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ICP7

```
import numpy as np
from keras.datasets import cifar10
from keras.models import Sequential
from keras.layers import Dense, Dropout, Flatten, Conv2D, MaxPooling2D
#from keras.constraints import maxnorm
from keras.optimizers import SGD
from keras.utils import to categorical
#from keras import backend as K
#K.set image dim ordering('th')
# fix random seed for reproducibility
seed = 7
np.random.seed(seed)
# load data
(X train, y train), (X test, y test) = cifar10.load data()
\# convert from int to float and normalize inputs from 0-255 to 0.0-1.0
X train = X train.astype('float32') / 255.0
X test = X test.astype('float32') / 255.0
# one hot encode outputs
y train = to categorical(y train)
y test = to categorical(y test)
num classes = y test.shape[1]
# transpose the dimensions of the input data
X \text{ train} = \text{np.transpose}(X \text{ train, } (0, 3, 1, 2))
X \text{ test} = \text{np.transpose}(X \text{ test, } (0, 3, 1, 2))
# Create the model
model = Sequential()
model.add(Conv2D(32, (3, 3), input shape=(3, 32, 32), padding='same',
activation='relu'))
model.add(Dropout(0.2))
model.add(Conv2D(32, (3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Flatten())
model.add(Dense(512, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(num classes, activation='softmax'))
```

```
# Compile model
epochs = 5
lrate = 0.01
decay = lrate/epochs
sgd = SGD(lr=lrate)
model.compile(loss='categorical_crossentropy', optimizer=sgd,
metrics=['accuracy'])
print(model.summary())
# Fit the model
model.fit(X_train, y_train, validation_data=(X_test, y_test),
epochs=epochs, batch_size=32)
# Final evaluation of the model
scores = model.evaluate(X_test, y_test, verbose=0)
print("Accuracy: %.2f%%" % (scores[1]*100))
```

In class programming:

1. Follow the instruction below and then report how the performance changed.(apply all at once)

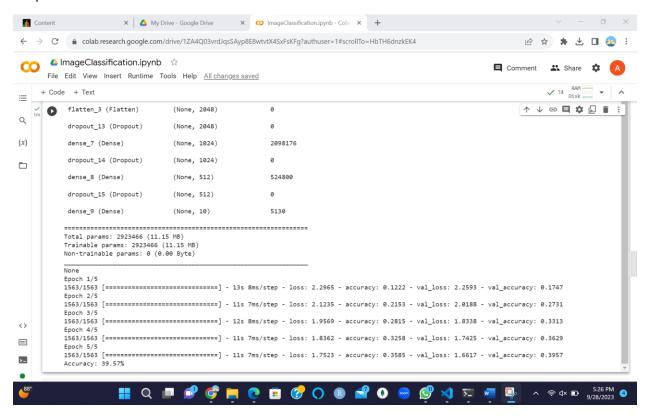
- Convolutional input layer, 32 feature maps with a size of 3×3 and a rectifier activation function.
- Dropout layer at 20%.
- Convolutional layer, 32 feature maps with a size of 3×3 and a rectifier activation function.
- Max Pool layer with size 2×2.
- Convolutional layer, 64 feature maps with a size of 3×3 and a rectifier activation function.
- Dropout layer at 20%.
- Convolutional layer, 64 feature maps with a size of 3×3 and a rectifier activation function.
- Max Pool layer with size 2×2.
- Convolutional layer, 128 feature maps with a size of 3×3 and a rectifier activation function.
- Dropout layer at 20%.
- Convolutional layer, 128 feature maps with a size of 3×3 and a rectifier activation function.
- Max Pool layer with size 2×2.
- Flatten layer.
- Dropout layer at 20%.
- Fully connected layer with 1024 units and a rectifier activation function.
- Dropout layer at 20%.
- Fully connected layer with 512 units and a rectifier activation function.
- Dropout layer at 20%.
- Fully connected output layer with 10 units and a Softmax activation function

Did the performance change?

```
import numpy as np
from keras.datasets import cifar10
from keras.models import Sequential
```

