18.06 - Vinear algebra Tread Course Info · please do not use audio · ask any guestions via chat Maxowa will answer Course Admin = Jeremy Hahn excuses/absences/etc

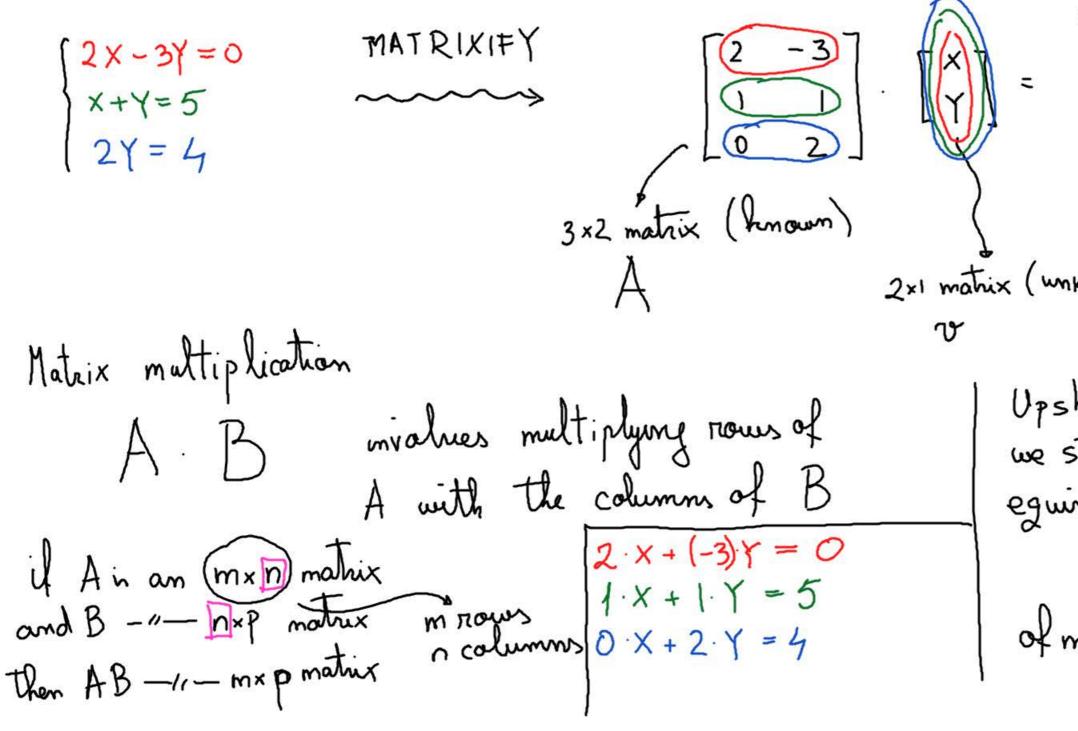
recitations + office hours must attend synchronously La the one you are enrolled (Theresa can help with sign-up) · if you want the in-person recitation, sign-up ASAP, because you must be enrolled in Covid Pass

TBA shortly through Canvos

coordinates )linear ephs language Linear Algebra geometric transformations how to use it how/why it works system of ~> 2.3-3.2=0 linear egris - SUBSTITION goal is to solve X=5-Y

(x,Y) = (3,2)

(x,Y)= (3,2) is the intersection of the lines



Upshot the system of egns we started off with is eguivalent with the single egn Av = b

nx1 matrix is called a (column) rector:  $v = \begin{vmatrix} v_1 \\ v_2 \end{vmatrix}$   $\Leftrightarrow$   $(v_1, v_2, ..., v_n) \in \mathbb{R}^n$  n-dimensional space Adding vectors of the same size  $v = \begin{bmatrix} v_1 \\ v_n \end{bmatrix}$  and  $v = \begin{bmatrix} v_1 \\ v_n \end{bmatrix}$ then  $v + w = \begin{bmatrix} v_1 \\ v_n \end{bmatrix}$   $v = \begin{bmatrix} v_1 \\ v_n \end{bmatrix}$  and  $c \in \mathbb{R}$  then  $cv = \begin{bmatrix} cv_1 \\ cv_n \end{bmatrix}$ Linear combination of XV+B.W Vectors V and W where &, B are coefficients of same numbers the linear combination

 $v = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$   $\omega = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$   $\epsilon \mathbb{R}^3$ real numbers, this  $dv + \beta w = \begin{bmatrix} d \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \beta \end{bmatrix} = \begin{bmatrix} d \\ 0 \\ \beta \end{bmatrix}$ traces out the XZ-plane in XYZ-space Fact: given two vectors, the set of their linear combinations traces out a plane , or Easier fact: given one vector, the C. V for some CER set of its linear combinations x v + p v = (x + p)vex:  $v = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ ,  $cv = \begin{bmatrix} c \\ 2c \end{bmatrix}$ 

$$A = \begin{cases} 2 - 3 \\ 1 & 1 \\ 0 & 2 \end{cases} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 - 3 \\ 1 & 1 \\ 0 & 2 \end{bmatrix} (x \begin{bmatrix} 1 \\ 0 \end{bmatrix} + Y \begin{bmatrix} 0 \\ 1 \end{bmatrix}) = \begin{cases} x \\ y \end{bmatrix} = x \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x \begin{bmatrix} 2 - 3 \\ 1 & 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = x \begin{bmatrix} 2 - 3 \\ 1 & 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = x \begin{bmatrix} 2 - 3 \\ 1 & 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = x \begin{bmatrix} 2 - 3 \\ 1 & 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = x \begin{bmatrix} 2 - 3 \\ 1 & 1 \\ 0 \end{bmatrix} = x \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} + x \begin{bmatrix} 2 - 3 \\ 1 & 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = x \begin{cases} 2 - 3 \\ 1 & 1 \\ 0 \end{bmatrix} = x \begin{cases} 2 - 3 \\ 1 & 1 \\ 0 \end{cases} = x \begin{cases} 2 - 3 \\ 1 & 1 \end{cases} = x \begin{cases} 2 - 3$$

Dot product 
$$v = \begin{cases} v_1 \\ v_n \end{cases} \quad w = \begin{bmatrix} \omega_1 \\ \omega_n \end{cases}$$

the number  $v \cdot w = v_1 \cdot w_1 + \cdots + v_n \cdot w_n$ 

$$v \cdot w = v_1 \cdot w_1 + \cdots + v_n \cdot w_n$$

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more generally; v.w gives you information about the angle O Letween v and w

$$v \cdot v = v_1^2 \cdot \dots + v_n^2 = ||v||^2$$

$$||v|| = \sqrt{v \cdot v}$$

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