

Capturing Dependency of Data using Graphical Models

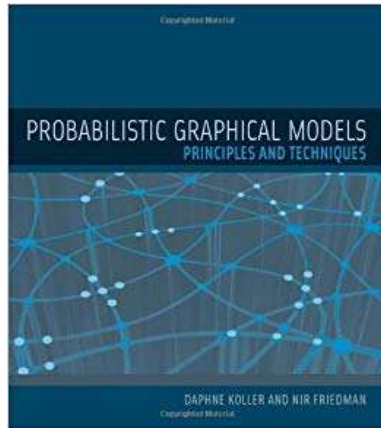
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Objectives

- Understand **equivalence** of **conditional independence of R.Vs** and **factorizations** of their probability distribution over a graph.
- Simple **undirected graphical models**:
 - Gaussian Markov Network
 - Logistic Model

References



- Today's class roughly follows Chapter 2.14 and Chapter 4 in Probabilistic Graphical Models by Koller and Friedman.

Dependency in Dataset: A Unit Score Example

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Example: Scores of Units

- Imagine a table of unit scores.

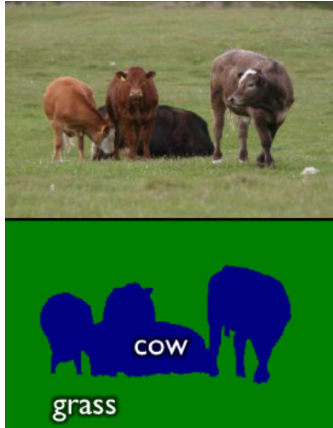
Name	SM1	Math	Python	Mach. Learn.
Song	80	70	50	60
Harry	50	40	70	80
Ron	50	50	...	45
Hermione	90	100	...	100
...

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Dependency of R.V.s and Probabilistic Models

- How do you construct a good $p(D|\theta)$ as the likelihood of this dataset?
- Scores of units are **dependent!**
 - Student with **high** Math, Python score is likely to receive **high** SM1 score.
 - Student with **high** SM1 score is likely to receive a **high** Mach. Learn. score.

Example: Pixel Correlation



- The likelihood of one pixel being “Cow” is dependent with labels of **adjacent pixels**.

Jamie Shotton et. al. IJCV 2009

How the dependencies between
R.V.s would affect likelihood
modelling?

Problem Formulation

- Given a dataset $\{\mathbf{x}_i\}_{i=1}^n$,
 - $\mathbf{x}_i = [x_i^{(1)}, x_i^{(2)} \dots x_i^{(d)}] \in R^d$
 - \mathbf{x}_i is a vector of a student i 's scores.
 - e.g., $x^{(1)}$ is SM1, $x^{(2)}$ is Math...
- **What does $p(x^{(1)}, x^{(2)} \dots x^{(d)})$ look like?**

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Note, here we do not distinguish the lower case x , an assignment of a random variable, and upper case X , a random variable.

Dependency and Likelihood

- If we assume $x_1 \dots x_n$ are IID.
- Likelihood factorizes into product over each x_i
 - $p(x_1, x_2, \dots x_n | \theta) = \prod_{i=1}^n p(x_i | \theta)$
- Maximum Likelihood Estimation
 - $\max_{\theta} \prod_{i=1}^n p(x_i | \theta)$
 - **First Lecture!**

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We can do the factorization of the likelihood function because of the independence of X_i !!!

Dependency and Likelihood

- IIDness is an extremely simple assumption.
- What about complicated dependencies?
 - How do we factorize our likelihood?
- To solve this problem, we **first** need to convert our dependences into a graphical representation, **then** use the graph to guide our factorization.
- Study of factorization of prob. distributions and dependencies of R.V.s is called **graphical modelling**.

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Review: Independence and Conditional Independence

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Independence of R.V.s

- Let's look at how independence between R.V.s are **expressed in probability distribution**:
- R.V. X is **independent** of Y :
 - $X \perp Y$
 - $\Leftrightarrow p(X, Y) = p(X)p(Y)$
 - Factorization
 - $\Leftrightarrow p(X|Y) = p(X) \Leftrightarrow p(Y|X) = p(Y)$
 - No Information exchange between X and Y .

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Notice the independence can be expressed via factorization and information flow.

Conditional Independence of R.V.s

- R.V. X is independent of Y **given** Z
 - $X \perp Y|Z$
 - $\Leftrightarrow p(X, Y|Z) = p(X|Z)p(Y|Z)$
 - $\Leftrightarrow p(X, Y, Z) \propto g_1(X, Z) \cdot g_2(Y, Z)$
 - Factorization
 - $\Leftrightarrow p(X|Y, Z) = p(X|Z)$
 - Y does not give any additional info which changes the prob. of X given Z .
 - No **direct** information exchange between X and Y
 - $\Leftrightarrow p(Y|X, Z) = p(Y|Z)$

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Z is called conditioning random variable.

What are g_1 and g_2 ? They are just two functions, does not have to be probability, does not have to be in any specific form. **Their existence guarantees** the conditional independence.

g function is called factor

(Conditional) Independence and Information Exchange

- (Conditional) Independ. tells how information **exchange** between R.V.s
 - $X \perp Y \Leftrightarrow$ no information exchanges in-between X and Y .
 - $X \perp Y|Z \Leftrightarrow$ no **direct** information exchanges between X and Y



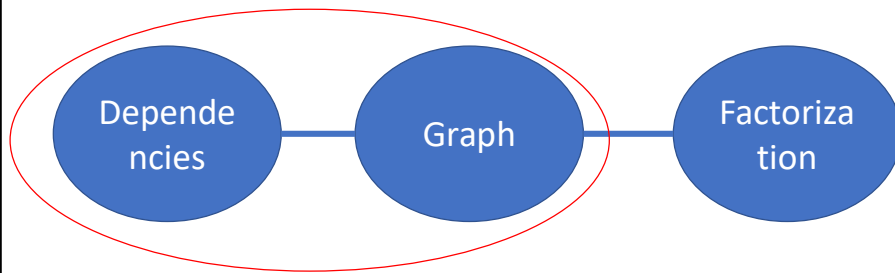
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The analogy is like relationship between people.

