Election

```
struct Party
   string name;
                   // number of votes
   int nVotes;
   Party * pNext;
};
struct Candidate
   string surname;
   int nVotes:
   Party * pParty;
   Candidate * pNext;
};
struct Constituency
   int number;
   Candidate * pCandidates;
   Constituency * pLeft, * pRight;
};
```

The structures are used to build a complicated data structure presented in Fig. [6]. Constituencies build a binary search tree ordered by constituency numbers. Each constituency has a singly linked list of candidates. Each candidate has a pointer (pParty) to a party they represent. All parties build a singly linked list.

We assume that each candidate has a unique surname. Also party names and constituency numbers are unique.

One function has been defined in the programme:

Party * findParty (Party * & pHead, const std::string & name);

The function returns a party in a list of parties pHead. If the party is missing, the function adds it and returns its address.

Attention: Do not modify definitions of structures **Party**, **Candidate**, and **Constituency**. Define functions:

```
1. Constituency * findConstituency (Constituency * & pRoot, int number);
```

The function returns an address of a constituency searched by its number in a tree pRoot. If a constituency is missing, the function adds a new constituency in correct location in the tree and returns an address of a newly added item.

The function add a candidate (named candidate_surname) from party_name party to a list in a constituency numbered constituency_number. The function finds a constituency in a tree and a party in a list with functions defined above. A candidate in placed in any location in a list of candidates.

int count_votes (Constituency * pConstituencies);

The function counts number of votes for each party from votes gained by party candidates. The function sets the field nVotes for each party. The function returns a sum of all votes of all candidates of all parties.

4. void remove_threshold(Constituency * pConstituencies, int nVotes, double threshold);

The function removes candidates which parties have less votes than threshold. The threshold is a number from interval [0,1]. The parameter nVotes denotes a total number of votes gained by all candidates. Let p be a threshold, n_i number of votes gained by the i-th party, and N number of all parties. The fraction of votes gained by the i-th party is calculated with formula

$$p_i = \frac{n_i}{\sum_{k=1}^N n_k}.$$

If $p_i < p$ then candidates of the *i*-th party are removed from the list of candidates.

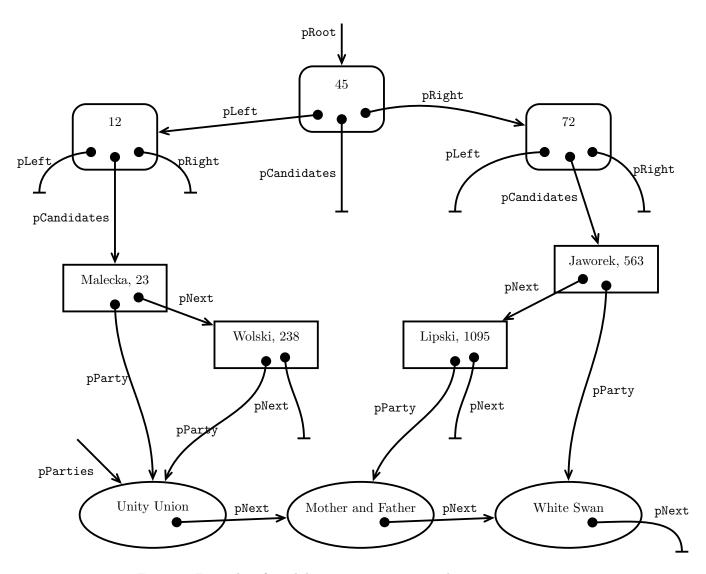


Figure 6: Examples of candidates, constituencies, and parties.