

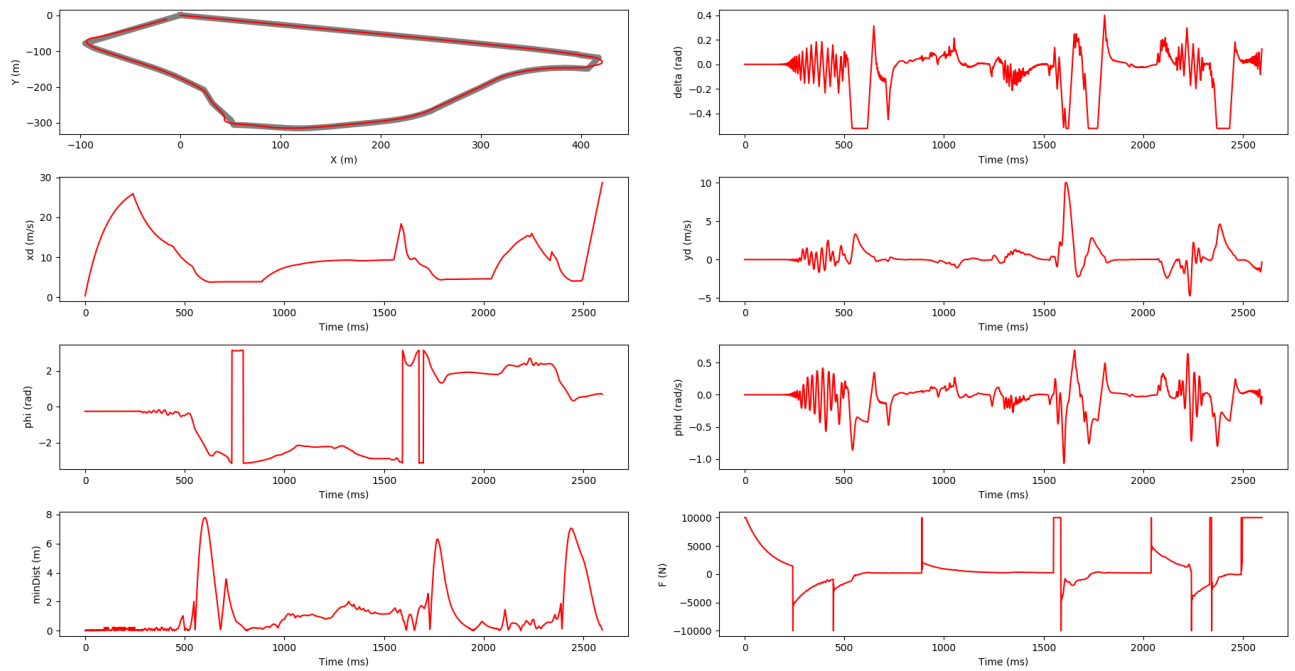
# 24-677 Project 3

Angelos Mavrogiannis

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## 1 Exercise 1

### Discrete Time Infinite Horizon LQR Lateral Controller - Response Plot



(Code in angelosm\_controller.py)