X and Y are independent: they do not talk to each other.

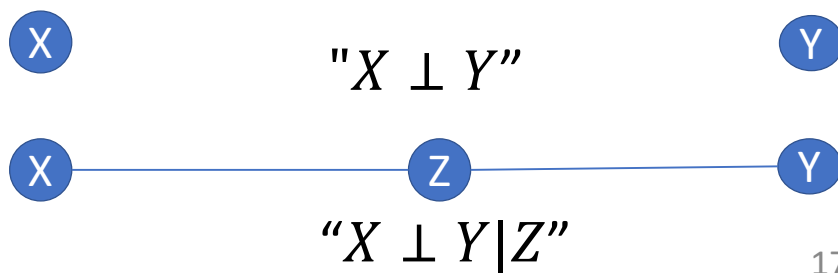
X and Y are conditional independent, they talk to each other via a middle man.

Creating a Graph of Independence



Representing (Conditional) Independence by Graph

- Given many R.Vs, listing all (cond.) independence can be cumbersome.
- A **graphical representation** is helpful:



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Because in many machine learning tasks, (conditional) independence are **valuable prior knowledge**, you may want to specify (conditional) independence of R.Vs in your dataset.

Imagining listing all the (conditional) independence in a very long document...

Representing Conditional Independence by Graph

- Given a graph $G = \langle E, V \rangle$,
 - V contains all the R.V.
- Given three subsets of R.V.: $X, Y, Z \subseteq V$
 - if X and Y are completely “**blocked**” in the graph by Z , we say $X \perp Y | Z$ is represented by G .

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Blocked, means there is no path linking X and Y

Example: Encoding (cond.) indep. by graph

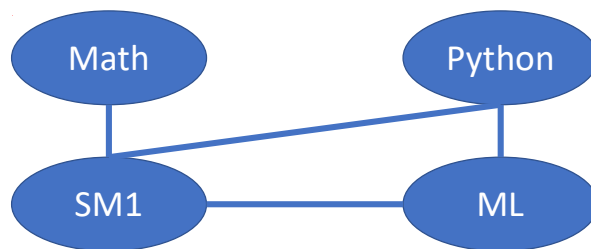
$\text{Math} \perp \text{ML} \mid \text{SM1}$

$\text{Math} \perp \text{Python} \mid \text{SM1}$

$\text{Math} \perp \text{ML} \mid \text{SM1}, \text{Python}$

$\text{Math} \perp \text{Python}, \text{ML} \mid \text{SM1}$

$\text{Math} \perp \text{Python} \mid \text{SM1}, \text{ML}$

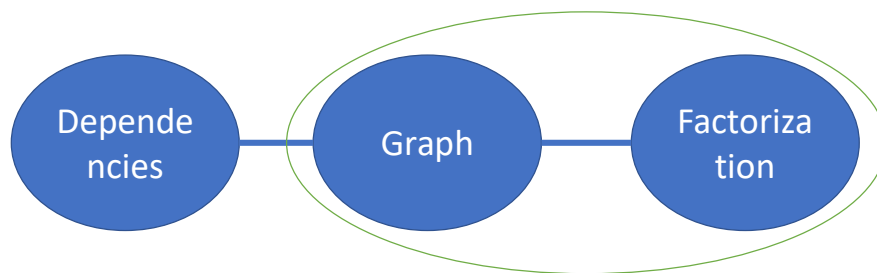


List of
conditional
independen
ce encoded
by Graph!

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Graph is a powerful tool to encode/visualize (conditional) independence.

Graph and Factorization



Factorization and Graph



- Factorizing a probability dist. greatly reduces complexity of modelling and computation of a probability dist.
- Think about that Maximum Likelihood under IID assumption!



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The motivation of factorizing a probability dist.

Representing Prob. Distribution Factorization by Graph

- Writing the factorization of a probability distribution of many factors can be cumbersome.
- Can we also use graph to help??

 " $P(X, Y)$ " = $P(X)$ $P(Y)$ 


" $P(X, Y, Z) \propto g_1(X, Z)g_2(Y, Z)$ " 

Representing Prob. Distribution Factorization by Graph

- Given a graph $G = \langle E, V \rangle$,
- We say $p(X)$ factorizes over G :
- If $p(X) \propto \prod_{c \in C} g_c(X^{(c)})$
 - where C is set of all **cliques** in G .
 - Clique: fully connected subgraph.
 - g_c is a function defined on $X^{(c)}$, which is the subset of X **restricted on c** .

