

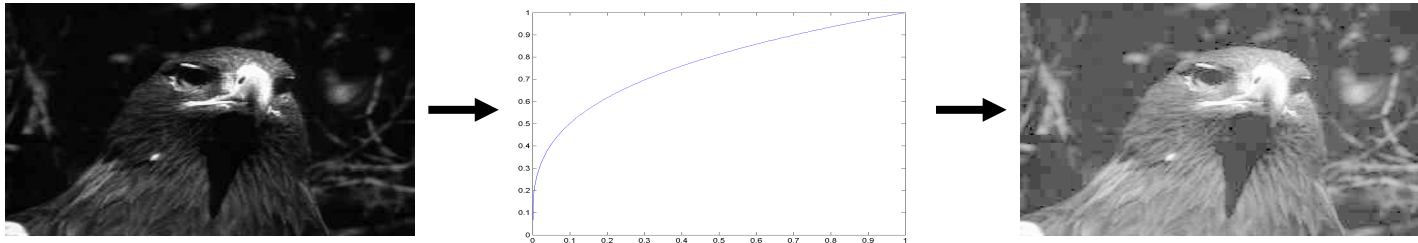
OPENCV

Session 2

Example 1. Smoothing

Example 2. Dilatation -Erosion

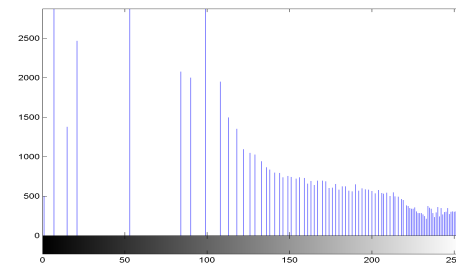
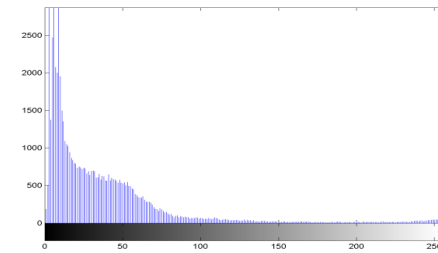
Example 3 . Histogram equalization



$$s = Cr^\gamma$$



$$S_k = T(r_k) = \sum_{j=1}^k \frac{n_j}{n}$$



Example 4 . Affine transformations

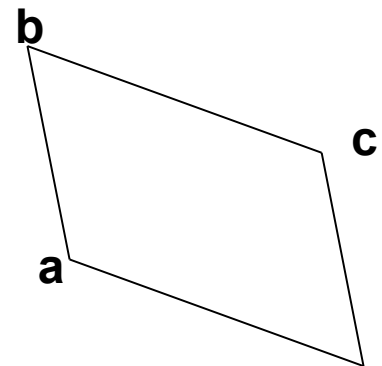
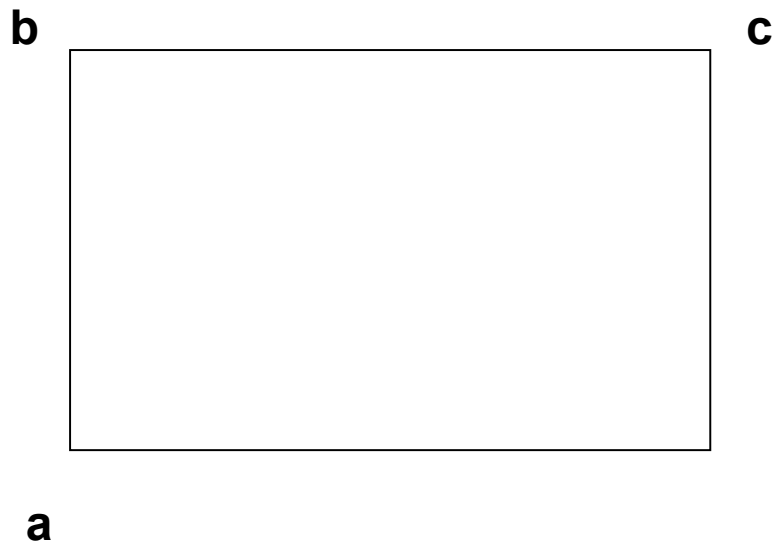
Keep parallel lines

