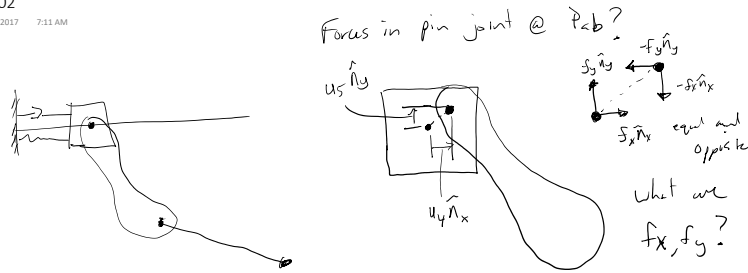


$u_4, u_5$  : auxiliary speeds

$$\dot{V} = u_1 \hat{n}_x + u_4 \hat{n}_x + u_5 \hat{n}_y$$

$$\dot{R}^{ab} = -k u_1 \hat{n}_x - c u_1 \hat{n}_x + F + f_x \hat{n}_x + f_y \hat{n}_y$$



$$\vec{V}^{P,ab} = u_1 \hat{n}_x + u_4 \hat{n}_x + u_5 \hat{n}_y \quad \text{accelerating speeds}$$

$$\vec{V}_1^{P,ab} = \hat{n}_x \quad \vec{V}_3^{P,ab} = 0 \quad \vec{V}_5^{P,ab} = \hat{n}_y$$

$$\vec{V}_2^{P,ab} = 0 \quad \vec{V}_4^{P,ab} = \hat{n}_x$$

$$\vec{R}^{P,ab} = -c u_1 \hat{n}_x - k_1 \hat{n}_x + f_x \hat{n}_x + f_y \hat{n}_y$$

$$\vec{F}_r^{P,ab} = \vec{V}_r \cdot \vec{R}^{P,ab}$$

$$\vec{F}_1^{P,ab} = -c u_1 - k_1 + f_x$$

$$\vec{F}_3^{P,ab} = 0$$

$$\vec{F}_5^{P,ab} = f_y$$

$$\vec{F}_2^{P,ab} = 0$$

$$\vec{F}_4^{P,ab} = -c u_1 - k_1 + f_x$$

$$\frac{d^2 \alpha}{dt^2} = (\ddot{u}_1 + \dot{u}_4) \hat{n}_x + \ddot{u}_5 \hat{n}_y$$

$$\vec{F}_1^{*P,ab} = -m_{ab} \ddot{\alpha} \cdot \hat{n}_x = -m_{ab} (\ddot{u}_1 + \dot{u}_4)$$

$$\vec{F}_3^{*} = 0$$

$$\vec{F}_5^{*} = -m_{ab} (\ddot{u}_5)$$

$$\vec{F}_2^{*} = 0$$

$$\vec{F}_4^{*} = -m_{ab} (\ddot{u}_1 + \dot{u}_4)$$

$$(1) \quad c u_1 - k_1 + f_x - m_{ab} (\ddot{u}_1 + \dot{u}_4) = 0 \Rightarrow f_x = c u_1 + k_1 - m_{ab} \ddot{u}_1$$

$$(2) \quad 0 + 0 = 0$$

$$(3) \quad 0 \quad 0 = 0$$

$$(4) \quad -c u_1 - k_1 + f_x - m_{ab} (\ddot{u}_1 + \dot{u}_4) = 0 \Rightarrow f_x = c u_1 + k_1 - m_{ab} \ddot{u}_1$$

$$(5) \quad f_y - m_{ab} \ddot{u}_5 = 0 \Rightarrow f_y = 0$$