

# Angelos Mavrogiannis

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## Education

**University of Maryland, College Park (UMD)** Aug 2020 – Summer 2025 (exp.)  
Doctor of Philosophy (PhD), Computer Science  
Thesis: “Translating Natural Language to Visually Grounded Verifiable Action Plans”  
Advisor: Prof. Yiannis Aloimonos

**University of Maryland, College Park (UMD)** Dec 2023  
Master of Science (MS), Computer Science  
Coursework: Robotics, Trustworthy ML, Computer Vision, Decision-Making for Robotics, Deep Learning, Computational Linguistics, Interactive Data Analytics, HCI  
GPA: 3.74/4.00

**Carnegie Mellon University (CMU)** May 2020  
Master of Science (MS), Mechanical Engineering  
Thesis: “Human Driver Behavior Classification from Partial Trajectory Observation”  
Advisor: Prof. Changliu Liu  
Selected Coursework: Advanced Control & Reinforcement Learning, Deep Learning, Mechanics of Manipulation, Machine Learning, Robot Design & Experimentation, Linear Control Systems, Engineering Computation  
GPA: 3.92/4.00

**University of Patras (UoP)** July 2017  
Bachelor of Science (BS) & Master of Engineering (MEng), Mechanical Engineering  
Concentration: Mechanical Design & Manufacturing  
Thesis: “Environment Development for Implementing Design Optimization Using Parsers and Genetic Algorithms”  
Advisor: Prof. Argyris Dentsoras  
GPA: 8.03/10.00 (top 10% in a class of 150 students)

## Honors & Awards

<b>ICRA@40 Travel Grant</b>	2024
IEEE Robotics and Automation Society	
<b>NSF AccelNet Grant</b>	2024
NeuroPAC Project: Neuromorphic Perception, Action, and Cognition	

<b>Scholarship for 4<sup>th</sup> Summer School on Social Human-Robot Interaction</b>	2023
<b>IROS Student and Developing Countries Travel Award</b>	2022
IEEE Robotics and Automation Society	
<b>Jacob K. Goldhaber Travel Grant</b>	2022
<b>International Conference Student Support Award (ICSSA)</b>	2022
<b>Computer Science Department Travel Grant</b>	2022
Department of Computer Science, The Graduate School, University of Maryland	
<b>Gerondelis Graduate Study Scholarship</b>	2022
Gerondelis Foundation	
<b>Dean's Fellowship</b>	2020-2022
Department of Computer Science, University of Maryland	
<b>Fulbright Scholarship</b>	2018-2020
Fulbright Foundation	
<b>Carnegie Mellon Mechanical Engineering MS Research Symposium Award</b>	2020
Department of Mechanical Engineering, Carnegie Mellon University	
<b>Duke Mech. Eng. &amp; Materials Science Graduate Scholarship (declined)</b>	2018
Duke University	
<b>Andreas Mentzelopoulos Scholarship</b>	2018-2020
University of Patras	
<b>Harry D. Triantafillu Scholarship</b>	2018
Harry D. Triantafillu Scholarship Fund - Institute of International Education	

## Research Experience

### Graduate Research Assistant

Department of Computer Science, University of Maryland

Perception and Robotics Group (PI: Prof. Yiannis Aloimonos) January 2022 – Present

- Research in the intersection of robotics and NLP (RoboNLP).
- Discovering Object Attributes by Prompting Large Language Models with Perception-Action APIs (under review: <https://arxiv.org/abs/2409.15505>, presented at ICRA@40 in Rotterdam, Netherlands)
- Cook2LTL: Translating Cooking Recipes to LTL Formulae using Large Language Models (paper: <https://ieeexplore.ieee.org/document/10611086>, presented at ICRA 2024 in Yokohama, Japan)

Gamma Group (PI: Prof. Dinesh Manocha)

Sept 2020 – December 2021

- B-GAP: Behavior-Rich Simulation and Navigation for Autonomous Driving (RA-L 2022 letter: <https://ieeexplore.ieee.org/document/9716825>, presented at IROS 2022 in Kyoto, Japan)