$$y \leftarrow \mathbf{A}x + \mathbf{b}$$

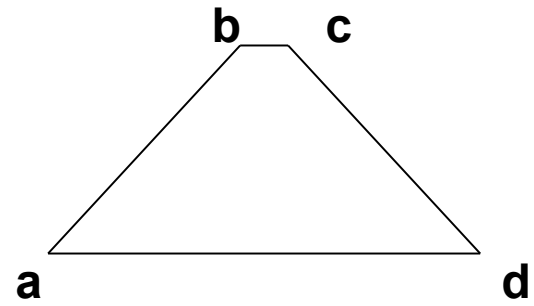
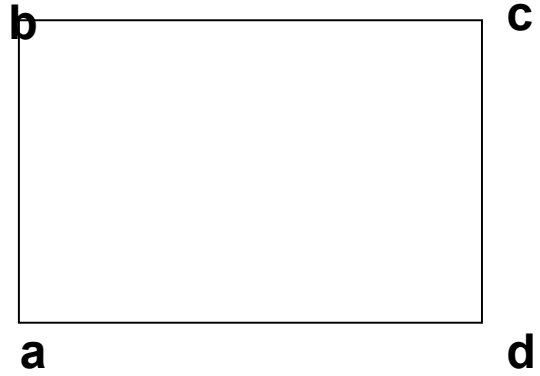
In OpenCV

$$T = [\mathbf{A} \quad \mathbf{b}] = \begin{bmatrix} a_{00} & a_{01} & b_0 \\ a_{10} & a_{11} & b_1 \end{bmatrix}$$

