

24-677 Project 3

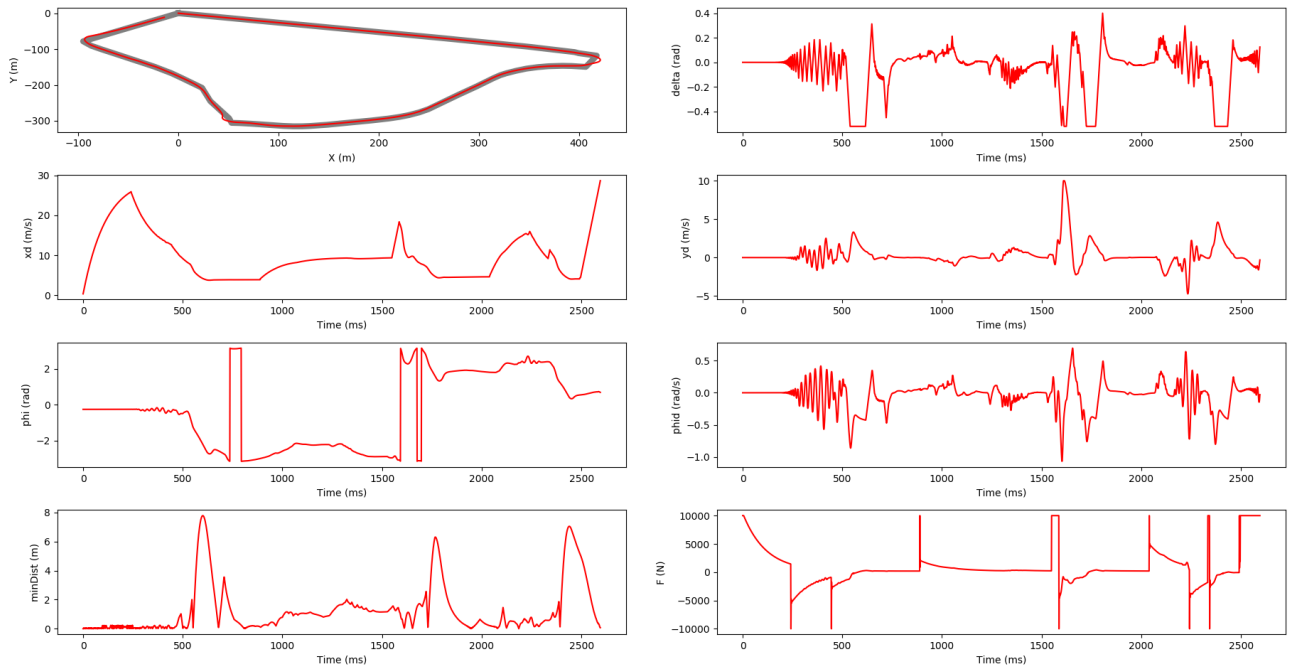
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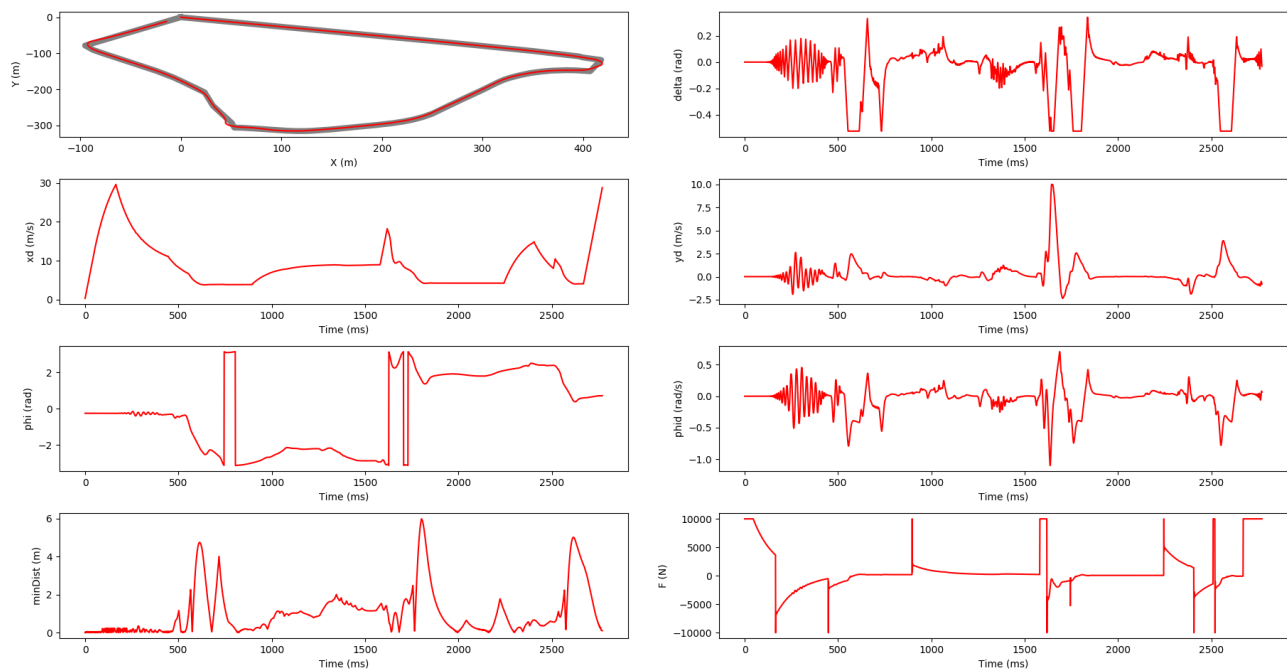
1 Exercise 1

Discrete Time Infinite Horizon LQR Lateral Controller - Response Plot

First submission: Satisfies time limit for bonus points, but does not satisfy max deviation constraint.



Second submission: Satisfies all constraints, except for the bonus.



(Code in angelosm_controller.py)