### Graduate Research Assistant

Jan 2019 – May 2020

The Robotics Institute, Carnegie Mellon University

Intelligent Control Lab (PI: Prof. Changliu Liu)

- Developed a machine learning framework (PyTorch, Scikit-Learn) for classifying human driver behaviors based on partial trajectory observations and applied it to vehicle trajectory prediction.
- Designed and created a data-driven simulator on Python for visualizing vehicle trajectories.
- Master thesis available at:  
[https://www.researchgate.net/publication/345780499\\_Human\\_Driver\\_Behavior\\_Classification\\_from\\_Partial\\_Trajectory\\_Observation](https://www.researchgate.net/publication/345780499_Human_Driver_Behavior_Classification_from_Partial_Trajectory_Observation)

#### **Graduate Research Assistant**

Sept 2018 – Dec 2018

Department of Mechanical Engineering, Carnegie Mellon University

Computational Engineering and Robotics Lab (PI: Prof. Kenji Shimada)

- Research on the design and control of an underwater, hull-cleaning robot (code in C++, communications through ROS, project funded by Tsuneishi Shipbuilding Co. Ltd and supervised by Prof. Kenji Shimada).

#### **Undergraduate Research Assistant**

Nov 2016 – July 2017

Mechanical Engineering and Aeronautics Department, University of Patras

Machine Design Laboratory (PI: Prof. Argyris Dentsoras)

- Developed a software tool (Visual Basic) for automatic parsing of optimization problems from mathematical expressions into numerical code and solving them using Genetic Algorithms (Diploma Thesis project).
- Demonstrated the efficacy of the tool in robotic grasping applications and specifically via minimizing the forces applied onto an object grasped by a robot arm.

## **Teaching Experience**

#### **Teaching Assistant**

Department of Computer Science, University of Maryland, College Park

CMSC 122: Intro to Computer Programming via the Web Spring 2023, Fall 2023-2024

Undergraduate Course, taught by Jen Manly, Pedram Sadeghian

- Holding weekly office hours and grading quizzes, projects, and exams.

CMSC 131: Object-Oriented Programming I (Java)

Spring 2024

Undergraduate Course, taught by Pedram Sadeghian

- Held weekly office hours and graded assignments and exams.

CMSC 426: Computer Vision

Fall 2022

Undergraduate Course, taught by Prof. Yiannis Aloimonos

- Held weekly office hours and graded projects and exams.

CMSC 216: Introduction to Computer Systems

Spring 2022

Undergraduate Course, taught by Larry Herman

- Taught weekly lectures on C programming, UNIX process control, and Assembly language.
- Held weekly office hours and offered assistance to a class of over 500 students.

CMSC 106: Introduction to C Programming Fall 2021

Undergraduate Course, taught by Prof. Jan Plane

- Hosted weekly lab sessions on C programming in a UNIX environment.
- Provided debugging assistance to a class of more than 50 students.
- Held weekly office hours, created and graded assignments and projects.

### **Course Assistant**

Department of Mechanical Engineering, Carnegie Mellon University

24-775: Robot Design & Experimentation Spring 2020

Graduate Course, taught by Prof. Aaron Johnson

- Advised students on robot design projects, organized and supervised group meetings and graded assignments and projects.

24-281: Introduction to Scientific Computing Spring 2019, Fall 2019

Undergraduate/Graduate Course, taught by Dr. Zhenguo Nie, Dr. Hugo Penelas

- Delivered MATLAB recitations, held weekly office hours, created and graded weekly assignments.

24-686: Advanced Mechanical Design Fall 2018

Graduate Course, taught by Prof. Rahul Panat

- Offered SolidWorks recitations, held weekly office hours and designed/graded assignments and projects.

## **Internships**

**Artificial Intelligence – Artificial Intelligence Engineer Intern** Summer 2024

LinkedIn Corporation, San Francisco, California

- Orchestrated a vLLM- and HuggingFace-powered batch inference pipeline to generate LLM member and ad campaign embeddings.
- Integrated the embeddings as input features into a two-tower recommendation model for embedding-based retrieval.
- Trained the model towards expanding the target audience of a campaign and outperformed the existing baseline in production.

