Lecture 07 recap

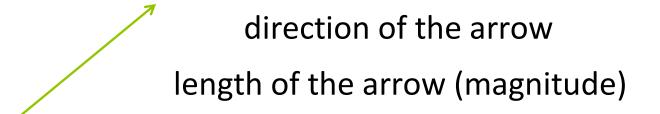
- 1) How elementary row operations changes the determinant of a matrix.
- 2) Using elementary row operations to find the determinant of a matrix.
- 3) A is invertible if and only if $det(A) \neq 0$.
- 4) $\det(cA)$, $\det(AB)$ and $\det(A^{-1})$.
- 5) Definition of adjoint of a matrix. Inverse in terms of adjoint.
- 6) Cramer's rule.

Lecture 08

Euclidean *n*-spaces
Linear combinations and linear spans

How do we represent vectors

Geometrically, a vector is represented by a directed line segment (or arrow).

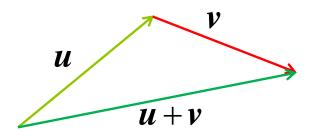


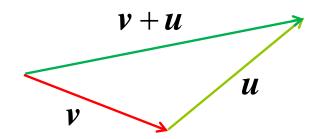
Two vectors u and v are said to be equal if they have the same length and direction.



Vector operations

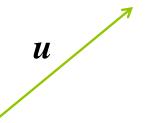
1) Addition: u + v





$$u + v = v + u$$

2) Negative of u: -u

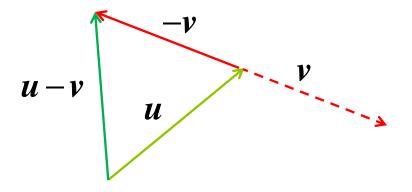




change in direction, no change in magnitude

Vector operations

3) Difference: u-v (same as u+(-v))



4) Scalar multiple: ku ($k \in \mathbb{R}$)

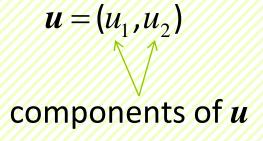


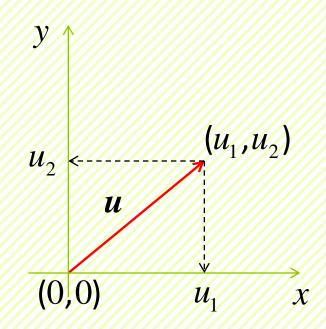
$$\frac{1}{2}u$$

(-1.2)u

Coordinate systems (2-space)

Position \boldsymbol{u} with its initial point at (0,0)

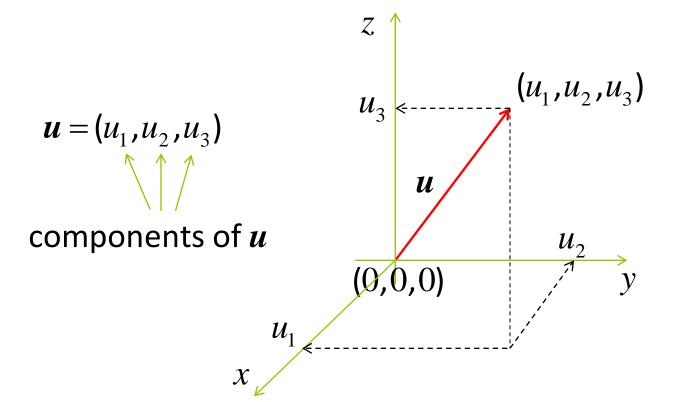




xy – plane

Coordinate systems (3-space)

Position u with its initial point at (0,0,0)



xyz — space

Addition and scalar multiplication

1) Addition: add component-wise.

$$(u_1, u_2) + (v_1, v_2) = (u_1 + v_1, u_2 + v_2)$$

$$(u_1, u_2, u_3) + (v_1, v_2, v_3) = (u_1 + v_1, u_2 + v_2, u_3 + v_3)$$

2) Scalar multiplication: multiply to each component.

