

Lecture 1: Brief Review on Stochastic Processes

A stochastic process is a collection of random variables $\{X_t(s) : t \in \mathcal{T}, s \in \mathcal{S}\}$, where \mathcal{T} is some index set and \mathcal{S} is the common sample space of the random variables. For each fixed $t \in \mathcal{T}$, $X_t(s)$ denotes a single random variable defined on \mathcal{S} . For each fixed $s \in \mathcal{S}$, $X_t(s)$ corresponds to a function defined on \mathcal{T} that is called a sample path or a stochastic realization of the process [1]. Unless otherwise stated, most of the time, the variable s is omitted when speaking of a stochastic process, and this is what we follow in this lecture.

In many stochastic processes, the index set \mathcal{T} often represents time, and we refer to X_t as the state of the process at time t , where $t \in \mathcal{T}$.

Any realization or sample path is also called a sample function of a stochastic process. For example, if events are occurring randomly in time and X_t represents the number of events that occur in $[0, t]$, as shown in Fig. 1, then a sample path corresponds to the initial event that occurs at time $t = 1$, the second event occurs at $t = 3$, and the third event at $t = 4$. There are no events occurring anywhere else [4].

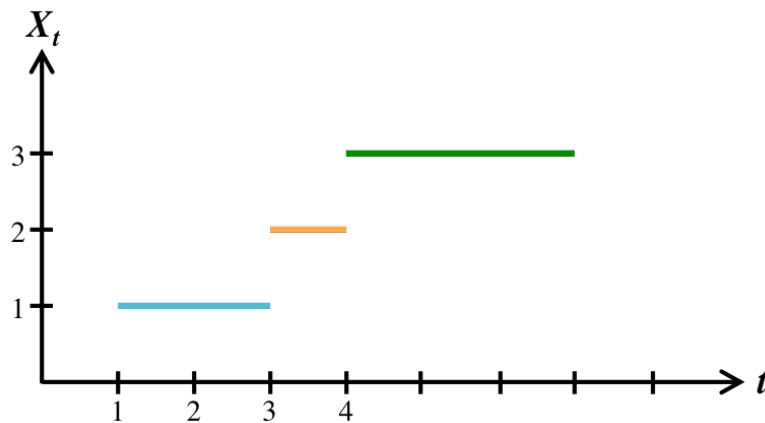


Figure 1: A sample path of X_t which is the number of events in $[0, t]$. From [4].

The main elements that distinguish stochastic processes are the state space \mathcal{S} , the index set \mathcal{T} , and the dependence relations among the random variables X_t .

State space \mathcal{S} is the space in which the possible values of each X_t lie:

- ▷ If the state space is countable, such as $\mathcal{S} = (0, 1, 2, 3, \dots)$, we refer to the process as an integer-valued or a discrete-state stochastic process.
- ▷ If $\mathcal{S} = (-\infty, \infty)$ is a real-valued space, the process is called a real-valued stochastic processes.
- ▷ If \mathcal{S} is Euclidean k space, then it is a k -vector stochastic process.

Index set \mathcal{T} characterizes stochastic processes into:

- If \mathcal{T} is a countable set (or a set of integers) representing specific time points, the stochastic process is said to be a **discrete-time** process. For instance, $\{X_t, t = 0, 1, 2, \dots\}$ is a discrete-time stochastic process indexed by the nonnegative integers.
- If \mathcal{T} is an interval of the real line, the stochastic process is said to be a **continuous-time** process. To distinguish from the discrete-time process, for the continuous-time process we may change the notation slightly, writing $X(t)$ rather than X_t . Hence, $\{X(t), 0 \leq t < \infty\}$ is a continuous-time stochastic process indexed by the nonnegative real numbers.

The values of X_t may be one-dimensional, two-dimensional, or general m dimensions. Two major examples of stochastic processes are the Brownian motion and Poisson process.

The classification of stochastic processes can be categorized into classical and modern classifications. Classical classification of stochastic processes is characterized by different dependence relationships among random variables, such as [2]:

(1) **Process with stationary independent increments**

If the real-valued random variables

$$X_{t_2} - X_{t_1}, X_{t_3} - X_{t_2}, \dots, X_{t_n} - X_{t_{n-1}}$$

are independent for all choices of t_1, t_2, \dots, t_n , for $t_i \geq 0$, satisfying

$$t_1 < t_2 < \dots < t_n,$$

then $\{X_t\}$ is said to be a process with **independent increments**. If the index set contains a smallest index t_0 , it is also assumed that

$$X_{t_0}, X_{t_1} - X_{t_0}, X_{t_2} - X_{t_1}, \dots, X_{t_n} - X_{t_{n-1}}$$

are independent. If the index set is discrete, that is, $\mathcal{T} = (0, 1, 2, \dots)$, then a process with independent increments reduces to a sequence of independent random variables $Z_0 = X_0, Z_i = X_i - X_{i-1}$, for $i = 1, 2, 3, \dots$.

