

# **DATA STRUCTURE AND ALGORITHMS**

## **LECTURE 7**

### **Searching and Binary Search Tree**

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# Reference links:

<https://cs.nyu.edu/courses/fall17/CSCI-UA.0102-007/notes.php>

<https://www.comp.nus.edu.sg/~stevenha/cs2040.html>

<https://visualgo.net/en/bst>

[M.Goodrich, chapter 11]

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# Lecture outline

- ❑ Searching Algorithms
  - Sequential Search
  - Binary Search
- ❑ Binary Search Tree (BST)
  - BST property
  - BST operations
  - BST applications
- ❑ Balanced Search Tree
- ❑ Other Search Trees

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# Searching Algorithms

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- Sequential Search
  - Binary Search
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# Searching Problem

- ❑ Search problem: find an item or group of items with specific properties within a collection of items. The question can be:
    - **Appear or not?** How many times? At which positions?
  - ❑ Collection of items
    - Store in a table: 1-dimension (list), 2-dimension (matrix)
    - Implement by array or linked list
  - ❑ Search algorithm:
    - Iterate and compare items
    - But how the list be created? – affect to algorithm complexity
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# Sequential Search

- ❑ Sequential Search or Linear Search (in 1-d)
  - ❑ **Iterate** begin from the first of the list until the item is found or the entire list has been searched
  - ❑ Advantages
    - Algorithm easy to implement
    - List can be in any order
  - ❑ Disadvantages
    - Inefficient (slow):  $O(n)$
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# Binary Search

- ❑ Binary Search or Bisection Search (in 1-d)
  - ❑ Using divide and conquer strategy
    - Compare the search value with the middle item of the list
    - Continue search in the half of the list where the value might be appear.
  - ❑ Advantages
    - Much more efficient than linear search  $O(\log N)$
  - ❑ Disadvantages
    - List be required in order (be sorted)
-

# Search Algorithm running time

Run time of list operations related to searching:

	Unsorted Array/List	Sorted Array	Unsorted Linked List
insert (add)	$O(1)$	$O(n)$	$O(1)$
delete (remove)	$O(n)$	$O(n)$	$O(1)$
search (isContain)	$O(n)$	$O(\log n)$	$O(n)$

GOAL:  $O(\log n)$  for all operations



Binary Search  
Tree



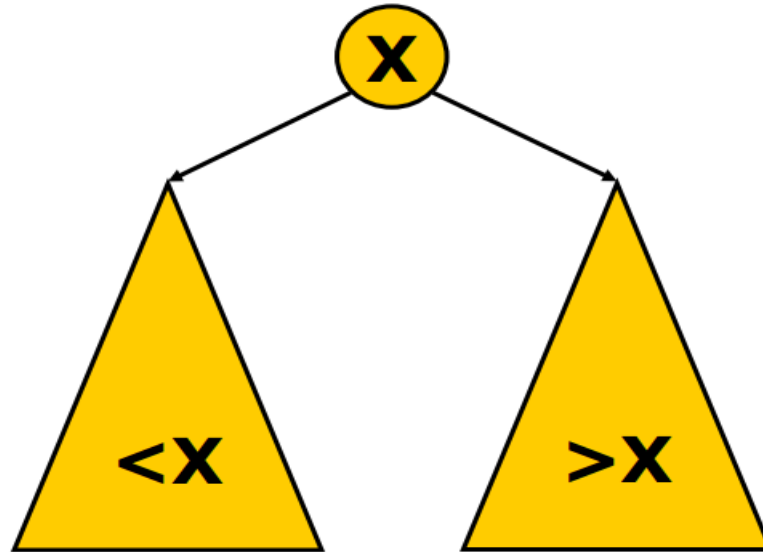
# Binary Search Trees (BST)

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[M.Goodrich, sec. 11.1, p. 460]

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# BST Property

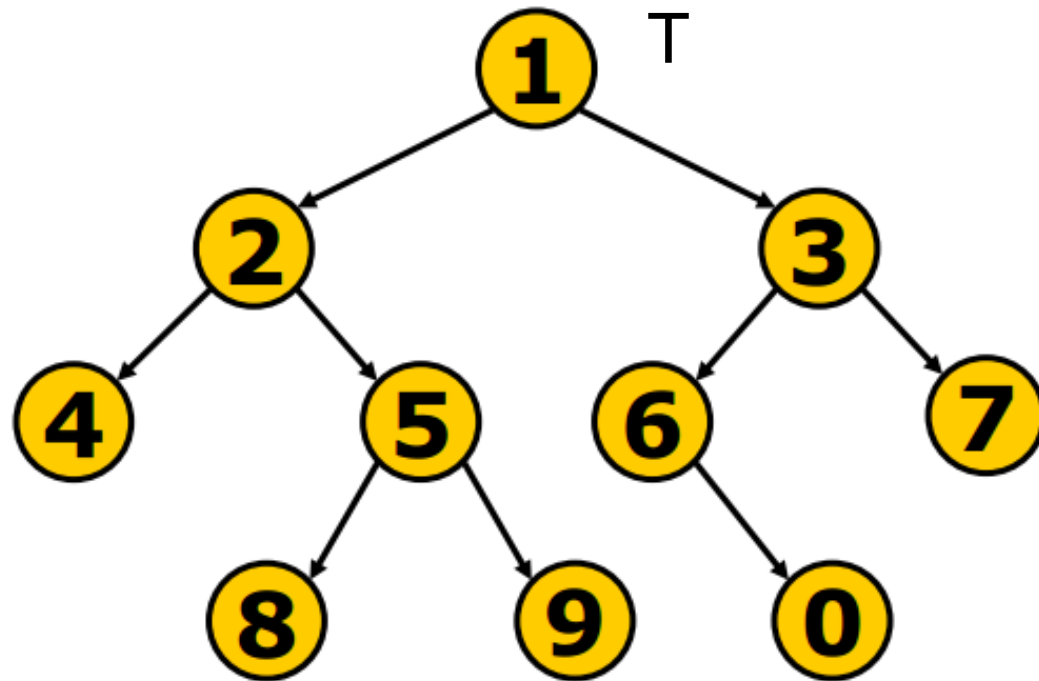


- BST organizes data in a binary tree such that
  - all keys **smaller** than the root are stored in the left subtree, and
  - all keys **larger** than the root are stored in the right subtree.

Q: Can we have the same key values in a BST?

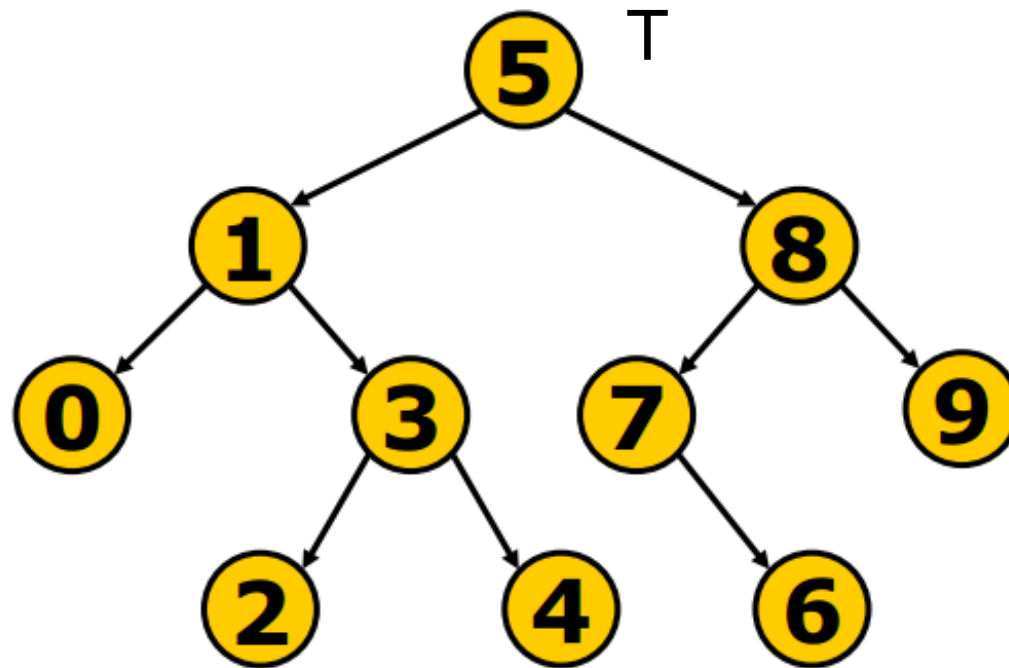
Or: How to handle duplicates in Binary Search Tree?

# BST Example



T is a BST or not? Why?

