```
sarafun::ExecuteAction
        < ActionClass, ActionGoal >

    action client

        - goal
        - action name
        - start time
        + ExecuteAction()
        + ~ExecuteAction()
        + executionRoutine()
        + preemptionRoutine()
        # fillGoal()
        # getTimeoutValue()
        # fillParameter()
        # fillParameter()
        # fillParameter()
        # fillParameter()
        # isSystemActive()
                       < sarafun_msgs::MoveKeyframe
                      Action, sarafun msgs::MoveKeyframe
                                      Goal >
sarafun::ExecuteAction
< sarafun msgs::MoveKeyframe
Action, sarafun_msgs::MoveKeyframeGoal >

    action client

- goal

    action name

- start time
+ ExecuteAction()
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# getTimeoutValue()
# fillParameter()
# fillParameter()
# fillParameter()
# fillParameter()
# isSystemActive()
            sarafun::MoveAction
            - node handle
            - node_name_
            - bt name
            + MoveAction()
            + ~MoveAction()
            + fillGoal()
```

+ getTimeoutValue()