

Lecture 08 recap

- 1) Geometric vectors and Euclidean n – space.
- 2) Identifying a vector with a matrix.
- 3) Subsets of \mathbb{R}^n . Implicit and explicit representations.
- 4) Linear combination
- 5) Linear span (set of all linear combinations).
- 6) Determining whether a set spans \mathbb{R}^n .

Lecture 09

**Linear combinations and
linear spans (cont'd)**

Subspaces

Discussion

Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \subseteq \mathbb{R}^n$. We want to determine if $\text{span}(S) = \mathbb{R}^n$.

$$\mathbf{u}_1 = (a_{11}, a_{12}, \dots, a_{1n}) \quad \mathbf{u}_2 = (a_{21}, a_{22}, \dots, a_{2n}) \quad \dots \quad \mathbf{u}_k = (a_{k1}, a_{k2}, \dots, a_{kn})$$

For any $\mathbf{v} = (v_1, v_2, \dots, v_n) \in \mathbb{R}^n$, consider the equation:

$$c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_k \mathbf{u}_k = \mathbf{v}$$

$$\begin{aligned} & c_1(a_{11}, a_{12}, \dots, a_{1n}) + c_2(a_{21}, a_{22}, \dots, a_{2n}) + \dots + c_k(a_{k1}, a_{k2}, \dots, a_{kn}) \\ &= (v_1, v_2, \dots, v_n) \end{aligned}$$

Discussion

Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \subseteq \mathbb{R}^n$. We want to determine if $\text{span}(S) = \mathbb{R}^n$.

$$c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_k \mathbf{u}_k = \mathbf{v}$$

$$c_1(a_{11}, a_{12}, \dots, a_{1n}) + c_2(a_{21}, a_{22}, \dots, a_{2n}) + \dots + c_k(a_{k1}, a_{k2}, \dots, a_{kn}) \\ = (v_1, v_2, \dots, v_n)$$

$$\begin{cases} a_{11}c_1 & + & a_{21}c_2 & + & \dots & + & a_{k1}c_k & = & v_1 \\ a_{12}c_1 & + & a_{22}c_2 & + & \dots & + & a_{k2}c_k & = & v_2 \\ \vdots & & \vdots & & & & \vdots & & \vdots \\ a_{1n}c_1 & + & a_{2n}c_2 & + & \dots & + & a_{kn}c_k & = & v_n \end{cases}$$

Discussion

Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \subseteq \mathbb{R}^n$. We want to determine if $\text{span}(S) = \mathbb{R}^n$.

$$c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_k \mathbf{u}_k = \mathbf{v} \quad (*)$$

$$c_1(a_{11}, a_{12}, \dots, a_{1n}) + c_2(a_{21}, a_{22}, \dots, a_{2n}) + \dots + c_k(a_{k1}, a_{k2}, \dots, a_{kn}) \\ = (v_1, v_2, \dots, v_n)$$

$$\begin{array}{c} n \\ \text{rows} \end{array} \left(\begin{array}{c} k \text{ columns} \\ \hline \mathbf{A} \\ \hline \end{array} \right) \begin{array}{c} v_1 \\ v_2 \\ : \\ v_n \end{array}$$

If a row-echelon form of \mathbf{A} does not have a zero row,

$(*)$ is always consistent regardless of \mathbf{v}

$$\Rightarrow \text{span}(S) = \mathbb{R}^n$$

if $\text{span}(S) = \mathbb{R}^n$.

$$c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_k \mathbf{u}_k = \mathbf{v} \quad (*)$$

$$c_1(a_{11}, a_{12}, \dots, a_{1n}) + c_2(a_{21}, a_{22}, \dots, a_{2n}) + \dots + c_k(a_{k1}, a_{k2}, \dots, a_{kn}) \\ = (v_1, v_2, \dots, v_n)$$

has at least one zero row,

(*) is not always consistent

$$\Rightarrow \text{span}(S) \neq \mathbb{R}^n$$

$$\begin{matrix} & & k \text{ columns} \\ n \text{ rows} & \left(\begin{array}{c|c} \text{matrix } A & \begin{matrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{matrix} \end{array} \right) \end{matrix}$$

Example

From earlier example:

Show that $\text{span}\{(1,0,1),(1,1,0),(0,1,1)\} = \mathbb{R}^3$.

