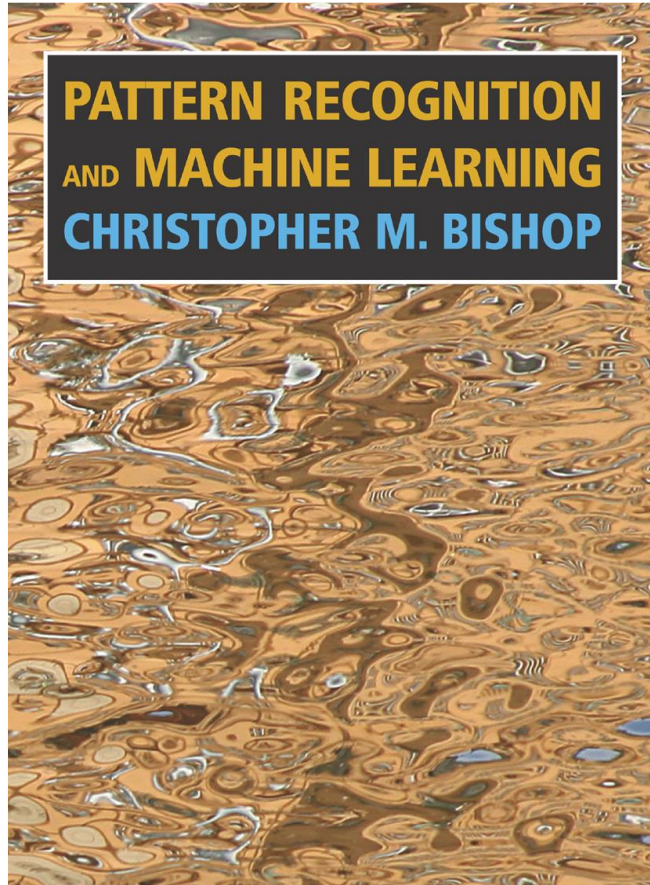
# Probabilistic Model Selection in Regression

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# Reference

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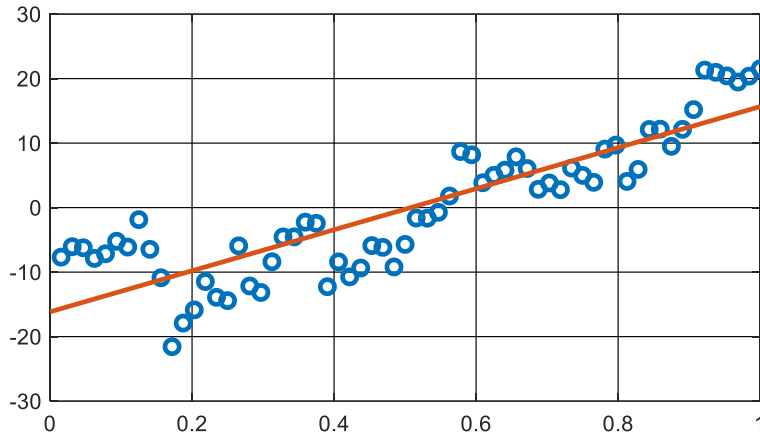
Today's class *roughly* follows Chapter 3.4-3.52.

