

Topo-Clustering Classification with Deep Neural Networks

ATLAS Machine Learning Forum

Aviv Cukierman^{1,2} **Michael Kagan**² **David Miller**³
Joakim Olsson³ **Ariel Schwartzman**²

¹Stanford University ²SLAC National Accelerator Laboratory ³University of Chicago

February 2, 2017



THE UNIVERSITY OF
CHICAGO

Introduction

(Slides from ATLAS Hadronic Final State Forum, Dec 2016 @SLAC)

- ▶ *Is it possible to do local cluster calibration using machine learning?*
- ▶ *How well can we do compared to default LC calibration?*

- ▶ Start with a simpler problem:

π^\pm vs. π^0 classifier

- ▶ Build images from cells associated with clusters for the 6 layers of the barrel calorimeter (LAr + Tile)

- EMB1, **EMB2**, EMB3, TileBar0, TileBar1, TileBar2

- ▶ Selection

- $|\eta_{\text{clus}}| < 0.7$ (Barrel only)
- $0.5 \text{ GeV} < E_{\text{clus}} < 100 \text{ GeV}$

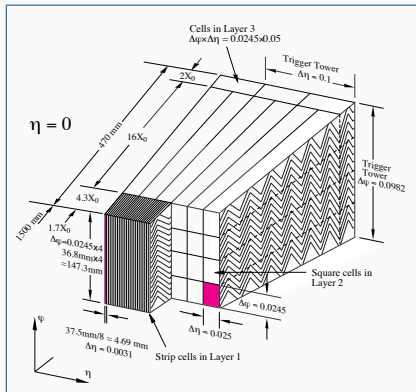
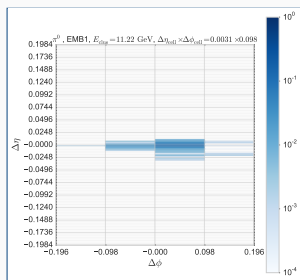


Figure 5.4: Sketch of a barrel module where the different layers are clearly visible with the ganging of electrodes in ϕ . The ganging is only done in the trigger towers. The three layers and of the trigger towers is also shown.

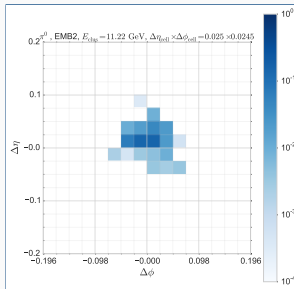
(LAr barrel module)

Preparing the Images

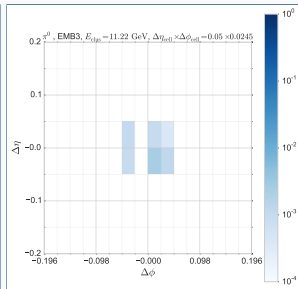
- ▶ Steps: ESD $\xrightarrow{\text{Athena}}$ TTree $\xrightarrow{\text{root_numpy}}$ numpy arrays for Keras
- ▶ Source code: <https://github.com/jmrolsson/MLTree>



(a) EMB1



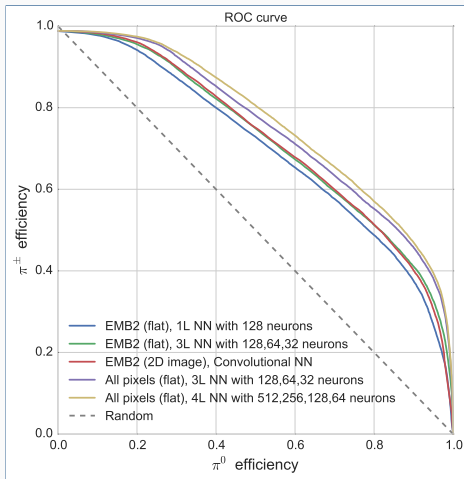
(b) EMB2



(c) EMB3

- ▶ Training performed using Keras (with TensorFlow)
 - 600 000 (50/50 π^0 and π^\pm) training clusters, and 66 000 test clusters
- ▶ EMB2 pixels, flattened to a 1D-array + total cluster energy
 - 1 layer with 128 neurons (seems to converge after about 100 epochs)
 - 3 layers with 128, 64, and 32 neurons, respectively (takes longer to run, but converges after fewer epochs)
- ▶ Convolutional NN in EMB2, keeping the 2D information (but not including cluster energy)
 - Takes longer to train, but converges after only 3-5 epochs or so
- ▶ All pixels in all layers, flattened to a 1D-array + total cluster energy
 - 3 layers with 128, 64, and 32 neurons, respectively
 - 4 layers with 512, 256, 128, and 64 neurons, respectively

Result



- Very preliminary, but we're definitely learning some information

Conclusions and Future Plans

► We are definitely doing better than random!

- The NN with 3 layers (128, 64, 32 neurons, respectively) does a little better than the one with just one 128 neuron layer
- The ConvNet does as well as the simple NNs, despite not including the total cluster energy as a feature
- Training on a feature vector of all the pixels (in all barrel layers) does improve things a little

► Next steps for cluster classification

- Compare with what is currently used for distinguishing EM vs. HAD showers
- Implement 2D DNN/ConvNet that takes all the (barrel) layers into account
- Add tracking information (per layer)
- Look at clusters in a more dense environment (inside jets, etc.)

► Main Goal: Cluster calibration using regression

- Perform cluster calibration by training on cells associated with a cluster (using the truth cluster energy as labels)
- How well we can do with a DNN compared to LC?

Thanks!