# Query Complexity: Worst-Case Quantum Versus Average-Case Classical

Scott Aaronson\*

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#### 1 Introduction

In this note we investigate the relationship between worst-case quantum query complexity and average-case classical query complexity. Specifically, we show that if a quantum computer can evaluate a total Boolean function f (with bounded error) using T queries in the worst case, then a deterministic classical computer can evaluate f using  $O(T^5)$  queries in the average case, under a uniform distribution of inputs. (If f is monotone, we show furthermore that only  $O(T^3)$  queries are needed.)

Previously, Beals et al. [3] showed that if a quantum computer can evaluate f (with bounded error) using T queries in the worst case, then a deterministic classical computer can evaluate f using  $O(T^6)$  queries in the worst case, or  $O(T^4)$  if f is monotone. The optimal bound is conjectured to be  $O(T^2)$ , but improving on  $O(T^6)$  remains an open problem. Relating worst-case quantum complexity to average-case classical complexity may suggest new ways to reduce the polynomial gap in the ordinary worst-case versus worst-case setting.

#### 2 Preliminaries

Let  $f: \{0,1\}^n \to \{0,1\}$  be a total Boolean function. Following [3], we let D(f),  $R_0(f)$ , and  $R_2(f)$  respectively denote the deterministic, zero-error, and bounded-error classical query complexities of f, and let  $Q_E(f)$ ,  $Q_0(f)$ , and  $Q_2(f)$  denote the corresponding quantum query complexities. We have:

- $n \ge D(f) \ge Q_E(f) \ge Q_0(f) \ge Q_2(f)$  and  $n \ge D(f) \ge R_0(f) \ge R_2(f) \ge Q_2(f)$ ,
- $D(f) = O(R_2(f)^3)$  and  $D(f) = O(R_0(f)^2)$  [5],
- $D(f) = O(Q_2(f)^6)$ , or  $O(Q_2(f)^4)$  if f is monotone [3], and
- $D(f) = O(Q_0(f)^4)$  [4].

Let  $\mu$  be the uniform distribution over  $\{0,1\}^n$ . Following Ambainis and de Wolf [2], we let  $D^{\mu}(f)$  be the average-case deterministic query complexity under the uniform distribution of inputs. (Note that in [2],  $\mu$  can be non-uniform, whereas here it is always uniform.) The average-case bounded-error analogs of  $D^{\mu}(f)$ ,

<sup>\*217</sup> West Avenue, Cornell University, Ithaca NY 14850. Email: sja8@cornell.edu.

 $R_2^{\mu}(f)$  and  $Q_2^{\mu}(f)$  in the classical and quantum settings respectively, can be super-exponentially smaller than  $D^{\mu}(f)$  [2]. On the other hand, we have  $D^{\mu}(f) = R_0^{\mu}(f)$  by Yao's minimax principle: viewing the questioner's choice of query algorithm and the oracle's choice of response algorithm in matrix-game terms, if the oracle is committed to a fixed randomized strategy (as it is in the average-case setting), then the questioner has nothing to gain by using randomization (assuming the questioner's goal is the same, namely to evaluate f with probability 1). Therefore we need not consider  $R_0^{\mu}(f)$ .

with probability 1). Therefore we need not consider  $R_0^{\mu}(f)$ . Here we show that  $D^{\mu}(f) = O(Q_2(f)^5)$ , or  $O(Q_2(f)^3)$  if f is monotone. The proof has two components. Theorem 1 gives a deterministic classical algorithm for evaluating f with few queries in the average case, yielding an upper bound on  $D^{\mu}(f)$ . The theorem is a refinement of [3, Lemma 5.3], which gives an upper bound on D(f). Theorem 2 gives a lower bound on  $Q_2(f)$  in terms of the expected block sensitivity. The bound is obtained via the quantum adversary argument, which was recently introduced by Ambainis [1].