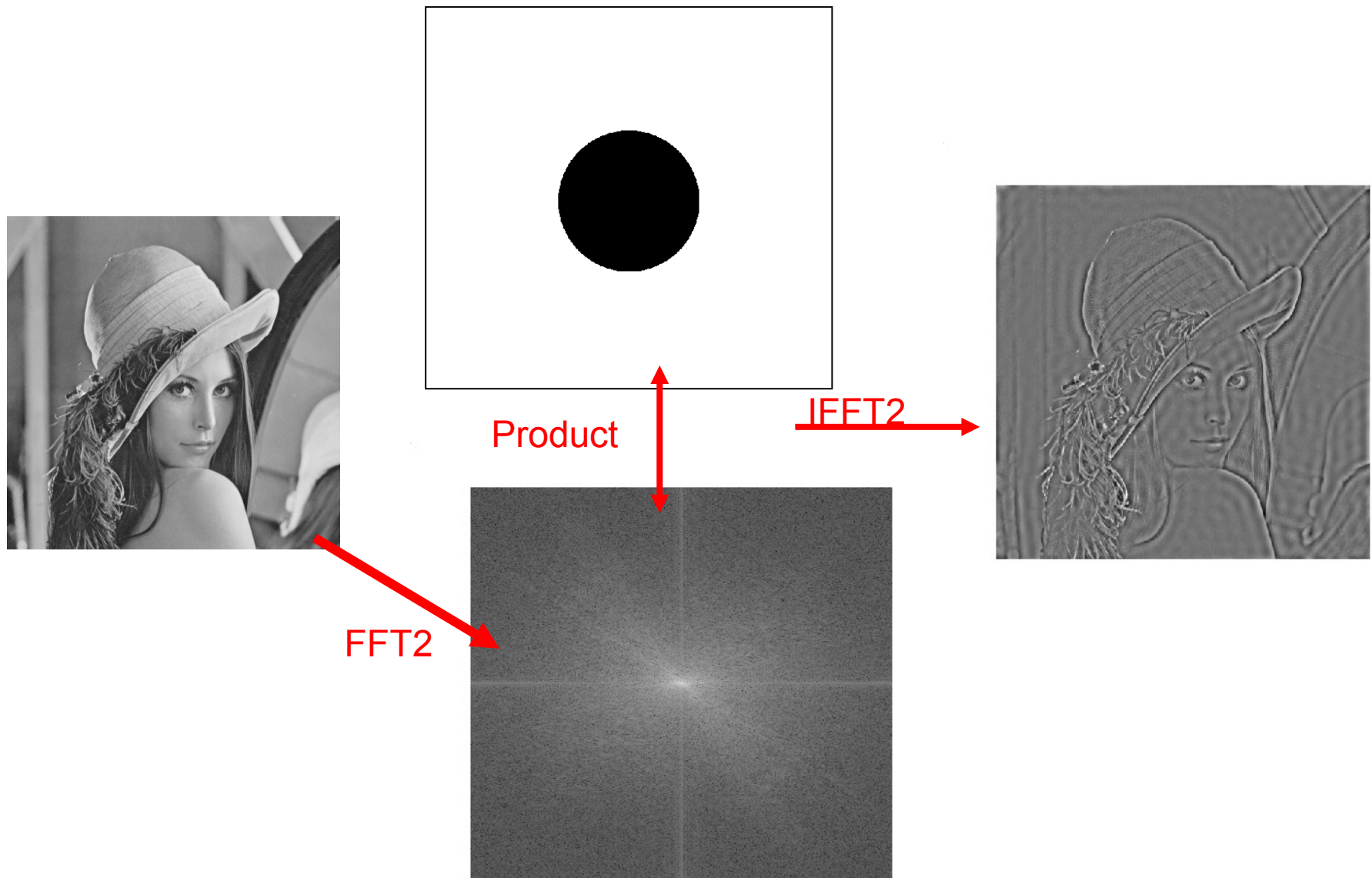
Example 5 . Get Affine transformations



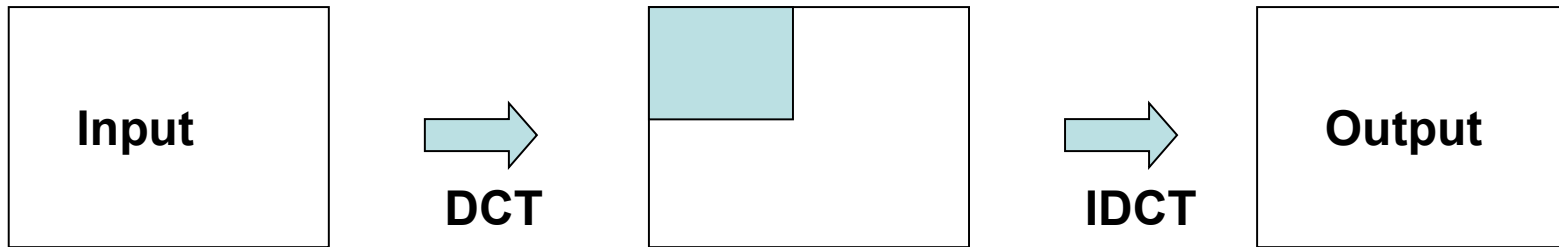
Example 6 . Get Perspective Transformation



