

Bayesian Statistics

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- This is a 60-hour, PhD-level course on Bayesian inference.
- We have 11 planned weeks. Reading material is posted at <https://github.com/maxbiostat/BayesianStatisticsCourse/>
- Assessment will be done via a written exam (70%) and an assignment (30%);
- Tenets:
 - ◊ Respect the instructor and your classmates;
 - ◊ Read before class;
 - ◊ Engage in the discussion;
 - ◊ Don't be afraid to ask/disagree.
- Books are
 - ◊ Robert (2007);
 - ◊ Hoff (2009);
 - ◊ Bernardo and Smith (2000).

Bayes's Theorem

What do

$$\Pr(A \mid B) = \frac{\Pr(B \mid A) \Pr(A)}{\Pr(B)}, \quad (1)$$

and

$$\Pr(A_i \mid B) = \frac{\Pr(B \mid A) \Pr(A)}{\sum_{i=1}^n \Pr(B \mid A_i) \Pr(A_i)}, \quad (2)$$

and

$$p(\theta \mid \mathbf{y}) = \frac{l(\mathbf{y} \mid \theta) \pi(\theta)}{\int_{\Theta} l(\mathbf{y} \mid t) \pi(t) dt}, \quad (3)$$

and

$$p(\theta \mid \mathbf{y}) = \frac{l(\mathbf{y} \mid \theta) \pi(\theta)}{m(\mathbf{y})}, \quad (4)$$

all have in common? In this course, we will find out how to use Bayes's rule in order to draw statistical inferences in a coherent and mathematically sound way.

Bayesian Statistics is a complete approach

Our whole paradigm revolves around the posterior:

$$p(\theta | \mathbf{x}) \propto l(\theta | \mathbf{x})\pi(\theta).$$

Within the Bayesian paradigm, you are able to

- Perform point and interval inference about unknown quantities;

$$\delta(\mathbf{x}) = E_p[\theta] := \int_{\Theta} t p(t | \mathbf{x}) dt,$$

$$\Pr(a \leq \theta \leq b) = 0.95 = \int_a^b p(t | \mathbf{x}) dt;$$

- Compare models:

$$\text{BF}_{12} = \frac{\Pr(M_1 | \mathbf{x})}{\Pr(M_2 | \mathbf{x})} = \frac{\Pr(\mathbf{x} | M_1) \Pr(M_1)}{\Pr(\mathbf{x} | M_2) \Pr(M_2)};$$

- Make predictions: $g(\tilde{x} | \mathbf{x}) := \int_{\Theta} f(\tilde{x} | t) p(t | \mathbf{x}) dt;$
- Make decisions: $E_p[U(r)].$

Statistical model: informal definition

Stuff you say at the bar:

Definition 1 (Statistical model: informal)

DeGroot, def 7.1.1, pp. 377 A statistical model consists in identifying the random variables of interest (observable and potentially observable), the specification of the joint distribution of these variables and the identification of parameters (θ) that index this joint distribution. Sometimes it is also convenient to assume that the parameters are themselves random variables, but then one needs to specify a joint distribution for θ also.

Statistical model: formal definition

Stuff you say in a Lecture:

Definition 2 (Statistical model: formal)

McCullagh, 2002. Let \mathcal{X} be an arbitrary sample space, Θ a non-empty set and $\mathcal{P}(\mathcal{X})$ the set of all probability distributions on \mathcal{X} , i.e. $P : \Theta \rightarrow [0, \infty)$, $P \in \mathcal{P}$. A parametric statistical model is a function $P : \Theta \rightarrow \mathcal{P}(\mathcal{X})$, that associates each point $\theta \in \Theta$ to a probability distribution P_θ over \mathcal{X} .

Examples:

- Put $\mathcal{X} = \mathbb{R}$ and $\Theta = (-\infty, \infty) \times (0, \infty)$. We say P is a *normal* (or *Gaussian*) statistical model¹ if for every $\theta = \{\mu, \sigma^2\} \in \Theta$,

$$P_\theta(x) \equiv \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right), \quad x \in \mathbb{R}.$$

- Put $\mathcal{X} = \mathbb{N} \cup \{0\}$ and $\Theta = (0, \infty)$. P is a Poisson statistical model if, for $\lambda \in \Theta$,

$$P_\lambda(k) \equiv \frac{e^{-\lambda} \lambda^k}{k!}, \quad k = 0, 1, \dots$$

¹Note the abuse of notation: strictly speaking, P_θ is a probability **measure** and not a *density* as we have presented it here.

