

Integration By Substitution

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<https://github.com/vitutorial/VITutorial>

Multivariate calculus recap

Let $x \in \mathbb{R}^K$ and let $\mathcal{T} : \mathbb{R}^K \rightarrow \mathbb{R}^K$ be differentiable and invertible

- ▶ $y = \mathcal{T}(x)$
- ▶ $x = \mathcal{T}^{-1}(y)$

Jacobian

The Jacobian matrix $J_{\mathcal{T}}(x)$ of \mathcal{T} assessed at x is the matrix of partial derivatives

$$J_{ij} = \frac{\partial y_i}{\partial x_j} = \frac{\partial \mathcal{T}(x)_i}{\partial x_j}$$

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Inverse function theorem

$$J_{\mathcal{T}^{-1}}(y) = (J_{\mathcal{T}}(x))^{-1}$$

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- ▶ dy/dx scales the differential dx to match it to dy
- ▶ if $dy/dx > 1$, \mathcal{T} expands the area around x locally

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Multivariate Case

$$dy = |\det J_{\mathcal{T}}(x)| dx$$

the absolute value absorbs the orientation

Integration by substitution

We can integrate a function $g(x)$
by substituting $x = \mathcal{T}^{-1}(y)$

$$\int g(\textcolor{blue}{x})\textcolor{red}{d}x$$

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and similarly for a function $h(y)$

$$\int h(y) dy$$

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$$\int h(\mathcal{T}(x)) dx = \int h(y) |\det J_{\mathcal{T}}(x)| dy$$

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and then it follows that

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