

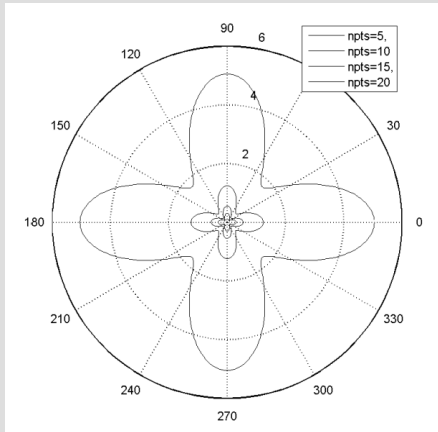
Questions

- Why Chebyshev?
- How about anisotropy?
- Are there also cases where Chebyshev is mixed with Fourier?
- What are the advantages and drawbacks with Chebyshev?

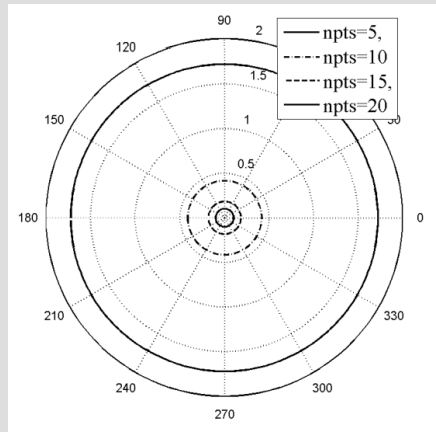
Repetition: Why pseudospectral method?

- reduced number of grid points and therefore less memory is required
- space-dependent fields are known exactly (up to machine precision) at the grid points
- no grid staggering required
- well suited for anisotropic problems
- mixed case (e.g. Tessmer (1995):
 - ▶ need for free surface condition on top boundary → Chebyshev
 - ▶ while horizontally no special boundary conditions are needed → Fourier (computationally easier than Chebyshev)
- avoids numerical anisotropy by the use of spectral derivatives

Numerical anisotropy



Numerical anisotropy from FD (picture from Igel, unpublished)



Numerical anisotropy from PS (picture from Igel, unpublished)

Why pseudospectral Chebyshev?

- implementation of boundary conditions like free-surface or non-reflecting boundaries
- ... with (almost) the same accuracy as within the medium

The acoustic 1D wave equation

$$\frac{\partial^2 p(x, t)}{\partial t^2} = \frac{\partial^2 p(x, t)}{\partial x^2} c(x)^2 + s(x, t)$$

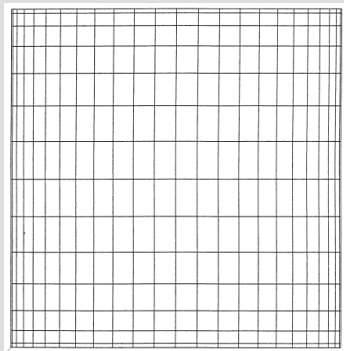
- L.h.s.: treated via FD ($\frac{p(x, t+dt) - 2p(x, t) + p(x, t-dt)}{dt^2}$)
- R.h.s: the spatial derivative is calculated using the Chebyshev polynomials T_n

Computational grid

- non uniform grid defined in the interval $[-1, 1]$
- field variables are defined on the Chebyshev (or Gauss-Lobatto) collocation points:

$$x_i = \cos\left(\frac{i\pi}{N}\right) \quad i = 0, \dots, N$$

- with N being the number of gridpoints per dimension
- resulting in a denser grid at the boundaries



Chebyshev collocation points in a 2D grid
(picture from Carcione and Wang (1993))

Chebyshev polynomials

- On this grid each field variable $u(x_i)$ ($x_i = \cos(\frac{i\pi}{N})$) is expanded as

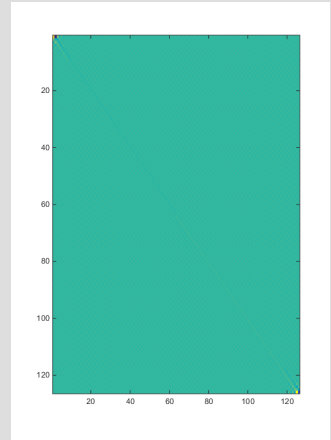
$$u(x_i) = \frac{1}{2}a_0 T_0(x_i) + \sum_{n=1}^N a_n T_n(x_i)$$

with Chebyshev polynomials $T_n(\cos(\frac{i\pi}{N})) = \cos(n\frac{i\pi}{N})$

- N.B.: Chebyshev polynomials form a set of orthogonal basis functions (analogous to the Fourier method)

Drawbacks with Chebyshev

- stretching of the grid near the boundaries required in order to fulfill a given stability criterion
- global communication of the spatial derivative difficult to implement on modern computer architectures
- application of characteristic variables (see e.g. Tessmer (1995)) require additional computational effort



Spatial derivative matrix

	Fourier	Chebyshev
collocation points	$x_i = \frac{2\pi}{N} i$	$x_i = \cos(\frac{\pi}{N} i)$
domain	periodic functions	limited area $[-1, 1]$
basis functions	$\cos(nx), \sin(nx)$	$T_n(x) = \cos(n\psi),$ $x = \cos(\psi)$
interpolating function	$f(x_i) = \frac{1}{2} a_0 + \frac{1}{2} a_m \cos(kx_i) + \sum_{k=1}^{m-1} (a_k \cos(kx_i) + b_k \sin(kx_i))$	$f(x_i) = \frac{1}{2} c_0 T_0 + \sum_{k=1}^m (c_k T_k(x_i))$
coefficients	$a_k = \frac{2}{N} \sum_{i=1}^N f(x_i) \cos(kx_i)$ $b_k = \frac{2}{N} \sum_{i=1}^N f(x_i) \sin(kx_i)$	$c_k = \frac{2}{N} \sum_{i=1}^N f(\cos(\psi_i)) \cos(k\psi_i)$

Chebyshev polynomials (cont.)

- The partial derivative of order q is given by:

$$\frac{\partial^q u(x)}{\partial x^q} = \sum_{n=0}^N a_n^{(q)} T_n(x)$$

with

$$c_0 = 2, \quad c_n = 1 \quad (n > 0)$$

and

$$c_{n-1} a_{n-1}^{(q)} - a_{n+1}^{(q)} = 2n a_n^{(q-1)} \quad (n \geq 1)$$

Chebyshev polynomials (cont.)

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