

### ESCUELA COLOMBIANA DE INGENIERÍA JULIO GARAVITO

VIGILADA MINEDUCACIÓN

SYSTEMS ENGINEERING

**Enterprise Architectures** 

**Laboratory 5** 

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## 1 Introduction

In this lab create a small web application using the Spark java micro-framework, also create a container for docker (to be used with the aforementioned application), where you deploy and configure both locally. Then in a repository that I created in Docker-Hub I uploaded the image so that finally in a virtual machine that I created in AWS (where we previously installed Docker) I could deploy my container.

### 2 Architecture

The architecture used is the Round Robin and we can see the physical design in the figure 1, this is a simplest architecture of an embedded system. The main method involves a loop that runs again and again, checking each I/O device in each round to see if they need maintenance, this no fancy interrupts, no worry about sharing data and use just a simple thread of execution can execute again and again.[1]

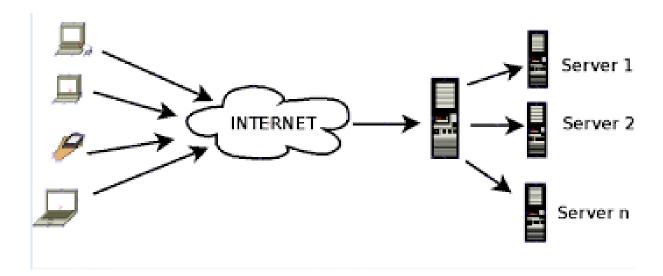


Figure 1: The architecture used

#### Pros:

- Simplest of all the architectures
- No interrupts
- No shared data
- No latency concerns
- No tight response requirements

#### Cons:

- A sensor connected to the Arduino that urgently needs service must wait its turn.
- Fragile. Only as strong as the weakest link. If a sensor breaks or something else breaks, everything breaks.
- Response time has low stability in the event of changes to the code.

## 3 Results

The results that were obtained in this laboratory are in the figure 2,3, 4

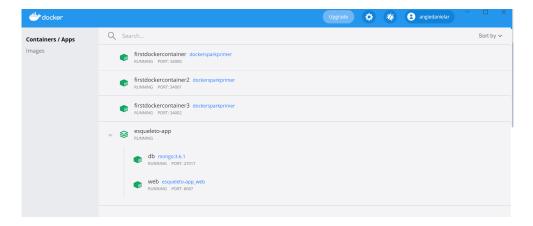


Figure 2: The results obtained

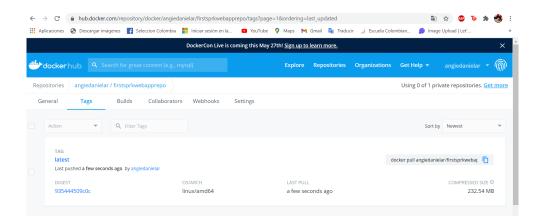


Figure 3: The results obtained

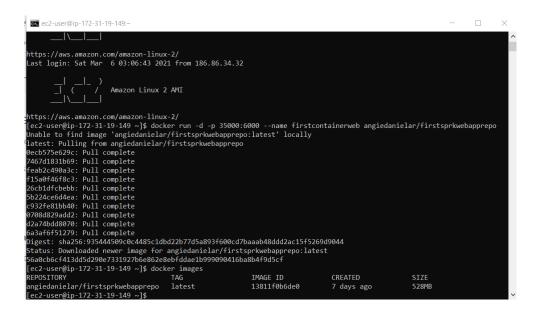


Figure 4: The results obtained

## 4 References

[1] A. Addison., Round-robin vs function-queue-scheduling | embedded software architecture, https://automaticaddison.com/round-robin-vs-function-queue-scheduling-embedded-software-architecture/#:~:text=The%20Round%20Robin%20architecture%20is,see%20if%20they%20need%20service,Accessed on 2021-03-15.