1 The Problem

One of the most challenging difficulties facing high-fidelity modeling is the treatment of high-dimensional parameter spaces: the Curse of Dimensionality. Consider a parameter study on some quantity of interest (QoI) f in a space of dimension d; a simple heuristic is to use 10 points per dimension, in order to well represent the parameter space. Then the total number of sample points is 10^d . If a computer code implementing our model executes in a fixed time of 1 second, then our parameter study execution time scales exponentially. Figure 1 depicts the aforementioned scenario.

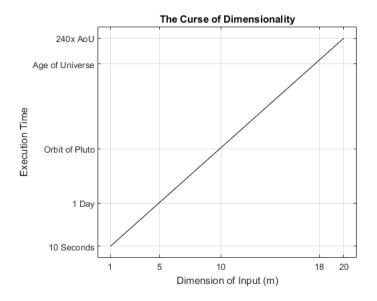


Figure 1: The Curse of Dimensionality; as dimensionality increases, the cost of many dimension-dependent studies (parameter studies, integration, etc.) increases exponentially. In this example, for modestly high-dimensional systems (say 10) the study is already completely intractable.

The only reasonable strategy to mitigate this challenge is to perform dimension reduction, that is, to reduce d. One scheme for dimension reduction of this sort is to seek Active Subspaces – linear subspaces in parameter space along which the majority of variation in our QoI is captured. [1] Active Subspaces gives a 'perfect' dimension reduction in the case that our QoI is a Ridge Function; that is, for $x \in \mathbb{R}^d$ and $A \in \mathbb{R}^{d \times k}$ with k < d, we have

$$f(\boldsymbol{x}) = f(A^T \boldsymbol{x}) \tag{1}$$

Active Subspaces have already proven to be a useful strategy in numerous engineering and scientific computing applications, though the technique has some limitations. Consider the function $f: \mathbb{R}^2 \to \mathbb{R}$ defined by

$$f(\mathbf{x}) = x_1^2 - 2x_2^2. (2)$$

Note that such a function does not

References

[1] P. Constantine. Active Subspaces: Emerging Ideas for Dimension Reduction in Parameter Studies. SIAM Philadelphia, 2015.