

# Yue Meng

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## EDUCATION

<b>Ph.D. in Aeronautics and Astronautics</b> Massachusetts Institute of Technology, MA, USA	Sep. 2020 - Current <b>GPA: 5.00/5.00</b>
<b>M.S. in Electrical and Computer Engineering</b> University of California San Diego, CA, USA	Sep. 2017 - Mar. 2019 <b>GPA: 3.97/4.00</b>
<b>B.E. in Department of Automation</b> Tsinghua University, Beijing, China	Aug. 2013 - Jul. 2017 <b>GPA: 87/100, rank: top 30%</b>

## FIELD OF INTERESTS

Safety-assured autonomy; efficient video understanding; 3D reconstruction; visual odometry

## RESEARCH EXPERIENCE

<b>Research Assistant</b> , Massachusetts Institute of Technology, Cambridge, MA Advisor: Chuchu Fan, Department of Aeronautics and Astronautics <ul style="list-style-type: none"><li>– Safe and decentralized multi-agent planning for autonomous driving via control barrier functions</li><li>– Learning-based reachability distribution estimation via solving Liouville PDE</li></ul>	Sep. 2020 - Current
<b>AI Resident</b> , IBM Thomas J. Watson Research Center, NY, USA Advisor: Rogerio S. Feris, Research Manager <ul style="list-style-type: none"><li>– Efficient video understanding and few-shot learning</li></ul>	Sep. 2019 - Aug. 2020
<b>Research Intern</b> , Honda Research Institute, CA, USA Advisor: Yi-Ting Chen, Research Scientist <ul style="list-style-type: none"><li>– Proposed a bird’s-eye view representation for driving scene understanding</li></ul>	Mar. 2019 - Jun. 2019
<b>Research Assistant</b> , University of California San Diego, CA, USA Advisor: Nikolay A. Atanasov, Electrical and Computer Engineering <ul style="list-style-type: none"><li>– Developed semantic perception and tracking pipeline for 3D reconstruction</li><li>– Conducted research in object level 3D compression for mapping</li></ul>	Jan. 2018 - Mar. 2019
<b>Research Assistant</b> , University of California San Diego, CA, USA Advisor: Dinesh Bharadia, Tara Javidi, Electrical and Computer Engineering <ul style="list-style-type: none"><li>– Proposed semantic unsupervised learning framework for depth and flow estimation</li></ul>	Sep. 2018 - Dec. 2018
<b>Research Assistant</b> , Tsinghua University, Beijing, China Advisor: Li Li, Department of Automation <ul style="list-style-type: none"><li>– Designed a traffic simulation platform and analyzed cooperative driving strategies at intersections</li></ul>	Sep. 2015 - Jun. 2017

## PUBLICATIONS

- Y. Meng**, Z. Qin and C. Fan, “Reactive and Safe Road User Simulations using Neural Barrier Certificates”, in *IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS)*, 2021
- Y. Meng**, R. Panda, C. Lin, P. Sattigeri, L. Karlinsky, K. Saenko, A. Oliva and R. Feris, “AdaFuse: Adaptive Temporal Fusion Network for Efficient Action Recognition,” in *Int. Conf. on Learning Representations (ICLR)*, 2021
- Y. Meng**, C. Lin, R. Panda, P. Sattigeri, L. Karlinsky, K. Saenko, A. Oliva and R. Feris, “AR-Net: Adaptive Frame Resolution for Efficient Action Recognition,” in *European Conf. on Computer Vision (ECCV)*, 2020 (acceptance rate 27.0%)
- C. Li, **Y. Meng**, S. Chan and Y. Chen, “Learning 3D-aware Egocentric Spatial-Temporal Interaction via Graph Convolutional Networks,” in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2020
- Q. Feng, **Y. Meng**, M. Shan, and N. Atanasov, “Localization and Mapping using Instance-specific Mesh Models,” in *IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS)*, 2019
- Y. Meng**, Y. Lu, A. Raj, S. Sunarjo, G. Bansal, R. Guo, T. Javidi, and D. Bharadia, “SIGNet: Semantic Instance Aided Unsupervised 3D Geometry Perception,” in *IEEE Conf. on Computer Vision and Pattern Recognition (CVPR)*, 2019 (acceptance rate 25.2%)
- Y. Meng**, L. Li, F. Wang, K. Li, and Z. Li, “Analysis of Cooperative Driving Strategies for Nonsignalized Intersections,” *IEEE Transactions on Vehicular Technology (TVT)*, 67 (4), 2900-2911

## PREPRINTS

**Y. Meng, D. Sun, Z. Qiu, M. Waez and C. Fan**, “Learning Density Distribution of Reachable States for Autonomous Systems”

## TEACHING EXPERIENCE

**Teaching Assistant**, University of California, San Diego, CA, USA Jan. 2019 - Mar. 2019  
Instructor: Behrouz Touri, Electrical and Computer Engineering  
Course: Stochastic Processes in Dynamic Systems I

## PROFESSIONAL EXPERIENCE

**Software Engineering Intern**, Google Geo, Mountain View, CA, USA Jun. 2019 - Sep. 2019  
– Improved user-photo timestamp correction by using image content-based annotation  
**Software Engineering Intern**, Google Ads, New York, NY, USA Jun. 2018 - Sep. 2018  
– Migrated Ads prediction modules from Sibyl to Tensorflow platform  
**System Development Intern**, TuSimple, Beijing, China Jul. 2017 - Sep. 2017  
– Implemented Faster-RCNN for cameras on bus and optimized the pipeline by 40%

## TECHNICAL SKILLS

**Programming:** Python, C++, Matlab, Julia, C#  
**Tools:** Tensorflow, Pytorch, ROS, Git, Linux, Docker, Kubernetes, L<sup>A</sup>T<sub>E</sub>X  
**Languages:** Proficient in English and Chinese

## GRADUATE COURSES (ALL)

MIT

6.867	Machine Learning	<b>A+</b>
16.413	Principles of Autonomy and Decision Making	<b>A</b>
6.832	Underactuated Robotics	<b>A</b>
16.S398	Advanced Subject in Information and Control	<b>A</b>

UCSD

ECE272A	Stochastic Processes in Dynamic Systems I	<b>A+, 1/78</b>
ECE269	Linear Algebra and Applications	<b>A+, 1/191</b>
ECE276A	Sensing and Estimation in Robotics	<b>A, 3/113</b>
ECE273	Convex Optimization and Applications	<b>A, 4/107</b>
ECE271A	Statistical Learning I	<b>A+, 5/202</b>
CSE252A	Computer Vision I	<b>A+, 5/165</b>
CSE253	Neural Networks for Pattern Recognition	<b>A+, 6/212</b>
CSE254	Intrinsic Dimension and Dimension Reduction	<b>A, */18</b>
MATH245B	Convex Analysis and Optimization II	<b>A, */25</b>
ECE271C	Deep Learning and Applications	<b>A, 13/33</b>
MAE281A	Nonlinear Systems	<b>A-, 15/39</b>

## AWARDS AND HONORS

Study Scholarship of Tsinghua University, 2014, 2015  
Sports Scholarship of Tsinghua University, 2014, 2015  
1<sup>st</sup> awards in male 1500m, 4×800m, 4×400m races in Tsinghua Athletic Meeting  
Tsinghua high school male 3000m race **record holder (2012-Present)**