Principle I: the sufficiency principle

Sufficiency plays a central role in all of Statistics.

Definition 3 (Sufficient statistic)

Let $x \sim f(x | \theta)$. We say $T : \mathcal{X} \rightarrow \mathbb{R}$ is a **sufficient statistic** for the parameter θ if $\Pr(X = x | T(x), \theta)$ is independent of θ .

This is the basis for a cornerstone of Statistics,

Theorem 1 (Factorisation theorem)

Under mild regularity conditions, we can write:

$$f(x | \theta) = g(T(x) | \theta)h(x | T(x)).$$

We can now state

Idea 1 (Sufficiency principle (SP))

For $x, y \in \mathcal{X}$, if T is sufficient for θ and $T(x) = T(y)$, then x and y should lead to the same inferences about θ .

Principle II: the Likelihood principle

The Likelihood Principle (LP) is a key concept in Statistics, of particular Bayesian Statistics.

Idea 2 (Likelihood Principle)

*The information brought by an observation $x \in \mathcal{X}$ about a parameter $\theta \in \Theta$ is **completely** contained in the likelihood function $l(\theta \mid x) \propto f(x \mid \theta)$.*

Example 1 (Uma vez Flamengo...)

Principle II: the Likelihood principle

Suppose a pollster is interested in estimating the fraction θ of football fans that cheer for Clube de Regatas do Flamengo (CRF). They survey $n = 12$ people and get $x = 9$ supporters and $y = 3$ “antis”. Consider the following two designs:

- i) Survey 12 people and record the number of supporters;
- ii) Survey until they get $y = 3$.

The likelihoods for both surveys are, respectively,

$$x \sim \text{Binomial}(n, \theta) \implies l_1(\theta | x, n) = \binom{n}{x} \theta^x (1 - \theta)^{n-x},$$

$$n \sim \text{NegativeBinomial}(y, 1 - \theta) \implies l_2(\theta | n, y) = \binom{n-1}{y-1} \theta^y (1 - \theta)^{n-y},$$

hence

$$l_1(\theta) \propto l_2(\theta) \propto \theta^3 (1 - \theta)^9.$$

Therefore, we say that these two experiments bring exactly the same information about θ .

A generalised version of the LP can be stated as follows:

Theorem 2 (Likelihood Proportionality Theorem (Gonçalves and Franklin, 2019))

Let Θ be a nonempty set and $\mathcal{P} = \{P_\theta; \theta \in \Theta\}$ be a family of probability measures on (Ω, \mathcal{A}) and ν_1 and ν_2 be σ -finite measures on (Ω, \mathcal{A}) . Suppose $P \ll \nu_1$ and $P \ll \nu_2$ for all $P \in \mathcal{P}$. Then there exists a measurable set $A \in \mathcal{A}$ such that $P_\theta(A) = 1$ for all $\theta \in \Theta$ and there exist $f_{1,\theta} \in \left[\frac{dP_\theta}{d\nu_1} \right]$ and $f_{2,\theta} \in \left[\frac{dP_\theta}{d\nu_2} \right]$ and a measurable function h such that

$$f_{1,\theta}(\omega) = h(\omega)f_{2,\theta}(\omega), \forall \theta \in \Theta \forall \omega \in A.$$

Principle III: stopping rule principle

A subject of contention between inference paradigms is the role of stopping rules in the inferences drawn.

Idea 3 (Stopping rule principle (SRP))

Let τ be a stopping rule directing a series of experiments $\mathcal{E}_1, \mathcal{E}_2, \dots$, which generates data $\mathbf{x} = (x_1, x_2, \dots)$. Inferences about θ should depend on τ only through \mathbf{x} .

Example 3 (Finite stopping rules)

Suppose experiment \mathcal{E}_i leads to the observation of $x_i \sim f(x_i \mid \theta)$ and let $\mathcal{A}_i \subset \mathcal{X}_1 \times \dots \times \mathcal{X}_i$ be a sequence of events. Define

$$\tau := \inf \{n : (x_1, \dots, x_n) \in \mathcal{A}_n\}.$$

It can be shown that $\Pr(\tau < \infty) = 1$ (exercise 1.20 BC).

