COSE474-2024F: DEEP LEARNING HW1

2022320338 데이터과학과 신민서

0.1 Installation

1 !pip install d2l==1.0.3

```
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        Downloading d2l-1.0.3-py3-none-any.whl.metadata (556 bytes)
     Collecting jupyter==1.0.0 (from d2l==1.0.3)
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google-colab 1.0.0 requires requests==2.32.3, but you have requests 2.31.0 which is incompatible.
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pandas-stubs 2.1.4.231227 requires numpy>=1.26.0; python_version < "3.13", but you have numpy 1.23.5 which is incompa
plotnine 0.13.6 requires pandas<3.0.0,>=2.1.0, but you have pandas 2.0.3 which is incompatible.
xarray 2024.9.0 requires numpy>=1.24, but you have numpy 1.23.5 which is incompatible.
xarray 2024.9.0 requires pandas>=2.1, but you have pandas 2.0.3 which is incompatible.
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WARNING: The following packages were previously imported in this runtime:
    [matplotlib, matplotlib_inline, mpl_toolkits, numpy]
You must restart the runtime in order to use newly installed versions.
```

2.1 Data Manipulation

2.1.1. Getting Started

```
1 import torch
 1 x = torch.arange(12, dtype=torch.float32)
 2 #arange function returns 1-dimensinal tensor of specified range
 3 x #x vectors
→ tensor([ 0., 1., 2., 3., 4., 5., 6., 7., 8., 9., 10., 11.])
 1 x.numel() #number of elements
→ 12
 1 x.shape #shape of vector
→ torch.Size([12])
 1 X = x.reshape(3, 4)
 2 X #X is a 3x4 matrix
1 X.shape #shape of matrix
→ torch.Size([3, 4])
 1 torch.zeros((2,3,4)) #zero matrix, tensor
→ tensor([[[0., 0., 0., 0.],
              [0., 0., 0., 0.],
[0., 0., 0., 0.]],
             [[0., 0., 0., 0.],
[0., 0., 0., 0.],
[0., 0., 0., 0.]]])
 1 torch.ones((2,3,4)) #one matrix, tensor
[[1., 1., 1., 1.],
              [1., 1., 1., 1.],
[1., 1., 1., 1.]])
 1 torch.randn(3,4) #randomly distributed from standard Gaussian (normal) distribution
→ tensor([[ 1.1764, 0.0816, -0.8972, 0.5053],
             [-0.0864, 0.4782, 0.0743, -0.2758],
[ 0.3064, -1.9109, -0.5629, 0.0577]])
 1 torch.tensor([[2,1,4,3],[1,2,3,4],[4,3,2,1]]) #assign exact values
→ tensor([[2, 1, 4, 3],
             [1, 2, 3, 4],
[4, 3, 2, 1]])
2.1.2. Indexing and Slicing (Discussion)
```

X[start:stop] includes start, but not stop

```
1 X[-1], X[1:3] #last row, second and third row
```

```
1 \times [1,2] = 17
 2 X #assign value
→ tensor([[ 0., 1., 2., 3.], [ 4., 5., 17., 7.],
                [8., 9., 10., 11.]])
 1 X[:2, :] = 12 #row 1,2 and all columns
 2 X

    tensor([[12., 12., 12., 12.],
                [12., 12., 12., 12.],
                [8., 9., 10., 11.]])
2.1.3. Operations
 1 torch.exp(x)
tensor([162754.7969, 162754.7969, 162754.7969, 162754.7969, 162754.7969,
                162754.7969, 162754.7969, 162754.7969,
                                                                2980.9580, 8103.0840,
                22026.4648, 59874.1406])
 1 x = torch.tensor([1.0, 2, 4, 8])
 2 y = torch.tensor([2,2,2,2,])
 3 x+y, x-y, x*y, x/y, x**y #elementwise computation
tensor([3., 4., 6., 10.]),
tensor([-1., 0., 2., 6.]),
tensor([2., 4., 8., 16.]),
tensor([0.5000, 1.0000, 2.0000, 4.0000]),
       tensor([ 1., 4., 16., 64.]))
 1 #concatenate multiple tensors
 2 X = torch.arange(12, dtype=torch.float32).reshape((3,4))
 3 Y = torch.tensor([[2.0, 1, 4, 3], [1,2,3,4,],[4,3,2,1]])
 4 torch.cat((X,Y), \dim=0), torch.cat((X,Y),\dim=1)
 5 #dim=0 concatenate along rows (stack the rows)
 6 #dim=1 concatenate along columns
(tensor([[ 0., 1., 2., 3.], [ 4., 5., 6., 7.], [ 8., 9., 10., 11.], [ 2., 1., 4., 3.],
       [ 1., 2., 3., 4.],

[ 4., 3., 2., 1.]]),

tensor([[ 0., 1., 2., 3., 2., 1., 4., 3.],

[ 4., 5., 6., 7., 1., 2., 3., 4.],

[ 8., 9., 10., 11., 4., 3., 2., 1.]]))
 1 X == Y \text{ #same number at [i,j] then True}
→ tensor([[False, True, False, True],
                [False, False, False, False], [False, False, False, False, False, False, False])
 1 X.sum() #sum all elements
→ tensor(66.)
2.1.4. Broadcasting
```