$$u = (u_1, u_2), k \in \mathbb{R}$$
 $ku = (ku_1, ku_2)$
 $u = (u_1, u_2, u_3), k \in \mathbb{R}$ $ku = (ku_1, ku_2, ku_3)$

Definitions (*n*-vectors and operations)

n-vector:
$$(u_1, u_2, ..., u_i, ..., u_n)$$

 $u_1, u_2, ..., u_n$ are real numbers.

 u_1 : 1st component (or 1st coordinate) of the vector

 u_i : ith component (or ith coordinate) of the vector

$$u = (u_1, u_2, ..., u_n)$$
 $v = (v_1, v_2, ..., v_n)$

Equality: u = v if and only if

$$u_i = v_i$$
 for all $i = 1, 2, ..., n$.

Definitions (*n*-vectors and operations)

$$u = (u_1, u_2, ..., u_n)$$
 $v = (v_1, v_2, ..., v_n)$

Addition:
$$u + v = (u_1 + v_1, u_2 + v_2, ..., u_n + v_n)$$

Scalar multiplication: $c \in \mathbb{R}$, $c\mathbf{u} = (cu_1, cu_2, ..., cu_n)$

Negative:
$$-u = (-u_1, -u_2, ..., -u_n)$$

Subtraction:
$$u - v = (u_1 - v_1, u_2 - v_2, ..., u_n - v_n)$$

Zero vector:
$$0 = (0, 0, ..., 0)$$

Example (vector operations)

$$u = (3,4,5,1)$$
 $v = (-1,0,1,2)$

$$u + 2v =$$

$$2u - 3v =$$

If w = (0,0,0,0,0), what is u - 2w?

Vectors and matrices

Identifying an *n*-vector $(u_1, u_2, ..., u_n)$ with:

 $1 \times n$ matrix $(u_1 \quad u_2 \quad \dots \quad u_n)$ (row vector)

or

$$n \times 1 \text{ matrix} \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}$$
 (column vector)

Properties of vector operations

Let u,v,w be n-vectors and a,b be real numbers.

1)
$$u + v = v + u$$

5)
$$a(bu) = (ab)u$$

2)
$$u + (v + w) = (u + v) + w$$

$$6) a(\mathbf{u} + \mathbf{v}) = a\mathbf{u} + a\mathbf{v}$$

3)
$$u + 0 = u = 0 + u$$

$$7) (a+b)u = au + bu$$

4)
$$u + (-u) = 0$$

8)
$$1u = u$$

Proof: Not discussed here.

Definition (Euclidean n-space)

Euclidean *n*-space, denoted by \mathbb{R}^n is the set of all *n*-vectors $(u_1, u_2, ..., u_n)$ where u_i , i = 1, ..., n, is a real number.

$$u = (u_1, u_2, ..., u_n) \in \mathbb{R}^n$$
 if and only if $u_1, ..., u_n \in \mathbb{R}$.

Note:

- 1) For any positive integer n, \mathbb{R}^n is a set.
- 2) How many vectors does \mathbb{R}^n contain?

Infinitely many!

3) Do \mathbb{R}^2 and \mathbb{R}^3 have any vector in common? (2,-3) $(-1.5,3\pi,0)$

No!

$$S = \{ (u_1, u_2, u_3) | u_1 = 0 \text{ and } u_2 = -u_3 \}$$

S contains vectors (u_1, u_2, u_3) from \mathbb{R}^3 such that

$$\left[u_1 = 0 \text{ and } u_2 = -u_3\right]$$

S is a subset of \mathbb{R}^3

$$(0,1,-1) \in S$$

$$(0,1,-1) \in S$$
 $(0,0,0) \in S$ $(1,0,0) \notin S$

$$(1,0,0) \notin S$$

We can also write S as

$$S = \{(0, a, -a) \mid a \in \mathbb{R}\}$$

$$S = \{(w, x, y, z) \mid w - x + y + z = 0, 2w + x - y + 2z = 1\}$$

S contains vectors (w,x,y,z) from \mathbb{R}^4 such that w,x,y,z satisfies

$$\begin{cases} w - x + y + z = 0 \\ 2w + x - y + 2z = 1 \end{cases}$$

 ${\it S}$ is the solution set of the above linear system.

