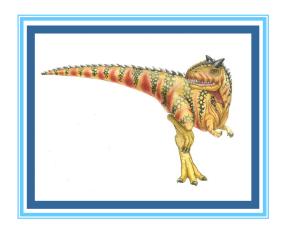
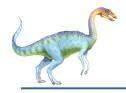
# Chapter 7: Synchronization Examples





# **Chapter 7: Synchronization Examples**

- Explain the bounded-buffer, readers-writers, and dining philosophers synchronization problems.
- Describe the tools used by Linux and Windows to solve synchronization problems.
- Illustrate how POSIX and Java can be used to solve process synchronization problems.





# **Classical Problems of Synchronization**

- Classical problems used to test newly-proposed synchronization schemes
  - Bounded-Buffer Problem
  - Readers and Writers Problem
  - Dining-Philosophers Problem





#### **Bounded-Buffer Problem**

- **n** buffers, each can hold one item
- Semaphore mutex initialized to the value 1
- Semaphore full initialized to the value 0
- Semaphore empty initialized to the value n





# **Bounded Buffer Problem (Cont.)**

The structure of the producer process

```
while (true) {
      /* produce an item in next produced */
   wait(empty);
   wait(mutex);
      /* add next produced to the buffer */
   signal(mutex);
   signal(full);
```





# **Bounded Buffer Problem (Cont.)**

The structure of the consumer process

```
while (true) {
   wait(full);
   wait(mutex);
       /* remove an item from buffer to next consumed */
    signal (mutex);
    signal(empty);
       /* consume the item in next consumed */
```





#### **Readers-Writers Problem**

- A data set is shared among a number of concurrent processes
  - Readers only read the data set; they do not perform any updates
  - Writers can both read and write
- Problem allow multiple readers to read at the same time
  - Only one single writer can access the shared data at the same time
- Several variations of how readers and writers are considered all involve some form of priorities
- Shared Data
  - Data set
  - Semaphore rw mutex initialized to 1
  - Semaphore mutex initialized to 1
  - Integer read\_count initialized to 0





# Readers-Writers Problem (Cont.)

The structure of a writer process





# Readers-Writers Problem (Cont.)

The structure of a reader process

```
while (true) {
        wait(mutex);
        read count++;
        if (read count == 1)
        wait(rw mutex);
        signal(mutex);
        /* reading is performed */
        wait(mutex);
        read count--;
        if (read count == 0)
                signal(rw mutex);
        signal(mutex);
```

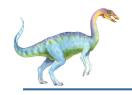




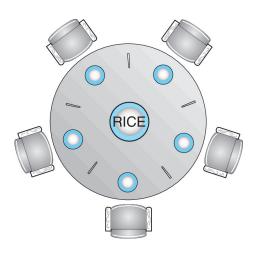
## **Readers-Writers Problem Variations**

- First variation no reader kept waiting unless writer has permission to use shared object
- Second variation once writer is ready, it performs the write ASAP
- Both may have starvation leading to even more variations
- Problem is solved on some systems by kernel providing reader-writer locks





## **Dining-Philosophers Problem**



- Philosophers spend their lives alternating thinking and eating
- Don't interact with their neighbors, occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl
  - Need both to eat, then release both when done
- In the case of 5 philosophers
  - Shared data
    - Bowl of rice (data set)
    - Semaphore chopstick [5] initialized to 1





# Dining-Philosophers Problem Algorithm

- Semaphore Solution
- The structure of Philosopher i:

```
while (true) {
    wait (chopstick[i] );
   wait (chopStick[ (i + 1) % 5] );
     /* eat for awhile */
   signal (chopstick[i] );
    signal (chopstick[ (i + 1) % 5] );
     /* think for awhile */
```

What is the problem with this algorithm?