→ 2.1.4. Discussion

- · can use broadcasting when shapes differ
- · the tensor with fewer dimensions is padded until dimension matches
- a: (3,1), b: (1,2),

```
• since a has 1 column, it is streched to match b's columns
   · a is stretch as
     [0,0],
     [1,1],
     [2,2]
 1 = \text{torch.arange}(3).\text{reshape}((3,1)) #3x1 shape
 2 b = torch.arange(2).reshape((1,2)) #1x2 shape
 3 a,b
→ (tensor([[0],
              [1],
              [2]])
      tensor([[0, 1]]))
2.1.5. Saving Memory
 1 \text{ before} = id(Y)
 2 Y = Y+X
 3 id(Y) == before #points to different memory address
→ False
   · we can use in-place operation to save memory
 1 Z = torch.zeros_like(Y) #creates tensor X with the same shape as Y
 2 print('id(Z):', id(Z)) #prints address of tensor Z
 3\ Z[:] = X + Y #slice all the elements of Z, assign X+Y to this slice
 4 print('id(Z):', id(Z)) #updates the new values directly to Z
→ id(Z): 133390961148128
     id(Z): 133390961148128
 1 \text{ before} = id(X)
 2 X += Y
 3 id(X) == before
→ True
2.1.6. Conversion to other Python Objects (Discussion)
Python libraries for multi-dimensional arrays (tensors)
   • NumPy (ndarray)
   • PyTorch (torch.Tensor)
 1 A = X.numpy()
 2 B = torch.from_numpy(A)
 3 type(A), type(B)
(numpy.ndarray, torch.Tensor)
 1 a = torch.tensor([3.5])
 2 a, a.item(), float(a), int(a) #convert to python scalar
```

2.2 Data Preprocessing

2.2.1. Reading the Dataset

```
1 import os
3 os.makedirs(os.path.join('...', 'data'), exist_ok=True)
4 data_file = os.path.join('...', 'data', 'house_tiny.csv')
5 with open(data_file, 'w') as f:
       f.write('''NumRooms,RoofType,Price
7 NA, NA, 127500
 8 2,NA,106000
9 4, Slate, 178100
10 NA,NA,140000''')
1 import pandas as pd
3 data = pd.read_csv(data_file)
4 print(data)
                                 Price
\overline{z}
        NumRooms RoofType
     0
              NaN
                         NaN 127500
     1
              2.0
                         NaN
                               106000
               4.0
                       Slate
                               178100
     3
              NaN
                         NaN
                               140000
```

2.2.2. Data Preparation (Discussion)

- supervised learning: trai models to predict a target value given some input values
- NaN are missing values, which we want to handle it via imputation or deletion
- · iloc: integer-location based indexing
- · RoofType originally consists of Slate and NaN
- convert this into 2 columns: RoofType_slate and Rooftype_NaN by True/false
- use pd.get_dummies to convert categorical data into numerical data (0,1)

```
1 inputs, targets = data.iloc[:, 0:2], data.iloc[:, 2] #target selects third column
2 inputs = pd.get_dummies(inputs, dummy_na=True)
3 print(inputs)
                 RoofType_Slate RoofType_nan
\overline{\Sigma}
       NumRooms
    0
            NaN
                           False
                                           True
    1
            2.0
                           False
                                           True
    2
            4.0
                            True
                                          False
    3
            NaN
                           False
                                           True
1 inputs = inputs.fillna(inputs.mean()) #replace NaN with mean value
2 print(inputs)
```

```
RoofType_Slate RoofType_nan
\overline{z}
       NumRooms
    a
             3.0
                             False
                                              True
    1
             2.0
                             False
                                              True
    2
                              True
                                             False
    3
             3.0
                             False
                                              True
```

2.2.3. Conversion to the Tensor Format

2.2 Discussion

· We can now load datasets into tensors and manipulate them with basic mathematical operations

2.3 Linear Algebra

```
→ 2.3.1. Scalars (Discussion)
```

```
x \in \mathbb{R}
x is a real-values scalars

1 import torch

1 x = \text{torch.tensor}(3.0)
2 y = \text{torch.tensor}(2.0)
3 x+y, x*y, x/y, x**y

\Rightarrow (tensor(5.), tensor(6.), tensor(1.5000), tensor(9.))
```