Pattern Recognition and  
Machine Learning

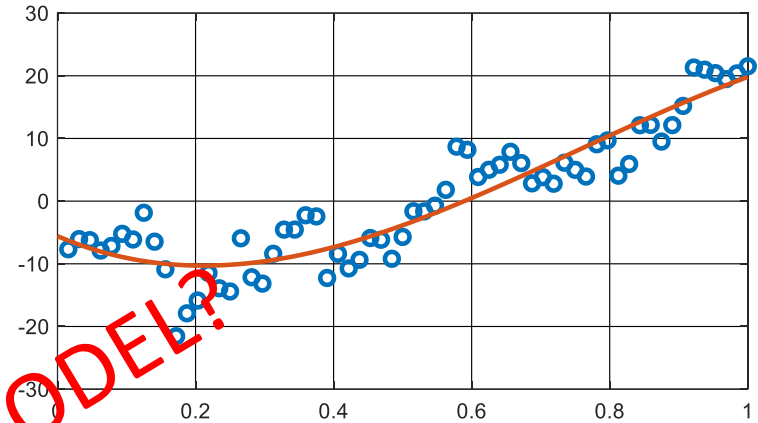
Christopher Bishop, 2006

# Apple Stock Price Jul – Sep

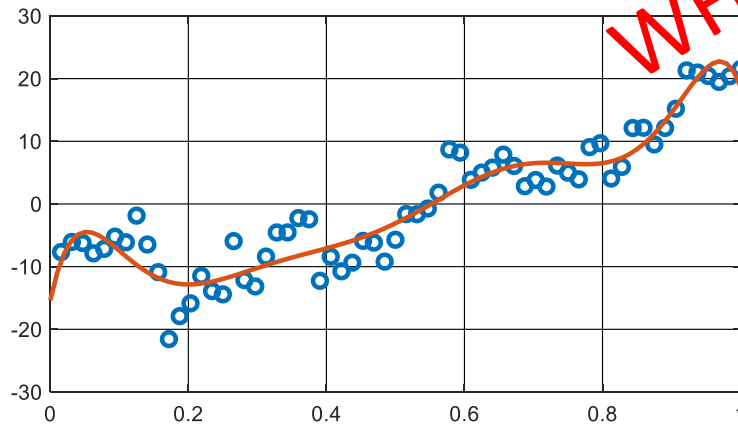
Linear Model



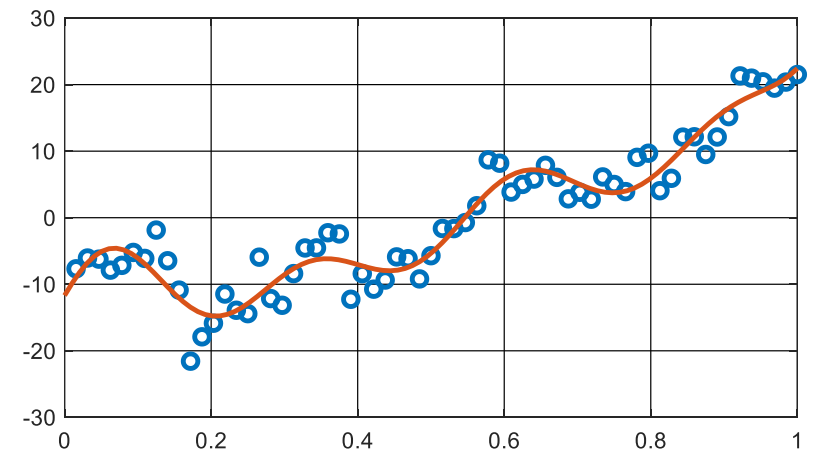
Polynomial



Trigonometric



RBF basis



WHICH MODEL?

# Frequentist Model Selection

- We want to minimize the expected (squared) error:
- $\mathbb{E}_D \left[ \sum_{i \in D_1} [y_i - f(\mathbf{x}_i; \mathbf{w})]^2 | \mathbf{x}_i \right]$ , expectation over the testing error.
- $\mathbb{E}_D [ [y_i - f(\mathbf{x}_i; \mathbf{w})]^2 | \mathbf{x}_i ]$  is **minimized**
  - when **bias** and **variance** is balanced
- This cannot be done in practice as,  $\mathbb{E}_D [ [y_i - f(\mathbf{x}_i; \mathbf{w})]^2 | \mathbf{x}_i ]$  cannot be calculated.
  - We do not know  $g$  and  $\epsilon$ .
- Use out sample error (can be approximated):
  - $\mathbb{E}_{\mathbf{x}} \left[ \mathbb{E}_D [ [y - f(\mathbf{x}_i; \mathbf{w})]^2 | \mathbf{x} ] \right] \approx \frac{1}{K} \sum_{k=1 \dots K} \frac{1}{n'} \sum_{(\mathbf{y}, \mathbf{x}) \in D_1^{(k)}} \left( y - f_{\text{LS}}^{(k)}(\mathbf{x}) \right)^2$

# Frequentist Model Selection

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- There are issues regarding this model selection approach.
- This frequentist approach requires us to hold out sample during training.
  - We lose information in part of our dataset.
  - CV helps, but **calculation is heavy**.
  - Our dataset **may not be IID**.
- How would we select a model if we adopt a probabilistic view?