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix} \quad \text{No zero row}$$

Show that $\text{span}\{(1,1,1),(1,2,0),(2,1,3),(2,3,1)\} \neq \mathbb{R}^3$.

$$\begin{pmatrix} 1 & 1 & 2 & 2 \\ 1 & 2 & 1 & 3 \\ 1 & 0 & 3 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 1 & 2 & 2 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \text{Has zero row}$$

If $k < n$, then S cannot span \mathbb{R}^n .

If $k < n$, then a row-echelon form of A has at least one zero row $\Rightarrow S$ cannot span \mathbb{R}^n .

Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \subseteq \mathbb{R}^n$. We want to determine if $\text{span}(S) = \mathbb{R}^n$.

$$c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_k \mathbf{u}_k = \mathbf{v} \quad (*)$$

$$\begin{matrix} & & k \text{ columns} \\ n \text{ rows} & \left(\begin{array}{c|c} \text{matrix } A & \begin{matrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{matrix} \end{array} \right) \end{matrix}$$

If a row-echelon form of A has at least one zero row,

(*) is not always consistent

Example

- 1) One vector cannot span \mathbb{R}^2 .
- 2) One or two vectors cannot span \mathbb{R}^3 .

Theorem

Let $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \subseteq \mathbb{R}^n$.

1) $\mathbf{0} \in \text{span}(S)$

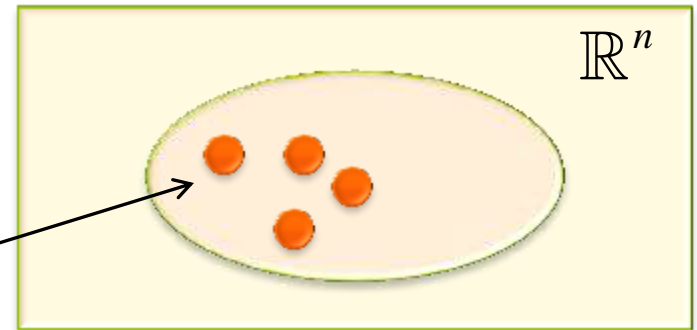
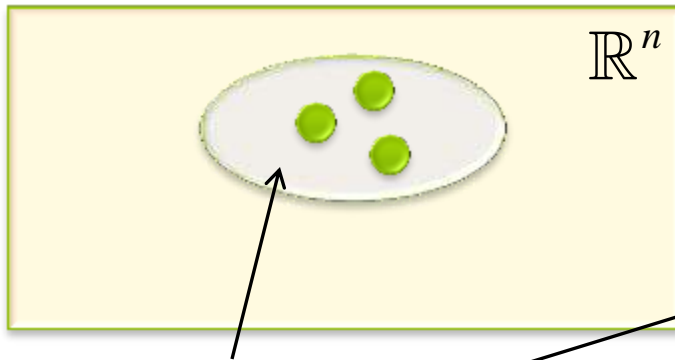
2) For any $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r \in \text{span}(S)$ and $c_1, c_2, \dots, c_r \in \mathbb{R}$,

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_r\mathbf{v}_r \in \text{span}(S).$$



Theorem

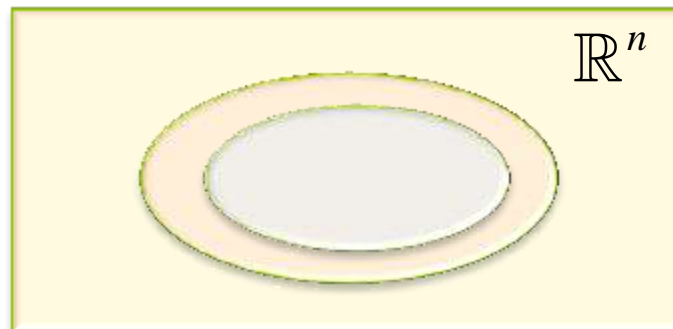
Let $S_1 = \{u_1, u_2, \dots, u_k\}$ and $S_2 = \{v_1, v_2, \dots, v_m\}$ be subsets of \mathbb{R}^n .