2.3.2. Vectors (Discussion)

• real world application: e.g. when training a model to predict the risk of a loean defaulting, each applicant can have a vector whose components correspond to quantities like income, length of employment, etc.

```
1 \times = torch.arange(3)
→ tensor([0, 1, 2])
x_2 denotes second element of x (scalar)
 1 x[2]
→ tensor(2)
 1 len(x)
→ 3
 1 x.shape
→ torch.Size([3])
2.3.3. Matrices
 1 A = torch.arange(6).reshape(3,2)
1 A.T #transpose
tensor([[0, 2, 4], [1, 3, 5]])
 1 A = torch.tensor([[1,2,3],[2,0,4],[3,4,5]])
 2 A == A.T
tensor([[True, True, True],
[True, True, True],
[True, True, True]])
```

y 2.3.4. Tensors (Discussion)

- use tensors for nth-order arrays
- · e.g. image can be represented in 3rd-order array: height, width, channel

```
1 torch.arange(24).reshape(2,3,4)
```

```
[[12, 13, 14, 15],
           [16, 17, 18, 19],
[20, 21, 22, 23]]])
```

2.3.5. Basic Properties of Tensor Arithmetic

```
1 A = torch.arange(6, dtype=torch.float32).reshape(2,3)
 2 B = A.clone() #copy A to B by allocating new memory
 3 A, A+B
→ (tensor([[0., 1., 2.],
      [3., 4., 5.]]),
tensor([[ 0., 2., 4.],
  [ 6., 8., 10.]]))
   · Hadamard product of two matrices
 1 A * B
⇒ tensor([[ 0., 1., 4.], [ 9., 16., 25.]])
 1 a = 2
 2 X = torch.arange(24).reshape(2,3,4)
 3 a + X, (a * X).shape
(tensor([[[ 2, 3, 4, 5], [ 6, 7, 8, 9], [10, 11, 12, 13]],
              [[14, 15, 16, 17],
               [18, 19, 20, 21],
[22, 23, 24, 25]]]),
      torch.Size([2, 3, 4]))
2.3.6. Reduction
 1 x = torch.arange(3, dtype=torch.float32)
 2 x, x.sum() #add all the elements in vector x
1 A.shape, A.sum() #sum of elements of mxn matrix A
→ (torch.Size([2, 3]), tensor(15.))
 1 A.shape, A.sum(axis=0).shape #sum along the rows (Axis 0)
→ (torch.Size([2, 3]), torch.Size([3]))
 1 A.shape, A.sum(axis=1).shape #sum along the columns (axis 1)
→ (torch.Size([2, 3]), torch.Size([2]))
 1 \text{ A.sum}(axis=[0,1]) == A.sum() \#same
→ tensor(True)
 1 A.mean(), A.sum()/A.numel() #mean
→ (tensor(2.5000), tensor(2.5000))
 1 A.mean(axis=0), A.sum(axis=0)/A.shape[0]
(tensor([1.5000, 2.5000, 3.5000]), tensor([1.5000, 2.5000, 3.5000]))
```

2.3.7. Non-Reduction Sum

```
1 sum_A = A.sum(axis=1, keepdims=True)
 2 sum_A, sum_A.shape
→ (tensor([[ 3.],
             [12.]]).
     torch.Size([2, 1]))
 1 A / sum_A #broadcasting
→ tensor([[0.0000, 0.3333, 0.6667],
            [0.2500, 0.3333, 0.4167]])
 1 A.cumsum(axis=0) #cumulative sum of elements A along axis 0
⇒ tensor([[0., 1., 2.], [3., 5., 7.]])
2.3.8. Dot Products
 1 y = torch.ones(3, dtype = torch.float32)
 2 x, y, torch.dot(x,y)
→ (tensor([0., 1., 2.]), tensor([1., 1., 1.]), tensor(3.))
 1 torch.sum(x*y) #equivalent to dot product
→ tensor(3.)
2.3.9. Matrix-Vector Products (Discussion)
   • torch.mv(A,x): matrix-vector multiplication
   • A@x is short-hand python operator for mv
 1 A.shape, x.shape, torch.mv(A,x), A@x

    2.3.10. Matrix-Matrix Multiplication

 1 B = torch.ones(3,4)
 2 torch.mm(A,B), A@B
tensor([[ 3., 3., 3., 3.], [12., 12., 12., 12.]]))

→ 2.3.11. Norms (Discussion)

   · norm of a vector tells us how big it is
 1 u = torch.tensor([3.0, -4.0])
 2 torch.norm(u)
\rightarrow tensor(5.)
 1 torch.abs(u).sum()
\rightarrow tensor(7.)
 1 torch.norm(torch.ones((4,9)))
→ tensor(6.)
```