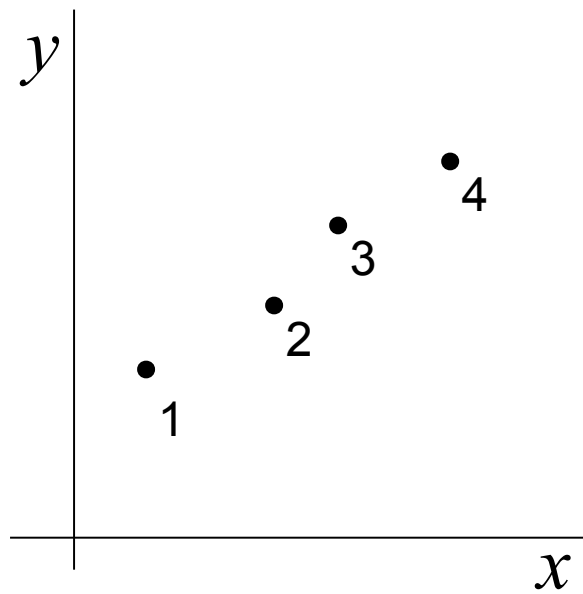
Example 7,8 9,10 . 2D DFT



Example 11 . 2D DCT

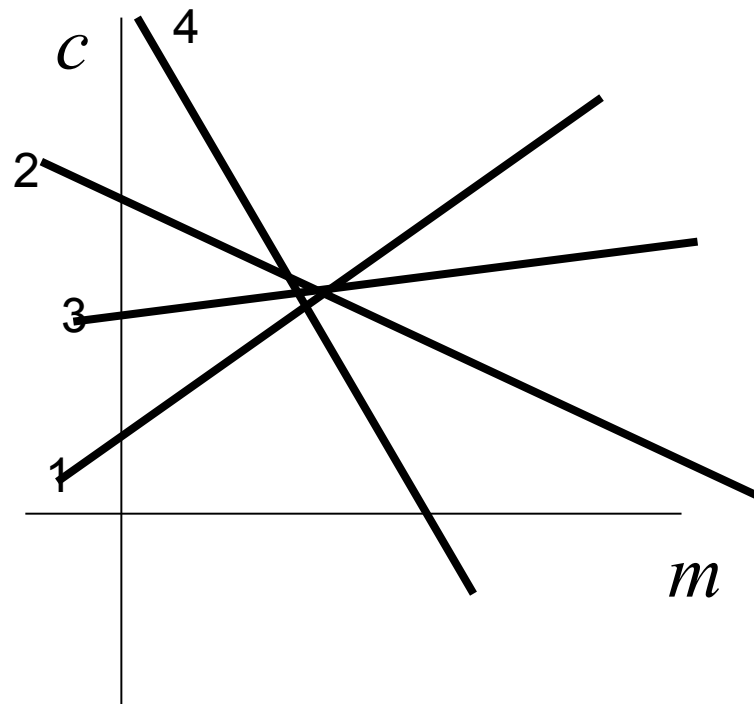


Example 12,13 .Feature extraction



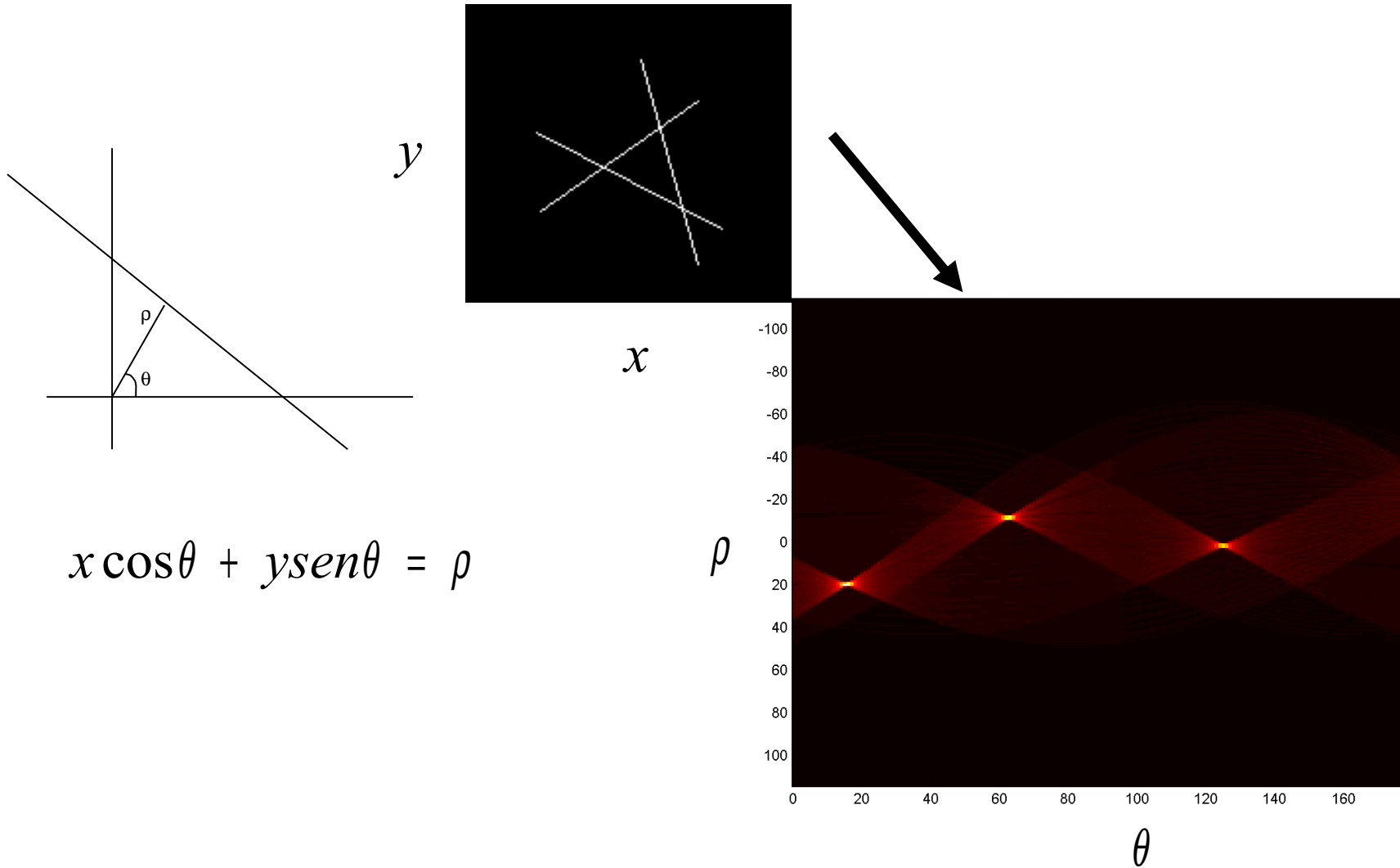
Line equation