Then $\text{span}(S_1) \subseteq \text{span}(S_2) \Leftrightarrow$ each u_i is a linear combination of



v_1, v_2, \dots, v_m .



Example

Let $\mathbf{u}_1 = (1, 0, 1)$, $\mathbf{u}_2 = (1, 1, 2)$, $\mathbf{u}_3 = (-1, 2, 1)$, $\mathbf{v}_1 = (1, 2, 3)$, $\mathbf{v}_2 = (2, -1, 1)$.

Show that $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

Idea: The previous theorem gives us a
necessary and sufficient condition for

$$\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}.$$

Each of $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ is a linear combination of $\mathbf{v}_1, \mathbf{v}_2$.

Example

Let $\mathbf{u}_1 = (1, 0, 1)$, $\mathbf{u}_2 = (1, 1, 2)$, $\mathbf{u}_3 = (-1, 2, 1)$, $\mathbf{v}_1 = (1, 2, 3)$, $\mathbf{v}_2 = (2, -1, 1)$.

Show that $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

Each of $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ is a linear combination of $\mathbf{v}_1, \mathbf{v}_2$.

$$= a(1, 2, 3) + b(2, -1, 1)$$

Example

$$\left(\begin{array}{cc|cc|c} 1 & 2 & 1 & 1 & -1 \\ 2 & -1 & 0 & 1 & 2 \\ 3 & 1 & 1 & 2 & 1 \end{array} \right)$$

Gauss-Jordan



Elimination

$$\left(\begin{array}{cc|cc|c} 1 & 0 & \frac{1}{5} & \frac{3}{5} & \frac{3}{5} \\ 0 & 1 & \frac{2}{5} & \frac{1}{5} & \frac{-4}{5} \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$(1,0,1) = (1,2,3) + (2,-1,1)$$

$$(1,1,2) = (1,2,3) + (2,-1,1)$$

$$(-1,2,1) = (1,2,3) + (2,-1,1)$$

Since each of u_1, u_2, u_3

is a linear combination of v_1, v_2 ,

$$\text{span}\{u_1, u_2, u_3\} \subseteq \text{span}\{v_1, v_2\}.$$

Example

Let $\mathbf{u}_1 = (1, 0, 1), \mathbf{u}_2 = (1, 1, 2), \mathbf{u}_3 = (-1, 2, 1), \mathbf{v}_1 = (1, 2, 3), \mathbf{v}_2 = (2, -1, 1)$.

Show that $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

Can we show

Shown:

$\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \supseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$ $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

Each of $\mathbf{v}_1, \mathbf{v}_2$ is a linear combination of $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$.

$$= a(1, 0, 1) + b(1, 1, 2) + c(-1, 2, 1)$$

Example

Let $u_1 = (1, 0, 1), u_2 = (1, 1, 2), u_3 = (-1, 2, 1), v_1 = (1, 2, 3), v_2 = (2, -1, 1)$.

$$\begin{pmatrix} 1 & 1 & -1 & | & 1 & | & 2 \\ 0 & 1 & 2 & | & 2 & | & -1 \\ 1 & 2 & 1 & | & 3 & | & 1 \end{pmatrix} \begin{array}{c} \text{Gauss-Jordan} \\ \longrightarrow \\ \text{Elimination} \end{array} \begin{pmatrix} 1 & 0 & -3 & | & -1 & | & 3 \\ 0 & 1 & 2 & | & 2 & | & -1 \\ 0 & 0 & 0 & | & 0 & | & 0 \end{pmatrix}$$

$$v_1 = a(1, 0, 1) + b(1, 1, 2) + c(-1, 2, 1)$$

Example

Let $\mathbf{u}_1 = (1, 0, 1), \mathbf{u}_2 = (1, 1, 2), \mathbf{u}_3 = (-1, 2, 1), \mathbf{v}_1 = (1, 2, 3), \mathbf{v}_2 = (2, -1, 1)$.