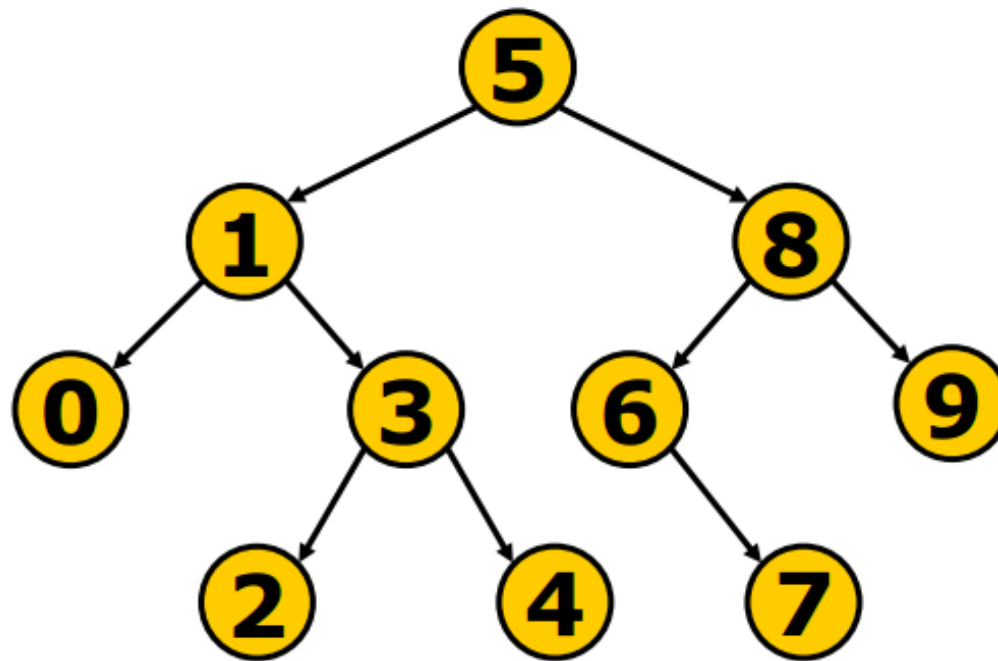
# BST Example



And this tree T? **No** - Why?

How to rearrange it to BST?

# BST Example



**A BST**

Q: What do you get when traverse a BST in **In-order**?

A: We get list **0, 1, 2, 3, 4, 5, 6, 7, 8, 9**

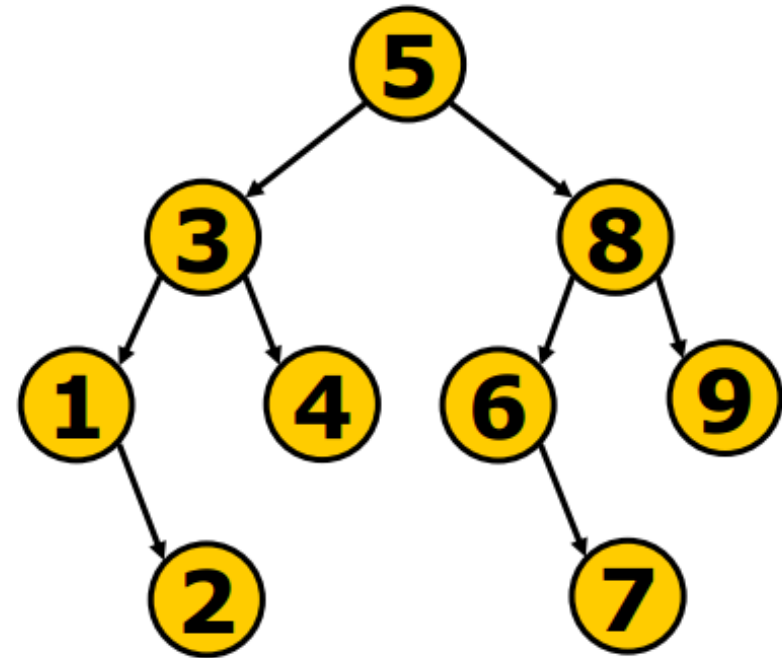
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# BST Operations

# Finding Minimum Element

```
findMin(T) ≡  
    while (T.left is not empty)  
        T = T.left;  
    return T.item;  
end.
```



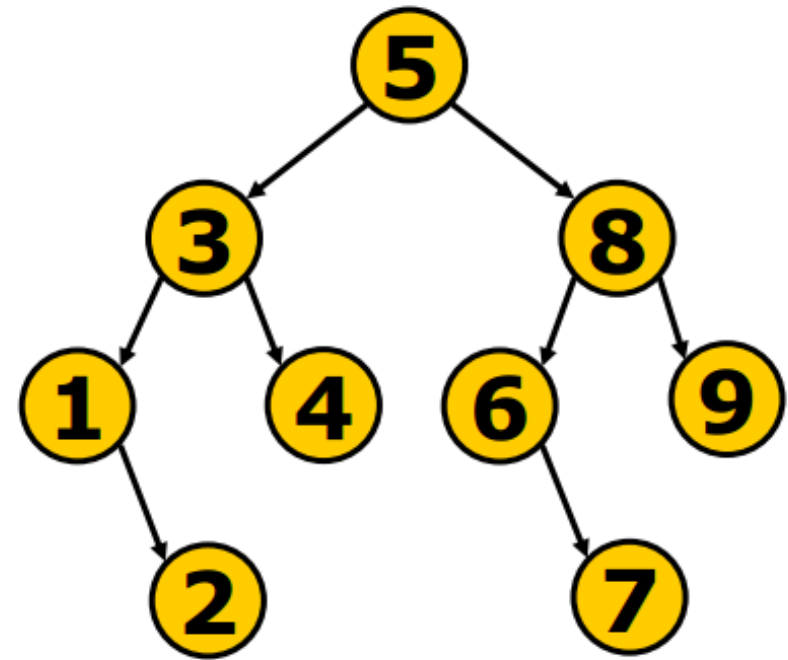
Running time:  $O(h)$

Q: How to find **maximum** element?

Q: How to find **top-k** (or **bottom-k**) element?

# Searching x in T (iterative solution)

```
search (x,T) ≡  
  while (T is not empty)  
    if (x==T.item)  
      return T  
    else if (x<T.item)  
      T = T.left  
    else  
      T = T.right  
  return null // T is empty, so x is not in T  
end.
```



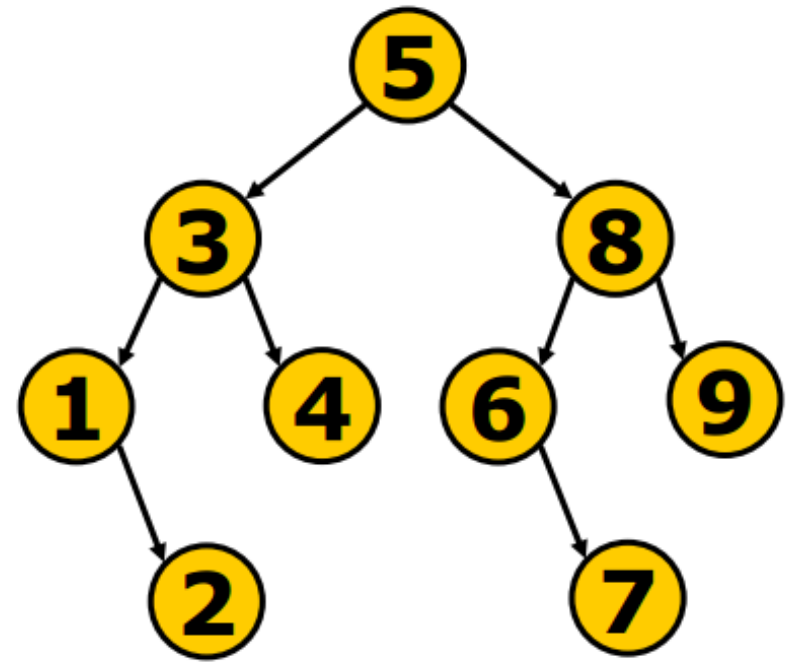
Ex: search(6,T)

Running time:  $O(h)$



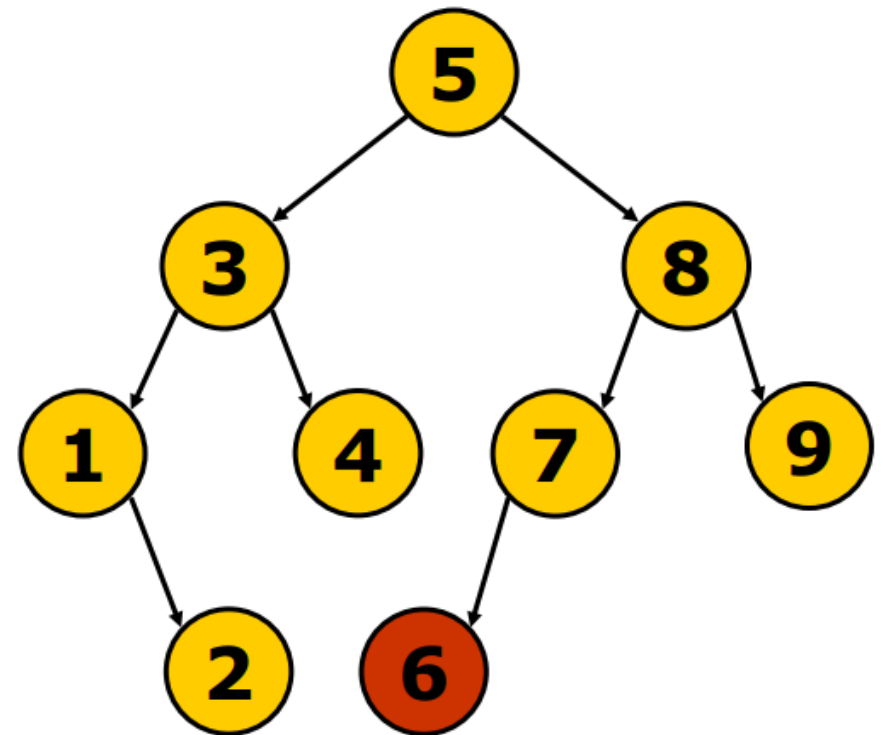
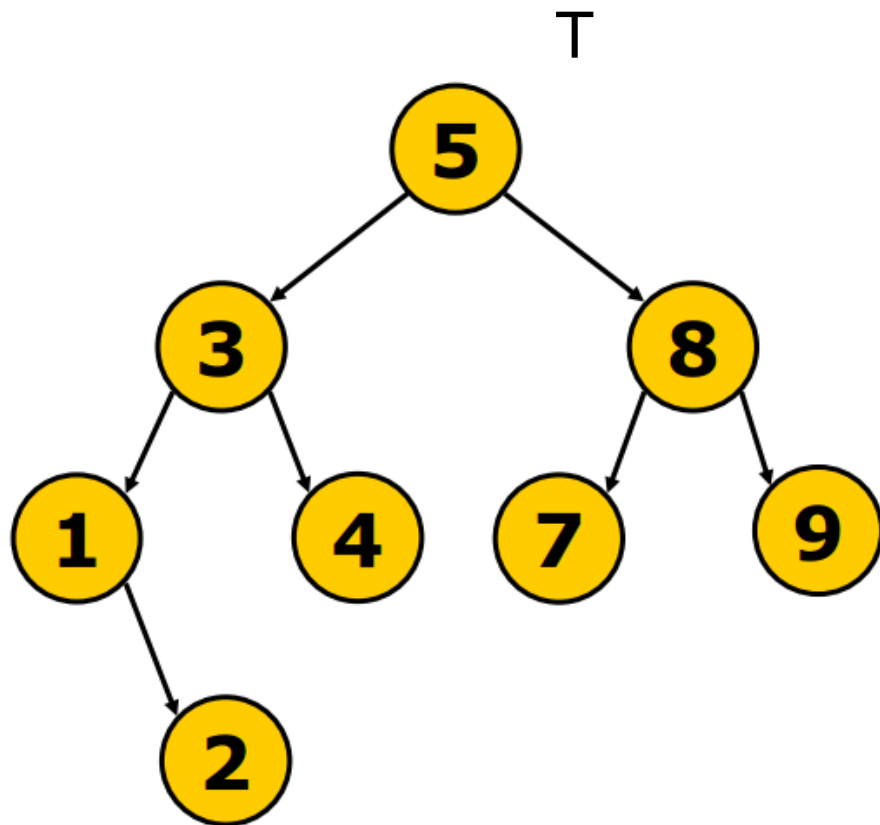
# Searching $x$ in $T$ (recursive solution)

```
search (x,T)  $\equiv$   
  if (T is empty)  
    return null  
  if (x==T.item)  
    return T  
  else if (x<T.item)  
    return search(x,T.left)  
  else  
    return search(x,T.right)  
end.
```