Given  $X \in \{0,1\}^n$  and a block B of variables, let X(B) be the input obtained from X by flipping the values of all the variables in B. Following [5, 3]:

- A 1-certificate is an assignment C: B → {0,1} of values to a block B of variables, such that f(X) = 1 whenever X is consistent with C. The size of C is |B|. A 0-certificate is defined similarly. A 1-certificate C is minimal if no proper sub-block C' of C is a 1-certificate (similarly for 0-certificates). The certificate complexity C<sub>X</sub>(f) of X is the size of the smallest f(X)-certificate that agrees with X. The certificate complexity C(f) of f is the maximum of C<sub>X</sub>(f) over all X.
- The block sensitivity  $bs_X(f)$  of X is the maximum number b of disjoint blocks  $B_1, \ldots, B_b$  of variables such that for all  $1 \le i \le b$ ,  $f(X) \ne f(X(B_i))$ . The block sensitivity bs(f) of f is the maximum of  $bs_X(f)$  over all X.

Let  $C_{\mu}(f) = E_{\mu}[C_X(f)]$  be the mean of  $C_X(f)$  over all X. Likewise let  $\mathrm{bs}_{\mu}(f) = E_{\mu}[\mathrm{bs}_X(f)]$  be the mean of  $\mathrm{bs}_X(f)$  over all X. Let  $\mathrm{bs}_{\mu}^{(1)}(f) = E_{\mu(1)}[\mathrm{bs}_X(f)]$  be the mean block sensitivity among X such that f(X) = 1, and let  $\mathrm{bs}_{\mu}^{(0)}(f) = E_{\mu(0)}[\mathrm{bs}_X(f)]$  be the mean block sensitivity among X such that f(X) = 0.

#### 3 Results

First we relate  $D^{\mu}(f)$  to the mean block sensitivity bs<sub> $\mu$ </sub>(f), along the lines of [3, Lemma 5.3].

Theorem 1  $D^{\mu}(f) \leq 2 \operatorname{bs}_{\mu}(f) C(f)$ .

**Proof.** Let a *satisfying* certificate be one that agrees with X; let a *consistent* certificate be one that agrees with the X-values queried so far. The following algorithm returns a satisfying 0-certificate in expected number of queries at most  $bs_{\mu}^{(0)}(f)C(f)$ , assuming that f(X) = 0 (the expectation is over the uniform distribution of all X satisfying this condition).

Choose a minimal consistent 1-certificate and query those of its variables whose X-values are still unknown. Repeat until a satisfying 0-certificate is found among the variables that have been queried.

Call this algorithm  $A_0$ .  $A_0$  can be made deterministic by choosing certificates in some fixed lexicographic order. To see that  $A_0$  always returns a satisfying 0-certificate, note that, for the special case f(X) = 0 that we're considering,  $A_0$  reduces to Algorithm A of [3, Lemma 5.3]. A always returns a satisfying 0-certificate when f(X) = 0, therefore so does  $A_0$ .

It remains to show that the expected number of queries used by  $A_0$  is at most  $\mathrm{bs}_{\mu}^{(0)}(f)C(f)$ . Suppose that, after  $A_0$  has queried k 1-certificates,  $C_1, \ldots, C_k$ , no satisfying 0-certificate has yet been found. Then

there exists a Y consistent with the bits queried so far such that f(Y) = 1. Furthermore, Y contains a satisfying 1-certificate  $C_{k+1}$ . We will derive from these  $C_i$  disjoint blocks  $B_i \subseteq X$  such that f is sensitive to each  $B_i$  on X. For each  $1 \leq i \leq k+1$ , let  $B_i$  be the set of variables on which X and  $C_i$  disagree. Clearly each  $B_i$  is non-empty. Now,  $X(B_i)$  agrees with  $C_i$ , therefore  $f(X(B_i)) = 1$ , so that f is sensitive to each  $B_i$  on X. Let v be a variable in some  $B_i$ ; then  $X^{(v)} = Y^{(v)} \neq C_i^{(v)}$ . For i > i,  $C_j$  has been chosen consistent with all variables queried so far (including v), so we cannot have  $X^{(v)} = Y^{(v)} \neq C_i^{(v)}$ , hence  $v \notin B_j$ . Therefore all  $B_i$  and  $B_j$  are disjoint. It follows that k (the number of 1-certificates queried) can be at most bs(X).