Principle IV: the conditionality principle

We will now state one of the main ingredients of the derivation of the LP. The Conditionality Principle (CP) is a statement about the permissible inferences from randomised experiments.

Idea 4 (Conditionality Principle)

Let \mathcal{E}_1 and \mathcal{E}_2 be two experiments about θ . Let $Z \sim \text{Bernoulli}(p)$ and

- If $Z = 1$, perform \mathcal{E}_1 to generate $x_1 \sim f_1(x_1 \mid \theta)$;*
- If $Z = 0$ perform \mathcal{E}_2 to generate $x_2 \sim f_2(x_2 \mid \theta)$.*

*Inferences about θ should depend **only** on the selected experiment, \mathcal{E}_i .*

Deriving the Likelihood Principle

Birnbaum (1962) showed that the simpler and mostly uncontroversial Sufficiency and Conditionality principles lead to the Likelihood Principle.

Theorem 2 (Birnbaum's theorem (Birnbaum, 1962))

$$SP + CP \implies LP. \quad (5)$$

Proof.

Sketch:

- Define a function $EV(\mathcal{E}, x)$ to quantify the evidence about θ brought by data x from experiment \mathcal{E} and consider a randomised experiment \mathcal{E}^* in which \mathcal{E}_1 and \mathcal{E}_2 are performed with probability p ;
- Show that CP implies $EV(\mathcal{E}^*, (j, x_j)) = EV(\mathcal{E}_j, x_j), j = 1, 2$;
- Show that SP implies $EV(\mathcal{E}^*, (1, x_1)) = EV(\mathcal{E}^*, (2, x_2))$ when

$$l(\theta \mid x_1) = cl(\theta \mid x_2).$$

□

See Robert (2007), pg.18 for a complete proof.

Recommended reading

 Robert (2007) Ch. 1;

▶▶ Next lecture: Robert (2007) Ch. 2 and * Schervish (2012) Ch.3;

Belief functions

Let F, G and $H \in \mathcal{S}$ be three (possibly overlapping) statements about the world. For example, consider the following statements about a person:

$F = \{\text{votes for a left-wing candidate}\};$

$G = \{\text{is in the 10\% lower income bracket}\};$

$H = \{\text{lives in a large}\};$

Definition 4 (Belief function)

For $A, B \in \mathcal{S}$, a belief function $\text{Be} : \mathcal{S} \rightarrow \mathbb{R}$ assigns numbers to statements such that $\text{Be}(A) < \text{Be}(B)$ implies one is more confident in B than in A .

Belief functions: properties

It is useful to think of Be as **preferences over bets**:

- $\text{Be}(F) > \text{Be}(G)$ means we would bet on F being true over G being true;
- $\text{Be}(F \mid H) > \text{Be}(G \mid H)$ means that, **conditional** on knowing H to be true, we would bet on F over G ;
- $\text{Be}(F \mid G) > \text{Be}(F \mid H)$ means that if we were forced to bet on F , we would be prefer doing so if G were true than H .

Belief functions: axioms

In order for Be to be **coherent**, it must adhere to a certain set of properties/axioms. A self-sufficient collection is:

A1 (boundedness of complete [dis]belief):

$$\text{Be}(\neg H \mid H) \leq \text{Be}(F \mid H) \leq \text{Be}(H \mid H), \forall F \in \mathcal{S};$$

A2 (monotonicity):

$$\text{Be}(F \text{ or } G \mid H) \geq \max \{ \text{Be}(F \mid H), \text{Be}(G \mid H) \};$$

A3 (sequentiality): There exists $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ such that

$$\text{Be}(F \text{ and } G \mid H) = f(\text{Be}(G \mid H), \text{Be}(F \mid G \text{ and } H)).$$

Exercise 1 (Probabilities and beliefs)

Show that the axioms of belief functions map one-to-one to the axioms of probability:

P1. $0 \leq \Pr(E), \forall E \in \mathcal{S}$;

P2. $\Pr(\mathcal{S}) = 1$;

P3. For any countable sequence of disjoint statements $E_1, E_2, \dots \in \mathcal{S}$ we have

$$\Pr\left(\bigcup_{i=1}^{\infty} E_i\right) = \sum_{i=1}^{\infty} \Pr(E_i).$$

Hint: derive the consequences (e.g. monotonicity) of these axioms and compare them with the axioms of belief functions.