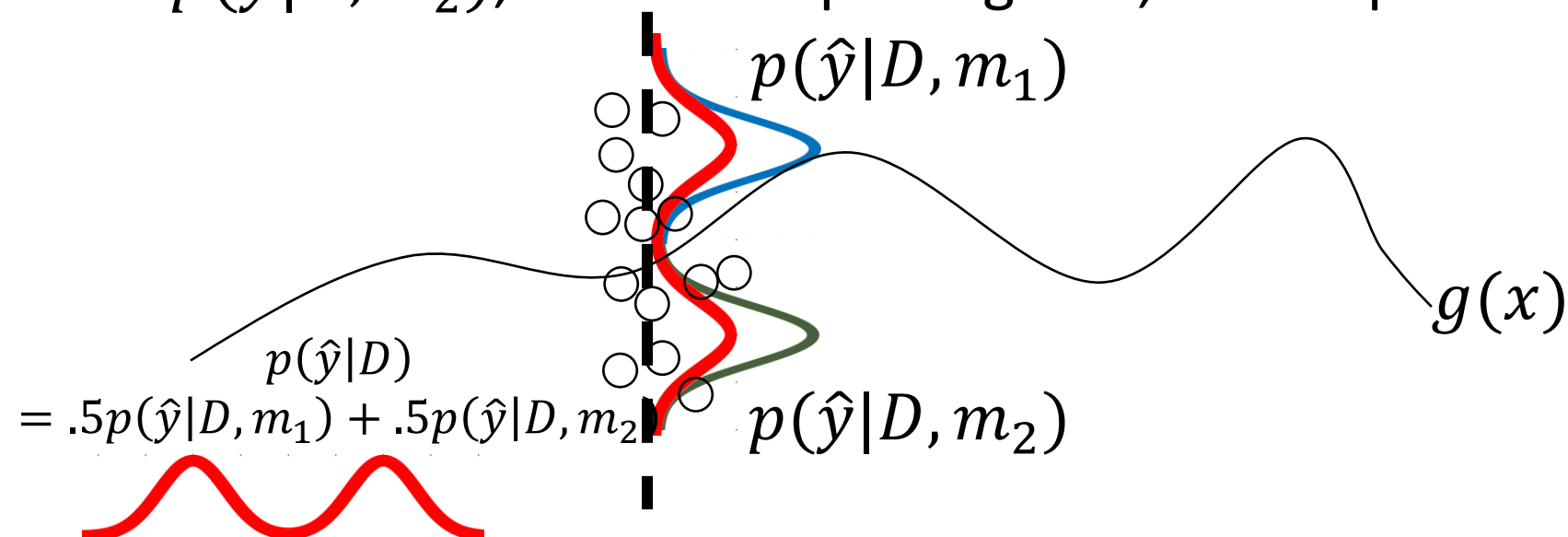
# Probabilistic Model “Selection”

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- Build uncertainty of models using **priors over models**:
- Let  $m \in \{m_1 \dots m_K\}$ ,
- If we choose  $p(m)$  as a model prior.
- Then we can write **posterior of** model using Bayes rule:
- $p(m|D) \propto p(D|m)p(m)$
- This express the preference over models given  $D$ .
- How do we choose a model for prediction?

# Probabilistic Model Average

- Bayesians never choose, they marginalize:
- $p(\hat{y}|D) = \sum_{m \in \{\dots\}} p(\hat{y}|D, m) p(m|D)$ 
  - a weighted sum
  - If  $p(\hat{y}|D, m_1)$  gives a different prediction than  $p(\hat{y}|D, m_2)$ , instead of picking one, we keep both.



# Probabilistic Model Average

- $p(\hat{y}|D) = \sum_{m \in \{\dots\}} p(\hat{y}|D, m)p(m|D)$ 
  - Probabilistic model sel.: Using all probable models given by  $p(m|D)$  to approx.  $p(\hat{y}|D)$ .
- In comparison with frequentist model sel.  
$$\hat{m} = \operatorname{argmin}_m \sum_{i=1..n} \mathbb{E}_D \left[ [y - f(\mathbf{x}_i; \mathbf{w}, m)]^2 | \mathbf{x}_i \right]$$
- We can see:
- Frequentist minimizes, Bayesian marginalizes.



# Probabilistic Model Selection

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- $p(\hat{y}|D) = \sum_{m \in \{\dots\}} p(\hat{y}|D, m)p(m|D)$
- How can you calculate  $p(m|D)$ ?

$$p(m|D) \propto \underbrace{p(D|m)}_{\text{model evidence}} \underbrace{p(m)}_{\text{prior}}$$