Running time is  $O(h)$ , isn't it?

# Insert x to T



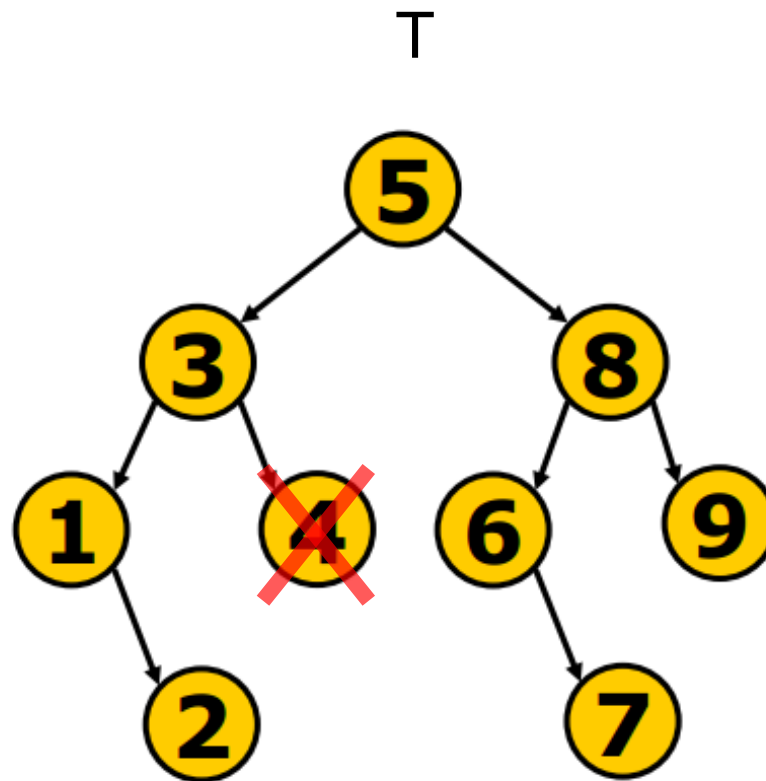
How to insert element with value key **6** to T?

# Insert x to T

```
insert (x,T) ≡  
    if (T is empty)  
        return new TreeNode(x) //a tree with only node x  
    else if (x<T.item)  
        T.left=insert(x,T.left)  
    else if (x>T.item)  
        T.right=insert(x,T.right)  
    else  
        ERROR! //x already in T  
    return T;    //return the new tree T  
end.
```

Running time is  $O(h)$

# Delete x from T



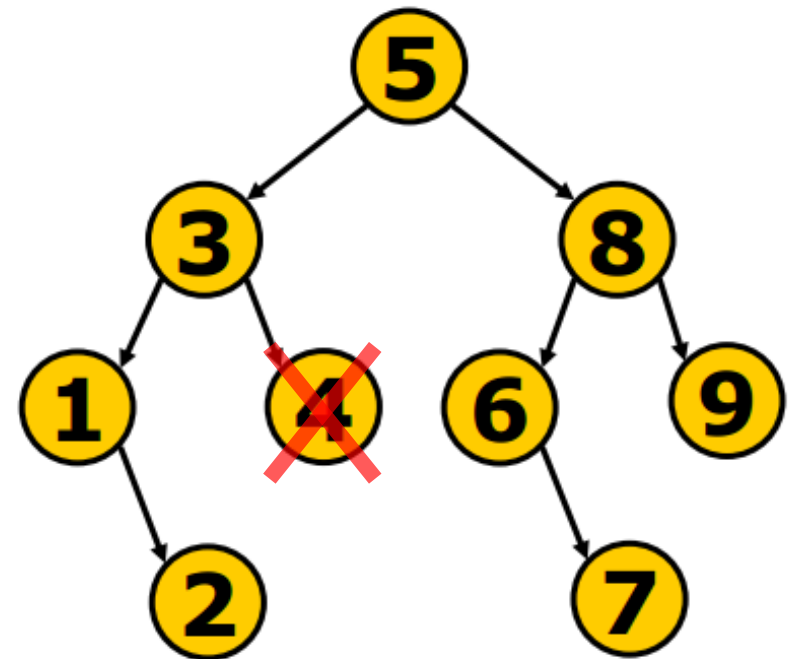
How to delete the element with value key x from T?

Some difference cases from T has children or not...

# Delete x from T: case 1

- Node to be deleted has no children. Ex: Delete 4 from T

```
delete (x,T) ≡  
  if (T has no children)  
    if (T.item == x)  
      return empty tree  
    else  
      NOT FOUND  
end.
```