$$\begin{pmatrix} 1 & 1 & -1 & | & 1 & | & 2 \\ 0 & 1 & 2 & | & 2 & | & -1 \\ 1 & 2 & 1 & | & 3 & | & 1 \end{pmatrix} \xrightarrow[\text{Elimination}]{\text{Gauss-Jordan}} \begin{pmatrix} 1 & 0 & -3 & | & -1 & | & 3 \\ 0 & 1 & 2 & | & 2 & | & -1 \\ 0 & 0 & 0 & | & 0 & | & 0 \end{pmatrix}$$

Since each of $\mathbf{v}_1, \mathbf{v}_2$ is a linear combination of $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$,

$$\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \supseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}.$$

Together with $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$, we have shown

$$\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}.$$

Example

Let $\mathbf{u}_1 = (1, 1, 0, 2)$, $\mathbf{u}_2 = (1, 0, 0, 1)$, $\mathbf{u}_3 = (0, 1, 0, 1)$,
 $\mathbf{v}_1 = (1, 1, 1, 1)$, $\mathbf{v}_2 = (-1, 1, -1, 1)$, $\mathbf{v}_3 = (-1, 1, 1, -1)$.

Show that $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ but
 $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \neq \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$.

To show $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$,

$$\left(\begin{array}{ccc|c|c|c} 1 & -1 & -1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 & 0 & 1 \\ 1 & -1 & 1 & 0 & 0 & 0 \\ 1 & 1 & -1 & 2 & 1 & 1 \end{array} \right)$$



How did this
matrix come
about?

Example

Let $\mathbf{u}_1 = (1, 1, 0, 2), \mathbf{u}_2 = (1, 0, 0, 1), \mathbf{u}_3 = (0, 1, 0, 1),$
 $\mathbf{v}_1 = (1, 1, 1, 1), \mathbf{v}_2 = (-1, 1, -1, 1), \mathbf{v}_3 = (-1, 1, 1, -1).$

Show that $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ but
 $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \neq \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}.$

To show $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\},$

$$\left(\begin{array}{ccc|c|c|c} 1 & -1 & -1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 & 0 & 1 \\ 1 & -1 & 1 & 0 & 0 & 0 \\ 1 & 1 & -1 & 2 & 1 & 1 \end{array} \right) \longrightarrow \left(\begin{array}{ccc|c|c|c} 1 & -1 & -1 & 1 & 1 & 0 \\ 0 & 2 & 2 & 0 & -1 & 1 \\ 0 & 0 & 2 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

Example

Let $u_1 = (1, 1, 0, 2)$, $u_2 = (1, 0, 0, 1)$, $u_3 = (0, 1, 0, 1)$,
 $v_1 = (1, 1, 1, 1)$, $v_2 = (-1, 1, -1, 1)$, $v_3 = (-1, 1, 1, -1)$.

Show that $\text{span}\{u_1, u_2, u_3\} \subseteq \text{span}\{v_1, v_2, v_3\}$ but
 $\text{span}\{u_1, u_2, u_3\} \neq \text{span}\{v_1, v_2, v_3\}$.

To show $\text{span}\{u_1, u_2, u_3\} \neq \text{span}\{v_1, v_2, v_3\}$,

$$v_1 = (1, 1, 1, 1) = a(1, 1, 0, 2) + b(1, 0, 0, 1) + c(0, 1, 0, 1)$$

has no solution.

So v_1 is not a linear combination of u_1, u_2, u_3 .

Example

Let $\mathbf{u}_1 = (1, 0, 0, 1), \mathbf{u}_2 = (0, 1, -1, 2), \mathbf{u}_3 = (2, 1, -1, 4),$
 $\mathbf{v}_1 = (1, 1, 1, 1), \mathbf{v}_2 = (-1, 1, -1, 1), \mathbf{v}_3 = (-1, 1, 1, -1).$

Show that $\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} \not\subset \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}.$

We try to write each \mathbf{v}_i as a linear combination of $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3.$

$$\left(\begin{array}{ccc|c|c|c} 1 & 0 & 2 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & -1 & -1 & 1 & -1 & 1 \\ 1 & 2 & 4 & 1 & 1 & -1 \end{array} \right) \longrightarrow \left(\begin{array}{ccc|c|c|c} 1 & 0 & 2 & 1 & -1 & -1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 2 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

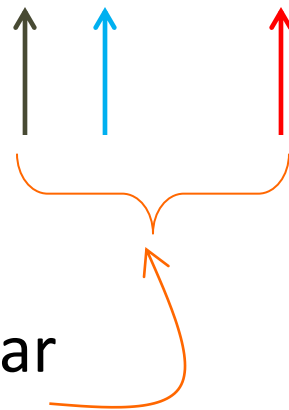
Which \mathbf{v}_i is NOT a linear combination of $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$?