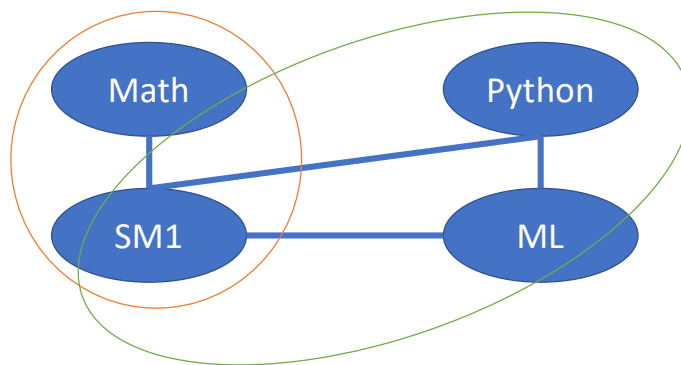
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Like what we saw before, g_c is a function that can be in any form.

g is called “factor”

Example

$$p(Ma, SM1, Py, ML) \\ \propto g_1(Ma, SM1) \cdot g_2(Py, ML, SM1).$$



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Equivalency between Factorization and Conditional Independence over G

- Using graph represent a factorization of a probability distribution
- Using graph represent a list of conditional independence
- Remarkably, these two seemingly irrelevant notions are **equivalent!**

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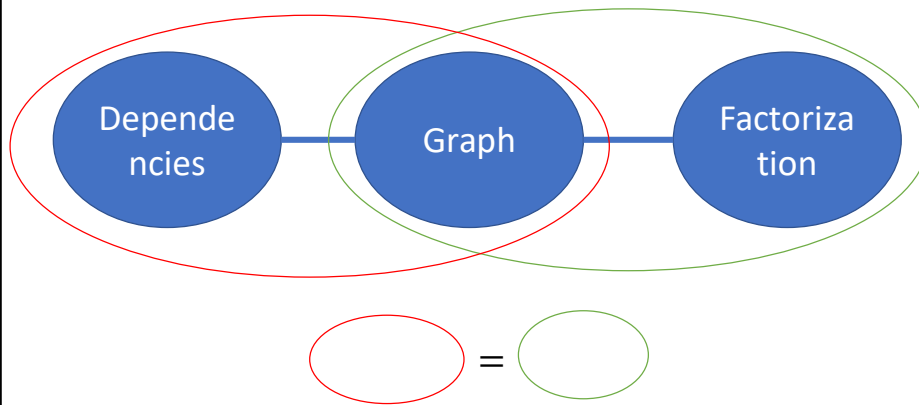
Equivalency between Factorization and Conditional Independence over G

- If p factorizes over G , p satisfies all conditional independence represented by G .
- If p satisfies all conditional independence represented by G , then p factorizes over G .

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What does that mean

Dependencies, Graph, Factorization



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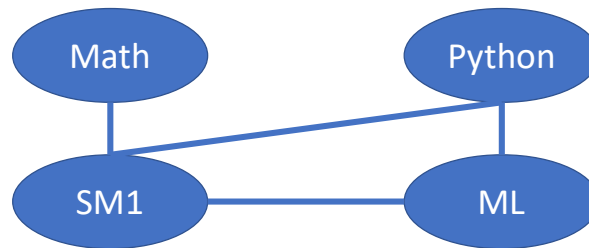
Equivalency between Factorization and Conditional Independence over G

- Verify this on Scores of Units example!
- **Homework:**
 - Create G using factorization on page 24 and check if the graph encodes all conditional Independence of $p(Ma, SM1, Py, ML)$.
 - Create G using all conditional independence on page 19 and check if it encodes the factorization of $p(Ma, SM1, Py, ML)$.

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Example

$$p(Ma, SPS, Py, ML) \\ \propto g_1(Ma, SPS) \cdot g_2(Py, ML, SPS).$$



Hint: $X \perp Y|Z \Leftrightarrow p(X, Y, Z) \propto g_1(X, Z) \cdot g_2(Y, Z)$
 $X \perp Y, W|Z \Rightarrow X \perp Y|Z$

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Example

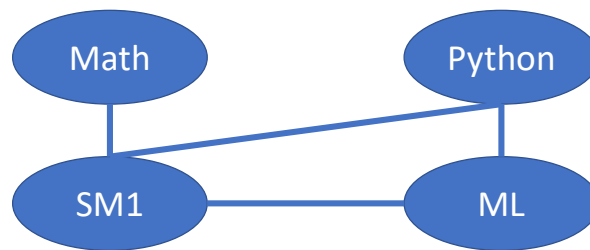
Math \perp ML | SM1

Math \perp Python | SM1

Math \perp ML | SM1, Python

Math \perp Python, ML | SM1

Math \perp Python | SM1, ML



Hint: $X \perp Y | Z \Leftrightarrow p(X, Y, Z) \propto g_1(X, Z) \cdot g_2(Y, Z)$

Weak Union Rule: $X \perp Y, W | Z \Rightarrow X \perp Y | W, Z$

Markov Network

- A probability distribution $p(X)$ which uses undirected graph representing its conditional independence, is called an **undirected graphical model**, or a **Markov network**.

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The definition of Markov network.

Gaussian Markov Network

- Multivariate Gaussian distribution:

- $\mathbf{x} \in R^d, \mathbf{x} \sim N(\mathbf{0}, \Sigma)$

- $p(\mathbf{x}) \propto \exp \left[-\frac{\mathbf{x}(\Sigma)^{-1}\mathbf{x}^\top}{2} \right]$ Let $\Theta = (\Sigma)^{-1}$.

$$\propto \exp \left[-\frac{\sum_{u,v} \Theta^{(u,v)} x^{(u)} x^{(v)}}{2} \right]$$

$$\propto \prod_{u,v; \Theta^{(u,v)} \neq 0} \exp(-\Theta^{(u,v)} x^{(u)} x^{(v)})$$

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$$\mathbf{a} \mathbf{B} \mathbf{a}^\top = \sum_{ij} B_{ij} a_i a_j$$

You can factorize the joint Gaussian using the pairwise factors

Gaussian Markov Network

- $p(\mathbf{x}) \propto \prod_{u,v; \Theta(u,v) \neq 0} g_{u,v}(x^{(u)}, x^{(v)})$

- $p(\mathbf{x})$ **factorizes over G !**

- G defined by the adjacency matrix

$$A^{(u,v)} = \begin{cases} 0, & \Theta(u,v) == 0 \\ 1, & \Theta(u,v) \neq 0 \end{cases}$$

- G must be an undirected graph (why?)

