sarafun::ExecuteAction
< ActionClass, ActionGoal >

- action_client_
- goal_
- action_name_
- start_time_

+ ExecuteAction()
+ ~ExecuteAction()
+ executionRoutine()
+ preemptionRoutine()
# fillGoal()
# getTimeoutValue()
# fillParameter()
# fillParameter()
# fillParameter()
# fillParameter()
# isSystemActive()

< sarafun_manipulation
::PlaceAction, sarafun
_manipulation::PlaceGoal >

sarafun::ExecuteAction
< sarafun_manipulation
::PlaceAction, sarafun
_manipulation::PlaceGoal >

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# fillParameter()
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sarafun::PlaceAction

- node_handle_
- node_name_
- bt_name_

+ PlaceAction()
+ ~PlaceAction()
+ fillGoal()
+ getTimeoutValue()