If the distribution of the increments

$$X(t_1 + h) - X(t_1) \quad (1)$$

depends only on the length of the interval h and not on the time t_1 , the process is said to have **stationary increments**. For a process with stationary increments, the distribution of $X(t_1 + h) - X(t_1)$ is the same as the distribution of $X(t_2 + h) - X(t_2)$, regardless the values of t_1 , t_2 , and h .

If a process $\{X_t, t \in \mathcal{T}\}$, where \mathcal{T} is either continuous or discrete, has stationary independent increments and a finite mean, then the expectation of X_t is given by

$$E(X_t) = m_0 + m_1 t, \quad (2)$$

where $m_0 = E(X_0)$ and $m_1 = E(X_1) - m_0$. A similar assertion holds for the variance,

$$\sigma_{X_t}^2 = \sigma_0^2 + \sigma_1^2 t, \quad (3)$$

where

$$\sigma_0^2 = E((X_0 - m_0)^2)$$

and

$$\sigma_1^2 = E((X_1 - m_1)^2) - \sigma_0^2.$$

Both the Brownian motion and Poisson process have stationary independent increments, as we shall see in next lectures.

(2) Martingales

Suppose X is a random variable measuring the outcome of some random experiment. If one knows nothing about the outcome of the experiment, then the best guess for the value of X would be the expectation, $E(X)$. Conditional expectation concerns with making the best guess for X given some but not all information about the outcome.

Let $\{X_t\}$ be a real-valued stochastic process with discrete or continuous index set \mathcal{T} . The process $\{X_t\}$ is called a *martingale* if

$$E(|X_t|) < \infty \quad \text{for } t = 0, 1, 2, \dots \quad (4)$$

and,

$$E(X_{t_{n+1}} | X_{t_0} = a_0, X_{t_1} = a_1, \dots, X_{t_n} = a_n) = a_n \quad (5)$$

for any $t_0 < t_1 < \dots < t_{n+1}$ and for all values a_0, a_1, \dots, a_n , states that the expected value of $X_{t_{n+1}}$ given the past and present values of $X_{t_0}, X_{t_1}, \dots, X_{t_n}$ equals the present value of X_{t_n} . A sequence of random variables having this property is called a *martingale*.

We may rewrite Eq. (5) as

$$E(X_{t_{n+1}} | X_{t_0}, X_{t_1}, \dots, X_{t_n}) = X_{t_n}$$

and taking expectations on both sides,

$$E(E(X_{t_{n+1}} | X_{t_0}, X_{t_1}, \dots, X_{t_n})) = E(X_{t_n})$$

using the law of total probability in the form

$$E(E(X_{t_{n+1}} | X_{t_1}, X_{t_2}, \dots, X_{t_n})) = E(X_{t_{n+1}}),$$

gives us

$$E(X_{t_{n+1}}) = E(X_{t_n}),$$

and consequently, a martingale has constant mean:

$$E(X_{t_0}) = E(X_{t_k}) = E(X_{t_n}), \quad 0 \leq k \leq n.$$

It can be verified that the process $X_n = Z_1 + Z_2 + \dots + Z_n$ for $n = 1, 2, 3, \dots$ is a **discrete-time martingale** if the Z_i are independent and have means zero. Similarly, if X_t for $0 \leq t < \infty$ has independent increments whose means are zero, then $\{X_t\}$ is a **continuous-time martingale**.

(3) Markov processes

A Markov process is a process with the property that, given the present state X_{t_n} , the future state $X_{t_{n+1}}$ depends only on the present state X_{t_n} , not on the past states $X_{t_1}, X_{t_2}, \dots, X_{t_{n-1}}$. However, if our knowledge of the present state of the process is imprecise, then the probability of some future behavior will be altered by additional information relating to the past behavior of the system.