## **Monitor Solution to Dining Philosophers**

```
monitor DiningPhilosophers
{
  enum { THINKING; HUNGRY, EATING) state [5] ;
   condition self [5];
  void pickup (int i) {
          state[i] = HUNGRY;
          test(i);
          if (state[i] != EATING) self[i].wait;
   }
   void putdown (int i) {
          state[i] = THINKING;
                   // test left and right neighbors
           test((i + 4) % 5);
           test((i + 1) % 5);
```





# Solution to Dining Philosophers (Cont.)

```
void test (int i) {
        if ((state[(i + 4) % 5] != EATING) &&
        (state[i] == HUNGRY) &&
        (state[(i + 1) % 5] != EATING) ) {
             state[i] = EATING ;
         self[i].signal () ;
    initialization code() {
       for (int i = 0; i < 5; i++)
       state[i] = THINKING;
     }
```





# **Solution to Dining Philosophers (Cont.)**

Each philosopher i invokes the operations pickup() and putdown() in the following sequence:

```
DiningPhilosophers.pickup(i);
    /** EAT **/
DiningPhilosophers.putdown(i);
```

No deadlock, but starvation is possible

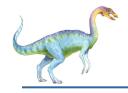




## **Kernel Synchronization - Windows**

- Uses interrupt masks to protect access to global resources on uniprocessor systems
- Uses **spinlocks** on multiprocessor systems
  - Spinlocking-thread will never be preempted
- Also provides dispatcher objects user-land which may act mutexes, semaphores, events, and timers
  - Events
    - An event acts much like a condition variable
  - Timers notify one or more thread when time expired
  - Dispatcher objects either signaled-state (object available) or non-signaled state (thread will block)

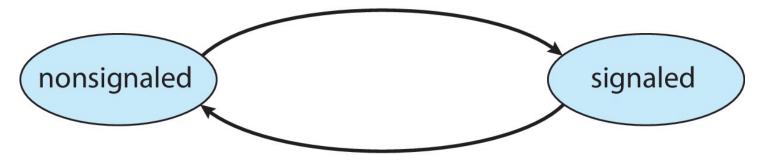




## **Kernel Synchronization - Windows**

Mutex dispatcher object





thread acquires mutex lock





# **Linux Synchronization**

- Linux:
  - Prior to kernel Version 2.6, disables interrupts to implement short critical sections
  - Version 2.6 and later, fully preemptive
- Linux provides:
  - Semaphores
  - atomic integers
  - spinlocks
  - reader-writer versions of both
- On single-cpu system, spinlocks replaced by enabling and disabling kernel preemption





## **Linux Synchronization**

Atomic variables

atomic\_t is the type for atomic integer

Consider the variables

```
atomic_t counter;
int value;
```

Atomic Operation	Effect
atomic_set(&counter,5);	counter = 5
atomic_add(10,&counter);	counter = counter + 10
atomic_sub(4,&counter);	counter = counter - 4
atomic_inc(&counter);	counter = counter + 1
<pre>value = atomic_read(&amp;counter);</pre>	value = 12





# **POSIX Synchronization**

- POSIX API provides
  - mutex locks
  - semaphores
  - condition variable
- Widely used on UNIX, Linux, and macOS





#### **POSIX Mutex Locks**

Creating and initializing the lock

```
#include <pthread.h>
pthread_mutex_t mutex;

/* create and initialize the mutex lock */
pthread_mutex_init(&mutex,NULL);
```

Acquiring and releasing the lock

```
/* acquire the mutex lock */
pthread_mutex_lock(&mutex);
/* critical section */
/* release the mutex lock */
pthread_mutex_unlock(&mutex);
```





## **POSIX Semaphores**

- POSIX provides two versions **named** and **unnamed**.
- Named semaphores can be used by unrelated processes, unnamed cannot.





