

## Hao A. Le

---

La Jolla, CA  
(310) 480-0992  
h3le@ucsd.edu

<b>PROFILE</b>	Electrical engineering undergraduate with over two years of machine shop manufacturing and mechatronics design experience. Capable of tackling a wide variety of projects as well as disseminating information concisely in writing and speech.
<b>EDUCATION</b>	<i>Bachelor of Science</i> University of California, San Diego, La Jolla, CA, expected June 2022 Concentration: Electrical Engineering Minor: Studio Art GPA (as of 2020): 3.91
<b>EXPERIENCE</b>	<div>Summer 2017, 2019</div> <div>Robotics and Mechanisms Laboratory UCLA, Westwood, CA<ul style="list-style-type: none"><li>• Worked under a doctoral student to develop a novel compliant robotic actuator design that is compact yet can deliver up to 150 Nm and 15 degrees of deflection.</li><li>• Designed in Solidworks and manufactured prototype parts using CNC and wire EDM; experimented using system ID, frequency sweep, and LabVIEW data collection.</li><li>• Aided in writing and editing paper using LaTeX to be submitted to IROS 2020.</li><li>• Prototyped a novel torque coupler design capable of selecting multiple paths of power transmission.</li></ul></div> <div>Spring 2019</div> <div>UCSD Electrical and Computer Engineering Department, IEEE Quarterly Projects (Theme: Home Automation)<ul style="list-style-type: none"><li>• Led a team of three to create the Modular Watering System capable of caring up to eight plants with a central watering arm.</li><li>• Soldered extensively to protoboards; manufactured with 3D printer and laser cutter; programmed using Arduino C and Blynk platform to monitor parameters of plants.</li><li>• Exhibited prototype and documentation at symposium; won first place overall.</li></ul></div> <div>Spring 2019</div> <div>ECE 5 Line Following Robot<ul style="list-style-type: none"><li>• Built an Arduino-powered line follower that processed photoresistor readings through a PID algorithm.</li><li>• Designed and 3D printed entire chassis.</li><li>• Competed with classmates in endurance and head-to-head courses; won first place overall.</li></ul></div> <div>Since Fall 2019</div> <div>IEEE Project Drive<ul style="list-style-type: none"><li>• Tasked with mechanical assembly and tuning of a tenth-scale RC car to be raced in F1Tenth 2020 in Berlin.</li><li>• 3D printed customized mounts for hardware.</li><li>• Worked with Docker-based ROS platform for real-time cartography.</li></ul></div>
<b>SKILLS</b>	C/C++; HTML with CSS; Docker; some Python (machine learning, computer vision, API integration, web-scraping); Solidworks; Eagle; MATLAB; Wire EDM; CNC milling; soldering
<b>PERSONAL INTERESTS</b>	Guitar; audio recording and production; oil painting; RC cars; fish-keeping; gardening; bowling; teaching kids; fostering animals