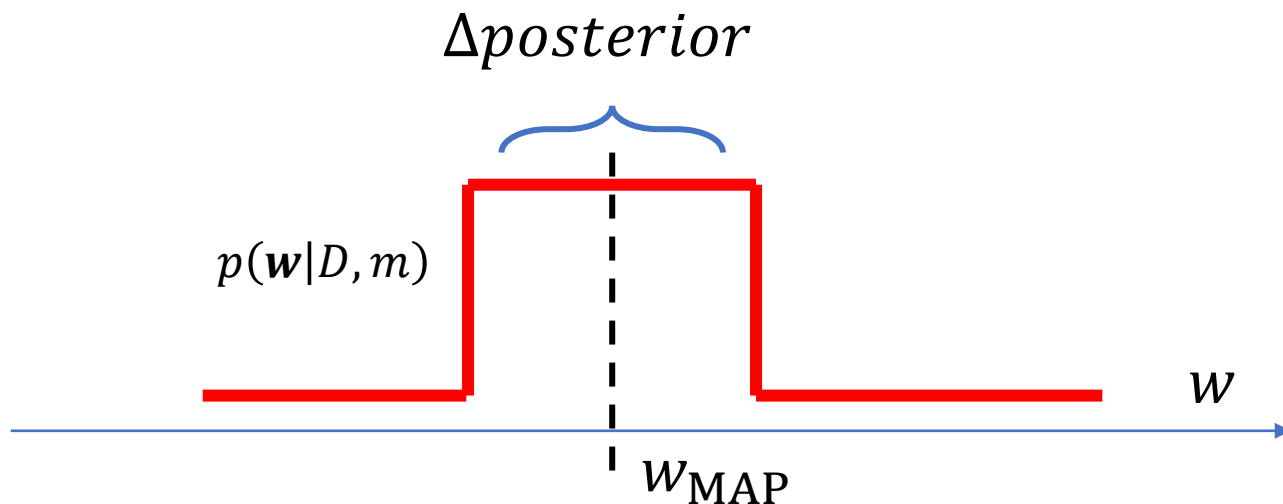
# Model Evidence

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- Suppose your model  $m$  is governed a set of parameters  $\mathbf{w}$
- Then  $p(D|m) = \int p(D|\mathbf{w}, m)p(\mathbf{w}|m)d\mathbf{w}$
- **Note:** model evidence is the normalizer of para. posterior
- $p(\mathbf{w}|D, m) = \frac{p(D|\mathbf{w}, m)p(\mathbf{w}|m)}{p(D|m)}$

# Model Evidence Approximation

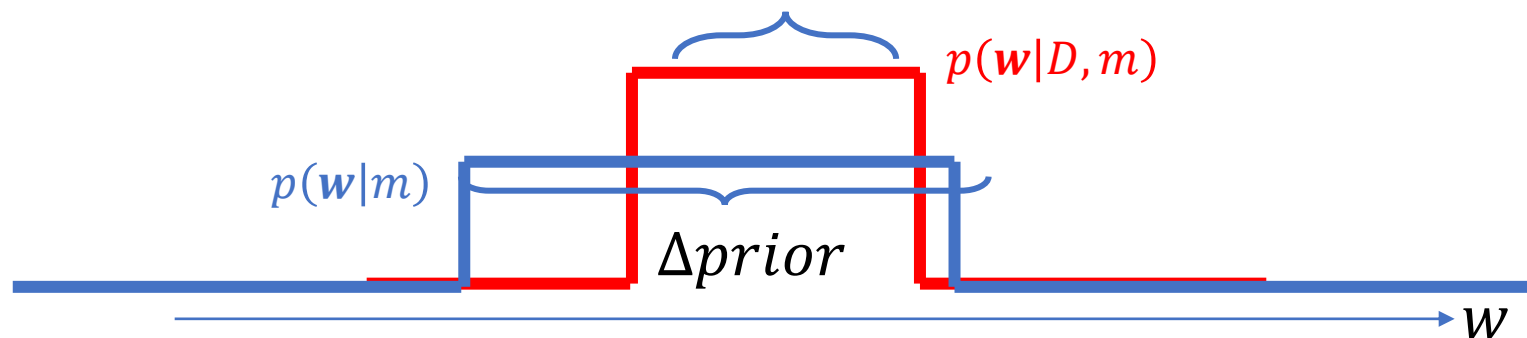
- Let us consider the simplest approximation of
- $p(D|m) = \int p(D|\mathbf{w}, m)p(\mathbf{w}|m)d\mathbf{w}$
- Note:  $p(\mathbf{w}|D, m) \propto p(D|\mathbf{w}, m)p(\mathbf{w}|m)$
- Suppose  $p(\mathbf{w}|D, m)$  plateaus at  $w_{\text{MAP}}$



# Model Evidence Approximation

- Then  $\int p(D|\mathbf{w}, m)p(\mathbf{w}|m)d\mathbf{w}$   
 $\approx p(D|\mathbf{w}_{\text{MAP}}, m)p(\mathbf{w}_{\text{MAP}}|m) \cdot \Delta\text{posterior}$
- as  $\int f(x)dx \approx f(x_0) \cdot \Delta x$ , if  $f$  can be approx. by a step function with “length”  $\Delta x$  peaks at  $x_0$
- If  $p(\mathbf{w}|m)$  is flat as well, then  $p(\mathbf{w}|m) = \frac{1}{\Delta\text{prior}}$

$$p(D|m) \approx p(D|\mathbf{w}_{\text{MAP}}, m) \frac{\Delta\text{posterior}}{\Delta\text{prior}}$$