Now, since the input is chosen uniformly at random among all X with f(X) = 0, the expectation of bs(X) is  $bs_{\mu}^{(0)}(f)$ . Therefore  $A_0$  returns a satisfying 0-certificate after querying an expected number of

certificates at most  $\mathrm{bs}_{\mu}^{(0)}(f)$ , or after an expected total number of queries at most  $\mathrm{bs}_{\mu}^{(0)}(f)C(f)$ .

An analogous algorithm,  $A_1$ , returns a satisfying 1-certificate in expected number of queries at most  $bs_{\mu}^{(1)}(f)C(f)$ , assuming that a 1-certificate exists (i.e. that f(X)=1). Suppose that we interleave  $A_0$  and  $A_1$ , alternating between the two until either  $A_0$  or  $A_1$  halts and returns a certificate, and that when X is chosen from  $\mu$ , f(X) = 1 with probability p. Then the expected total number of queries is at most

$$2p \operatorname{bs}_{\mu}^{(1)}(f)C(f) + 2(1-p) \operatorname{bs}_{\mu}^{(0)}(f)C(f) = 2 \operatorname{bs}_{\mu}(f)C(f). \blacksquare$$

 $2p\operatorname{bs}_{\mu}^{(1)}(f)C(f) + 2(1-p)\operatorname{bs}_{\mu}^{(0)}(f)C(f) = 2\operatorname{bs}_{\mu}(f)C(f).$  

One can show, using a similar argument, that  $D^{\mu}(f) \leq 2\operatorname{bs}(f)C_{\mu}(f).$  We conjecture that  $D^{\mu}(f) = 2\operatorname{bs}(f)C_{\mu}(f)$  $O(bs_{\mu}(f)C_{\mu}(f))$ , but are unable to show this.

We next give a lower bound on  $Q_2(f)$  in terms of the mean block sensitivity. The proof is along the lines of Ambainis [1, Theorem 3]; for completeness, we recapitulate some of the material in that manuscript.

**Theorem 2** 
$$Q_2(f) \ge (1/2 - \sqrt{2}/3) \operatorname{bs}_{\mu}(f)$$
.

**Proof.** For each X, choose  $bs_X(f)$  disjoint minimal blocks  $B_1^{(X)}, \ldots, B_{bs_X(f)}^{(X)}$  such that for all  $i, f(X) \neq 0$  $f(X(B_i^{(X)}))$ . (By minimal, we mean that for each i, no proper sub-block B' of  $B_i^{(X)}$  has the property that  $f(X) \neq f(X(B'))$ .) Call  $X(B_1^{(X)}), \ldots, X(B_{\operatorname{bs}_X(f)}^{(X)})$  the block-neighbors of X. (Note that if Y is a block-neighbor of X, X is not necessarily a block-neighbor of Y.)

Let A be a quantum algorithm to evaluate f(X) with probability of error  $\varepsilon = 1/3$ . Following [1], instead of running A with a single string as input, we run A with the uniform superposition of all strings in  $\mu$  as input. Let  $\mathcal{H}_I$  be the 'input subspace' spanned by basis vectors  $|X\rangle$  corresponding to the possible inputs X. Let  $\rho_k$  be the density matrix of  $\mathcal{H}_I$  after A has made k queries. Let  $S_k$  be the sum of  $(\rho_k)_{X,Y}$  for all ordered pairs (X,Y) such that Y is a block-neighbor of X. Suppose that A makes a total number of queries T. Then:

- 1.  $S_0 = bs_{\mu}(f)$ . This is because there are  $2^n$  input strings, the mean number of block-neighbors of a string is  $bs_{\mu}(f)$ , and every entry of  $\rho_0$  is  $2^{-n}$ .
- 2.  $S_T \leq 2\sqrt{\varepsilon(1-\varepsilon)} \operatorname{bs}_u(f) = (2\sqrt{2}/3) \operatorname{bs}_u(f)$ , by [1, Lemma 1].
- 3.  $S_{k-1} S_k \le 2$ .

