

Washington State University
School of Electrical Engineering and Computer Science
Fall 2020

CptS 440/540 Artificial Intelligence

Homework 3

Due: September 17, 2020 (11:59pm pacific time)

General Instructions: Put your answers to the following problems into a PDF document and submit as an attachment under Content → Homework 3 for the course CptS 440 Pullman (all sections of CptS 440 and 540 are merged under the CptS 440 Pullman section) on the Blackboard Learn system by the above deadline. Note that you may submit multiple times, but we will only grade the most recent entry submitted before the deadline.

1. Consider the following initial and goal states for the 8-puzzle problem. In the search algorithms below, when iterating over possible actions (i.e., moving the blank tile), always consider the actions in the order: Up, Down, Left, Right. *Be sure to use the search algorithms as defined in the lecture notes.*

1	2	3
4		5
7	8	6

Initial State

1	2	3
4	5	6
7	8	

Goal State

- a. Draw the search tree showing all nodes generated by the **Breadth-First Search** algorithm to solve this problem.
 - b. Draw the search trees showing all nodes generated for each iteration of the **Iterative-Deepening Search** algorithm to solve this problem.
 - c. Draw the search tree generated by the **A* search** algorithm to solve this problem using the **city-block distance** for the heuristic h . The city-block distance for an 8-puzzle state is the sum of the city-block distances of each tile in the puzzle (excluding the blank tile). Next to every node, show the **values of f , g and h** . If two nodes have the same f value, then prefer nodes farther to the left in the search tree.
 - d. Draw the search tree generated by the **Hill-Climbing search** algorithm to solve this problem, where a state's **Value = $1 / (h + 1)$** , where h is the heuristic from part (c). Next to every node, show its Value. Finally, indicate which node is returned. Be careful; note that the Hill-Climbing algorithm does not employ the goal test, but stops only after none of the generated neighbor nodes has a strictly better Value.
2. Consider the heuristic which is the **average** of the city-block distances of each tile, instead of the **sum**. Is this heuristic admissible for the 8-puzzle search problem? Justify your answer.
3. *CPTS 540 Students Only:* Suppose you want to replace the initial state in problem 1 with a state such that the optimal solution to the 8-puzzle problem is exactly 10 moves. Explain how you could use one of the search algorithms discussed in class to find such a state.