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This pairwise factorization implies the distribution factorizes over a G whose edges are defined by the structure of Θ

Gaussian Markov Network

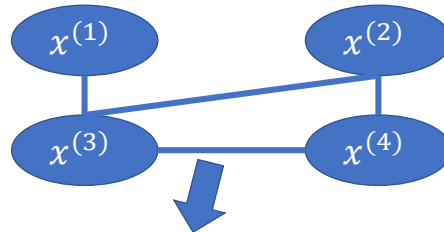
- Give me a graph G that encodes all conditional independence of your Gaussian R.V., I can infer the sparsity of your Θ .

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Theta must be positive definite!!

We are using graph to construct our probabilistic model, hence the name, graphical model!!

Example



$$\bullet \Theta = \begin{bmatrix} \Theta_{11} & 0 & \Theta_{13} & 0 \\ 0 & \Theta_{22} & \Theta_{23} & \Theta_{24} \\ \Theta_{13} & \Theta_{23} & \Theta_{33} & \Theta_{34} \\ 0 & \Theta_{24} & \Theta_{34} & \Theta_{44} \end{bmatrix}$$

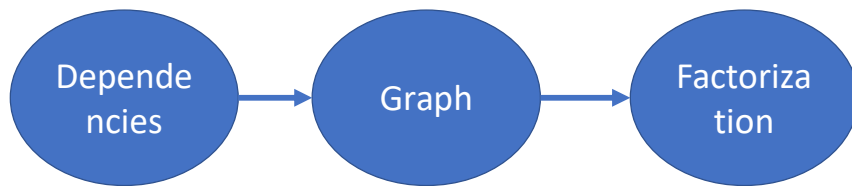
sparsity
of Θ =
sparsity
of the G !

- If I know dependency of my R.V.s, I can easily write down my Gaussian model.

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Theta must be positive definite!!

From Dependency to Factorization



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Homework question:

- Suppose graph G encodes all cond. indep. in your Gaussian distribution p . G contains **three edges, five nodes**. How many **non-zero elements** are there in **inverse covariance** matrix of p ?
- A.3
- B.8
- C.6
- D.10
- E.11

Constructing Likelihood

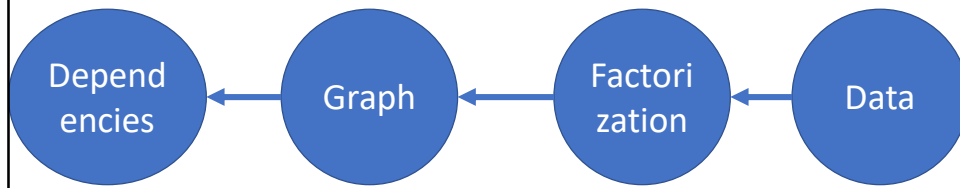
- **PC:** If (x_0, \mathbf{x}) are drawn from a joint Gaussian $p(x_0, \mathbf{x})$, show log likelihood $\log p(x_0 | \mathbf{x})$ has the form:
 - $-(x_0 - \sum_i \beta_i x_i)^2 / b$, where $\beta_i \neq 0$ iff (X_0, X_i) is an edge in the Markov network structure of p .
 - How does it help us select good features in least squares fitting?

Gaussian Markov Network

- If we do not know, cond. independence of $p(\mathbf{x})$, we can infer it from data!
- Given dataset D , we can fit a $\hat{\Theta}$.
 - Using MLE: $\hat{\Theta} = \underset{\Theta}{\operatorname{argmax}} \log p(D; \Theta)$
 - The sparsity of $\hat{\Theta}$ gives a graph corresponds to factorization of $p(\mathbf{x})$!
 - Such graph also reveals how R.V. are dependent on each other!

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From Factorization to Graph

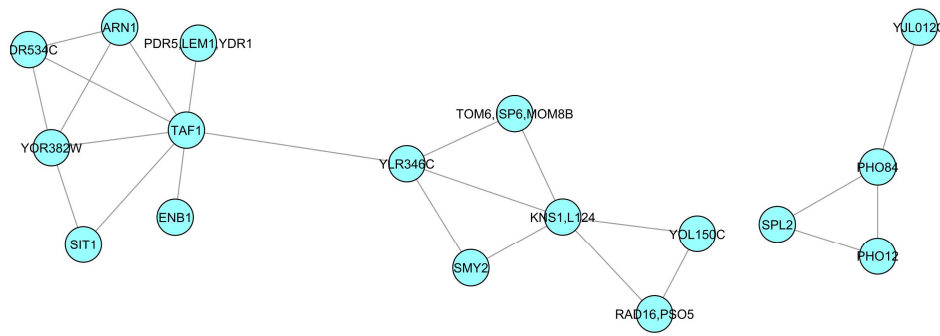


Example: Gene Expression Data

Time stamp	Gene1	Gene2	Gene3	Gene4
t1	.1	.2	.5	.2
t2	.5	.4	.7	.8
t3	.5	.545
t4	.9	.201
...