Ex: Delete 4 in tree T

# Delete x from T: case 2(a)

- Node to be deleted has only left child

**delete (x,T)  $\equiv$**

**if (T has only 1 child (left))**

**if (x==T.item)**

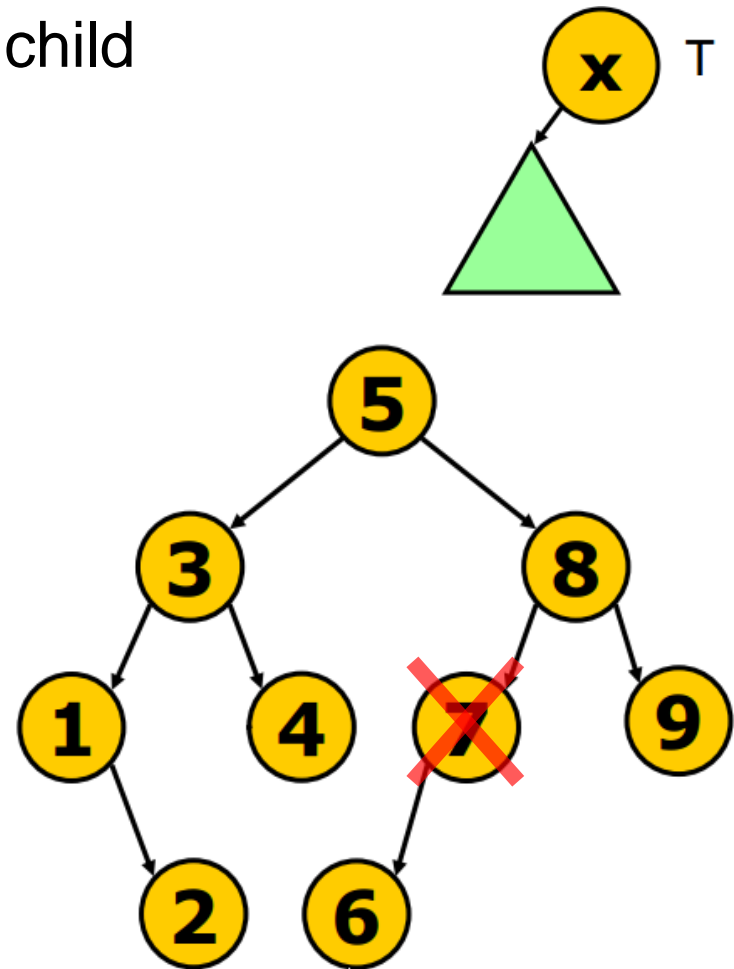
**return T.left**

**else**

**T.left=delete(x,T.left)**

**return T**

**end.**



Ex: Delete 7 from tree T

# Delete x from T: case 2(b)

□ Node to be deleted has only right child

**delete (x,T)  $\equiv$**

**if** (T has only 1 child (right))

**if** (x==T.item)

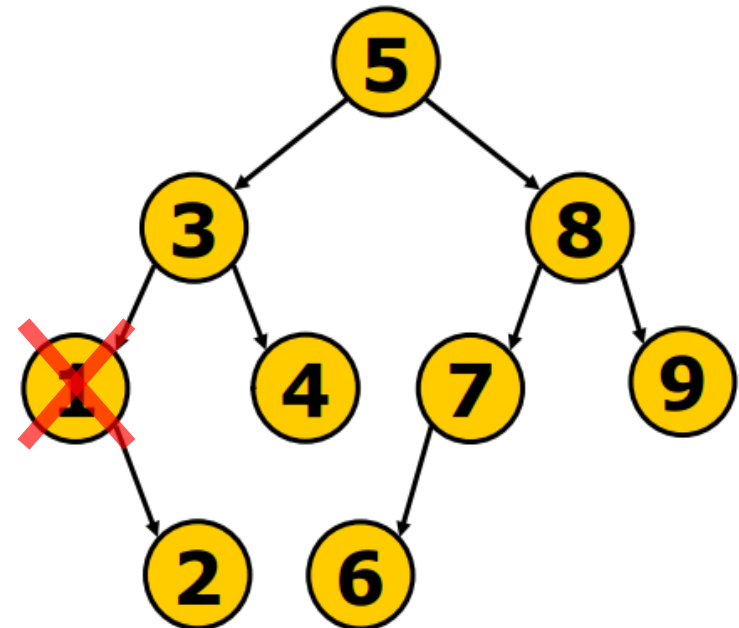
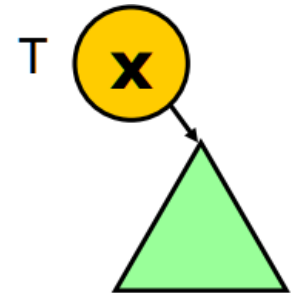
**return** T.right

**else**

T.right=delete(x,T.right)

**return** T

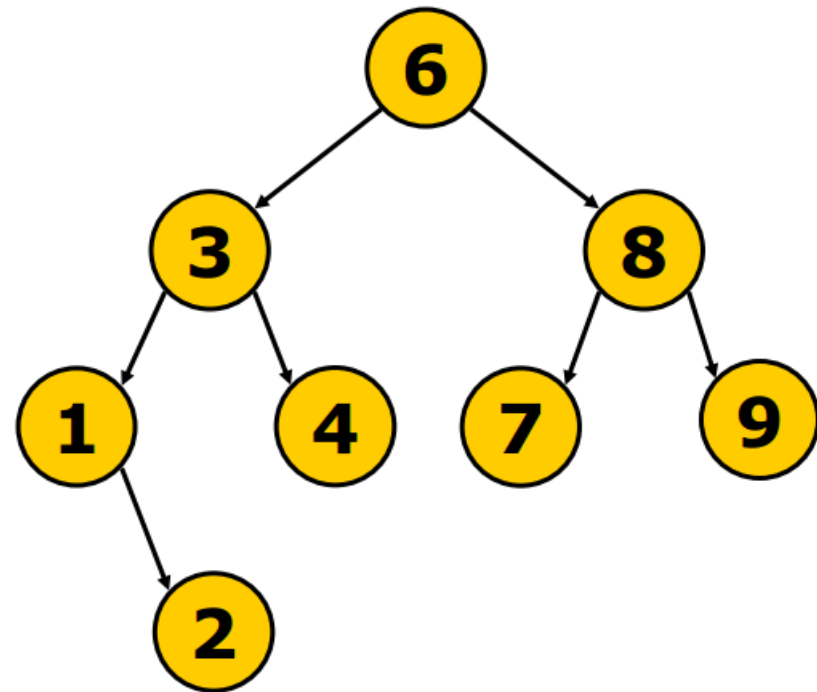
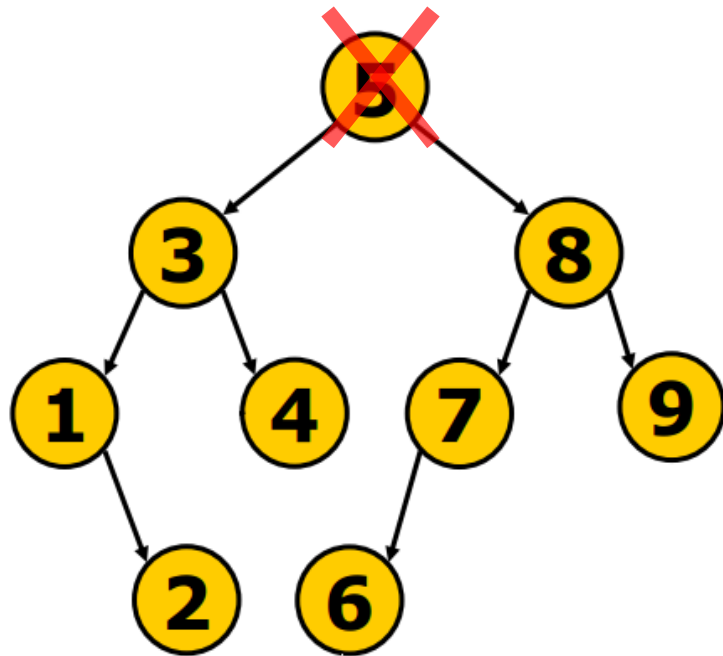
**end.**



Ex: Delete 1 from tree T

# Delete x from T: case 3

- Node to be deleted has 2 children. Ex: Delete 5 from T



5 deleted from T!



# Delete x from T: case 3

**delete (x,T)  $\equiv$**

**if** (T has two children)

**if** (T.item == x)

T.item=findMin(T.right) //replace T.item by min of right

T.right = delete(T.item, T.right)

**else if** (x<T.item)

T.left=delete(x,T.left)

**else**

T.right=delete(x,T.right)

**return** T

**end.**

Running time is  $O(h)$

# BST algorithms running time

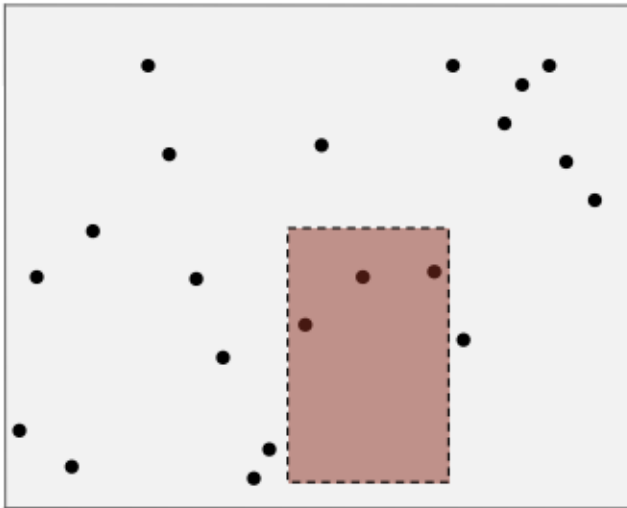
□ Running time of BST operations:

	Unsorted Array/List
findMin()	$O(h)$
search(x,T)	$O(h)$
insert(x,T)	$O(h)$
delete(x,T)	$O(h)$

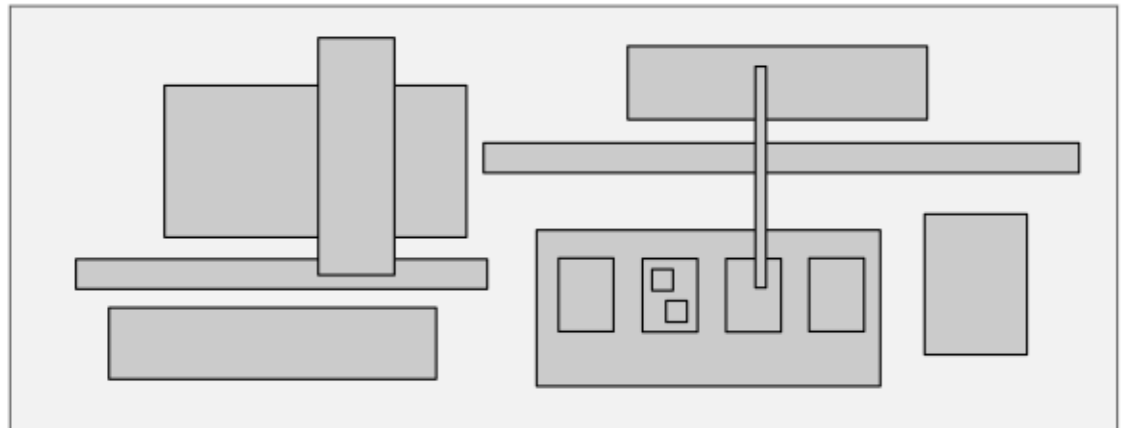
GOAL:  $O(\log n)$  for all operations – REACHED!

# BST Applications

- ❑ Intersections among geometric object



2d orthogonal range search



orthogonal rectangle intersection

- **Applications:** CAD, games, movies, virtual reality, databases, GIS...
- **Efficient solutions:** Binary search trees (and extensions).

