

let V be the subspace spanned by vectors $v_1, \dots, v_n \in \mathbb{R}^m$

$$\{ \alpha_1 v_1 + \dots + \alpha_n v_n, \text{ for all real } \alpha_1, \dots, \alpha_n \in \mathbb{R} \}$$

a linear combination

But what if one of the vectors, say v_i , is a linear combination of the others, i.e.

$$v_i = \beta_1 v_1 + \dots + \beta_{i-1} v_{i-1} + \beta_{i+1} v_{i+1} + \dots + \beta_n v_n \quad \text{for some reals } \beta_1, \dots, \beta_n?$$

$$V = \{ \alpha_1 v_1 + \dots + \alpha_{i-1} v_{i-1} + \alpha_i (\beta_1 v_1 + \dots + \beta_{i-1} v_{i-1} + \beta_{i+1} v_{i+1} + \dots + \beta_n v_n) + \alpha_{i+1} v_{i+1} + \dots + \alpha_n v_n \}$$
$$= \{ \gamma_1 v_1 + \dots + \gamma_{i-1} v_{i-1} + \gamma_{i+1} v_{i+1} + \dots + \gamma_n v_n \}$$

\Rightarrow UPSHOT: V is actually spanned by $v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_n$

Def: vectors v_1, \dots, v_n are called **(linearly) independent** if none of them is a linear combination of the others

(they are called **linearly dependent** if one of them is a linear combination of the others)

independent: if $\alpha_1 v_1 + \dots + \alpha_n v_n \neq 0$ except if all the α 's are 0

dependent: there exists a relation $\alpha_1 v_1 + \dots + \alpha_n v_n = 0$ without the α 's being all 0

if a vector space V is spanned by a bunch of linearly dependent v_1, \dots, v_n

then you can remove some of the v_i 's such that the remaining ones are linearly independent and span the same vector space V

$$\alpha_1 v_1 + \dots + \alpha_n v_n = 0$$

assume $\alpha_i \neq 0$

$$\Rightarrow \alpha_i v_i = -\alpha_1 v_1 - \dots - \alpha_{i-1} v_{i-1} - \alpha_{i+1} v_{i+1} - \dots - \alpha_n v_n$$
$$\Downarrow$$
$$v_i = \frac{1}{\alpha_i} (-\alpha_1 v_1 - \dots - \alpha_{i-1} v_{i-1} - \alpha_{i+1} v_{i+1} - \dots - \alpha_n v_n)$$

$$V_1 = \begin{bmatrix} 2 \\ 5 \\ 1 \end{bmatrix}, \quad V_2 = \begin{bmatrix} 1 \\ -3 \\ -1 \end{bmatrix}$$

are they independent? **YES**

if they were dependent $\Rightarrow \alpha V_1 + \beta V_2 = 0 \Rightarrow V_1 = -\frac{\beta}{\alpha} V_2$
 \Rightarrow one is a multiple of the other \Rightarrow not true

what about V_1, V_2 and

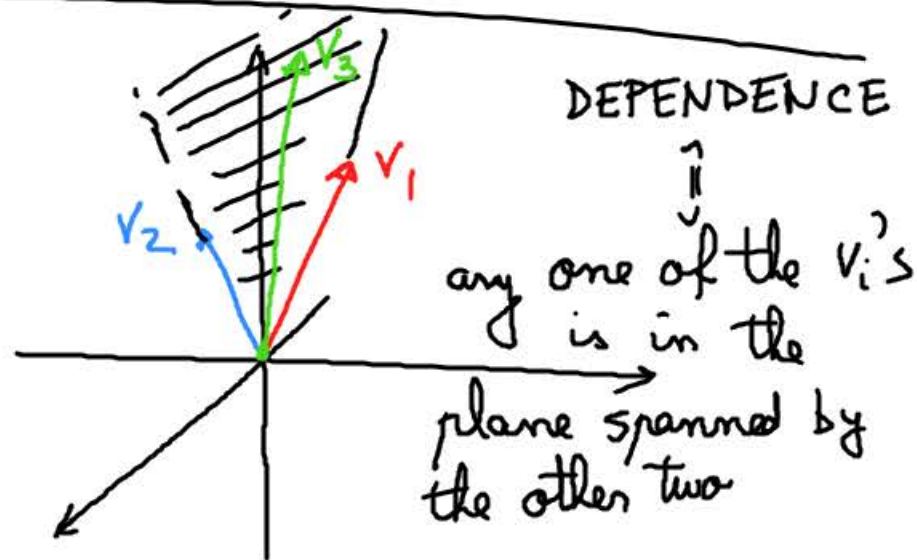
$$V_3 = \begin{bmatrix} 4 \\ -1 \\ -1 \end{bmatrix}; \quad \text{NO}$$