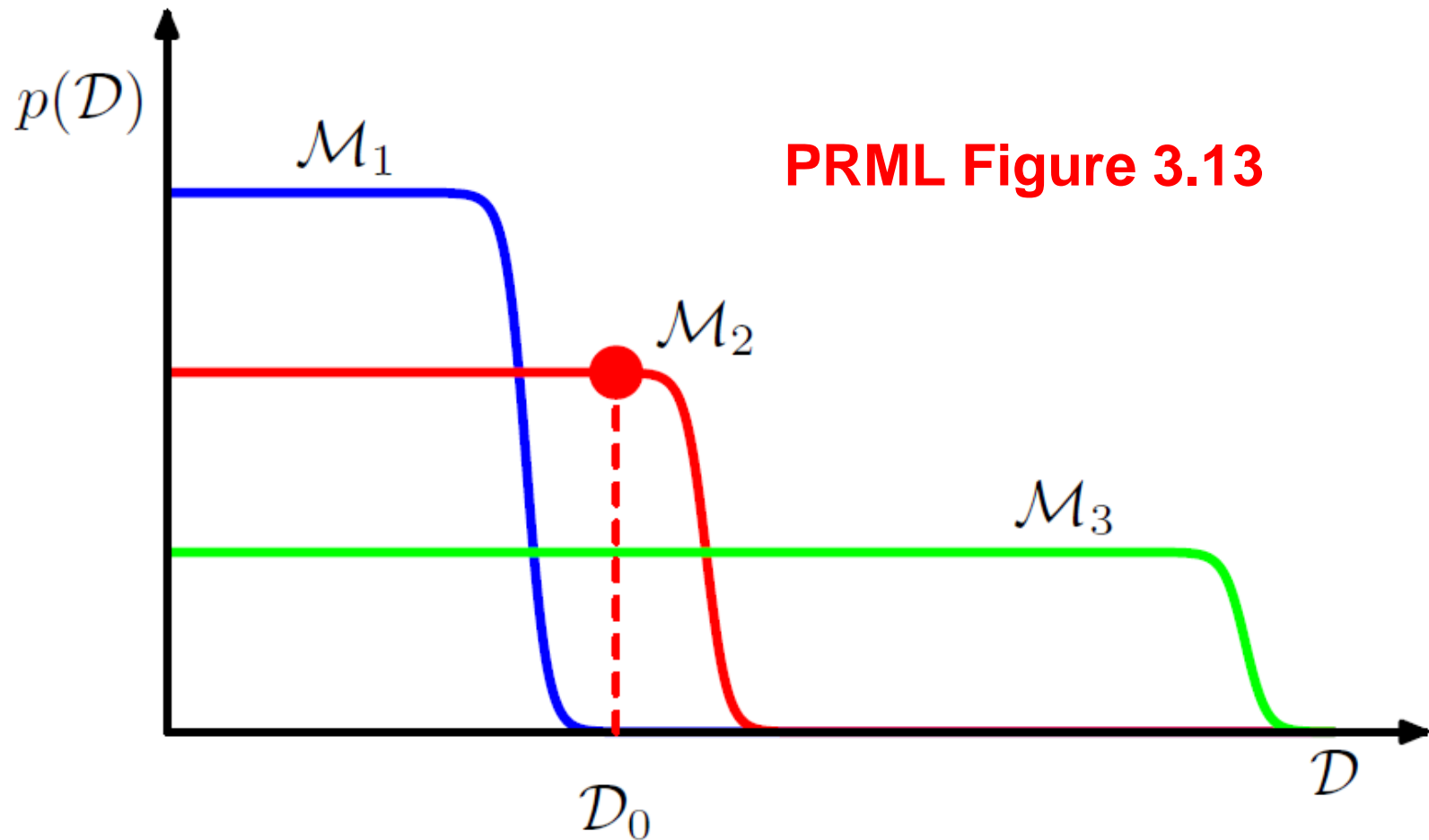
# Model Evidence Approximation

- $\log p(D|m) \approx \log p(D|w_{\text{MAP}}, m) + \log \frac{\Delta_{\text{posterior}}}{\Delta_{\text{prior}}}$
- As posterior is almost always sharper than prior,  $\frac{\Delta_{\text{posterior}}}{\Delta_{\text{prior}}} < 1$ .
- The second term is always negative. In fact, **the sharper** our posterior is, **more negative** it is.
- Trade-off is made between  $\log p(D|w_{\text{MAP}}, m)$  and  $\log \frac{\Delta_{\text{posterior}}}{\Delta_{\text{prior}}}$

# Model Evidence Approximation

- Now, analyze a model with  $b$  parameters:
- Assuming  $\frac{\Delta_{\text{posterior}}}{\Delta_{\text{prior}}}$  is the same for all  $w_i$  and  $w_i$  are independent
- $\log p(D|m) \approx \log p(D|w_{\text{MAP}}, m) + b \log \frac{\Delta_{\text{posterior}}}{\Delta_{\text{prior}}}$
- Why? Prove this.
- If too many parameters in a model,  $b \log \frac{\Delta_{\text{posterior}}}{\Delta_{\text{prior}}}$  decreases!
  - $\log p(D|w_{\text{MAP}}, m)$  increases (why?).
- Model evidence prefers intermediate model complexity.