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# BST Applications

## □ Geometric Application of BSTs

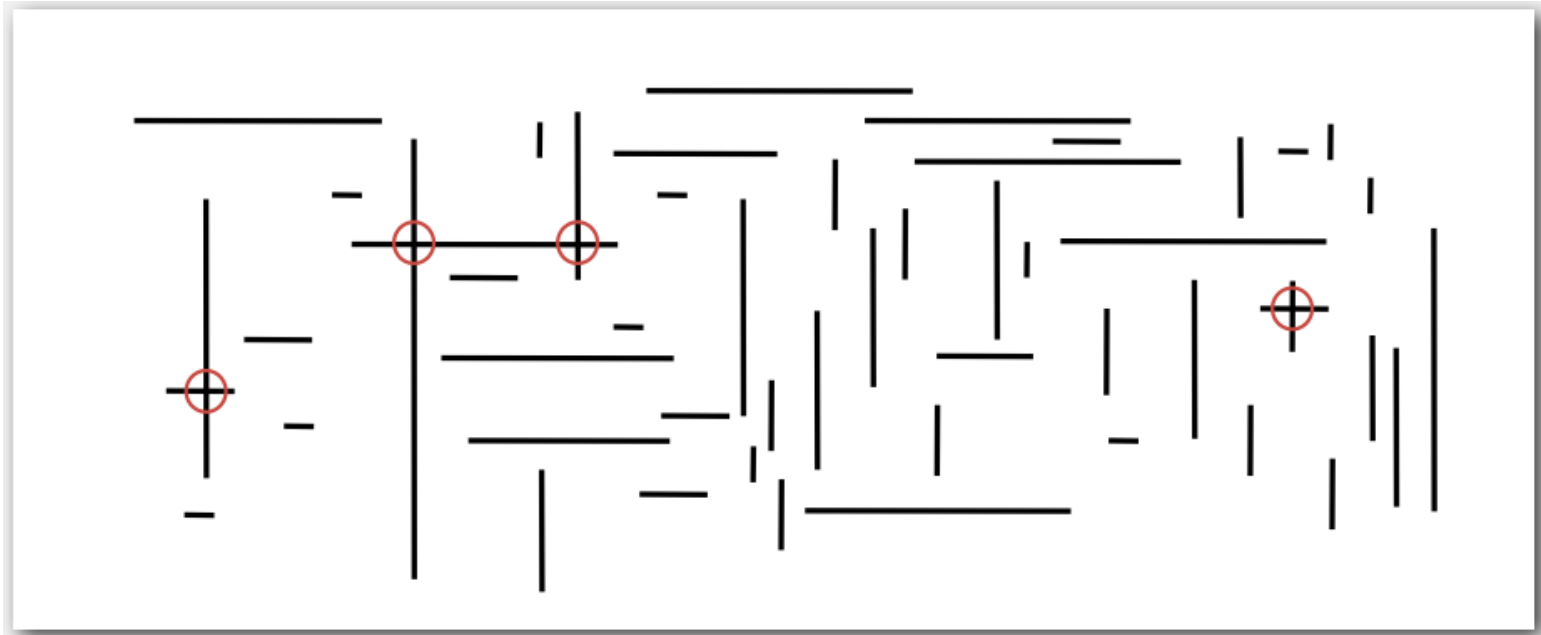
- 1-d range search (tìm kiếm 1 chiều)
- Line segment intersection (giao đoạn thẳng)
- k-d trees (cây k chiều)
- Interval search trees (cây tìm kiếm khoảng)
- Rectangle intersection (giao các hình chữ nhật)

For more detail: [Geometric Application of BST.pdf](#)

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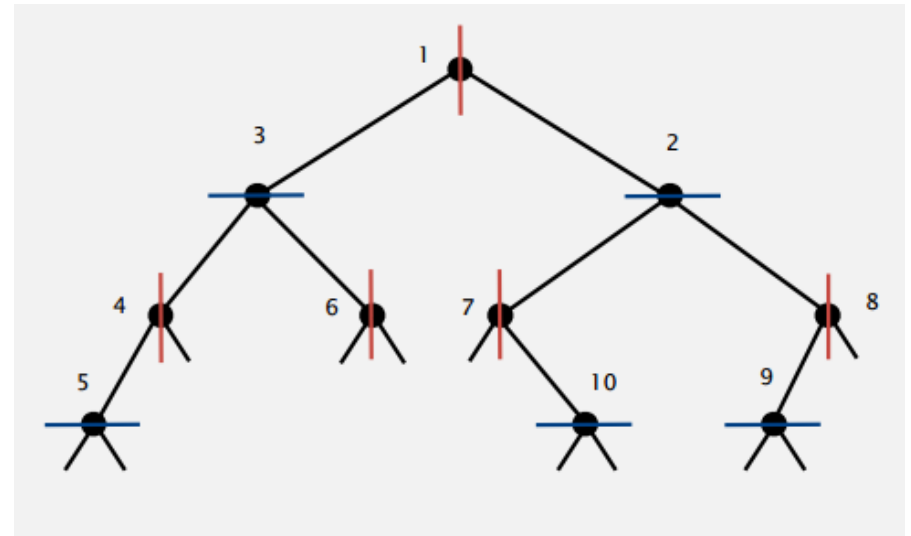
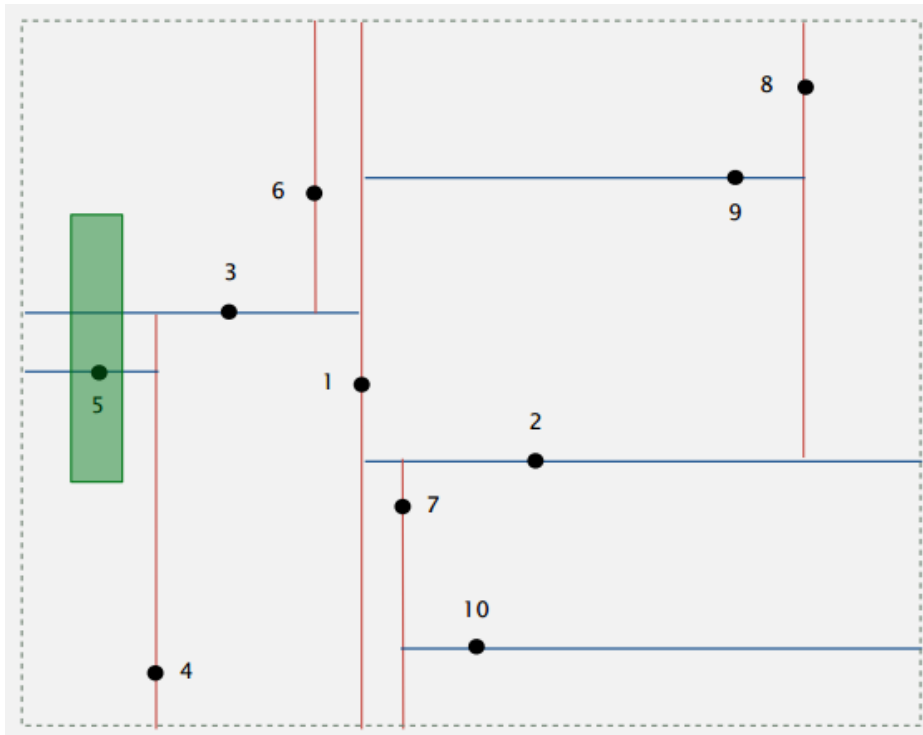
# BST Applications

- Line segment intersection



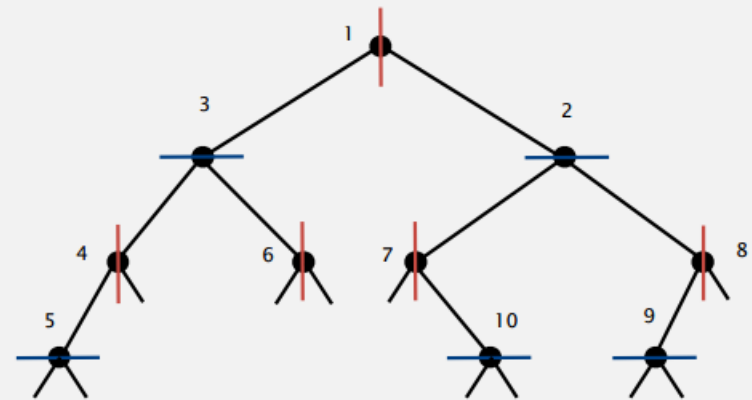
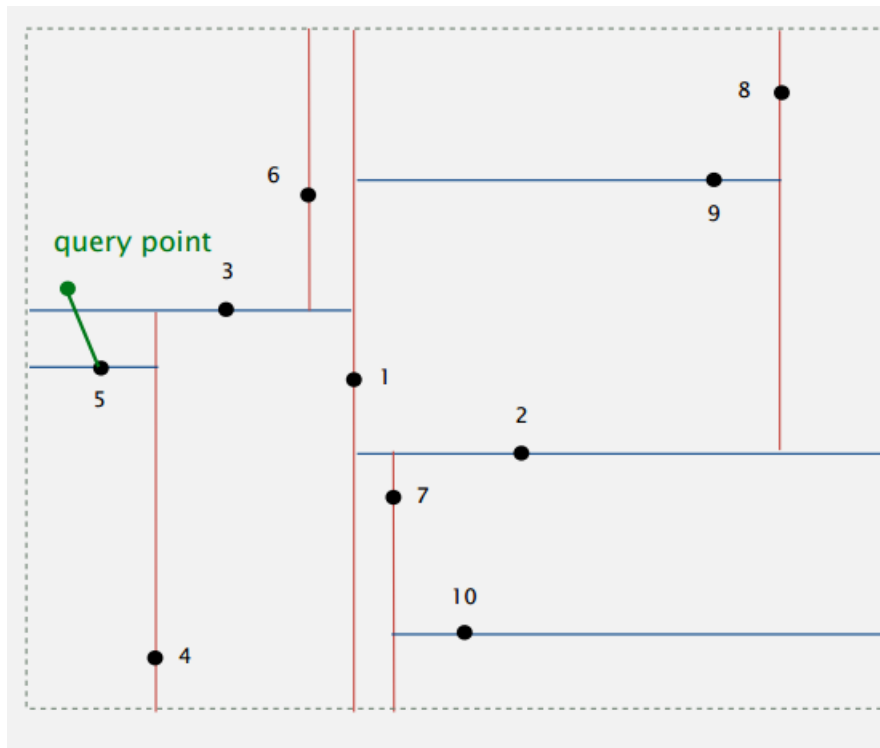
# BST Applications