Together, these statements imply that  $T \geq (1/2 - \sqrt{2}/3) \operatorname{bs}_{\mu}(f)$ . We now prove the third statement. Express the state before the  $k^{th}$  query as  $|\psi_{k-1}\rangle = \sum_{i,a,z,X} \alpha_{i,a,z,X} |i,a,z\rangle \otimes |X\rangle$ 

where i is the index of the variable  $X_i$  being queried, a is a bit for recording the answer, and z is a

collection of extra work bits. Then after the 
$$k^{th}$$
 query we have  $|\psi_k\rangle = \sum_{i,a,z,X} \alpha_{i,a,z,X} |i,a \oplus X_i,z\rangle \otimes |X\rangle = \sum_{i,a,z,X} \alpha_{i,a \oplus X_i,z,X} |i,a,z\rangle \otimes |X\rangle.$ 

$$|\psi_{i,a,z}\rangle = \sum_{X} \alpha_{i,a,z,X} |X\rangle$$
 and  $|\psi'_{i,a,z}\rangle = \sum_{X} \alpha_{i,a \oplus X_i,z,X} |X\rangle$ .

Then  $\rho_{k-1,i} = \sum_{a,z} |\psi_{i,a,z}\rangle \langle \psi_{i,a,z}|$  and  $\rho_{k,i} = \sum_{a,z} |\psi_{i,a,z}\rangle \langle \psi_{i,a,z}|$  are the components of  $\rho_{k-1}$  and  $\rho_k$  respectively corresponding to querying  $X_i$ . We can then represent  $\rho_{k-1}$  as  $\sum_{i=1}^n \rho_{k-1,i}$  and  $\rho_k$  as  $\sum_{i=1}^n \rho_{k,i}$ .

Then 
$$S_{k-1} - S_k \leq \sum_{i=1}^n S_{k,i}$$
 where  $S_{k,i} = \sum_{X,Y: Y \text{ a block-} | (\rho_{k-1,i})_{X,Y} - (\rho_{k,i})_{X,Y}|.$ 

The only entries that differ in  $\rho_{k,i}$  and  $\rho_{k-1,i}$  are the ones that correspond to X,Y with  $X_i \neq Y_i$ . For every X, there is at most one block-neighbor Y having this property. (The fact that we're dealing with block-neighbors, rather than with ordinary neighbors as in [1], doesn't change this.) Therefore

$$\sum_{\substack{X,Y:\ Y \text{ a block-} \\ \text{neighbor of } X}} (\rho_{k-1,i})_{X,Y} \leq \sum_{\substack{X,Y:\ Y \text{ a block-} \\ \text{neighbor of } X}} [(\rho_{k-1,i})_{X,X} + (\rho_{k-1,i})_{Y,Y}]/2 \leq \sum_{\substack{X}} (\rho_{k-1,i})_{X,X} = \operatorname{Tr} \rho_{k-1,i}.$$
A similar result is true for  $\rho_{k,i}$ . So we have that  $S_{k,i} \leq \operatorname{Tr} \rho_{k-1,i} + \operatorname{Tr} \rho_{k,i}$  and that

$$S_{k-1} - S_k \le \sum_i S_{k,i} \le \sum_i (\operatorname{Tr} \rho_{k-1,i} + \operatorname{Tr} \rho_{k,i}) = 2.$$

Combining Theorem 1 and Theorem 2 with  $C(f) \le \operatorname{bs}(f)^2$  [5] and  $\operatorname{bs}(f) \le 16Q_2(f)^2$  [3] we obtain  $D^{\mu}(f) \le 2\operatorname{bs}_{\mu}(f)C(f) \le 12(3+2\sqrt{2})\operatorname{bs}(f)^2Q_2(f) \le 3072(3+2\sqrt{2})Q_2(f)^5 \approx 17905Q_2(f)^5$ .

When 
$$f$$
 is monotone,  $C(f) = bs_{\mu}(f)$  [5], so we obtain  $D^{\mu}(f) \le 2 bs_{\mu}(f) bs(f) \le 192(3 + 2\sqrt{2})Q_2(f)^3 \approx 1119Q_2(f)^3$ .

## Some Open Problems

- For the case of zero-error quantum algorithms, Buhrman et al. [4] showed that  $D(f) = O(Q_0(f)^4)$ . Can we relate  $D^{\mu}(f)$  to  $Q_0(f)$ ?
- What can we say when  $\mu$  is non-uniform?

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