$$y = mx + c$$

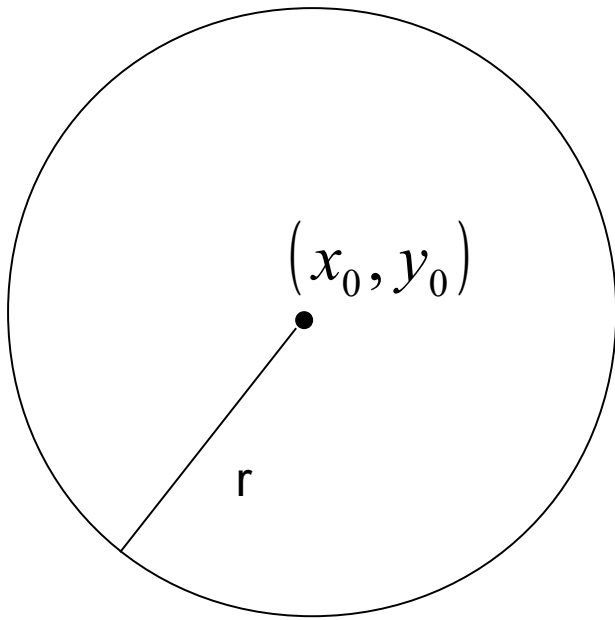


$$c = y - mx$$

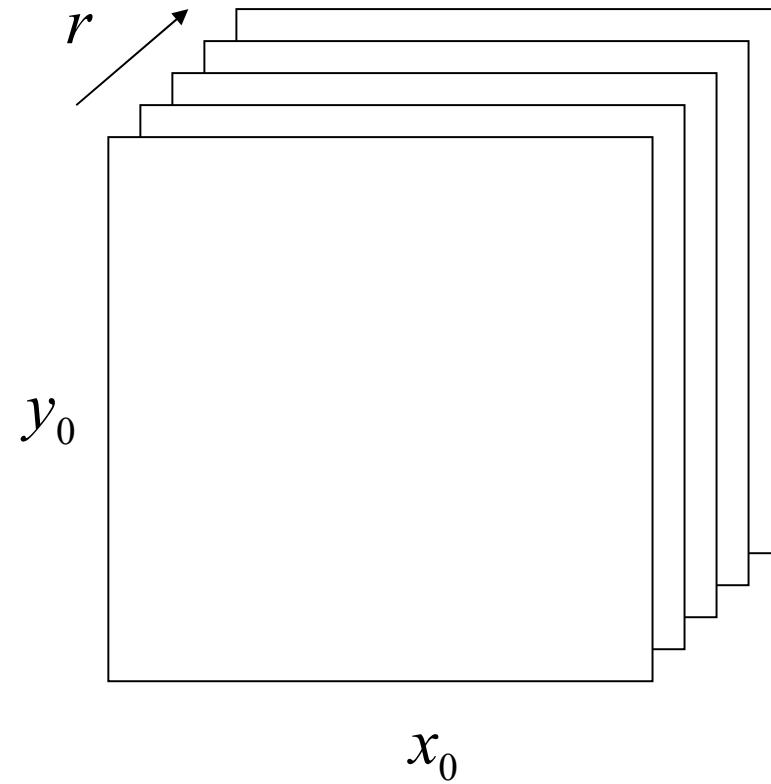
Example 12. Hough Transform, polar form for line detection



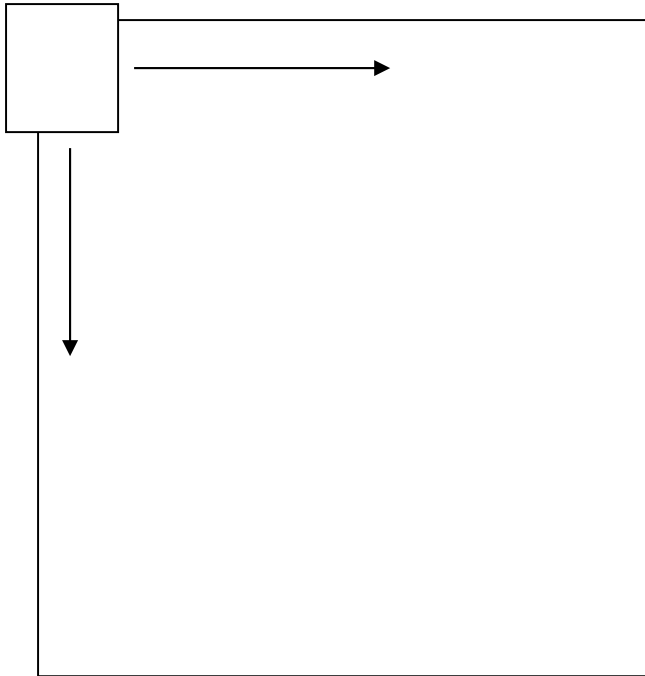
Example 13. Hough Transform, for circle detection



$$(x - x_0)^2 + (y - y_0)^2 = r^2$$



Example 14. Template Matching



- Square of the difference (look for the minimum)
- Correlation (look for the maximum)