# Model Evidence Prefers Intermediate Model Complexity



# Tuning Hyper Parameters

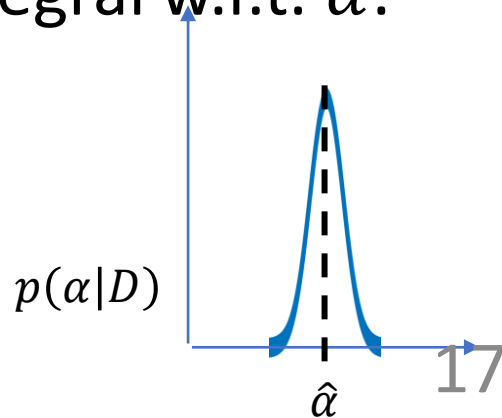
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- In most cases, we select a model by selecting a hyper parameter, such as regularization parameter, the degree of the polynomial transform, etc.
- Can probabilistic model selection help us determine a hyper parameter?



# Tuning Hyper Parameters

- We would like to calculate the predictive distribution:
- $$p(\hat{y}|D) = \int p(\hat{y}|D, \alpha) p(\alpha|D) d\alpha$$
$$= \int \int p(\hat{y}|\mathbf{w}, \alpha) p(\mathbf{w}|D, \alpha) p(\alpha|D) d\mathbf{w} d\alpha$$
- However, integral w.r.t.  $\alpha$  may not be easy (“intractable”).
- If  $p(\alpha|D)$  is super “pointy” at  $\hat{\alpha}$ , we only need to use one function evaluation to approximate the integral w.r.t.  $\alpha$ .
- $$\int \int p(\hat{y}|\mathbf{w}, \alpha) p(\mathbf{w}|D, \alpha) p(\alpha|D) d\mathbf{w} d\alpha \approx \int p(\hat{y}|\mathbf{w}, \hat{\alpha}) p(\mathbf{w}|D, \hat{\alpha}) d\mathbf{w}$$



# Model Evidence Approximation with Hyper Parameters

- To find  $\hat{\alpha}$  at the peak, we need to maximize  $p(\alpha|D)$
- $p(\alpha|D) \propto \underbrace{p(D|\alpha)p(\alpha)}_{\text{Model Evidence!}} = p(\alpha) \int p(D|\mathbf{w}, \alpha)p(\mathbf{w}|\alpha)d\mathbf{w}$

Model Evidence!

- If  $p(\alpha)$  is relatively flat, we just
- $\hat{\alpha} := \underset{\alpha}{\operatorname{argmax}} \int p(D|\mathbf{w}, \alpha)p(\mathbf{w}|\alpha)d\mathbf{w}$

