

ANGUS LEIGH

250 Durham St., Kincardine, ON, Canada, N2Z-2X9

angusleigh@gmail.com ♦ +1-226-339-9707

<http://www.cs.mcgill.ca/~aleigh1>

EDUCATION

M.Sc., Computer Science, McGill University, Montreal, QC *2013–present*
Specialization in robotics, machine learning and computer vision. Advisor: Joelle Pineau.

B.A.Sc., Systems Design Engineering, University of Waterloo, ON *2008–2013*
German minor. Cumulative GPA: 87%.

Study Abroad Semester, Technische Universität Braunschweig, Germany *Oct, 2011–Mar, 2012*
Completed full engineering course load in foreign language.

ACADEMIC RESEARCH EXPERIENCE

Graduate Researcher *2013–present*
McGill University *Montreal, QC*

- Developing vision, navigation and control techniques for an autonomous powered wheelchair.
- Emphasis on fast prototyping of state-of-the-art techniques and testing/breaking existing algorithms in the real-world to focus research on areas of highest practical impact.

Undergraduate Research Assistant (part-time) *May–Aug, 2011*
University of Waterloo *Waterloo, ON*

- Updated a muscle fiber action potential simulator to reflect recent findings in the literature.

Undergraduate Research Assistant (part-time) *Sept–Dec, 2010*
University of Waterloo *Waterloo, ON*

- Created a novel method for comparing image noise reduction and estimation techniques.

PUBLICATIONS

A. Leigh and J. Pineau, “Laser-based Person Tracking for Clinical Locomotion Analysis”, *IROS Workshop on Rehabilitation & Assistive Robotics*, Chicago, Illinois, USA, 2014.

A. Leigh, A. Wong, D. A. Clausi and P. Fieguth, “Comprehensive analysis on the effects of noise estimation strategies on image noise artifact suppression performance”, *IEEE International Symposium of Multimedia*, Dana Point, California, USA, 2011.

DEMONSTRATIONS

M. Gerdzhev, J. Pineau, **A. Leigh** and A. Sutcliffe, “SmartWheeler - A smart robotic wheelchair platform”, demonstrated at *Neural Information Processing Systems (NIPS)*, Montreal, Canada, 2014.

WORKS SUBMITTED OR UNDER REVIEW

A. Leigh, J. Pineau, N. Olmedo and H. Zhang, “Person Tracking and Following with 2D Laser Scanners”, *Submitted to the International Conference on Robotics and Automation (ICRA)*, submission number: 1523, date submitted: Oct. 1, 2014.

INDUSTRY EXPERIENCE

Robotics Engineering Student Developer

Siemens Corporate Research and Technologies

Apr–Aug, 2012

Munich, Germany

- Developed a simulated robotic model of a new concept of electric car using C++, Robot Operating System (ROS) and Unified Robot Description Format (URDF).
- Researched and implemented low-and high-level control systems for driving and steering, including a non-holonomic trajectory follower to allow for autonomous driving.

Systems Design Engineering Student

DurrIDGE Co.

Jan–Apr, 2011

Billerica, MA, USA

- Multi-task development of a novel Radon-detection device, including modification of electrical schematics in EAGLE, writing firmware in C and placing product orders with manufacturers.

Design Engineering Student

Automation Engineering Associates

May–Aug, 2010

Toronto, ON

- Designed, coded, tested, and troubleshoot control programs for automating commercial and residential heating, cooling and ventilation systems.

.NET Programmer

Human Resources Canada

Sept–Dec, 2009

Ottawa, ON

Engineering Assistant

Hatch Ltd.

Jan–Apr, 2009

Mississauga, ON

TEACHING EXPERIENCE

Teaching Assistant

COMP-598: Applied Machine Learning

2014

McGill University

- Delivered guest lecture on online learning.

AWARDS

Graduate Research Award

Tenured at McGill University

2014

McGill Graduate Excellence Award

Tenured at McGill University

2013

NSERC Canada Graduate Scholarship - Master's

Tenured at McGill University

2013

Ontario Graduate Scholarship

Not tenured

2013

Best design project of 4th year engineering class (tied)

2013

Wilfred L. Bitzer Award

For outstanding exchange students to Germany

2011

Engineering President's & Entrance Scholarships

Tenured at the University of Waterloo

2008

Queen Elizabeth II Provincial Scholarship

Tenured at the University of Waterloo

2008

VOLUNTEER EXPERIENCE

Robotics Competition Referee

First Lego League

Mar, 2014

Montreal, QC

- Observed matches to ensure fair play and a smoothly operating tournament. Single day.

Bicycle Repair Mentor

University of Waterloo

2012–2013

Waterloo, ON

- Responsible for the university's student bicycle shop for two hours per week.
- Helped customers in a fast-paced environment and used my bicycle repair expertise to mentor them on various bicycle repair techniques.

SKILLS

Programming	Python, C++, MATLAB, C (firmware)
Robotics	ROS, OpenCV, Gazebo, URDF
Computer	Linux, Git, \LaTeX
Languages	English (native), German (fluent but rusty), French (intermediate)

HOBBIES

Acoustic guitar, sports, building and flying radio controlled planes, catamaran sailing and bicycle touring (two months from Vancouver to Tijuana).