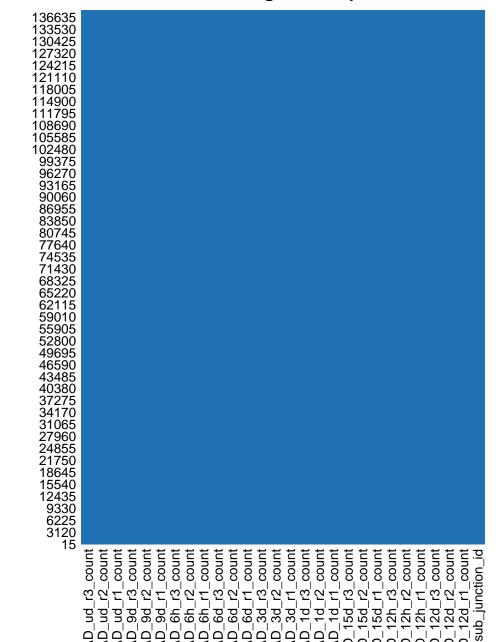
Missingness Map



Missing (0%)

Observed (100%)