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Gene Network ([Banerjee et al., 2008](#))



Exponential Family Distribution



- Gaussian Markov network belongs to a wider **family** of distributions, which are defined using a generic form:
- $p(\mathbf{x}; \boldsymbol{\theta}) := \frac{\exp(\langle \boldsymbol{\theta}, \mathbf{f}(\mathbf{x}) \rangle)}{Z(\boldsymbol{\theta})}$
 - $\mathbf{f}(\mathbf{x})$ is a feature transform on \mathbf{x} .
 - $Z(\boldsymbol{\theta}) := \int \exp(\langle \boldsymbol{\theta}, \mathbf{f}(\mathbf{x}) \rangle) d\mathbf{x}$
- PC: show when \mathbf{f} is 2nd degree poly. transform with pairwise terms, $p(\mathbf{x}; \boldsymbol{\theta})$ is a multivariate Gaussian distribution.

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Graphical Lasso (Jerome Friedman et al., 2008)

- Given $D = \{\mathbf{x}_i\}_{i=1}^n$, $\mathbf{x} \in R^d$,
- Construct a Gaussian likelihood:
 - $p(D|\Theta) = \prod_i N_{\mathbf{x}_i}(\mathbf{0}, \Theta^{-1})$
- $\hat{\Theta} := \operatorname{argmax}_{\Theta} \log p(D|\Theta) - \lambda \|\Theta\|_1$
 - $= \operatorname{argmax}_{\Theta} -\operatorname{tr}(\mathbf{S}\Theta) + \log \det \Theta - \lambda \|\Theta\|_1$
 - \mathbf{S} : sample cov; $\|\Theta\|_1 = \sum_{i,j} |\Theta^{(i,j)}|$
- Construct a graph using sparsity of $\hat{\Theta}$

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Conditional Markov Network

- In many tasks, the conditional distribution is the key interest.
 - $p(Y|X)$ measures the randomness on Y given X and help us make a prediction.
 - Both regression and classification requires a **conditional** model.
- How to factorize a conditional distribution over G ?

Conditional Markov Network

- We say a conditional probability distribution $P(Y|X)$ factorizes over G whose nodes $V = X \cup Y$, if
- $p(Y|X) = \frac{1}{N(X)} \prod_{c \in \mathcal{C}} g_c(V_c)$,
 - $\mathcal{C} := \{c \text{ is a clique in } G \mid V_c \not\subseteq X\}$
- $N(X) := \int \prod_{c \in \mathcal{C}} g_c(V_c) dY$
- Normalizing constant:
 - It normalizes the distribution to 1 over the domain of the random variable (Y).

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Conditional Markov Network

- $p(Y|X)$ does not include factors defined on subsets of conditioning variable X !

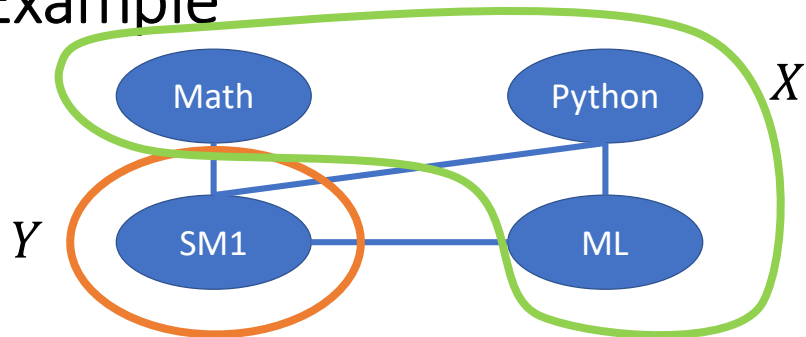
- $p(Y|X) = \frac{1}{N(X)} g_1(Y, X) g_2(X)$

- $N(X) =$

$$\int g_1(Y, X) g_2(X) dY = g_2(X) \int g_1(Y, X) dY$$

- $p(Y|X) = \frac{g_1(Y, X) g_2(X)}{g_2(X) \int g_1(Y, X) dY} = \frac{g_1(Y, X)}{\int g_1(Y, X) dy}$

Example



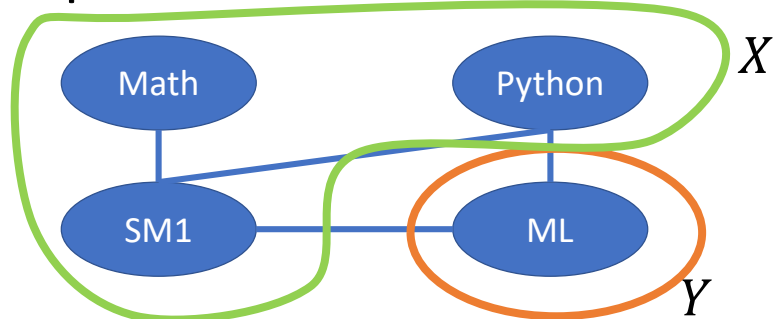
- $$p(SM1|Ma, Py, ML)$$

$$= \frac{1}{N(Ma, Py, ML)} g_1(SM1, Py, ML) g_2(SM1, Ma)$$

- $$N(Ma, Py, ML) = \int g_1(SM1, Py, ML) g_2(SM1, Ma) dSM1$$

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Example



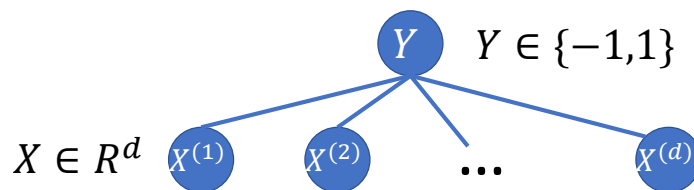
$$\begin{aligned} & \bullet p(ML | Ma, Py, SM1) \\ &= \frac{1}{N(Py, SM1)} g_1(SM1, Py, ML) \end{aligned}$$

$$\bullet N(SM1, Py) = \int g_1(SM1, Py, ML) dML$$

• g_2 is gone! Math is gone!