2.3 Discussion

- · we can now use linear algebra to deal with basic mathematical objects like scalars, vectors, matrices, tensors
- Tensors can be sliced or reduced along axis0/1, via indexing or operations
- · Hadamard products
- · matrix-matrix products

2.5 Automatic Differentiation

- 2.5.1. A Simple Function (Discussion)
 - goal: differentiate $y = 2x^Tx$ with respect to column vector x

$$y=2\sum_{i=1}^n x_i^2 \qquad \qquad y=2x^Tx_i$$

$$x^Tx=x_1^2+x_2^2+\cdots+x_n^2$$

```
1 \times = torch.arange(4.0)
\rightarrow tensor([0., 1., 2., 3.])
1 x.requires_grad_(True) #need a place to store gradient of y
2 # x=torch.arange(4.0, requires_grad=True)로도 가능
3 x.grad #default value is None
1 y = 2 * torch.dot(x,x)
2 y
tensor(28., grad_fn=<MulBackward0>)
1 \text{ y.backward()} #take the gradient of y with respect to x
2 x.grad
→ tensor([ 0., 4., 8., 12.])
1 \times grad == 4 \times x
→ tensor([True, True, True, True])
1 x.grad.zero_()
2 y=x.sum()
3 y.backward()
4 x.grad
\rightarrow tensor([1., 1., 1., 1.])
```

2.5.2. Backward for Non-Scalar Variables

```
1 x.grad.zero_()
2 y = x*x
3 y.backward(gradient=torch.ones(len(y))) #Faster: y.sum().backward()
4 x.grad

tensor([0., 2., 4., 6.])
```

2.5.3. Detaching Computation

```
1 x.grad.zero_()
2 y = x*x
3 u = y.detach()
4 z = u*x
5
6 z.sum().backward()
7 x.grad == u

tensor([True, True, True, True])

1 x.grad.zero_()
2 y.sum().backward()
3 x.grad == 2*x

tensor([True, True, True, True])
```

2.5.4. Gradients and Python Control Flow

```
1 def f(a):
2   b = a*2
3   while b.norm() <1000:
4   b = b*2
5   if b.sum() > 0:
6   c = b
7   else: c = 100*b
8   return c

1 a = torch.randn(size=(), requires_grad=True)
2 d = f(a)
3 d.backward()

1 a.grad == d/a

tensor(False)
```

2.5 Discussion

- · we can now compute differentiation of functions using python tools
- 1. attach gradients to those variables with respect to which we desire derivaties
- 2. record the computation of the target value
- 3. execute the backpropagation function
- 4. access the resulting gradient
- · this can come handy when optimizing models

3.1 Linear Regression

→ 3.1.2. Vectorization for Speed

```
1 %matplotlib inline
2 import math
3 import time
4 import numpy as np
5 import torch
6 from d2l import torch as d2l

1 n = 10000 #10000-dimensional vectors
2 a = torch.ones(n)
3 b = torch.ones(n)
1 c = torch.zeros(n)
2 t = time.time()
```

```
3 for i in range(n):

4  c[i] = a[i] + b[i]

5 f'{time.time() - t:.5f} sec'

→ '0.13676 sec'

1 t = time.time()

2 d = a + b

3 f'{time.time() - t:.5f} sec' #faster method

→ '0.00130 sec'
```

→ 3.1.3. The Normal distribution and squared loss

• Note that changing the mean corresponds to a shift along the axis, and increasing the variance spreads the distribution out, lowering its peak.

3.1 Discussion

0.0

· we now can interpret traditional linear regression, and how linear models could be represented by simple neural networks

3.2 Object-Oriented Design for Implementation

```
1 import time
2 import numpy as np
3 import torch
4 from torch import nn
5 from d2l import torch as d2l
```

→ 3.2.1. Utilities

```
1 def add_to_class(Class):
2   def wrapper(obj):
3    setattr(Class, obj.__name__, obj)
4   return wrapper

1 class A:
2   def __init__(self):
3    self.b = 1
4   5 a = A()
```

```
1 @add_to_class(A)
2 def do(self):
    print('Class attribute "b" is', self.b)
3
5 a.do()

    Class attribute "b" is 1

1 class HyperParameters:
   def save_hyperparameters(self, ignore=[]):
      raise NotImplemented
1 class B(d2l.HyperParameters):
   def __init__(self, a, b, c):
       self.save_hyperparameters(ignore=['c'])
       print('self.a =', self.a, 'type:', type(self.a))
       print('There is no self.c = ', not hasattr(self, 'c'))
5
7 b = B(a=1, b=2, c=3)
⇒ self.a = 1 type: <class 'int'>
    There is no self.c = True
1 class ProgressBoard(d2l.HyperParameters):
     def __init__(self, xlabel=None, ylabel=None, xlim=None,
3
                   ylim=None, xscale='linear', yscale='linear',
                   ls=['-', '--', '-.', ':'], colors=['C0', 'C1', 'C2', 'C3'], fig=None, axes=None, figsize=(3.5, 2.5), display=True):
4
5
6
       self.save_hyperparameters()
7
     def draw(self, x, y, label, every_n=1):
8
         raise NotImplemented
1 board = d2l.ProgressBoard('x')
2 for x in np.arange(0, 10, 0.1):
    board.draw(x, np.sin(x), 'sin', every_n=2)
board.draw(x, np.cos(x), 'cos', every_n=10)
\overline{z}
       1.0
       0.5
       0.0
      -0.5
                                          sin
      -1.0
            0
                   2
                                6
                                      8
                                            10
```