Useful probability laws

Definition 5 (Partition)

If $H = \{H_1, H_2, \dots, H_K\}$, $H_i \in \mathcal{S}$, such that $H_i \cap H_j = \emptyset$ for all $i \neq j$ and $\bigcup_{k=1}^K H_k = \mathcal{S}$, we say H is a partition of \mathcal{S} .

For any $H \in \mathcal{D}(\mathcal{S})$:

- **Total probability:** $\sum_{k=1}^K \Pr(H_k) = 1$;
- **Marginal probability:**

$$\Pr(E) = \sum_{k=1}^K \Pr(E \cap H_k) = \sum_{k=1}^K \Pr(E | H_k) \Pr(H_k),$$

for all $E \in \mathcal{S}$;

- Consequence \implies Bayes's rule:

$$\Pr(H_j | E) = \frac{\Pr(E | H_j) \Pr(H_j)}{\sum_{k=1}^K \Pr(E | H_k) \Pr(H_k)}.$$

Independence

We will now state a central concept in probability theory and Statistics.

Definition 6 ((Conditional) Independence)

For any $F, G \in \mathcal{S}$, we say F and G are **conditionally independent** given A if

$$\Pr(F \cap G \mid A) = \Pr(F \mid A) \Pr(G \mid A).$$

Remark 1

If F and G are conditionally independent given A , then

$$\Pr(F \mid A \cap G) = \Pr(F \mid A).$$

Proof.

First, notice that the axioms P1-P3 imply $\Pr(F \cap G \mid A) = \Pr(G \mid A) \Pr(F \mid A \cap G)$. Now use conditional independence to write

$$\Pr(G \mid A) \Pr(F \mid A \cap G) = \Pr(F \cap G \mid A) = \Pr(F \mid A) \Pr(G \mid A),$$

$$\Pr(G \mid A) \Pr(F \mid A \cap G) = \Pr(F \mid A) \Pr(G \mid A).$$

Definition 7 (Exchangeable)

We say a sequence of random variables $Y = \{Y_1, Y_2, \dots, Y_n\}$ are **exchangeable** if

$$\Pr(Y_1, Y_2, \dots, Y_n) = \Pr(Y_{\xi_1}, Y_{\xi_2}, \dots, Y_{\xi_n}),$$

for all **permutations** ξ of the labels of Y .

Example 4 (Uma vez Flamengo... continued)

Suppose we survey 12 people and record whether they cheer for Flamengo $Y_i = 1$ or not $Y_i = 0$, $i = 1, 2, \dots, 12$. What value should we assign to :

- $p_1 := \Pr(1, 0, 0, 1, 0, 1, 1, 1, 1, 1, 1, 1)$;
- $p_2 := \Pr(1, 1, 0, 1, 0, 1, 1, 1, 1, 0, 1, 1)$;
- $p_3 := \Pr(1, 1, 1, 1, 1, 1, 1, 1, 1, 0, 0, 0)$?

If your answer is $p_1 = p_2 = p_3$ then you are saying the Y_i are (at least partially) exchangeable!

An application of conditional independence

For $\theta \in (0, 1)$, consider the following sequence of probability statements:

$$\begin{aligned}\Pr(Y_{12} = 1 \mid \theta) &= \theta, \\ \Pr(Y_{12} = 1 \mid Y_1, \dots, Y_{11}, \theta) &= \theta, \\ \Pr(Y_{11} = 1 \mid Y_1, \dots, Y_{10}, Y_{12}, \theta) &= \theta.\end{aligned}$$

These imply that the Y_i are conditionally independent and identically distributed (iid), and in particular:

$$\begin{aligned}\Pr(Y_1 = y_1, \dots, Y_{12} = y_{12} \mid \theta) &= \prod_{i=1}^{12} \theta^{y_i} (1 - \theta)^{1-y_i}, \\ &= \theta^S (1 - \theta)^{12-S},\end{aligned}$$

with $S := \sum_{i=1}^{12} y_i$. Also, under a uniform prior,

$$\Pr(Y_1, \dots, Y_{12}) = \int_0^1 t^S (1 - t)^{12-S} \pi(t) dt = \frac{(S+1)!(12-S+1)!}{13!} = \binom{13}{S+1}^{-1}.$$

Relaxing exchangeability (a bit)