Theorem ('useless vector')

Suppose $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$ are vectors taken from \mathbb{R}^n .

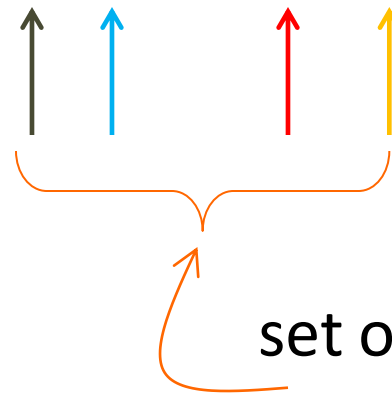
If \mathbf{u}_k is a linear combination of $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_{k-1}$, then

$$\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_{k-1}\} = \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_{k-1}, \mathbf{u}_k\}$$



set of ALL linear
combinations of

=



set of ALL linear
combinations of

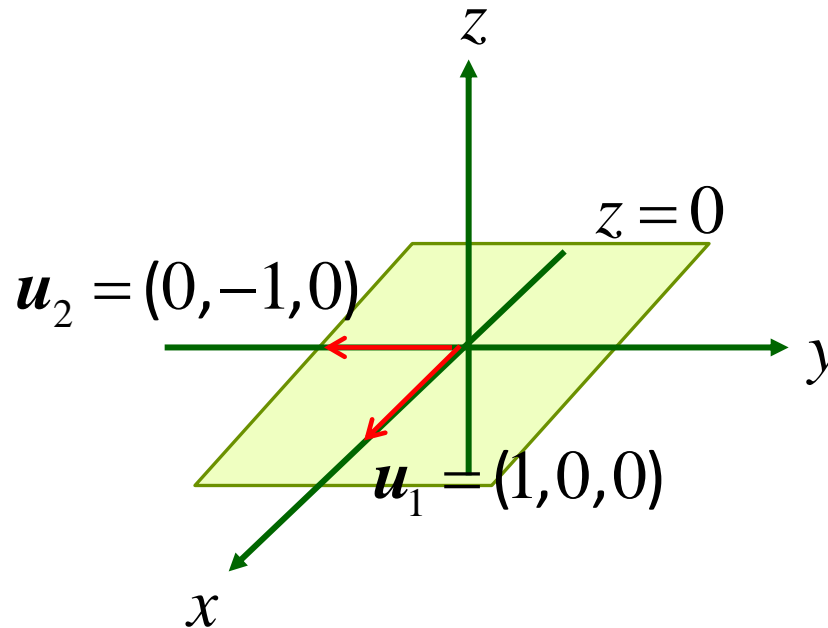


Example

Let $\mathbf{u}_1 = (1, 0, 0)$, $\mathbf{u}_2 = (0, -1, 0)$, $\mathbf{u}_3 = (2, 3, 0)$.

Clearly, $\mathbf{u}_3 = 2\mathbf{u}_1 - 3\mathbf{u}_2$. So $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \text{span}\{\mathbf{u}_1, \mathbf{u}_2\}$.

Can you describe $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ geometrically?



Definition (Subspaces)

Let V be a subset of \mathbb{R}^n .