→ 3.2.2. Models

```
1 class Module(nn.Module, d2l.HyperParameters):
       """The base class of models."""
 2
       def __init__(self, plot_train_per_epoch=2, plot_valid_per_epoch=1):
 3
 4
           super().__init__()
 5
           self.save_hyperparameters()
 6
           self.board = ProgressBoard()
 7
 8
       def loss(self, y_hat, y):
 9
           raise NotImplementedError
10
11
       def forward(self, X):
           assert hasattr(self, 'net'), 'Neural network is defined'
12
13
           return self.net(X)
14
15
       def plot(self, key, value, train):
           """Plot a point in animation."""
16
           assert hasattr(self, 'trainer'), 'Trainer is not inited'
self.board.xlabel = 'epoch'
17
18
19
           if train:
20
               x = self.trainer.train_batch_idx / \
21
                    self.trainer.num_train_batches
22
               n = self.trainer.num_train_batches / \
```

```
23
                    self.plot_train_per_epoch
24
           else:
25
               x = self.trainer.epoch + 1
26
               n = self.trainer.num_val_batches / \
                    self.plot_valid_per_epoch
27
28
           self.board.draw(x, value.to(d2l.cpu()).detach().numpy(),
29
                            ('train_' if train else 'val_') + key,
30
                            every_n=int(n))
31
32
       def training_step(self, batch):
33
           l = self.loss(self(*batch[:-1]), batch[-1])
34
           self.plot('loss', l, train=True)
35
           return l
36
37
       def validation_step(self, batch):
38
           l = self.loss(self(*batch[:-1]), batch[-1])
           self.plot('loss', l, train=False)
39
40
41
       def configure_optimizers(self):
42
           raise NotImplementedError
  3.2.3. Data
 1 class DataModule(d2l.HyperParameters):
       """The base class of data."""
 3
       def __init__(self, root='../data', num_workers=4):
 4
           self.save_hyperparameters()
 5
 6
       def get_dataloader(self, train):
           raise NotImplementedError
 7
 8
 9
       def train_dataloader(self):
10
           return self.get_dataloader(train=True)
11
12
       def val_dataloader(self):
13
           return self.get_dataloader(train=False)
3.2.4. Training
 1 class Trainer(d2l.HyperParameters):
       """The base class for training models with data."""
       \label{lem:condition} \mbox{def $\_$init$\_(self, max\_epochs, num\_gpus=0, gradient\_clip\_val=0):}
 3
 4
           self.save_hyperparameters()
 5
           assert num_gpus == 0, 'No GPU support yet'
 6
       def prepare_data(self, data):
 8
           self.train_dataloader = data.train_dataloader()
 9
           self.val_dataloader = data.val_dataloader()
10
           self.num_train_batches = len(self.train_dataloader)
11
           self.num_val_batches = (len(self.val_dataloader)
12
                                     if self.val_dataloader is not None else 0)
13
       def prepare_model(self, model):
14
15
           model.trainer = self
16
           model.board.xlim = [0, self.max_epochs]
           self.model = model
17
18
19
       def fit(self, model, data):
20
           self.prepare_data(data)
21
           self.prepare_model(model)
22
           self.optim = model.configure_optimizers()
23
           self.epoch = 0
24
           self.train_batch_idx = 0
25
           self.val_batch_idx = 0
26
           for self.epoch in range(self.max_epochs):
27
               self.fit_epoch()
28
29
       def fit_epoch(self):
```

4.1 Softmax Regression (Discussion)

raise NotImplementedError

30

 optimizing over discrete output spaces using probabilistic approach and treating the categories as instances of draws from a probability distribution