# **POSIX Named Semaphores**

Creating an initializing the semaphore:

```
#include <semaphore.h>
sem_t *sem;

/* Create the semaphore and initialize it to 1 */
sem = sem_open("SEM", O_CREAT, 0666, 1);
```

- Another process can access the semaphore by referring to its name **SEM**.
- Acquiring and releasing the semaphore:

```
/* acquire the semaphore */
sem_wait(sem);
/* critical section */
/* release the semaphore */
sem_post(sem);
```





# **POSIX Unnamed Semaphores**

Creating an initializing the semaphore:

```
#include <semaphore.h>
sem_t sem;

/* Create the semaphore and initialize it to 1 */
sem_init(&sem, 0, 1);
```

Acquiring and releasing the semaphore:

```
/* acquire the semaphore */
sem_wait(&sem);
/* critical section */
/* release the semaphore */
sem_post(&sem);
```





#### **POSIX Condition Variables**

Since POSIX is typically used in C/C++ and these languages do not provide a monitor, POSIX condition variables are associated with a POSIX mutex lock to provide mutual exclusion: Creating and initializing the condition variable:

```
pthread_mutex_t mutex;
pthread_cond_t cond_var;

pthread_mutex_init(&mutex,NULL);
pthread_cond_init(&cond_var,NULL);
```





#### **POSIX Condition Variables**

Thread waiting for the condition a == b to become true:

```
pthread_mutex_lock(&mutex);
while (a != b)
    pthread_cond_wait(&cond_var, &mutex);
pthread_mutex_unlock(&mutex);
```

Thread signaling another thread waiting on the condition variable:

```
pthread_mutex_lock(&mutex);
a = b;
pthread_cond_signal(&cond_var);
pthread_mutex_unlock(&mutex);
```





- Java provides rich set of synchronization features:
- Java monitors
- Reentrant locks
- Semaphores
- Condition variables





#### **Java Monitors**

- Every Java object has associated with it a single lock.
- If a method is declared as **synchronized**, a calling thread must own the lock for the object.
- If the lock is owned by another thread, the calling thread must wait for the lock until it is released.
- Locks are released when the owning thread exits the synchronized method.

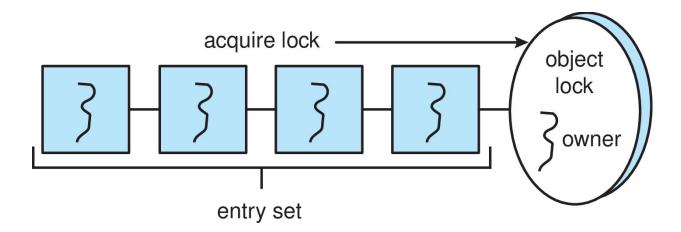


# **Bounded Buffer – Java Synchronization**

```
public class BoundedBuffer<E>
  private static final int BUFFER_SIZE = 5;
  private int count, in, out;
  private E[] buffer;
  public BoundedBuffer() {
     count = 0;
     in = 0;
     out = 0;
     buffer = (E[]) new Object[BUFFER_SIZE];
  /* Producers call this method */
  public synchronized void insert(E item) {
     /* See Figure 7.11 */
  /* Consumers call this method */
  public synchronized E remove() {
     /* See Figure 7.11 */
```

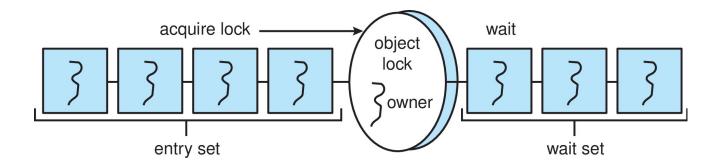


A thread that tries to acquire an unavailable lock is placed in the object's entry set:





- Similarly, each object also has a wait set.
- When a thread calls wait():
- It releases the lock for the object
- 2. The state of the thread is set to blocked
- 3. The thread is placed in the wait set for the object







- A thread typically calls wait() when it is waiting for a condition to become true.
- How does a thread get notified?
- When a thread calls notify():
- 1. An arbitrary thread T is selected from the wait set
- 2. T is moved from the wait set to the entry set
- Set the state of T from blocked to runnable.
- T can now compete for the lock to check if the condition it was waiting for is now true.