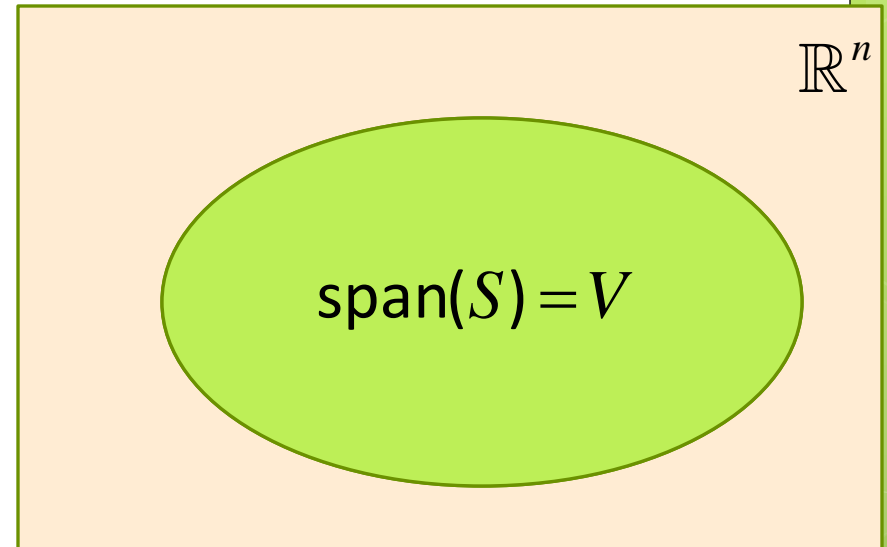
If there exists a set of vectors

$$S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \text{ in } \mathbb{R}^n$$
$$\{ \bullet \quad \bullet \quad \bullet \}$$

such that $\text{span}(S) = V$,

then V is said to be

a **subspace** of \mathbb{R}^n .



Remember: $\text{span}(S)$ = set of all linear combinations of $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$.

Definition (Subspaces)

Let V be a subset of \mathbb{R}^n .

If there exists a set of vectors

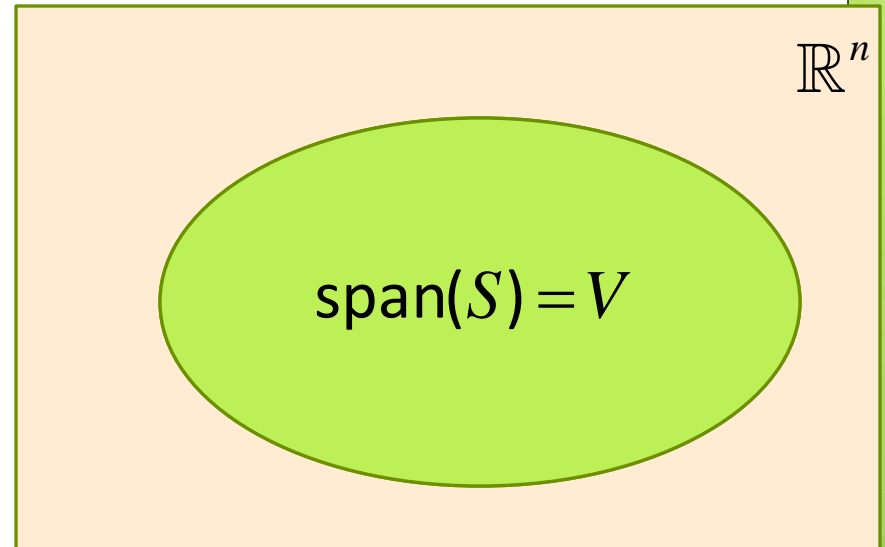
$$S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \text{ in } \mathbb{R}^n$$
$$\{ \bullet \bullet \bullet \}$$

such that $\text{span}(S) = V$,

then V is said to be
a **subspace** of \mathbb{R}^n .

More precisely, we say:

- 1) V is the subspace spanned by S .
- 2) V is the subspace spanned by $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$.
- 3) S spans V .



Remark

$\{\mathbf{0}\} = \text{span}\{\mathbf{0}\}$ is the zero subspace of \mathbb{R}^n .

(Here, $\mathbf{0}$ is the zero vector of \mathbb{R}^n .)

It is also called the **zero space** of \mathbb{R}^n .

It is also the only subspace of \mathbb{R}^n with a finite number (in this case, one), and thus the least, of vectors.