4.2 The Image Classification Dataset

```
1 %matplotlib inline
  2 import time
  3 import torch
  4 import torchvision
  5 from torchvision import transforms
  6 from d2l import torch as d2l
 8 d2l.use_svg_display()

    4.2.1. Loading the Dataset

  1 class FashionMNIST(d2l.DataModule):
         """The Fashion-MNIST dataset."""
  3
         def __init__(self, batch_size=64, resize=(28, 28)):
  4
              super().__init__()
  5
              self.save_hyperparameters()
  6
             trans = transforms.Compose([transforms.Resize(resize),
  7
                                                   transforms.ToTensor()])
 8
             self.train = torchvision.datasets.FashionMNIST(
 9
                   root=self.root, train=True, transform=trans, download=True)
10
              self.val = torchvision.datasets.FashionMNIST(
                   root=self.root, train=False, transform=trans, download=True)
  1 data = FashionMNIST(resize=(32, 32))
 2 len(data.train), len(data.val)
      Downloading http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx3-ubyte.gz
      Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx3-ubyte.gz">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-images-idx3-ubyte.gz</a> to ../data/Fashion!
                       26421880/26421880 [00:07<00:00, 3447323.46it/s]
      Extracting ../data/FashionMNIST/raw/train-images-idx3-ubyte.gz to ../data/FashionMNIST/raw
      Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-labels-idx1-ubyte.gz">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-labels-idx1-ubyte.gz</a>
      Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-labels-idx1-ubyte.gz">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/train-labels-idx1-ubyte.gz</a> to ../data/Fashion
                      29515/29515 [00:00<00:00, 324950.80it/s]
      \texttt{Extracting ...} / \texttt{data/FashionMNIST/raw/train-labels-idx1-ubyte.gz to ...} / \texttt{data/FashionMNIST/raw/train-labels-idx1-ubyte.gz} \\
      Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-images-idx3-ubyte.gz">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-images-idx3-ubyte.gz</a>
      Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-images-idx3-ubyte.gz">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-images-idx3-ubyte.gz</a> to ../data/FashionMI 100%|
      Extracting ../data/FashionMNIST/raw/t10k-images-idx3-ubyte.gz to ../data/FashionMNIST/raw
      Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-labels-idx1-ubyte.gz">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-labels-idx1-ubyte.gz</a>
      Downloading <a href="http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-labels-idx1-ubyte.gz">http://fashion-mnist.s3-website.eu-central-1.amazonaws.com/t10k-labels-idx1-ubyte.gz</a> to ../data/FashionMi
                       ■ 5148/5148 [00:00<00:00, 4871903.65it/s]Extracting ./data/FashionMNIST/raw/t10k-labels-idx1-ubyte.g
      (60000, 10000)
  1 data.train[0][0].shape
 → torch.Size([1, 32, 32])
  1 torch.Size([1, 32, 32])
→ torch.Size([1, 32, 32])
 1 @d2l.add_to_class(FashionMNIST)
  2 def text_labels(self, indices):
         """Return text labels."""
         5
```

4.2.2. Reading a Minibatch

```
1 @d2l.add_to_class(FashionMNIST)
2 def get_dataloader(self, train):
```

return [labels[int(i)] for i in indices]

```
3
      data = self.train if train else self.val
 4
      return torch.utils.data.DataLoader(data, self.batch_size, shuffle=train,
 5
                                      num_workers=self.num_workers)
 1 X, y = next(iter(data.train_dataloader()))
 2 print(X.shape, X.dtype, y.shape, y.dtype)
warnings.warn(_create_warning_msg(
    torch.Size([64, 1, 32, 32]) torch.float32 torch.Size([64]) torch.int64
 1 tic = time.time()
 2 for X, y in data.train_dataloader():
     continue
 4 f'{time.time() - tic:.2f} sec'
→ '15.23 sec'

    4.2.3. Visualization

 1 def show_images(imgs, num_rows, num_cols, titles=None, scale=1.5):
2 """Plot a list of images."""
      raise NotImplementedError
 3
 1 @d2l.add_to_class(FashionMNIST)
 2 def visualize(self, batch, nrows=1, ncols=8, labels=[]):
 3
      X, y = batch
      if not labels:
 5
          labels = self.text_labels(y)
      d2l.show_images(X.squeeze(1), nrows, ncols, titles=labels)
 7 batch = next(iter(data.val_dataloader()))
```

ankle boot pullover trouser trouser shirt trouser coat shirt

ankle boot pullover trouser trouser shirt trouser coat shirt

4.2 Discussion

8 data.visualize(batch)

- · using the Fashion-MNIST dataset, we have classified into 10 categories
- · there is just one channel as the images are grayscale

4.3 The Base Classification Model


```
1 @d2l.add_to_class(Classifier)
2 def accuracy(self, Y_hat, Y, averaged=True):
3 """Compute the number of correct predictions."""
4 Y_hat = Y_hat.reshape((-1, Y_hat.shape[-1]))
```

```
preds = Y_hat.argmax(axis=1).type(Y.dtype)
compare = (preds == Y.reshape(-1)).type(torch.float32)
return compare.mean() if averaged else compare
```