Logistic Regression

- This way of constructing a conditional likelihood gives us: Logistic Regression.
- Consider a simple Markov Net



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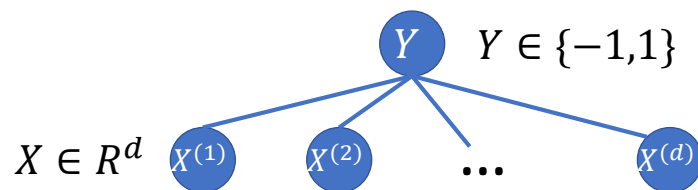
Y is the variable for class labels, that can be either positive +1 or negative -1 as we saw before.

Logistic Model

- Using the factorization rule above,

- $p(Y|X) = \frac{1}{N(X)} \prod_i g_i(Y, X^{(i)})$

- $N(X) = \sum_{Y \in \{-1,1\}} \prod_i g_i(Y, X^{(i)})$



Logistic Model

- Let us construct a model of cond. likelihood $p(Y|X)$!

- By setting

$$g_i(Y = y, X_i = x^{(i)}; \beta_i, \beta_0) := \exp(y(\beta^{(i)} \cdot x^{(i)} + \beta_0))$$

- $$p(y|x; \boldsymbol{\beta}, \beta_0) = \frac{1}{N(X)} \prod_i \exp(y(\beta^{(i)} \cdot x^{(i)} + \beta_0))$$

$$= \frac{1}{N(X)} \exp(y(\langle \boldsymbol{\beta}, \mathbf{x} \rangle + d\beta_0)).$$

- $$N(X; \boldsymbol{\beta}, \beta_0) = \sum_{y \in \{1, -1\}} \exp(y(\langle \boldsymbol{\beta}, \mathbf{x} \rangle + d\beta_0))$$

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This is another example, of **graphical modelling**. We have a graph, which encodes the conditional independence. We then create a probabilistic model based on that graph.

We replaced the integral by sum in the normalizing term, which is required by a discrete variable Y

Logistic Regression

- Logistic model:

- $p(y|\mathbf{x}; \boldsymbol{\beta}, \beta_0) = \frac{1}{N(\mathbf{x})} \exp(y(\langle \boldsymbol{\beta}, \mathbf{x} \rangle + d\beta_0))$

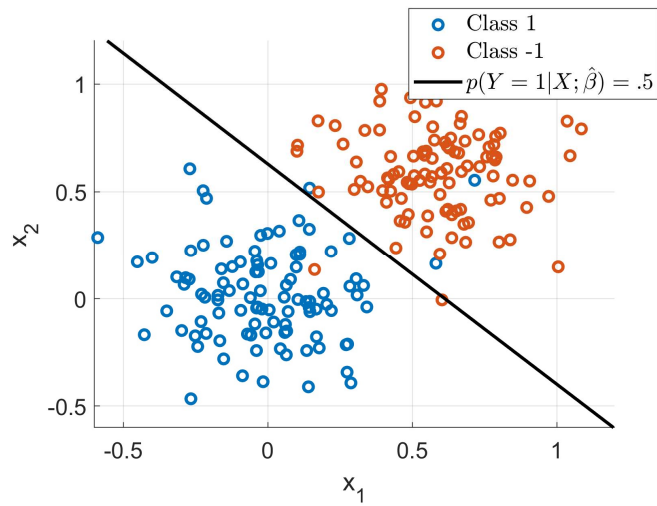
- $N(\mathbf{x}) = \exp(\langle \boldsymbol{\beta}, \mathbf{x} \rangle + d\beta_0) + \exp(-\langle \boldsymbol{\beta}, \mathbf{x} \rangle - d\beta_0)$

- $\boldsymbol{\beta}, \beta_0$ can be fitted using MLE.

- $\hat{\boldsymbol{\beta}}, \hat{\beta}_0 = \arg \max_{\boldsymbol{\beta}, \beta_0} \sum_{i=1}^n \log p(y_i | \mathbf{x}_i; \boldsymbol{\beta}, \beta_0)$

- Homework: Show this is the same Logistic Regression we talked about in Lec 10.

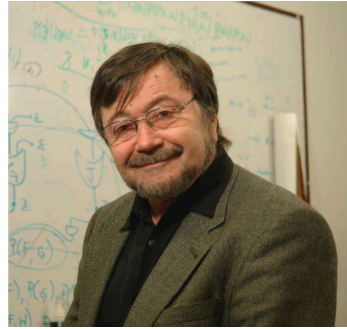
Example



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Conclusion

- Markov network uses an **undirected graph** to represent conditional independencies and factorizations of a probability distribution.
- Two examples of Markov network
 - Gaussian Markov network factorizes over the graph defined by its **inverse covariance**.
 - Logistic model is a conditional prob. dist. factorizes over a classification network.