## □ Range search in a 2-d tree



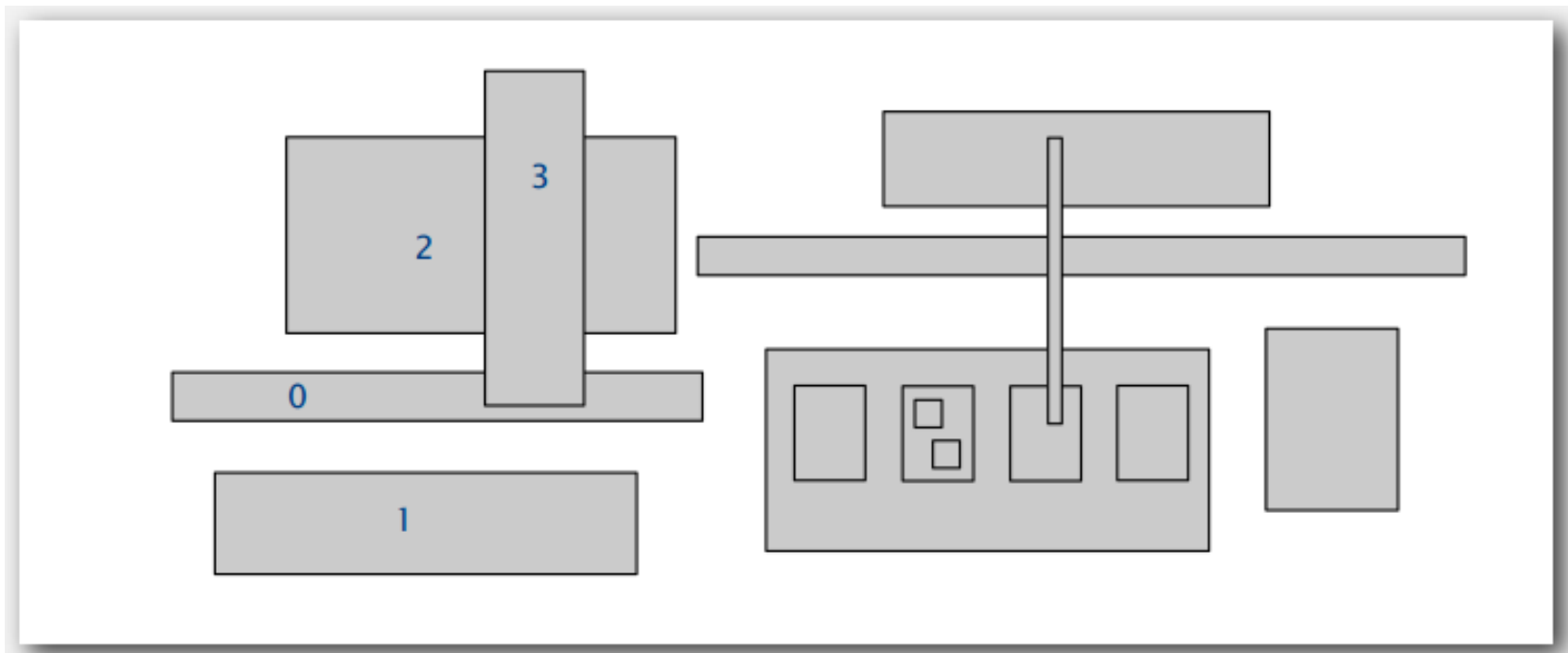
# BST Applications

- Nearest neighbor search in a 2-d tree (Láng giềng gần nhất)



# BST Applications

## □ Rectangle intersection





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# BST Applications

- ❑ Interesting natural phenomenon and math algorithm:

Flocking birds and [Boids Algorithm](#)



<https://www.youtube.com/watch?v=4LWmRuB-uNU>

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# BST Applications

For more details: [Geometric Application of BST.pdf](#)

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# Binary Search Tree

Running time of BST operations:

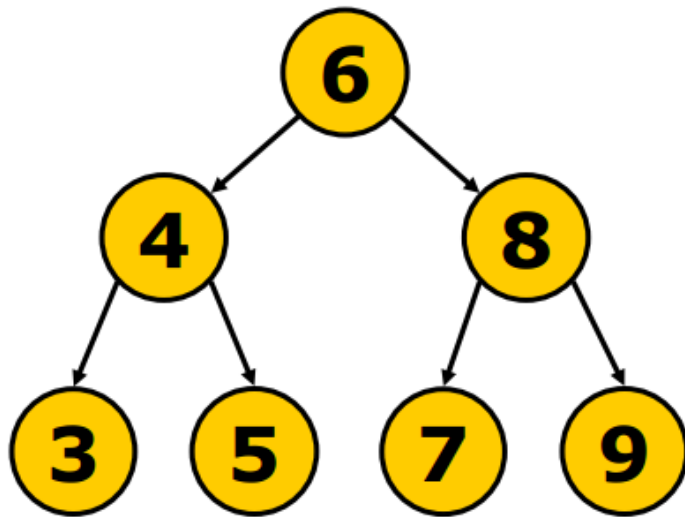
	Unsorted Array/List
findMin()	$O(h)$
search(x,T)	$O(h)$
insert(x,T)	$O(h)$
delete(x,T)	$O(h)$

GOAL:  $O(\log n)$  for all operations – REACHED!

**BUT...!**

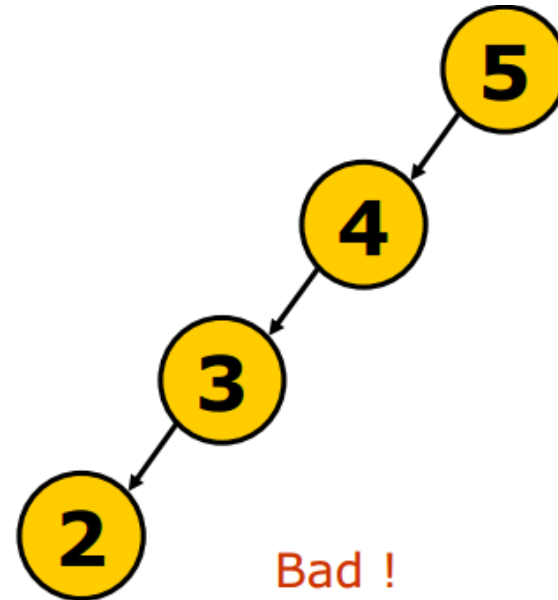
# BST algorithms running time

**But...**  $h$  is not always  $O(\log n)$  with BST size  $n$ !!!



Good !

$$h = O(\log n)$$



Bad !

$$h = O(n)$$

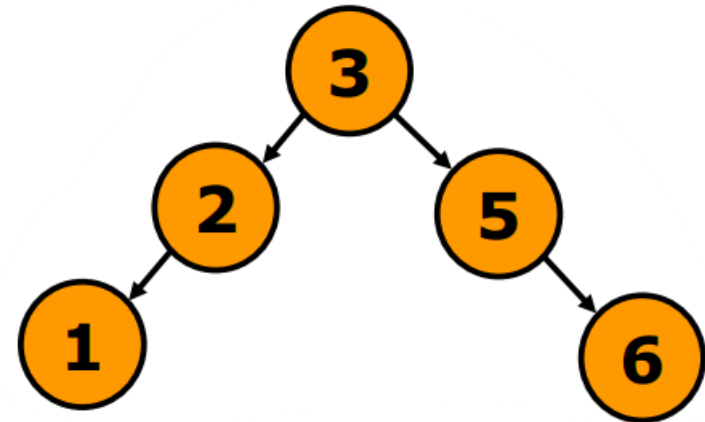
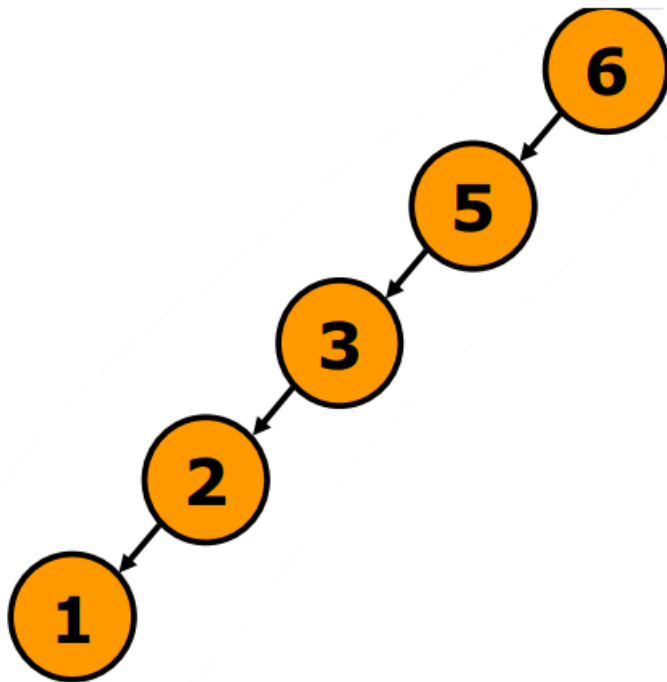
We get **skewed** tree when nodes are inserted in  
increasing or decreasing order.