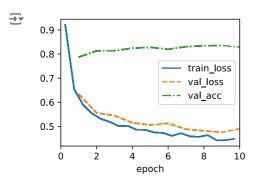
4.4 Softmax Regression Implementation from Scratch

4.4.1 .The Softmax

```
1 X = torch.tensor([[1.0, 2.0, 3.0], [4.0, 5.0, 6.0]])
 2 X.sum(0, keepdims=True), X.sum(1, keepdims=True)
→ (tensor([[5., 7., 9.]]),
      tensor([[ 6.],
              [15.]]))
 1 def softmax(X):
       X_{exp} = torch.exp(X)
       partition = X_exp.sum(1, keepdims=True)
       return X_{exp} / partition # The broadcasting mechanism is applied here
 1 X = torch.rand((2, 5))
 2 X_prob = softmax(X)
 3 X_prob, X_prob.sum(1)
(tensor([[0.1647, 0.1440, 0.1487, 0.3321, 0.2106], [0.1333, 0.1750, 0.2688, 0.1655, 0.2574]]),
      tensor([1.0000, 1.0000]))
1 class SoftmaxRegressionScratch(d2l.Classifier):
       def __init__(self, num_inputs, num_outputs, lr, sigma=0.01):
 3
           super().__init__()
 4
           self.save_hyperparameters()
 5
           self.W = torch.normal(0, sigma, size=(num_inputs, num_outputs),
 6
                                 requires_grad=True)
           self.b = torch.zeros(num_outputs, requires_grad=True)
 8
 9
       def parameters(self):
10
           return [self.W, self.b]
 1 @d2l.add_to_class(SoftmaxRegressionScratch)
 2 def forward(self, X):
       X = X.reshape((-1, self.W.shape[0]))
       return softmax(torch.matmul(X, self.W) + self.b)
1 y = torch.tensor([0, 2])
 2 y_hat = torch.tensor([[0.1, 0.3, 0.6], [0.3, 0.2, 0.5]])
 3 y_hat[[0, 1], y]
→ tensor([0.1000, 0.5000])
 1 def cross_entropy(y_hat, y):
       return -torch.log(y_hat[list(range(len(y_hat))), y]).mean()
 4 cross_entropy(y_hat, y)
→ tensor(1.4979)
 1 @d2l.add_to_class(SoftmaxRegressionScratch)
 2 def loss(self, y_hat, y):
       return cross_entropy(y_hat, y)
```

4.4.4. training

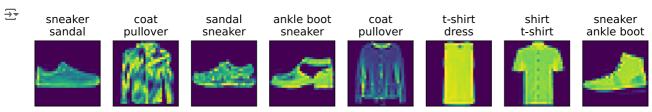
```
1 data = d2l.FashionMNIST(batch_size=256)
2 model = SoftmaxRegressionScratch(num_inputs=784, num_outputs=10, lr=0.1)
3 trainer = d2l.Trainer(max_epochs=10)
4 trainer.fit(model, data)
```




```
1 X, y = next(iter(data.val_dataloader()))
2 preds = model(X).argmax(axis=1)
3 preds.shape

   torch.Size([256])

1 wrong = preds.type(y.dtype) != y
2 X, y, preds = X[wrong], y[wrong], preds[wrong]
3 labels = [a+'\n'+b for a, b in zip(
4    data.text_labels(y), data.text_labels(preds))]
5 data.visualize([X, y], labels=labels)
```



4.4 Discussion

· we can adjust the hyperparamters such as epochs, minibatch size, and learning rate to train the model

5.1 Multilayer Perceptrons

```
1 %matplotlib inline
2 import torch
```

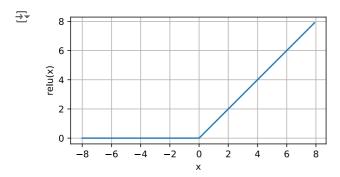
3 from d2l import torch as d2l

5.1.1.4. Universal Approximators (discussion)

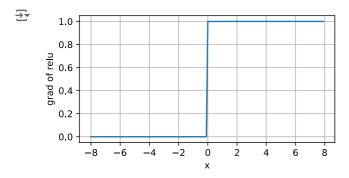
- Even with single-hidden-layer network, given enough nodes (possible absurdly many), and the right set of weights, we can model any function
- kernel methods are way more effective, since they are capable of solving the problem exactly even in **infinite dimesional** spaces(=universal approximator theorem)
- · we can approximate many functions much more compactly by using deeper (rather than sider) networks

→ 5.1.2.1. ReLU Function (Discussion)

```
1 x = torch.arange(-8.0, 8.0, 0.1, requires_grad=True)
2 y = torch.relu(x) #output of relu
3 d2l.plot(x.detach(), y.detach(),'x','relu(x)', figsize=(5,2.5))
```