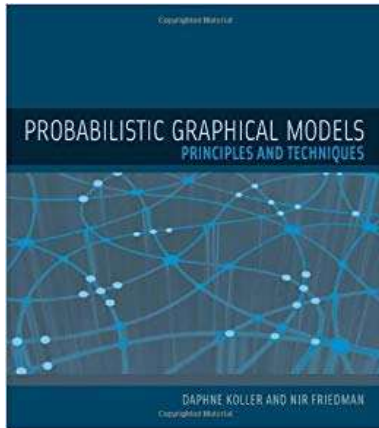


Judea Pearl

Bayesian Network

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References



- Today's class roughly follows Chapter 3 in Probabilistic Graphical Models by Koller and Friedman.

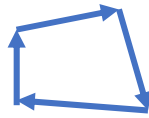
A Directed Graphical Model

- Markov network is an **undirected graphical model**.
 - which encodes **cond. indep.**
 - and **factorization** of a probability dist.
- Can we use a **directed graphical model** to do the same job?
 - Some dependencies are better addressed using a directed model.

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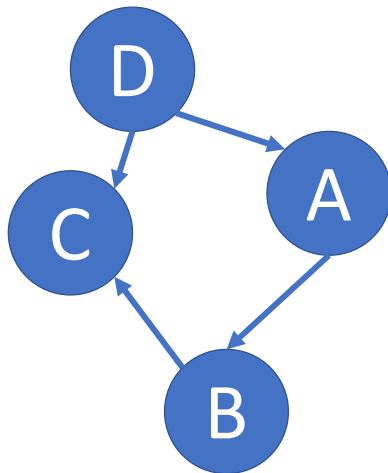
Directed Acyclic Graph

- The directed graphical model uses Directed Acyclic Graph (DAG) as its graphical representation.
- $G := \langle E, V \rangle$, E is directed edge set.
- DAG: G **without directed cycles**.



A directed cycle

Parents, Children, Descendants



One node may have
more than one parent
or child!

If there exists a
directed edge $A \rightarrow B$:
 A is the parent of B and
 B is the child of A .

If there exists a
directed path $A \rightarrow B$: B
is the descendant of A .

Parent(A): D

Children(A): B

Descendants(A): B, C

However, a Bayesian network not necessarily comes with causal information. This is important but not in this class

Example

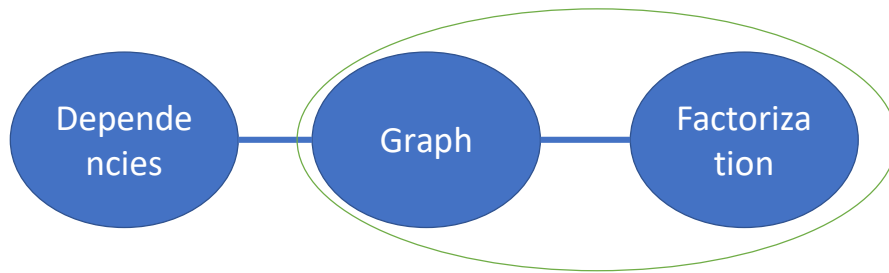


- DAG is usually used to represent causal relationship.
- e.g. high temp yesterday causes high temp today, not **vice versa**!

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However, a Bayesian network not necessarily comes with causal information. This is important but not in this class

Graph and Factorization



Representing Factorization using DAG

- DAG can also be used to represent the factorization of a probability dist.
- We say a probability dist. $p(X)$ factorizes over a DAG G if
- $p(X) = \prod_{v \in V} p(X_v | X_{\text{parent}(X_v)})$

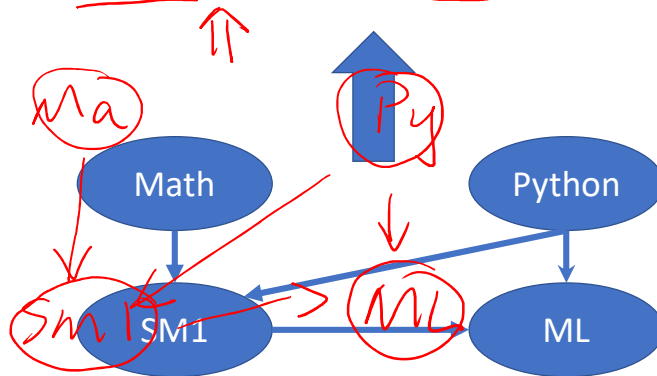
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Equality

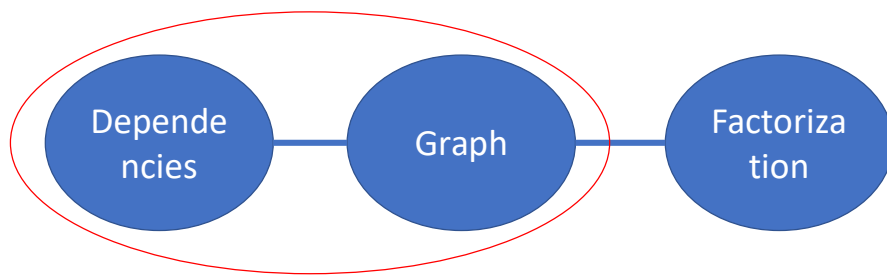
Probability

Example

$$\bullet p(Ma, Py, SM1, ML) = \underbrace{p(Ma)}_{\downarrow} \underbrace{p(Py)}_{\uparrow} \underbrace{p(SM1|Ma, Py)}_{\downarrow} \underbrace{p(\overset{\vee}{ML}|SM1, Py)}_{\downarrow}$$