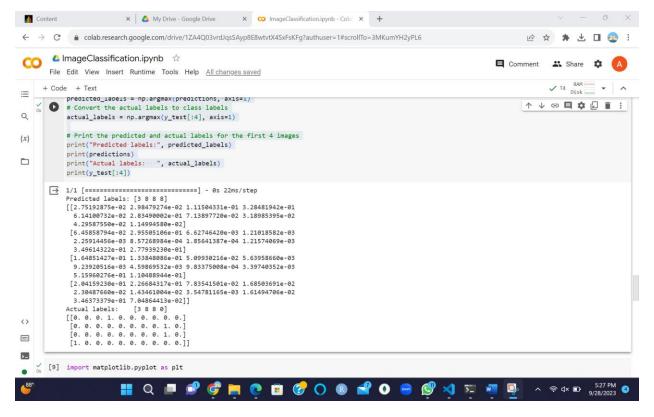
```
from keras.layers import Dense, Dropout, Flatten, Conv2D, MaxPooling2D
#from keras.constraints import maxnorm
from keras.optimizers import SGD
from keras.utils import to categorical
# from keras import backend as K
# K.tensorflow backend.set image dim ordering('th')
# fix random seed for reproducibility
seed = 7
np.random.seed(seed)
# load data
(X train, y train), (X test, y test) = cifar10.load data()
\# convert from int to float and normalize inputs from 0-255 to 0.0-1.0
X train = X train.astype('float32') / 255.0
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num classes = y test.shape[1]
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# Create the model
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model.add(Conv2D(32, (3, 3), input shape=(3, 32, 32), padding='same',
activation='relu'))
model.add(Dropout(0.2))
model.add(Conv2D(32, (3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Conv2D(64, (3, 3), padding='same', activation='relu'))
model.add(Dropout(0.2))
model.add(Conv2D(64, (3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool size=(1, 1)))
model.add(Conv2D(128, (3, 3), padding='same', activation='relu'))
model.add(Dropout(0.2))
model.add(Conv2D(128, (3, 3), activation='relu', padding='same'))
model.add(MaxPooling2D(pool size=(1, 1)))
model.add(Flatten())
model.add(Dropout(0.2))
model.add(Dense(1024, activation='relu'))
model.add(Dropout(0.2))
```

```
model.add(Dense(512, activation='relu'))
model.add(Dropout(0.2))
model.add(Dense(num classes, activation='softmax'))
# Compile model
epochs = 5
lrate = 0.01
decay = lrate/epochs
sqd = SGD(lr=lrate)
model.compile(loss='categorical crossentropy', optimizer=sgd,
metrics=['accuracy'])
print(model.summary())
# Fit the model
history=model.fit(X train, y train, validation data=(X test, y test),
epochs=epochs, batch size=32)
# Final evaluation of the model
scores = model.evaluate(X test, y test, verbose=0)
print("Accuracy: %.2f%%" % (scores[1]*100))
```



2. Predict the first 4 images of the test data using the above model. Then, compare with the actual label for those 4 images to check whether or not the model has predicted correctly

```
# Predict the first 4 images of the test data
predictions = model.predict(X_test[:4])
# Convert the predictions to class labels
predicted_labels = np.argmax(predictions, axis=1)
# Convert the actual labels to class labels
actual_labels = np.argmax(y_test[:4], axis=1)
# Print the predicted and actual labels for the first 4 images
print("Predicted labels:", predicted_labels)
print(predictions)
print(predictions)
print("Actual labels: ", actual_labels)
print(y test[:4])
```



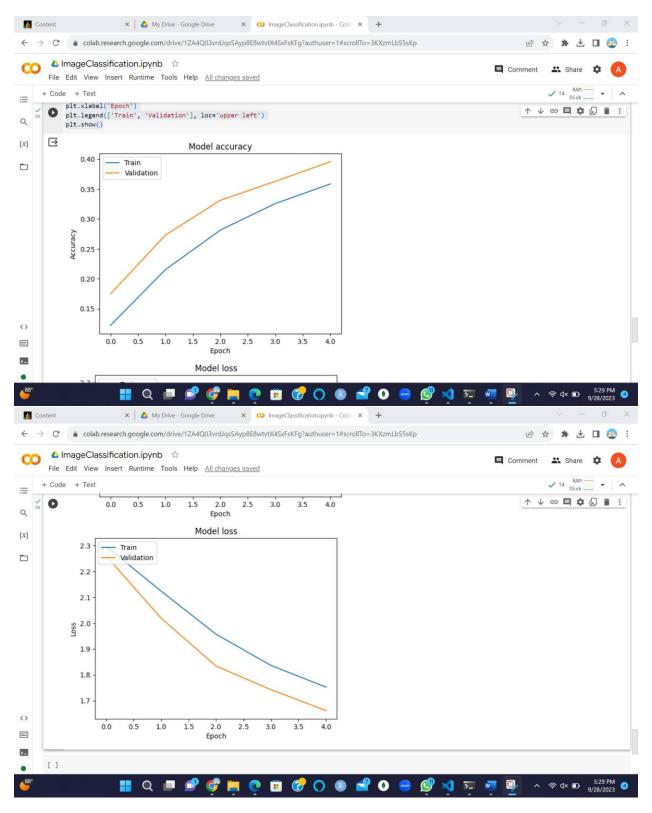
3. Visualize Loss and Accuracy using the history object

```
import matplotlib.pyplot as plt

# Plot training & validation accuracy values
plt.plot(history.history['accuracy'])
plt.plot(history.history['val_accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
```

```
plt.xlabel('Epoch')
plt.legend(['Train', 'Validation'], loc='upper left')
plt.show()

# Plot training & validation loss values
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('Model loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.legend(['Train', 'Validation'], loc='upper left')
plt.show()
```



GitHub:

https://github.com/angelreddy09/DNN/tree/main/ICP7