# BST Solution for worst case

Skewed trees



Balanced trees





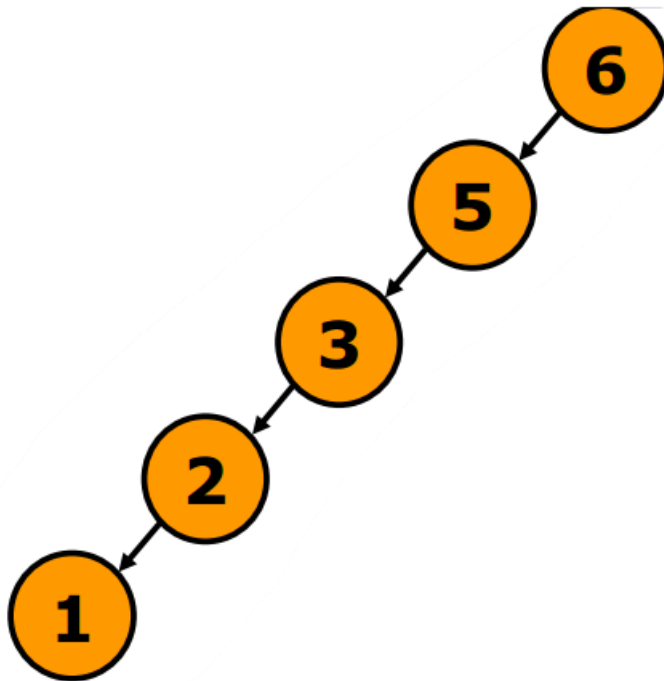
# Balanced Search Tree

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[M.Goodrich, sec. 11.2, p. 472]

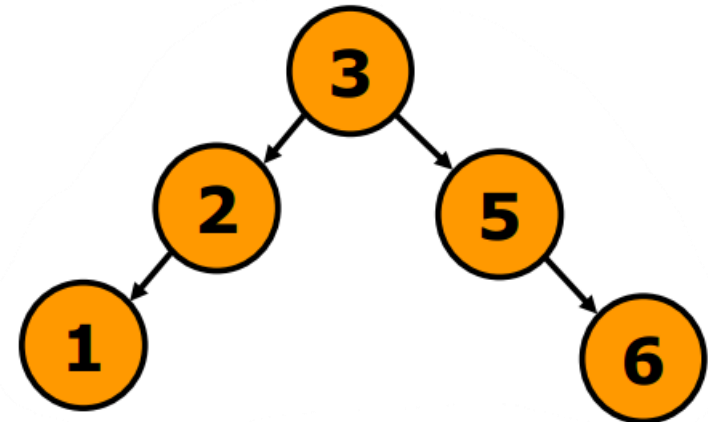
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# BST Solution for worst case



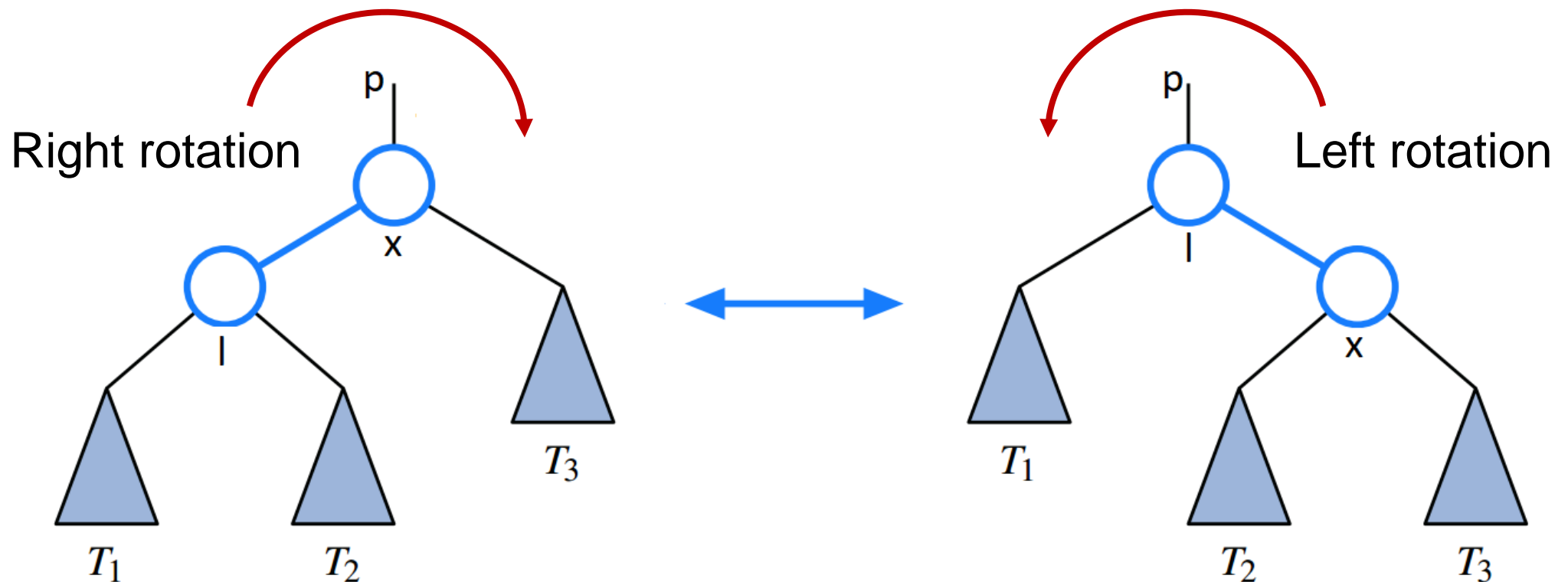
Skewed tree

convert into  
through a series of  
**rotations**



Balanced tree

# Balanced Tree: Rotation



**Rotate:** A child to be above its parent



# Balanced Tree: Rotation algorithm

**rotateRight (x)  $\equiv$**

l = x.left

**if** (l is empty)

**return**

x.left = l.right //(1)

l.right = x //(2)

p = x.parent

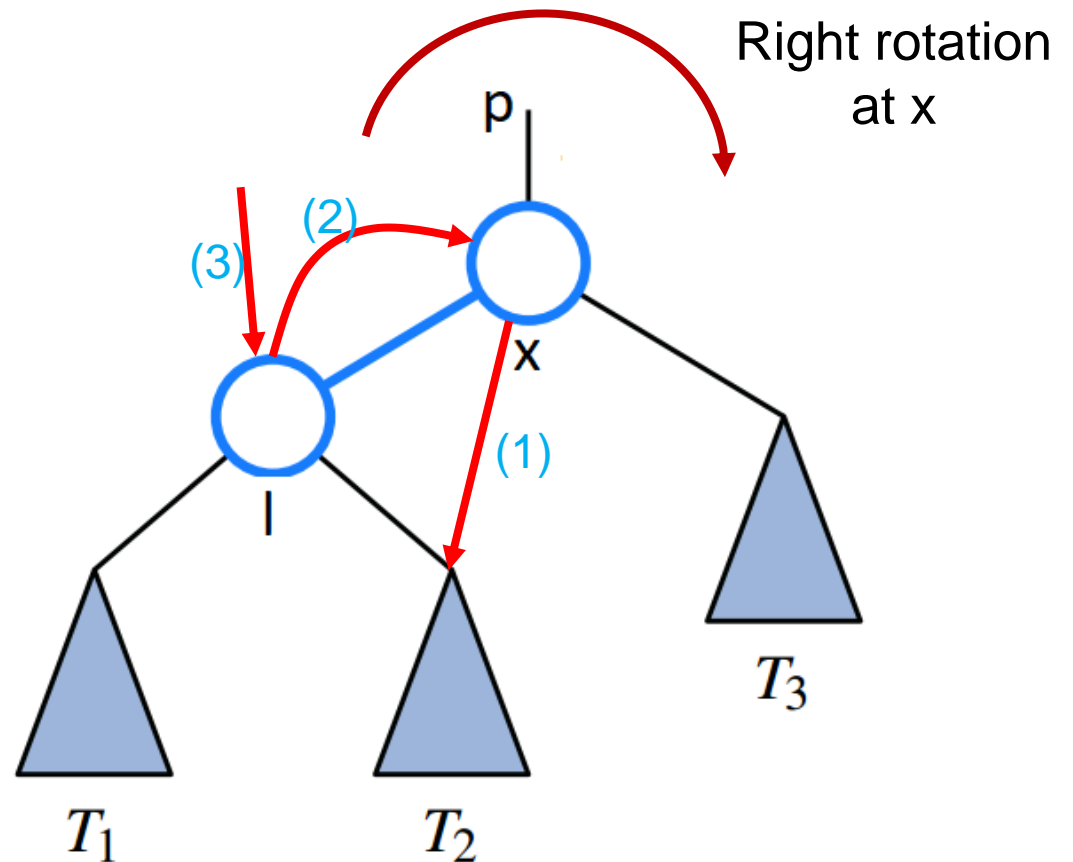
**if** (x is a left child)

p.left = l //(3)

**else**

p.right = l //(3)