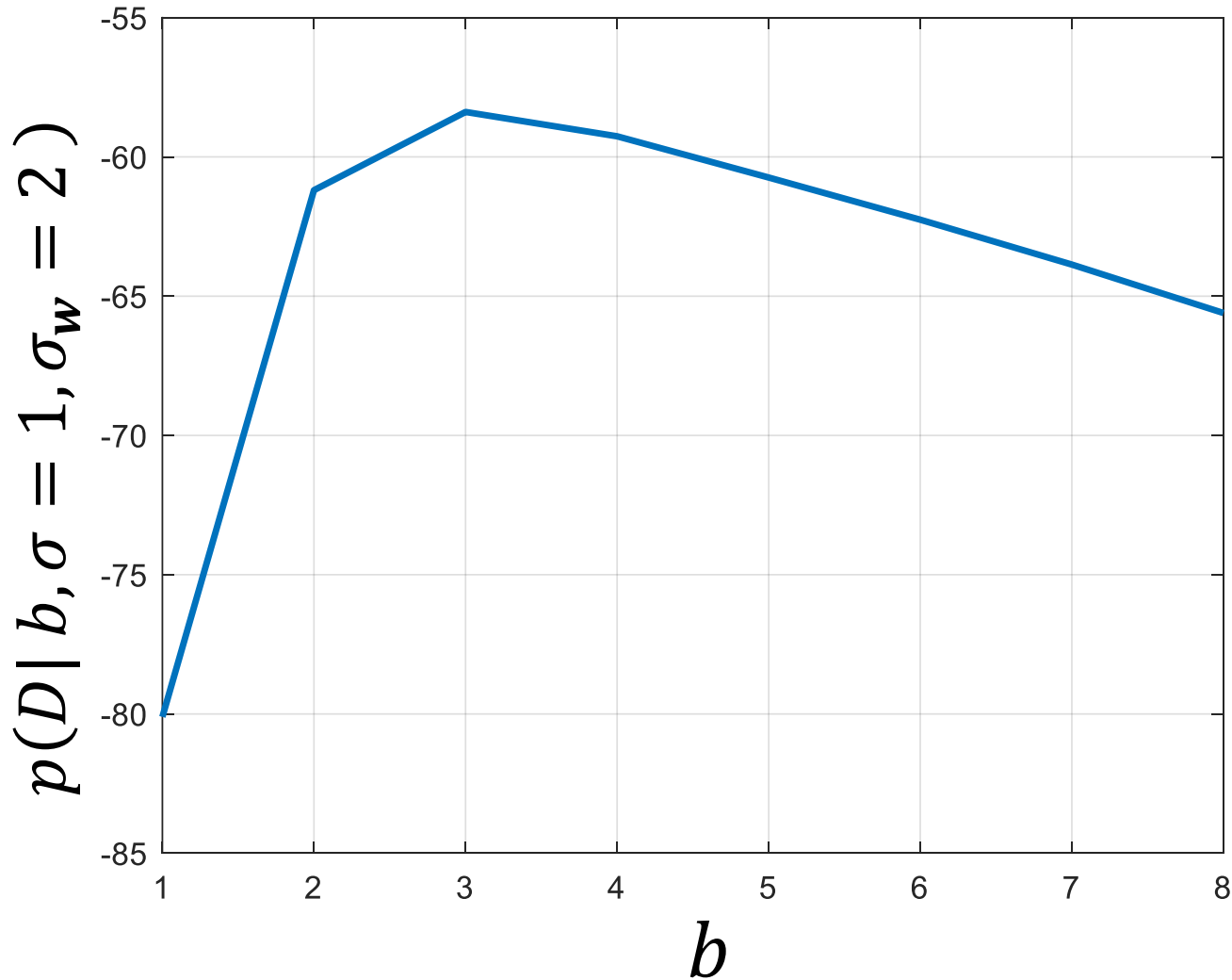
- “Marginalized Likelihood Maximization”
- Or “Evidence Approximation”

# Example: Linear Regression

- Suppose we have a likelihood model:
- $p(\mathbf{y}_1 \dots \mathbf{y}_n | \mathbf{x}_1 \dots \mathbf{x}_n; \mathbf{w}, b) := \prod_{i \in D} N_{y_i}(\langle \mathbf{w}, \boldsymbol{\phi}_b(\mathbf{x}_i) \rangle, \sigma^2 \mathbf{I})$
- $p(\mathbf{w}; \sigma_w, b) := N_{\mathbf{w}}(\mathbf{0}, \sigma_w^2 \mathbf{I}_b)$
- Marginalized Likelihood
- $p(\mathbf{y}_1 \dots \mathbf{y}_n | \mathbf{x}_1 \dots \mathbf{x}_n; b, \sigma, \sigma_w)$   
 $= \int p(\mathbf{y}_1 \dots \mathbf{y}_n | \mathbf{x}_1 \dots \mathbf{x}_n; \mathbf{w}, b, \sigma, \sigma_w) p(\mathbf{w}) d\mathbf{w}$   
 $= N_{\mathbf{y}}(\mathbf{0}, \sigma_w^2 \boldsymbol{\Phi}^\top \boldsymbol{\Phi} + \sigma^2 \mathbf{I})$