Example 15. Contour detection

Example 16. Ellipse Fitting

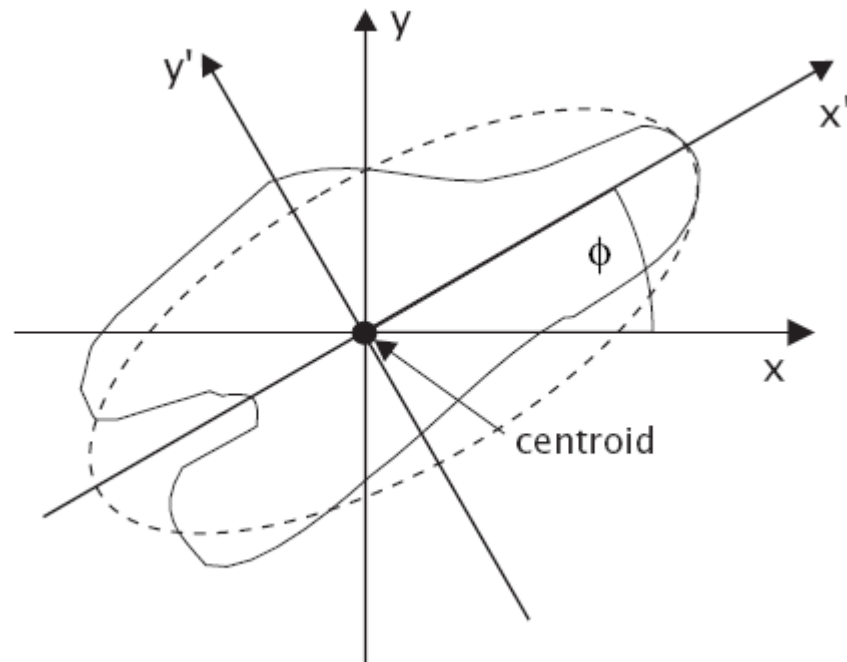


Image from: Jahne Bernd. Digital Image Processing. Springer-Verlag. 2002.

Example 17. Minimum enclosing rectangle

Example 18. Moments

$$m_{pq} = \sum_x \sum_y x^p y^q I(x, y)$$

$$m_{00} = \sum_x \sum_y I(x, y)$$

$$m_{10} = \sum_x \sum_y x I(x, y)$$

$$m_{01} = \sum_x \sum_y y I(x, y)$$

Central Moments

$$\mu_{10} = \frac{m_{10}}{m_{00}} \quad \mu_{01} = \frac{m_{01}}{m_{00}}$$

$$\mu_{pq} = \sum_x \sum_y (x - \mu_{10})^p (y - \mu_{01})^q I(x, y)$$

Normalized central moments

$$\eta_{p,q} = \frac{\mu_{p,q}}{m_{0,0}^{\frac{(p+q)+1}{2}}}$$

Example 19. Hu Moments

$$I_1 = \eta_{20} + \eta_{02}$$

$$I_2 = (\eta_{20} - \eta_{02})^2 + (2\eta_{11})^2$$

$$I_3 = (\eta_{30} - 3\eta_{12})^2 + (3\eta_{21} - \eta_{03})^2$$

$$I_4 = (\eta_{30} + \eta_{12})^2 + (\eta_{21} + \eta_{03})^2$$

$$I_5 = (\eta_{30} - 3\eta_{12})(\eta_{30} + \eta_{12})[(\eta_{30} + \eta_{12})^2 - 3(\eta_{21} + \eta_{03})^2] + \\ (3\eta_{21} - \eta_{03})(\eta_{21} + \eta_{03})[3(\eta_{30} + \eta_{12})^2 - (\eta_{21} + \eta_{03})^2]$$

$$I_6 = (\eta_{20} - \eta_{02})[(\eta_{30} + \eta_{12})^2 - (\eta_{21} + \eta_{03})^2] + 4\eta_{11}(\eta_{30} + \eta_{12})(\eta_{21} + \eta_{03}).$$

$$I_7 = (3\eta_{21} - \eta_{03})(\eta_{30} + \eta_{12})[(\eta_{30} + \eta_{12})^2 - 3(\eta_{21} + \eta_{03})^2] - \\ (\eta_{30} - 3\eta_{12})(\eta_{21} + \eta_{03})[3(\eta_{30} + \eta_{12})^2 - (\eta_{21} + \eta_{03})^2].$$

`cvGetHuMoments(CvMoments* moments, CvHuMoments* hu_moments);`