S is a subset of \mathbb{R}^4 .

Note that the solution set of a linear system involving n variables will be a subset of \mathbb{R}^n .

$$S = \{(w, x, y, z) \mid w - x + y + z = 0, 2w + x - y + 2z = 1\}$$

(Implicit)

Solving the linear system, we have a general solution

$$\begin{cases} w = \frac{1}{3} - t \\ x = \frac{1}{3} + s \end{cases}$$

$$\begin{cases} y = s \\ z = t \end{cases} \quad s, t \in \mathbb{R}$$

We are now able to rewrite the set *S* in another way:

$$S = \{(\frac{1}{3} - t, \frac{1}{3} + s, s, t) \mid s, t \in \mathbb{R}\}$$

(Explicit)

Lines in \mathbb{R}^2

Recall that the equation ax + by = c in two variables x, yrepresents a line in \mathbb{R}^2 .

(Implicit) representation:

Solving

$$\{(x,y) \mid ax+by=c\}, \ a,b \in \mathbb{R} \text{ not both zero.}$$

(Explicit) representation:

$$\{(\frac{c-bt}{a},t)|t\in\mathbb{R}\}, \text{ if } a\neq 0;$$

$$\{(\frac{c-bt}{a},t)|t\in\mathbb{R}\}, \text{ if } a\neq 0; \qquad \{(t,\frac{c-at}{b})|t\in\mathbb{R}\}, \text{ if } b\neq 0.$$

Planes in \mathbb{R}^3

Recall that the equation $\underline{ax + by + cz = d}$ in three variables x, y, z represents a plane in \mathbb{R}^3 .

(Implicit) representation:

 $\{(x, y, z) | ax + by + cz = d\}, a,b,c \in \mathbb{R} \text{ not all zero.}$

What about explicit representation?

Solving ax + by + cz = d. One equation, 3 unknowns.

Planes in \mathbb{R}^3

Recall that the equation ax + by + cz = d in three variables x, y, z represents a plane in \mathbb{R}^3 .

Explicit representations:
$$\{(\frac{d-bs-ct}{a},s,t) \mid s,t \in \mathbb{R}\}, \text{ if } a \neq 0;$$

$$\{(s,\frac{d-as-ct}{b},t)\mid s,t\in\mathbb{R}\}, \text{ if } b\neq 0;$$

$$\{(s,t,\frac{d-as-bt}{c})|s,t\in\mathbb{R}\}, \text{ if } c\neq 0;$$

How do we represent lines in \mathbb{R}^3 ?

A line in \mathbb{R}^3 is usually represented explicitly.

So what do we need?



A point and a direction...or two points.

A line in \mathbb{R}^3 is represented by the set

$$\{(a_0,b_0,c_0)\mid t(a,b,c)\mid t\in\mathbb{R}\}$$

(point on the line) (a_0, b_0, c_0)

$$(a_0, b_0, c_0) + 2(a, b, c)$$

$$(a_0, b_0, c_0) + (a, b, c)$$

$$(a_0,b_0,c_0)-(a,b,c)$$

(a,b,c) (direction of the line)

origin

A line in \mathbb{R}^3 is represented by the set

$$\{(a_0,b_0,c_0)+t(a,b,c)|t\in\mathbb{R}\} = \{(a_0+ta,b_0+tb,c_0+tc)|t\in\mathbb{R}\}$$

Remember:

A line in \mathbb{R}^3 cannot be represented by a single linear equation like in \mathbb{R}^2 .

Notation

S is a finite set. We use |S| to denoted the number of elements in S.

$$S_1 = \{1, 2, 3\}, S_2 = \{(1, 2, 3)\}, S_3 = \{(1, 2, 3), (2, 3, 4)\}$$

$$|S_1| = 3$$
, $|S_2| = 1$, $|S_3| = 2$

Definition (Linear Combination)

Consider u = (1, 2, -1), v = (0, 2, 5).

$$2u + 3v = (2,10,13)$$
 $u - 2v = (1,-2,-11)$

(2,10,13) and (1,-2,-11) are both linear combinations of \boldsymbol{u} and \boldsymbol{v} .

