```
sarafun::ExecuteAction
         < ActionClass, ActionGoal >

    action client

         - goal
         - action_name_
         - start time
         + ExecuteAction()
         + ~ExecuteAction()
         + executionRoutine()
         + preemptionRoutine()
         # fillGoal()
         # getTimeoutValue()
         # fillParameter()
         # fillParameter()
         # fillParameter()
         # fillParameter()
         # isSystemActive()
                        < sarafun msgs::PickUpKeyframe
                       Action, sarafun_msgs::PickUpKeyframe
                                        Goal >
sarafun::ExecuteAction
< sarafun_msgs::PickUpKeyframe
Action, sarafun_msgs::PickUpKeyframeGoal >

    action client

- goal

    action name

- start time
+ ExecuteAction()
+ ~ExecuteAction()
+ executionRoutine()
+ preemptionRoutine()
# fillGoal()
# getTimeoutValue()
# fillParameter()
# fillParameter()
# fillParameter()
# fillParameter()
# isSystemActive()
            sarafun::PickupAction
            - node_handle_
            - node_name_
            - bt name
            + PickupAction()
            + ~PickupAction()
            + fillGoal()
            + getTimeoutValue()
```