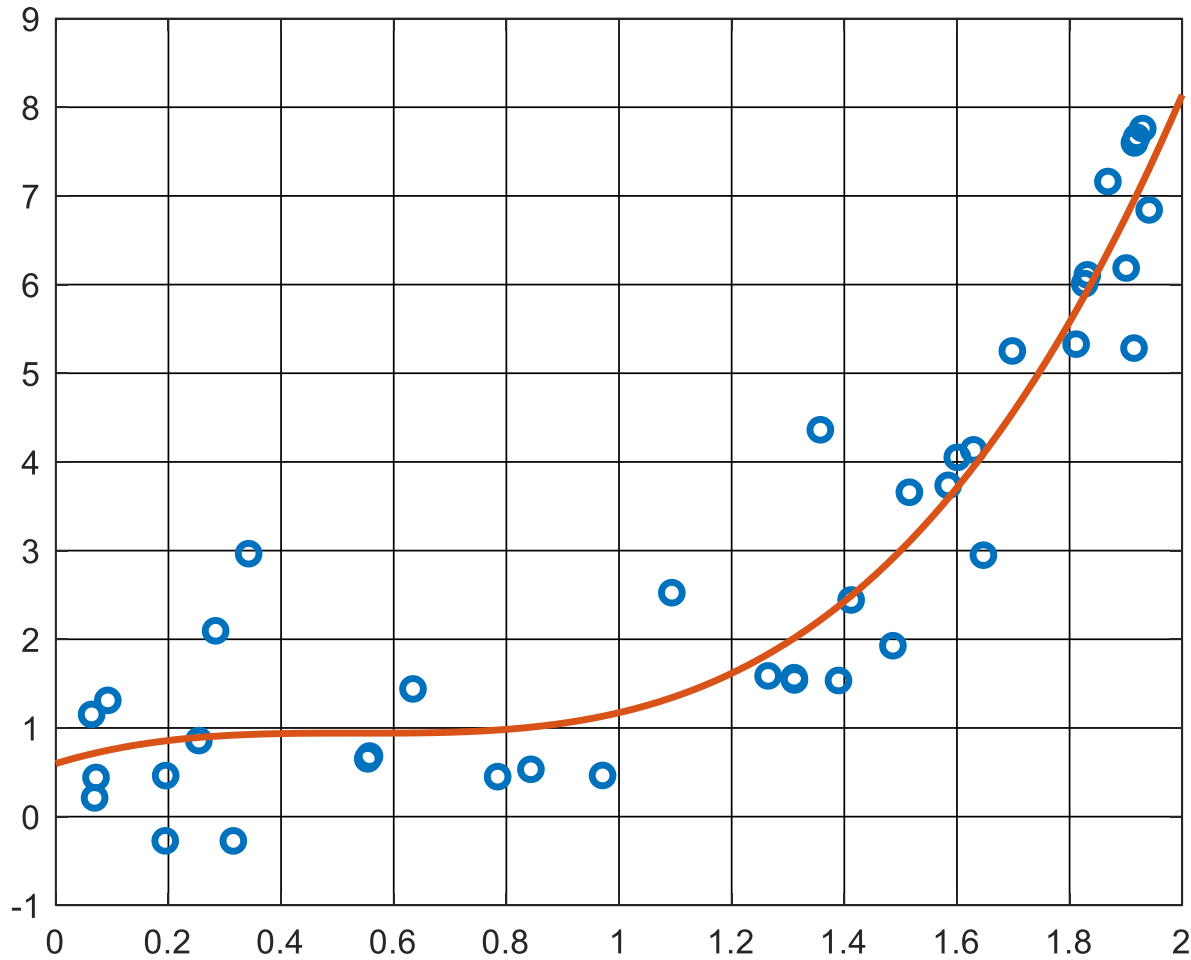
hint: use Gaussian identity!

# Example: Linear Regression



# Example: Linear Regression

$$f(x; w_{LS}), b = 3$$



# Conclusion

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- We introduced probabilistic model selection.
- The principle: Integrate over models w.r.t. model posterior.
- $p(m|D) \propto p(D|m)p(m)$
- Approximation using flat posterior and prior of  $\mathbf{w}$ .
  - The log ratio term decreases as  $b$  increase.
- Approximation using marginalized likelihood.
  - Allows us to select hyper-parameters

# Homework

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- Prove statement on page 14.
- Prove statement on page 19.
- Read PRML 3.52

# Computing Lab

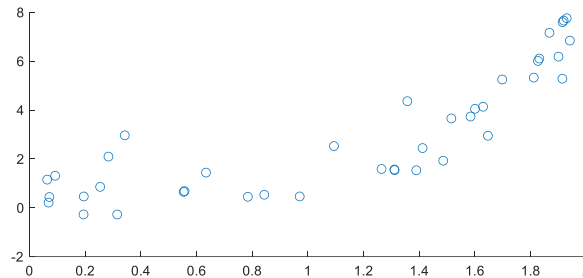
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- Implementing least square regression with different choices of kernels:
  - Linear kernel,
  - Polynomial kernel,
  - RBF kernel.
- 
- Apply it on prostate cancer dataset. What choice of kernel/kernel parameters minimizes the CV error?



# Computing Lab

- Generate,  $x \sim U(0,2)$ ,  $y = \exp(1.5x-1) + \epsilon$ ,  $\epsilon \sim N(0,1)$ ,



- Select number of basis using marginalized likelihood for different basis:
- Polynomial basis
- Trigonometric basis
- RBF basis

(Fix  $\sigma$  and  $\sigma_w$ )