Let $u_1, u_2, ..., u_k$ be vectors in \mathbb{R}^n .

For any real numbers $c_1, c_2, ..., c_k$, the vector

$$c_1 u_1 + c_2 u_2 + ... + c_k u_k$$

is a linear combination of $u_1, u_2, ..., u_k$.

Consider u = (1, 2, -1), v = (0, 2, 5), w = (1, 0, -2).

Question: Compute the linear combination 2u + 3v - w

Answer: This is simple.

$$2u + 3v - w =$$

Consider u = (1, 2, -1), v = (0, 2, 5), w = (1, 0, -2).

Question: Is (0,4,8) a linear combination of u,v,w?

Answer: We need to check whether there are real numbers a,b,c such that

$$au + bv + cw = (0,4,8)$$

$$a(1,2,-1)+b(0,2,5)+c(1,0,-2)=(0,4,8)$$

How to check?



Consider
$$u = (2,1,3)$$
, $v = (1,-1,2)$, $w = (3,0,5)$.

Question: Is (3,3,4) a linear combination of u,v,w?

$$au + bv + cw = (3,3,4)$$

$$a(2,1,3) + b(1,-1,2) + c(3,0,5) = (3,3,4)$$

$$\begin{cases} 2a + b + 3c = 3 \\ a - b = 3 \\ 3a + 2b + 5c = 4 \end{cases} \qquad \begin{pmatrix} 2 & 1 & 3 & 3 \\ 1 & -1 & 0 & 3 \\ 3 & 2 & 5 & 4 \end{pmatrix}$$

Consider
$$u = (2,1,3)$$
, $v = (1,-1,2)$, $w = (3,0,5)$.

Question: Is (3,3,4) a linear combination of u,v,w?

$$a\mathbf{u} + b\mathbf{v} + c\mathbf{w} = (3,3,4)$$
 $a(2,1,3) + b(1,-1,2) + c(3,0,5) = (3,3,4)$

$$\begin{pmatrix}
2 & 1 & 3 & 3 \\
1 & -1 & 0 & 3 \\
3 & 2 & 5 & 4
\end{pmatrix}$$
Gaussian
$$\begin{pmatrix}
2 & 1 & 3 & 3 \\
0 & -\frac{3}{2} & -\frac{3}{2} & \frac{3}{2} \\
0 & 0 & 0 & 0
\end{pmatrix}$$

Is the linear system consistent? Are the solutions unique?

Consider u = (2,1,3), v = (1,-1,2), w = (3,0,5).

Question: Is (3,3,4) a linear combination of u,v,w?

$$au + bv + cw = (3,3,4)$$
 $a(2,1,3) + b(1,-1,2) + c(3,0,5) = (3,3,4)$

$$\begin{cases} a = 2-t & (a,b,c) = (2,-1,0) \\ b = -1-t & 2(2,1,3)-(1,-1,2)+0(3,0,5) = (3,3,4) \\ c = t & t \in \mathbb{R} \end{cases}$$

$$(a,b,c) = (1,-2,1)$$

$$(2,1,3)-2(1,-1,2)+(3,0,5) = (3,3,4)$$

Consider
$$u = (2,1,3), v = (1,-1,2), w = (3,0,5).$$

Question: Is (1,2,4) a linear combination of u,v,w?

$$au + bv + cw = (1, 2, 4)$$

$$a(2,1,3) + b(1,-1,2) + c(3,0,5) = (1,2,4)$$

$$\begin{cases} 2a + b + 3c = 1 \\ a - b = 2 \\ 3a + 2b + 5c = 4 \end{cases} = 2$$

$$\begin{pmatrix} 2 & 1 & 3 & 1 \\ 1 & -1 & 0 & 2 \\ 3 & 2 & 5 & 4 \end{pmatrix}$$

Consider u = (2,1,3), v = (1,-1,2), w = (3,0,5).

