בס"ד

1/3/17

* The points are not stable enough and the values are changing
* If you have 74 threads and you need to double that for example 5 times its two much ergo need a better solution
* Maybe take a picture and not live stream
* Worst case scenario I need to redo the landmarks extraction
* Check in the matlab code what are the methods for recognition

6/3/17

* I have a problem with data correction. Confidence is not good enough. Looks like it's only 0 or 100 and not levels
* I don't want to recreate recognition module.
* It'll have to be capture a moment where all points are at level 100 of confidence and then activate the numeration of the points process.
* **Represent the data in binary BCD data so that it'll be easier to detect repetitive chunks of data.**
* Check in the code samples how they determined the proper position for the face. Maybe I can include position in the string to server.
* Maybe size of querying rect should be a certain size
* Should compare the landmarks points to the bounding rect and check that all within bounds or center of the rect as another confirmation technique
* Probably need to use OpenCV for the windows. I have a feeling it's just going to work better…. Maybe check again how the 3d data is convertable

21/03/17

* Add graphics
* Regular binary numbers
* 15 frames after 10 stable frames
* Get boost for threads
* Pitch yew and roll – good idea