$$\left(\text{if } V_1 = C \cdot V_2 \Rightarrow \begin{bmatrix} 2 \\ 5 \\ 1 \end{bmatrix} = C \cdot \begin{bmatrix} 1 \\ -3 \\ -1 \end{bmatrix} \Rightarrow \begin{array}{l} C = 2 \\ C = -\frac{5}{3} \\ C = -1 \end{array} \begin{array}{l} \text{simult} \\ \text{aneously} \end{array} \right)$$

because there exists a linear relation

$$1 \cdot \begin{bmatrix} 2 \\ 5 \\ 1 \end{bmatrix} + 2 \cdot \begin{bmatrix} 1 \\ -3 \\ -1 \end{bmatrix} + (-1) \cdot \begin{bmatrix} 4 \\ -1 \\ -1 \end{bmatrix} = 0 \Rightarrow \left. \begin{array}{l} V_1 = -2V_2 + V_3 \\ V_2 = \frac{-V_1 + V_3}{2} \\ V_3 = V_1 + 2V_2 \end{array} \right\}$$

i.e. $1 \cdot V_1 + 2 \cdot V_2 + (-1) V_3 = 0$ relation



why $1 \cdot v_1 + 2 \cdot v_2 + (-1) \cdot v_3 = 0$?

suppose you want $\alpha, \beta, \gamma \in \mathbb{R}$ such that

Def: a **basis** of a vector space V is a collection of **linearly independent** vectors which span V

(ex: v_1, v_2 were a basis, but also v_2, v_3 were a basis but also v_1, v_3 were a basis)

Def: the **dimension** of V is the number of vectors that comprise any basis of V

$\dim(\text{line}) = 1$
 $\dim(\text{plane}) = 2$
 \vdots
 $\dim(\text{origin}) = 0$

$$\alpha v_1 + \beta v_2 + \gamma v_3 = 0$$

$$\begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix} \cdot \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = 0$$

$$\begin{bmatrix} 2 & 1 & 4 \\ 5 & -3 & -1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = 0 \iff \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} \in N(A)$$

Nullspaces are computed by Gauss-Jordan of A

if given v_1, \dots, v_n , how can you tell if they are dependent or not?

v_1, v_2, v_3 from before $\Rightarrow A = \begin{bmatrix} 2 & 1 & 4 \\ 5 & -3 & -1 \\ 1 & -1 & -1 \end{bmatrix}$

\downarrow REF

$U = \begin{bmatrix} \boxed{2} & 1 & 4 \\ 0 & \boxed{-5.5} & -11 \\ 0 & 0 & 0 \end{bmatrix}$

\downarrow RREF

at most 2 pivots
at most 2 pivot rows
at least 1 free var

you can always find
 α, β, γ not all 0 such
that $U \cdot \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = 0$
(A)

exists $\alpha_1 v_1 + \dots + \alpha_n v_n = 0$

$A \cdot \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} = 0$

where $A = [v_1 | \dots | v_n]$

dependent if $N(A) \neq 0$
independent if $N(A) = 0$

Fact: $\text{rank} = \dim C(A)$
 \parallel
(# of pivots of A in (R)REF)

i.e. $\text{rank}(A) = \text{rank}(R)$

its reduced row echelon form

every column of
 A is a linear
combination of
its pivot columns

$$R = \begin{bmatrix} \boxed{1} & * & 0 & \textcircled{*} & 0 \\ 0 & 0 & 0 & \textcircled{0} & 0 \\ 0 & 0 & \boxed{1} & \textcircled{*} & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \boxed{1} \end{bmatrix}$$

all the non-pivot columns
are linear combinations
of the pivot columns

2 ways to present a subspace $V =$ spanned by v_1, \dots, v_n
 \parallel
 cut out by some equations

how do we go from one presentation to the other?

Ex: $V = \left\{ \begin{array}{l} 2x - 2y - 6z - 4t = 0 \\ 5x + y - 3z + 8t = 0 \\ -3x + 2y + 7z + 3t = 0 \end{array} \right\} \subset \mathbb{R}^4 \quad \rightsquigarrow \begin{bmatrix} 2 & -2 & -6 & -4 \\ 5 & 1 & -3 & 3 \\ -3 & 2 & 7 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = 0$

expect V to be a line in \mathbb{R}^4
 not so fast!

i.e. $V = N(A)$

I want a basis of $V = N(A)$

$$A \xrightarrow{\text{RREF}} R = \begin{bmatrix} \boxed{1} & 0 & -1 & 1 \\ 0 & \boxed{1} & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{cases} x = z - t \\ y = -2z - 3t \end{cases} \iff R \cdot \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = 0$$

pivot vars (pointing to x and y)
free vars (pointing to z and t)

solve for x, y

; a basis of $N(A)$ is given
 by setting one of the free variables = 1
 and all other free variables = 0

$$V_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} \quad V_2 = \begin{bmatrix} -1 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

a basis of $V \Rightarrow \dim V = 2$.