Graph and Dependency



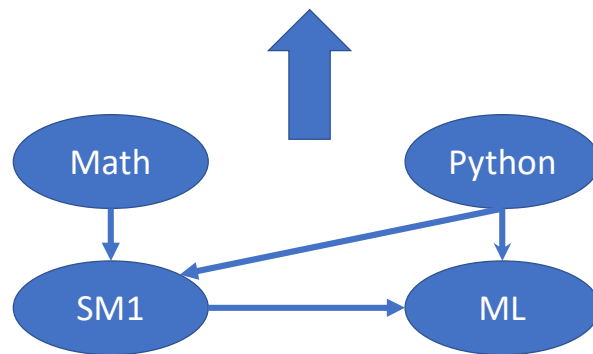
Represent Cond. Indep. using DAG

- Given DAG G .
- X_v is independent of $X_{\text{non-desc}(X_v)}$ given $X_{\text{parent}(X_v)}$, $\forall v$.
 - This is an analogy to Markov net, as X_v and all non-descendants of X_v are “blocked” by the parents of X_v .
- Knowing $X_{\text{parent}(X_v)}$, $X_{\text{non-desc}(X_v)}$ tell us nothing new about X_v .

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Example

- $ML \perp Math \mid SM1, Python$
- $Math \perp Python$



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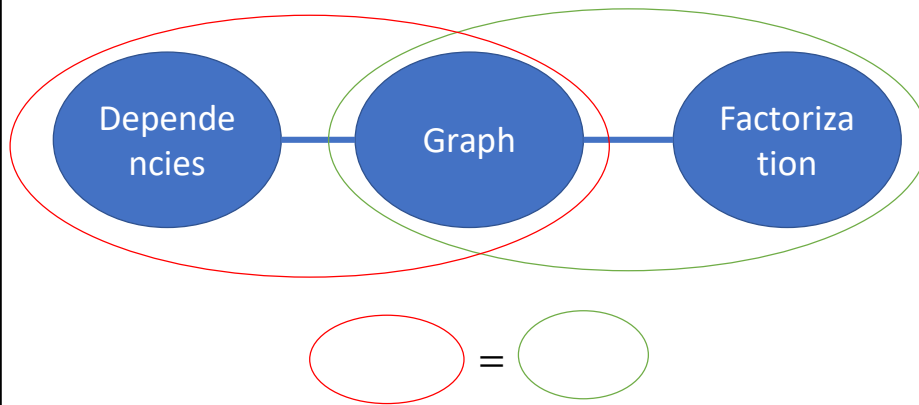
Equivalency between Factorization and Conditional Independence over DAG G

- If p factorizes over G , p satisfies all conditional independence represented by G .
- If p satisfies all conditional independence represented by G , then p factorizes over G .

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PC: verify this on unit score example.

Dependencies, Graph, Factorization

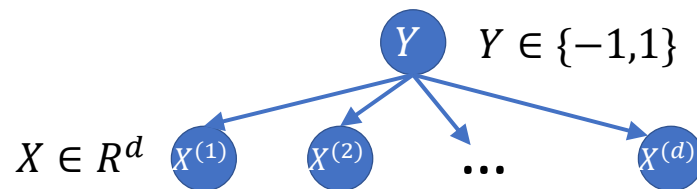


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Bayesian Network

- A probability dist. $p(x)$ factorizes over a DAG G is called Bayesian network.

Bayesian Network for Classification



- Looks familiar?

Bayesian Network for Classification

- Write down the conditional probability $P(Y|X)$.

- $$P(Y|X) = \frac{\prod_i P(X^{(i)}|Y)P(Y)}{P(X)}$$

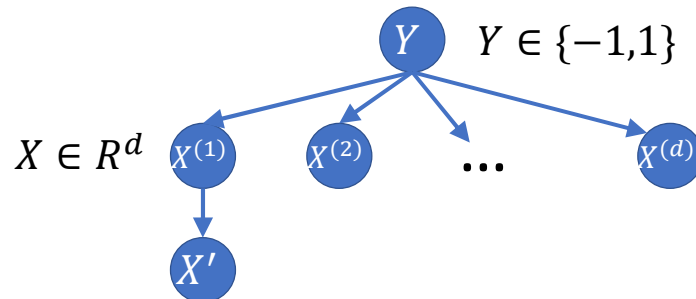
- This is how Naïve Bayes is derived!

Bayesian Network for Classification

- Compare NB and Logistic regression from the following perspectives:
 - The graphical structure
 - Same structure
 - Directed vs. Undirected
 - The factorization
 - Pairwise factors between Y and X_i .
 - **Factor on cliques** vs. **Conditional Prob.**
 - The probabilistic model
 - Both use $p(Y|X)$ to make prediction
 - NB **does not** give you $p(Y|X)$, only up to a constant
 - The training/fitting of a classifier
 - Estimation of $p(Y|X)$ vs. $P(X|Y)$
 - Prediction rule
 - Both $\hat{y} := \operatorname{argmax}_y p(Y|X)$

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Question



- Homework: Given this Bayesian Net for a classification task, should you include feature X' for classification? Why?

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$$P(Y|X) = \frac{\prod_i P(X_i|Y)P(Y)}{P(X)} p(X'|X)$$

$$\hat{y} := \operatorname{argmax}_y p \left(\frac{\prod_i P(X_i|Y)P(Y)}{P(X)} \mathbf{p(X'|X)} \right), \text{ for a specific } x!$$

Constant!

Conclusion

- Bayesian Net uses a **DAG** to represent factorization and conditional independence of a probability distribution .
 - Similar to Markov net
- **Naïve Bayes** is derived from a simplified Bayesian net for a conditional probability $P(Y|X)$.