A process is said to be Markov if

$$P\{a < X_{t_{n+1}} \leq b | X_{t_n} = x_n, \dots, X_{t_2} = x_2, X_{t_1} = x_1\} = P\{a < X_{t_{n+1}} \leq b | X_{t_n} = x_n\}$$

whenever $t_1 < t_2 < \dots < t_n < t$.

A Markov process having a countable or denumerable state space is called a **Markov chain**. A Markov process for which all sample functions $\{X_t, 0 \leq t < \infty\}$ are continuous functions is called a **diffusion process**. The Poisson process is a continuous-time Markov chain and Brownian motion is a diffusion process.

(4) Stationary processes

A stochastic process $\{X_t\}$ for $t \in \mathcal{T}$, where \mathcal{T} is either discrete or continuous, is

said to be **strictly stationary** if the joint distribution functions of the families of random variables

$$(X_{t_1+h}, X_{t_2+h}, \dots, X_{t_n+h}) \quad \text{and} \quad (X_{t_1}, X_{t_2}, \dots, X_{t_n})$$

are the same for all $h > 0$ and arbitrary selections t_1, t_2, \dots, t_n from \mathcal{T} . This condition asserts that the process is in probabilistic equilibrium and that the particular times of the process being examined are of no relevance.

A stochastic process $\{X_t, t \in \mathcal{T}\}$ is said to be **wide sense stationary** or **co-variance stationary** if it possesses finite second moments and if $\text{Cov}(X_t, X_{t+h}) = E(X_t X_{t+h}) - E(X_t) E(X_{t+h})$ depends only on h for all $t \in \mathcal{T}$.

Neither the Poisson process nor the Brownian motion is stationary. No non-constant process with stationary independent increment is stationary. However, if $\{X_t, t \in [0, \infty)\}$ is a Brownian motion or a Poisson process, then $Z_t = X_{t+h} - X_t$ is a stationary process for any fixed $h \geq 0$.

(5) **Renewal processes**

Let T_1, T_2, \dots be independent, identically distributed, nonnegative random variables with distribution function $F(x) = P\{T_i \leq x\}$. We may think of the random variables T_i as being the lifetimes of a component or as the times between occurrences of some events: the first event is placed in operation at time zero; it fails at time T_1 and is immediately replaced by a new event which then fails at time $T_1 + T_2$, and so on, thus motivating the name “**renewal process**”. The time of the n th renewal is $S_n = T_1 + T_2 + \dots + T_n$.

A renewal counting process N_t counts the number of renewals in the interval $[0, t]$,

$$N_t = n \quad \text{for} \quad S_n \leq t < S_{n+1}, \quad n = 0, 1, 2, \dots$$

The Poisson process with parameter λ is a renewal counting process with $\mu = 1/\lambda$.

(6) **Point processes**

Let S be a set in n -dimensional space and let \mathcal{A} be a family of subsets of S . A **point process** is a stochastic process indexed by the sets $A \in \mathcal{A}$ and having the set $\{0, 1, \dots, \infty\}$ of nonnegative integers as its state space.

Meanwhile, modern classification of stochastic processes depends on whether the random variables or the index set are discrete or continuous [1, 3]:

- (1) Stochastic processes whose time and random variables are discrete-valued. Some examples of these processes are discrete-time Markov chain models and discrete-time branching processes.

- (2) Stochastic processes whose time is continuous but the random variables are discrete-valued. Some examples are continuous-time Markov chain models.
- (3) Stochastic processes whose random variables are continuous but the time is discrete-valued.
- (4) Stochastic processes whose both time and random variables are continuous-valued. Examples are continuous-time and continuous-state Markov processes. These models are also referred to as diffusion processes, where the stochastic realization is a solution of a stochastic differential equation.

In this lecture, we follow the modern classification of stochastic processes. Our materials here are based on known textbooks on stochastic processes and modeling [1, 2, 3], where we include stochastic processes that have a wide variety of applications. As these lecture notes are growing, as we will add more materials and technique over time.

References

- [1] Linda J. S. Allen. *An Introduction to Stochastic Processes with Applications to Biology 2nd Edition*. CRC Press, 2010.
- [2] Samuel Karlin, Howard M. Taylor. *A First Course in Stochastic Processes*. Academic Press, 1975.
- [3] Sheldon M. Ross. *Introduction to Probability Models 9th Edition*. Elsevier, 2007.
- [4] Sheldon M. Ross. *Stochastic Processes 2nd Edition*. John Wiley & Sons, 1996.