**Artificial Intelligence – Machine Learning Engineer Intern** Summer 2023

LinkedIn Corporation, Mountain View, California

- Fine-tuned state-of-the-art open-source Large Language Models towards optimizing LinkedIn's audience targeting pipeline.
- Outperformed the existing audience targeting module that was used in production at that time.

## **Artificial Intelligence – Machine Learning Engineer Intern**

Summer 2022

LinkedIn Corporation, Mountain View, California

- Developed a Real-Time Bidding environment for second-price auctions on OpenAI gym.
- Modeled a multi-constraint bidding problem for ad optimization using a Constrained Markov Decision Process (CMDP).
- Trained a Deep Reinforcement Learning policy that can outperform the company's currently used automatic bidding policy.

## **Jr. Technical Superintendent**

Summer 2012, Summer 2013

Euronav Ship Management Hellas Ltd, Athens, Greece

- Interned in the technical department of the company and assisted with various day-to-day tasks.
- Reviewed weekly fleet reports to analyze and optimize on-ship oil and energy consumption.

# **Skills**

## **Programming**

Python, C/C++, MATLAB, SQL, Scala, Visual Basic, Fortran

## **Machine Learning Libraries/Toolkits**

Huggingface, spaCy, Tensorflow, PyTorch, OpenCV, Scikit-Learn, Open AI Gym

## **Engineering Software**

ROS (Robot Operating System), AI2-THOR, Gazebo, Solidworks, Catia, AutoCAD

## **Technologies**

Linux, Git, Apache Spark, Hadoop

## **Languages**

English (Fluent, TOEFL 115/120, CPE University of Cambridge 2008)

French (Intermediate, DALF C2 2010)

Greek (Native)

# **Teamwork & Class Projects**

## **Evaluating the Fairness of Diffusion-based Face Generation**

Fall 2023

CMSC 848I: Trustworthy Machine Learning, taught by Hal Daumé III, UMD

- Designed a pilot study that mines information about users' facial features by asking them LLM-generated questions.
- Evaluated the fairness of a diffusion model on face reconstruction based on the information extracted during the pilot study.

### **VR-Integrated Real-Time Racetrack Simulator**

Spring 2023

CMSC 730: Interactive Technologies in HCI, taught by Huaishu Peng, UMD

- Proposed and led a group project on building a 3D-printed chessboard-resembling racetrack and an interactive system that converts it to a VR-simulated racing environment.
- Implemented the entire computer vision module, tracking the position and orientation of the pieces using ArUco markers and mapping them to poses and ego-vehicle control commands in a simulated racetrack in Unity.

### **Predictive Modeling Using Linguistic Signal for Suicidality**

Spring 2021

CMSC 723: Computational Linguistics, taught by Jordan Boyd-Graber, P. Resnik, UMD

- Proposed a modified Hierarchical Attention Network architecture to assess the potential suicide risk of reddit users based on their post history.
- Extracted post-level features based on users' emotional states and tuned a Latent Dirichlet Allocation (LDA) model to retrieve meaningful subreddit clusters.

### **News Scraper (Full Disclosure Project)**

Spring 2021

CMSC 828D: Interactive Data Analytics, taught by Leilani Battle, UMD

- Collaborated with a team of students to develop an application that continuously scrapes the web for articles related to potential police misconduct.
- Developed an NLP-based algorithm that assigns a probability score to scraped articles based on their potential indication of police misconduct.

### **Automatic Parking using Reinforcement Learning**

Fall 2020

CSMC 828W: Foundations of Deep Learning, taught by Soheil Feizi, UMD

- Presented a Curriculum Learning-based setup for the efficient training of a Reinforcement Learning policy on autonomous parking.
- Demonstrated the benefits of the proposed approach in parking environments of varying traffic density on an OpenAI gym-based simulator.

