

24-677 Project 4

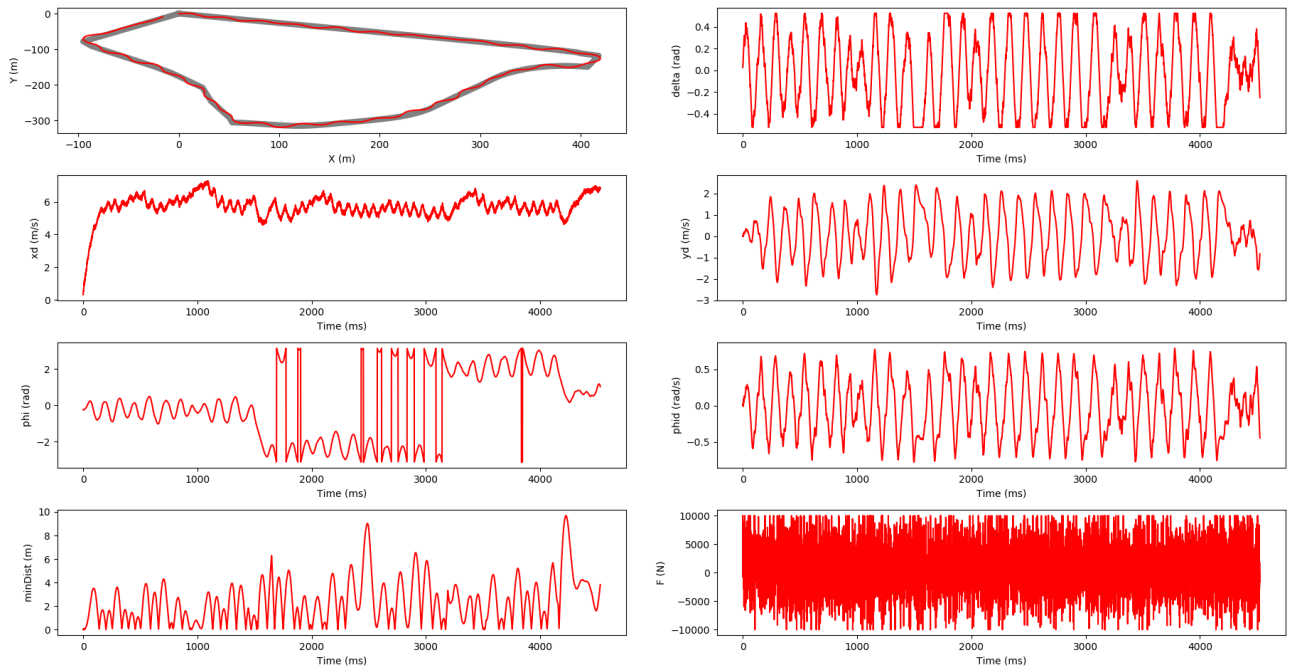
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1 Exercise 1

Discrete Time Infinite Horizon LQR Lateral Controller with Kalman Filter

Response Plot



(Code in angelosm_controller.py)