# **B**ounded Buffer – Java Synchronization

```
/* Producers call this method */
public synchronized void insert(E item) {
    while (count == BUFFER_SIZE) {
        try {
            wait();
        }
        catch (InterruptedException ie) { }
    }

buffer[in] = item;
    in = (in + 1) % BUFFER_SIZE;
    count++;

notify();
}
```



# **B**ounded Buffer – Java Synchronization

```
/* Consumers call this method */
public synchronized E remove() {
  E item;
  while (count == 0) {
     try {
       wait();
     catch (InterruptedException ie) { }
  item = buffer[out];
  out = (out + 1) % BUFFER_SIZE;
  count--:
  notify();
  return item;
```





#### **Java Reentrant Locks**

- Similar to mutex locks
- The finally clause ensures the lock will be released in case an exception occurs in the try block.

```
Lock key = new ReentrantLock();
key.lock();
try {
   /* critical section */
}
finally {
   key.unlock();
}
```





## **Java Semaphores**

Constructor:

```
Semaphore(int value);
```

Usage:

```
Semaphore sem = new Semaphore(1);

try {
    sem.acquire();
    /* critical section */
}
catch (InterruptedException ie) { }
finally {
    sem.release();
}
```





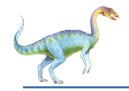
#### **Java Condition Variables**

- Condition variables are associated with an ReentrantLock.
- Creating a condition variable using newCondition() method of ReentrantLock:

```
Lock key = new ReentrantLock();
Condition condVar = key.newCondition();
```

A thread waits by calling the await() method, and signals by calling the signal() method.





#### **Java Condition Variables**

- Example:
- Five threads numbered 0 .. 4
- Shared variable turn indicating which thread's turn it is.
- Thread calls dowork() when it wishes to do some work. (But it may only do work if it is their turn.
- If not their turn, wait
- If their turn, do some work for awhile ......
- When completed, notify the thread whose turn is next.
- Necessary data structures:

```
Lock lock = new ReentrantLock();
Condition[] condVars = new Condition[5];
for (int i = 0; i < 5; i++)
    condVars[i] = lock.newCondition();</pre>
```





#### **Java Condition Variables**

```
/* threadNumber is the thread that wishes to do some work */
public void doWork(int threadNumber)
  lock.lock();
  try {
     /**
      * If it's not my turn, then wait
      * until I'm signaled.
     if (threadNumber != turn)
        condVars[threadNumber].await();
     /**
      * Do some work for awhile ...
      */
     /**
      * Now signal to the next thread.
      */
     turn = (turn + 1) \% 5;
     condVars[turn].signal();
  catch (InterruptedException ie) { }
  finally {
     lock.unlock();
```



# **Alternative Approaches**

- Transactional Memory
- OpenMP
- Functional Programming Languages





# **Transactional Memory**

Consider a function update() that must be called atomically. One option is to use mutex locks:

```
void update ()
{
   acquire();
   /* modify shared data */
   release();
}
```

A memory transaction is a sequence of read-write operations to memory that are performed atomically. A transaction can be completed by adding atomic{S} which ensure statements in s are executed atomically:

```
void update ()
{
   atomic {
     /* modify shared data */
   }
}
```





# **OpenMP**

OpenMP is a set of compiler directives and API that support parallel programming.

```
void update(int value)
{
     #pragma omp critical
     {
          count += value
     }
}
```

The code contained within the **#pragma** omp critical directive is treated as a critical section and performed atomically.





# **Functional Programming Languages**

- Functional programming languages offer a different paradigm than procedural languages in that they do not maintain state.
- Variables are treated as immutable and cannot change state once they have been assigned a value.
- There is increasing interest in functional languages such as Erlang and Scala for their approach in handling data races.



# **End of Chapter 7**