### **Reinforcement Learning-based Object Placement on Small Surfaces**

Fall 2020

CMSC 818B: Decision-Making for Robotics, taught by Pratap Tokekar, UMD

- Realigned a Reinforcement Learning-based Pick-and-Place approach to an approximation of object stacking upon small surfaces.

### **Sentiment Analysis on Audiovisual Speech Samples**

Spring 2020

24-789: Deep Learning, taught by Amir Barati Farimani, CMU

- Collaborated with a team of students to develop a multi-modal deep learning framework for extracting the sentiment of a short audiovisual speech sample.
- Implemented a deep neural network which receives text as input and outputs the polarity of the given text (positive/negative sentiment).

### **Autonomous Vehicle Controller Design**

Fall 2019

24-677: Linear Control Systems, taught by Ding Zhao, CMU

- Designed a lateral and a longitudinal controller to track the route of an autonomous vehicle around the CMU campus.
- Investigated various methods for improved performance (PID, pole placement, Discrete Time Infinite Horizon LQR) and used Kalman Filter for noise filtering.

### **Bioinspired Robot Design**

Spring 2019

24-775: Robot Design & Experimentation, taught by Aaron Johnson, CMU

- Collaborated with a team of students to design and manufacture an underwater penguin-inspired robot.
- Incorporated a ball-and-socket motion transmission mechanism for the movement of the flippers.
- Designed a control system using Arduino microcontroller and tested the robot in underwater environments.

### **Game Design**

Fall 2018

24-780: Engineering Computation, taught by Nestor Gomez, CMU

- Implemented applications with 3D graphics and audio programming, using C++ and the OpenGL library.
- Orchestrated a team project on the development of an interactive entertainment software package (a fighting game).

### **Manipulation Project**

Fall 2018

16-741: Mechanics of Manipulation, taught by Matt Mason, CMU

- Collected a synthetic dataset of manipulator postures and object poses in OpenAI Gym.
- Trained a multilayer perceptron in order to map changes in hand pose to object displacements.
- Modified the OpenAI Gym simulator to demonstrate the predicted object pose and validated the method on occluded object tracking problems.

### **Computational Robotics Project**

Fall 2016

MEA-KY3: Robotics, taught by Nikos Aspragathos, UoP

- Developed forward and inverse kinematics software in Matlab for a KUKA KR 6 R700 sixx WP industrial robot.
- Applied the framework to trajectory planning problems and visualized the joint and end-effector trajectories.

## **Extracurricular Coursework**

### **The Machine Learning Summer School (MLSS) in Okinawa**

March 2024

Okinawa Institute of Science and Technology (OIST), Riken AIP

### **4<sup>th</sup> Summer School on Social Human-Robot Interaction**

Sept 2023

Human Interactivity and Language Lab, IEEE Robotics and Automation Society

**DISC Summer School 2021 for Planning, Learning and Control for Multi-Robot and Multi-Agent Systems** June 2021  
Dutch Institute of Systems and Control

**Robotics & AI Summer School** June 2021  
IRI - Institut de Robòtica i Informàtica industrial, CSIC-UPC

**3rd ACM Summer School in Data Science** July 2019  
Association for Computing Machinery

## Outreach

### Paper Reviewing

- IEEE TPAMI Sept 2024
- IEEE ICRA 2025 Sept 2024
- IEEE ICRA 2024 Oct 2023
- IEEE IROS 2023 March 2023

**Intelligent Control Lab Tour**, Carnegie Mellon University May 2019

- Presented the lab equipment and gave a brief talk for a group of students from Choate Rosemary Hall.

**Makerspace and Machine-Shop Tour**, Carnegie Mellon University December 2018

- Gave a tour of the makerspace and the machine-shop to a group of CMU kindergarten kids.

**F1 in Schools, 4x4 in Schools**, Athens, Greece May 2018

- Constructed a set of different racetracks and supervised the F1 in Schools STEM Challenge.
- Collaborated with a team of engineers to inspect and validate F1 and 4x4 student-designed vehicles.