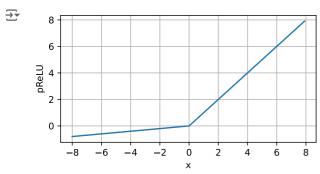
```
1 y.backward(torch.ones_like(x), retain_graph=True)
2 d2l.plot(x.detach(), x.grad, 'x', 'grad of relu', figsize=(5, 2.5))
```



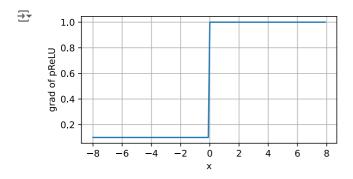
→ 5.1.2.1. Exercise / discussion

$$pReLU(x) = max(0, x) + \alpha min(0, x)$$

```
1 pReLU = lambda x, a: torch.max(torch.tensor(0), x) + a * torch.min(torch.tensor(0), x)
1 y = pReLU(x=x, a=0.1)
2
3 d2l.plot(x.detach(), y.detach(), 'x', 'pReLU', figsize=(5, 2.5))
```

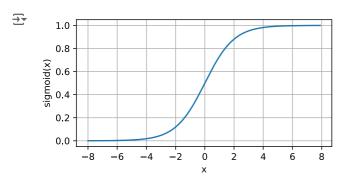


```
1 x.grad.data.zero_() #
2 y.backward(torch.ones_like(x), retain_graph=True)
3 d2l.plot(x.detach(), x.grad, 'x', 'grad of pReLU', figsize=(5, 2.5))
```

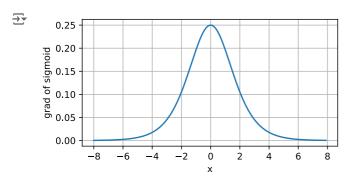


∨ 5.1.2.2. Sigmoid Function

1 y = torch.sigmoid(x)
2 d2l.plot(x.detach(), y.detach(), 'x', 'sigmoid(x)', figsize=(5, 2.5))



1 x.grad.data.zero_()
2 y.backward(torch.ones_like(x), retain_graph=True)
3 d2l.plot(x.detach(), x.grad, 'x', 'grad of sigmoid', figsize=(5, 2.5))



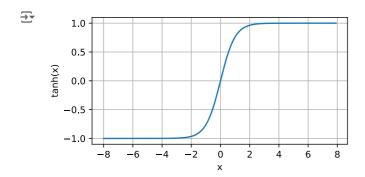
• Gradient Vanishing Problem ~ Backpropagation / Activation functions

5.1.2.3. Tanh Function

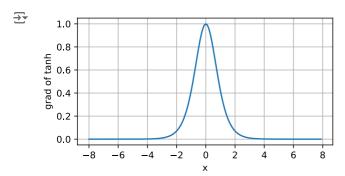
→ 5.1.2.3. Tanh Discussion

•
$$tanh(x) = \frac{1 - exp(-2x)}{1 + exp(-2x)} = \frac{exp(x) - exp(-x)}{exp(x) + exp(-x)}$$

```
1 y = torch.tanh(x)
2 d2l.plot(x.detach(), y.detach(), 'x', 'tanh(x)', figsize=(5, 2.5))
```



```
1 # Clear out previous gradients
2 x.grad.data.zero_()
3 y.backward(torch.ones_like(x),retain_graph=True)
4 d2l.plot(x.detach(), x.grad, 'x', 'grad of tanh', figsize=(5, 2.5))
```



5.1 Discussion

· we can incorporate nonlinear models to build more multilayer neural network architectures

5.2 Implementation of Multilayer Perceptrons

```
1 import torch
2 from torch import nn
3 from d2l import torch as d2l
```

5.2.1. Implementation from Scratch

5.2.1.1. Initializing Model Parameters (Discussion)

- Fashion-MNIST has 10 classes, each image with 28x28 = 784 grid of grayscale pixel values
- This means: 784 input features & 10 classes
- Implement 1 hidden layer and 256 hidden units

```
1 class MLPScratch(d2l.Classifier):
2    def __init__(self, num_inputs, num_outputs, num_hiddens, lr, sigma=0.01):
3        super().__init__()
4        self.save_hyperparameters()
5        self.W1 = nn.Parameter(torch.randn(num_inputs, num_hiddens) * sigma)
6        self.b1 = nn.Parameter(torch.zeros(num_hiddens))
7        self.W2 = nn.Parameter(torch.randn(num_hiddens, num_outputs) * sigma)
8        self.b2 = nn.Parameter(torch.zeros(num_outputs))
```

5.2.1.2. Model (Discussion)

· Compared to softmax regression, this has 2 fully connected layers (one hidden layer, one output layer)

```
1 def relu(X):
2    a = torch.zeros_like(X)
3    return torch.max(X, a)
```

✓ 5.2.1.3. Training