Remark

Consider the vectors in \mathbb{R}^n :

$$\mathbf{e}_1 = (1, 0, \dots, 0) \quad \mathbf{e}_2 = (0, 1, \dots, 0) \quad \dots \quad \mathbf{e}_n = (0, 0, \dots, 1)$$

$$\mathbb{R}^n = \{(u_1, u_2, \dots, u_n) \mid u_1, u_2, \dots, u_n \in \mathbb{R}\}$$

$$= \{u_1 \mathbf{e}_1 + u_2 \mathbf{e}_2 + \dots + u_n \mathbf{e}_n \mid u_1, u_2, \dots, u_n \in \mathbb{R}\}$$

$$= \text{the set of all linear combinations of } \mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n$$

$$= \text{span}\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\} = \text{a subspace of } \mathbb{R}^n$$

So \mathbb{R}^n is a subspace of itself and to some extent, it can be thought of as the subspace of \mathbb{R}^n with the 'largest' number of vectors.

Remark

In more advance textbooks on linear algebra, 'subspace' is defined differently. We will discuss this briefly later in today's lecture.

Example (subspaces)

$V_1 = \{(a - 2b, 3b) \mid a, b \in \mathbb{R}\}$. V_1 is a subset of \mathbb{R}^2 .

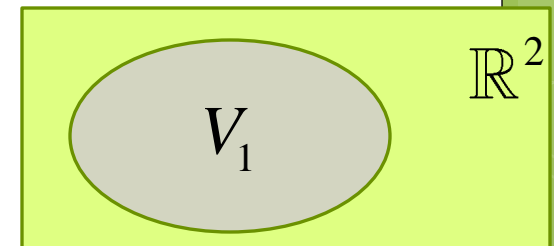
Is V_1 a subspace of \mathbb{R}^2 ?

Idea: Can you try to write V_1 as a linear span?

Is $V_1 = \mathbb{R}^2$?

So V_1 is a subspace of \mathbb{R}^2 .

Is there a vector in \mathbb{R}^2 that is not in V_1 ?



Example (subspaces)

$$V_1 = \{(a - 2b, 3b) \mid a, b \in \mathbb{R}\}.$$

Is $V_1 = \mathbb{R}^2$?

Idea: Is every vector in \mathbb{R}^2 a linear combination of $(1, 0)$ and $(-2, 3)$?

Example (subspaces)

$V_2 = \{(x, y, z) \mid x - 3y + 2z = 0\}$. V_2 is a subset of \mathbb{R}^3 .

Describe V_2 geometrically. Is V_2 a subspace of \mathbb{R}^3 ?

Idea: V_2 is given in implicit form. Can you find its explicit form?

Example (subspaces)

$V_3 = \{(x, y, z) \mid x - 3y + 2z = 1\}$. V_3 is a subset of \mathbb{R}^3 .

Describe V_3 geometrically. Is V_3 a subspace of \mathbb{R}^3 ?

$(0, 0, 0) \notin V_3$ since $0 - 3(0) + 2(0) \neq 1$.

If V_3 is a subspace, then it can be expressed as a linear span, that is, $V_3 = \text{span}(S)$ for some finite set S .

By (first) theorem in today's lecture, $(0, 0, 0) \in \text{span}(S) = V_3$.

Contradiction! So V_3 is not a subspace of \mathbb{R}^3 .

Example (subspaces)

$V_4 = \{(x, y, z) \mid x \leq y \leq z\}$. V_4 is a subset of \mathbb{R}^3 .

Is V_4 a subspace of \mathbb{R}^3 ? **No!**

If V_4 is a subspace, then it can be expressed as a linear span, that is, $V_4 = \text{span}(T)$ for some finite set T .

By (first) theorem in today's lecture,

For any $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r \in \text{span}(T) = V_4$ and $c_1, c_2, \dots, c_r \in \mathbb{R}$,

$$c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_r \mathbf{v}_r \in \text{span}(T) = V_4.$$

$(1, 1, 2), (0, 2, 4) \in V_4$ but $(1, 1, 2) - 2(0, 2, 4) = (1, -3, -6) \notin V_4$.

End of Lecture 09

Lecture 10:

Subspaces (cont'd)

Linear independence

Bases (till Example 3.5.5.1)