

“Request for Plot”:
is **softmax cross-normalization**
fruitful in transformers?

Mishka (Michael Bukatin)

Dataflow Matrix Machines project

<https://github.com/anhinga>

I am looking for collaborators

“Request for Plot”

Replace

$$\text{Attention}(Q, K, V) = \text{softmax}(cKQ^T)V$$

with

$$\text{Attention}(Q, K, V) = \text{softmax}(cKQ^T)\text{softmax}^T(V)$$

Does your favorite learning curve improve?

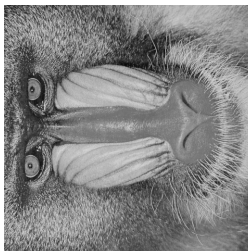
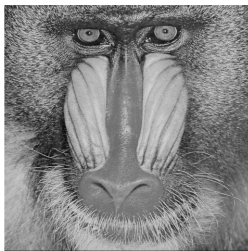
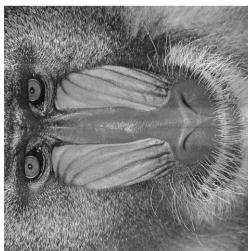
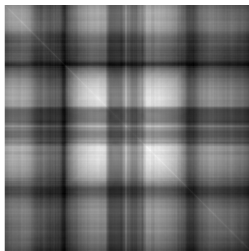
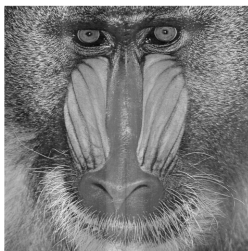
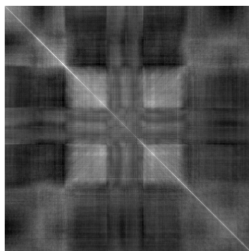
Why do I think this is a good shot?

Why this might be a good idea?

I experimented with interpreting monochrome images as matrices and multiplying those matrices via matrix product and checking whether results are visually interesting.

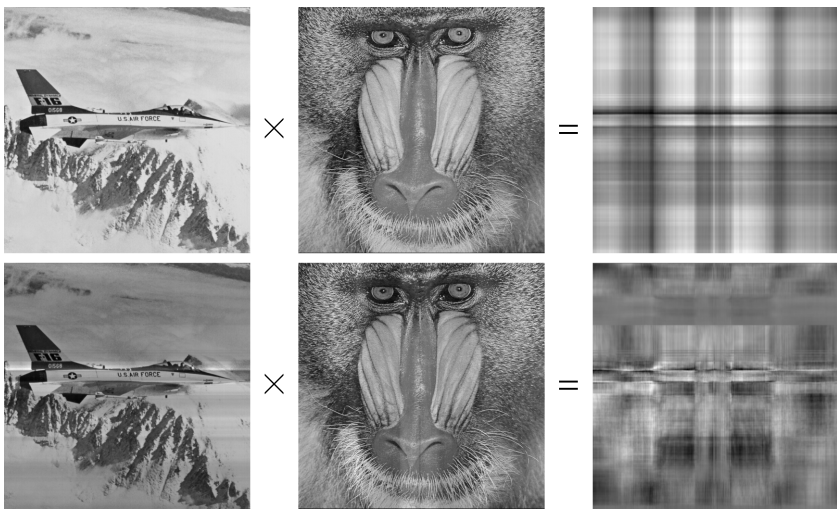
Multiplying monochrome images as matrices:
 $A*B$ and softmax

<https://github.com/anhinga/JuliaCon2021-poster>

 \times  $=$  \times  $=$ 

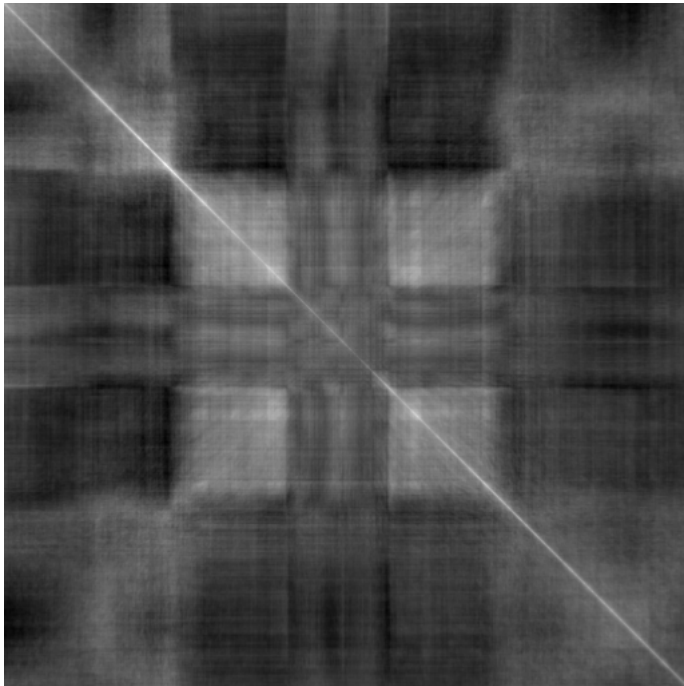
In Transformers people sometimes **softmax** rows of the left matrix:
 $\text{Attention}(Q, K, V) = \text{softmax}(cKQ^T)V$ from "Attention Is All You Need" (2017).

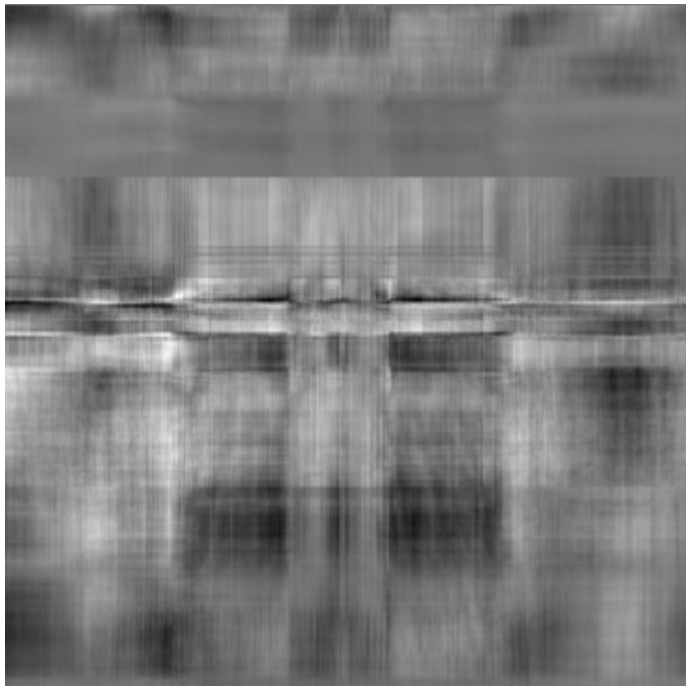
In the second example we **softmax** rows of the left matrix **and**
columns of the right matrix resulting in products with richer,
more fine-grained structure.



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Cross-normalization

$$\text{softmax}^T(V)$$



values are horizontal stripes

cross-norm: softmax vertical vectors

a vertical vector consists of i 's coords of all values for a given i

Contact

Open an issue in

<https://github.com/anhinga/JuliaCon2021-poster>

or send an e-mail to [bukatin @ cs dot brandeis dot edu](mailto:bukatin@cs.brandeis.edu)