**end.**

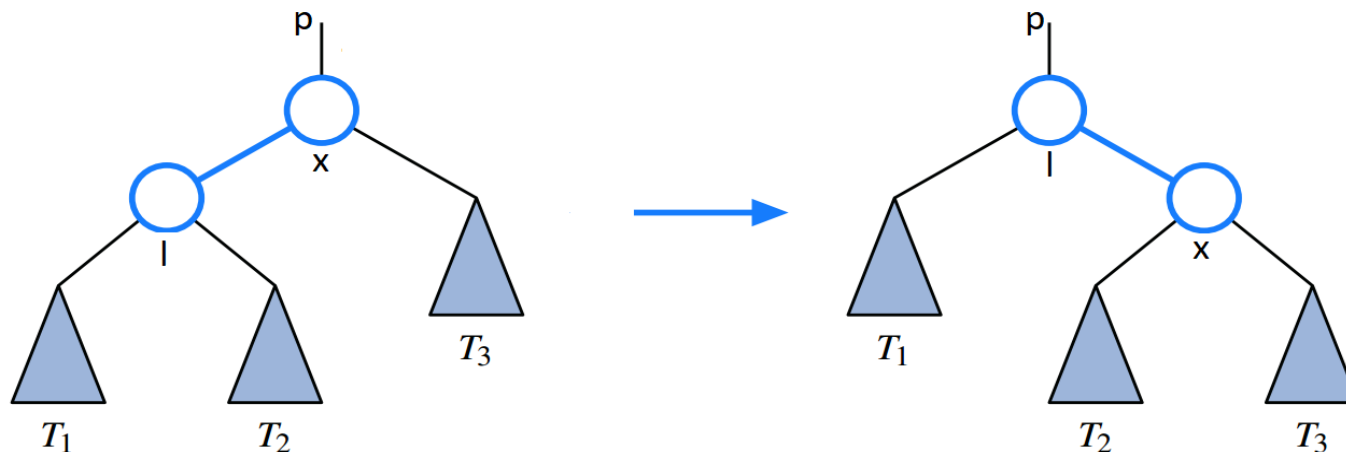


Run time: O(1)

# Balanced Tree: Rotation algorithm

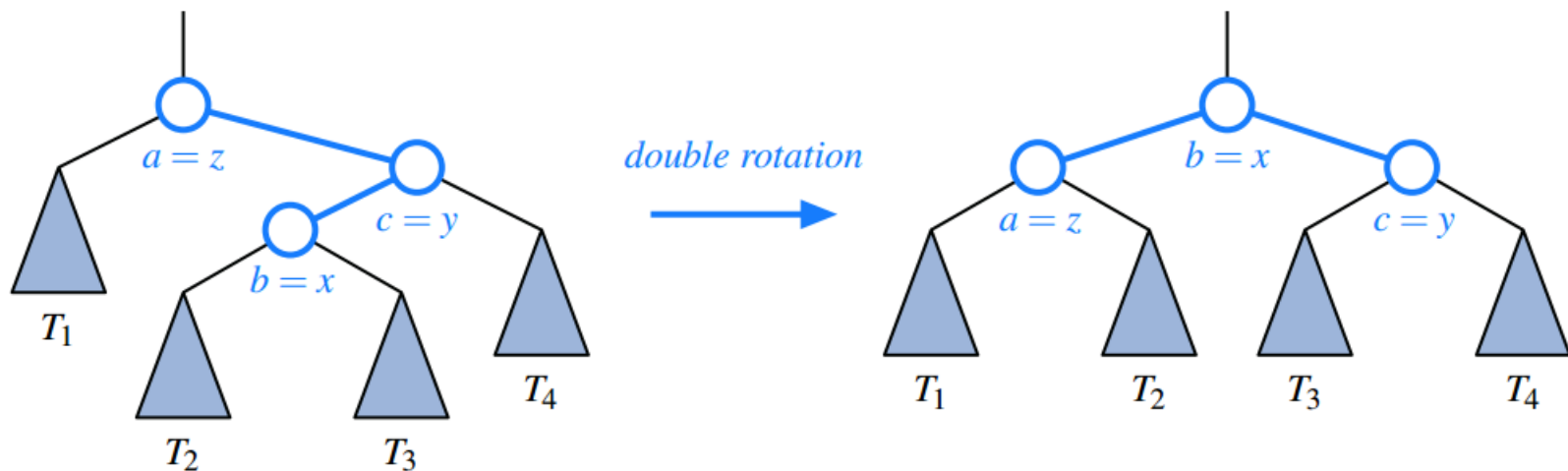
## □ Effect of Rotate Right at x

- l which is x's left child, and l's left subtree ( $T_1$ ), move up 1 level
- x and x's right subtree move down 1 level
- l's right subtree becomes x's left subtree and remains at the same level
- x's parent becomes l's parent, and x becomes the right child of l



# Balanced Tree: Rotation algorithm

- ❑ Rotate Left: same Rotate Right
- ❑ Multi Rotate: One or more rotations can be combined to provide broader rebalancing within a tree
  - Trinote restructuring algorithm



Let's study it more by yourself! [M.Goodrich, p. 473]

# Other Search Trees

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[M.Goodrich, sec. 11.6, p. 510]

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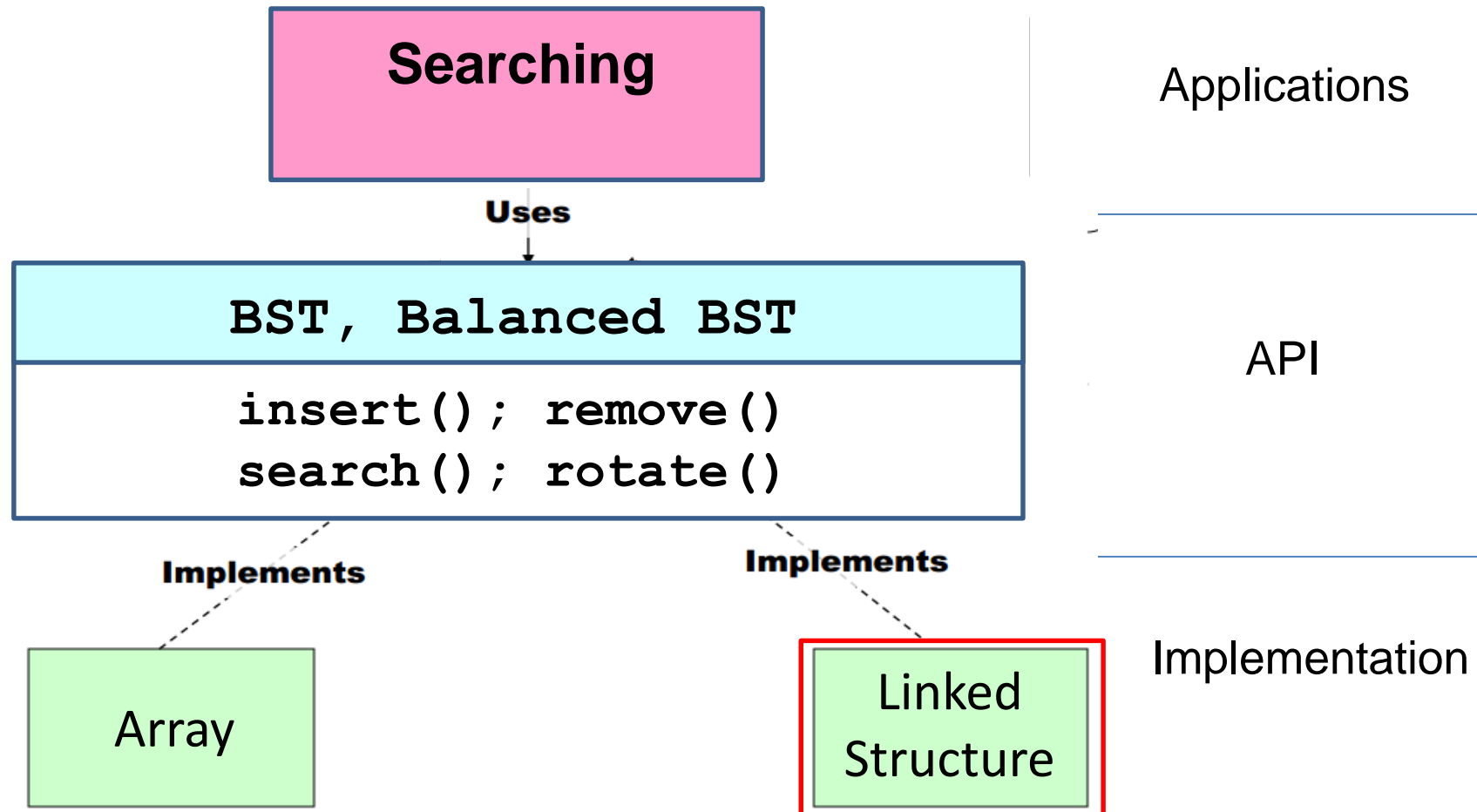
# Other Search Trees

- ❑ AVL Trees – Cây AVL [M.Goodrich, sec. 11.3]
- ❑ Red-Black Trees – Cây đỏ đen [M.Goodrich, sec. 11.6]
- ❑ ...

Self study to find out interesting things!

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# Summary



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# Other ADTs

- ❑ Graph (đồ thị)
  - ❑ Maps (ánh xạ, từ điển)
  - ❑ Hash table (bảng băm)
  - ❑ Set, Multisets and Multimaps (tập hợp)
  - ❑ Text Processing and Prefix/Suffix Tree
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# Study about a new data structure

- ❑ The need for a new data structure (ADT)
  - ❑ Definition
  - ❑ Specification
  - ❑ Implementation
    - Storing data
    - Algorithm
  - ❑ Application
-