```
sarafun::ExecuteAction
  < ActionClass, ActionGoal >
  action_client_
  - goal
  - action name
  start_time_
  + ExecuteAction()
  + ~ExecuteAction()
  + executionRoutine()
  + preemptionRoutine()
  # fillGoal()
  # getTimeoutValue()
  # fillParameter()
  # fillParameter()
  # fillParameter()
  # fillParameter()
  # isSystemActive()
                  < sarafun_assembly
                 ::InsertionAction, sarafun
                  _assembly::InsertionGoal >
 sarafun::ExecuteAction
  < sarafun assembly::Insertion
 Action, sarafun_assembly::
         InsertionGoal >

    action client

 goal

    action name

 - start time
 + ExecuteAction()
 + ~ExecuteAction()
 + executionRoutine()
 + preemptionRoutine()
 # fillGoal()
 # getTimeoutValue()
 # fillParameter()
 # fillParameter()
 # fillParameter()
 # fillParameter()
 # isSystemActive()
sarafun::InsertionWithDeformation
              Action
node handle
- node name
- bt name
+ InsertionWithDeformation
Action()
+ ~InsertionWithDeformation
Action()
+ fillGoal()
+ getTimeoutValue()
```