Question: Is (1,2,4) a linear combination of u,v,w? No!

$$au + bv + cw = (1,2,4)$$
 $a(2,1,3) + b(1,-1,2) + c(3,0,5) = (1,2,4)$

$$\begin{pmatrix}
2 & 1 & 3 & 1 \\
1 & -1 & 0 & 2 \\
3 & 2 & 5 & 4
\end{pmatrix}$$
Gaussian
$$\begin{pmatrix}
2 & 1 & 3 & 1 \\
0 & -\frac{3}{2} & -\frac{3}{2} & \frac{3}{2} \\
0 & 0 & 0 & 3
\end{pmatrix}$$

Is the linear system consistent?

Consider
$$e_1 = (1,0,0,0)$$
, $e_2 = (0,1,0,0)$, $e_3 = (0,0,1,0)$, $e_4 = (0,0,0,1)$
$$(1,2,3,4) =$$

$$(-3,\frac{1}{3},0,2) =$$

Any (w, x, y, z) in \mathbb{R}^4 :

Every vector $\mathbf{u} = (w, x, y, z)$ in \mathbb{R}^4 is a linear combination of $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \mathbf{e}_4$.

Consider u = (1, 2, -1), v = (0, 2, 5), w = (1, 0, -2).

Question: Is every vector in \mathbb{R}^3 a linear combination of u,v,w?



Discussion (Linear Combination)

Consider u = (1, 2, -1), v = (0, 2, 5), w = (1, 0, -2).

How many different linear combinations of u,v and w are there?

Quite a bit...

What if I put <u>ALL</u> different linear combinations of u,v and w into a set?



Definition (Linear Span)

Let $S = \{u_1, u_2, ..., u_k\}$ be a set of vectors in \mathbb{R}^n .

The set of all linear combinations of $u_1, u_2, ..., u_k$,

$$\{c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_k \mathbf{u}_k \mid c_1, c_2, \dots, c_k \in \mathbb{R}\}$$

is called the linear span of S (or linear span of $u_1, u_2, ..., u_k$).

This set is denoted by span(S) or span{ $u_1, u_2, ..., u_k$ }.

Consider
$$u = (2,1,3), v = (1,-1,2), w = (3,0,5).$$

Question: Is (3,3,4) a linear combination of u,v,w?

So
$$(3,3,4) \in \text{span}\{u,v,w\}$$

Question: Is (1,2,4) a linear combination of u,v,w?

No!

So
$$(1,2,4) \notin \operatorname{span}\{u,v,w\}$$

$$S = \{(1,1,0),(2,-1,1)\}.$$

span(S) = set of all linear combinations of (1,1,0) and (2,-1,1)

Every vector in span(S) is of the form

a(1,1,0) + b(2,-1,1) where a,b are any real numbers.

So span(
$$S$$
) = { $a(1,1,0) + b(2,-1,1) | a,b \in \mathbb{R}$ }

$$V = \{(2a+b, a, 3b-a) \mid a, b \in \mathbb{R}\}$$

V is a subset of \mathbb{R}^3 . Can V be written as a linear span?

$$(2a+b,a,3b-a)$$

$$= a(2,1,-1) + b(1,0,3)$$

So
$$V = \{a(2,1,-1) + b(1,0,3) \mid a,b \in \mathbb{R}\}\$$

= span $\{(2,1,-1),(1,0,3)\}$

Show that span $\{(1,0,1),(1,1,0),(0,1,1)\} = \mathbb{R}^3$.

We need to show that every vector in \mathbb{R}^3 can be written as a linear combination of (1,0,1),(1,1,0),(0,1,1).

Show that span{(1,1,1),(1,2,0),(2,1,3),(2,3,1)} $\neq \mathbb{R}^3$.

We need to show that there is some vector in \mathbb{R}^3 that cannot be written as a linear combination of (1,1,1),(1,2,0),(2,1,3),(2,3,1).

End of Lecture 08

Lecture 09:

Linear combinations and linear spans (cont'd) Subspaces (till end of Section 3.3)