Sometimes total symmetry can be a burden. We can relax this slightly by introducing the concept of **partial exchangeability**:

Definition 8 (Partially exchangeable)

Let $\mathbf{X} = \{X_1, \dots, X_n\}$ and $\mathbf{Y} = \{Y_1, \dots, Y_m\}$ be two sets of random variables. We say \mathbf{X} and \mathbf{Y} are **partially exchangeable** if

$$\Pr(X_1, \dots, X_n; Y_1, \dots, Y_m) = \Pr(X_{\xi_1}, \dots, X_{\xi_n}; Y_{\sigma_1}, \dots, Y_{\sigma_m}),$$

for any two permutations ξ and σ of $1, \dots, n$ and $1, \dots, m$, respectively.

Example 5 (Uma vez Flamengo...continued)

To see how exchangeability can be relaxed into partial exchangeability, consider \mathbf{X} and \mathbf{Y} as observations coming from populations from Rio de Janeiro and Ceará, respectively. If the covariate “state” were deemed to not matter, then we would have complete exchangeability.

A statistically useful remark

Remark 2 (Exchangeability from conditional independence)

Take $\theta \sim \pi(\theta)$, i.e., represent uncertainty about θ using a probability distribution. If $\Pr(Y_1 = y_1, \dots, Y_n = y_n \mid \theta) = \prod_{i=1}^n \Pr(Y_i = y_i \mid \theta)$, then Y_1, \dots, Y_n are exchangeable.

Proof.

Sketch: Use

- Marginalisation;
- Conditional independence;
- Commutativity of products in \mathbb{R} ;
- Definition of exchangeability.



A fabulous theorem!

Theorem 3 (De Finetti's theorem²)

If $\Pr(Y_1, \dots, Y_n) = \Pr(Y_{\xi_1}, \dots, Y_{\xi_n})$ for all permutations ξ of $1, \dots, n$, then

$$\Pr(Y_1, \dots, Y_n) = \Pr(Y_{\xi_1}, \dots, Y_{\xi_n}) = \int_{\Theta} \Pr(Y_1, \dots, Y_n \mid t) \pi(t) dt, \quad (6)$$

for some choice of triplet $\{\theta, \pi(\theta), f(y_i \mid \theta)\}$, i.e., a parameter, a prior and a sampling model.

See Proposition 4.3 in [Bernardo and Smith \(2000\)](#) for a proof outline. Here we shall prove the version from [De Finetti \(1931\)](#).

²Technically, the theorem stated here is more general than the representation theorem proven by De Finetti in his seminal memoir, which concerned binary variables only.

This theorem has a few important implications, namely:

- $\pi(\theta)$ represents our beliefs about $\lim_{n \rightarrow \infty} \sum_i (Y_i \leq c)/n$ for all $c \in \mathcal{Y}$;
- $\{Y_1, \dots, Y_n \mid \theta \text{ are i.i.d}\} + \{\theta \sim \pi(\theta)\} \iff \{Y_1, \dots, Y_n \text{ are exchangeable for all } n\}$;
- If $Y_i \in \{0, 1\}$, we can also claim that:
 - ◊ If the Y_i are assumed to be independent, then they are distributed Bernoulli conditional on a random quantity θ ;
 - ◊ θ has a prior measure $\Pi \in \mathcal{P}((0, 1))$;
 - ◊ By the strong law of large numbers (SLLN), $\theta = \lim_{n \rightarrow \infty} (\frac{1}{n} \sum_{i=1}^n Y_i)$, so Π can be interpreted as a “belief about the limiting relative frequency of 1’s”.

The soul of Statistics


As the exchangeability results above clearly demonstrate, being able to use conditional independence is a handy tool. More specifically, knowing on what to condition so as to make things exchangeable is key to statistical analysis.

Idea 5 (Conditioning is the soul of Statistics³)

Knowing on what to condition can be the difference between an unsolvable problem and a trivial one. When confronted with a statistical problem, always ask yourself “What do I know for sure?” and then “How can I create a conditional structure to include this information?”.

³This idea is due to Joe Blitzstein, who did his PhD under no other than the great Persi Diaconis.

Recommended reading

 Hoff (2009) Ch. 2 and *Schervish (2012) Ch.1;

- *Paper: Diaconis and Freedman (1980) explains why if n samples are taken from an exchangeable population of size $N \gg n$ without replacement, then the sample Y_1, \dots, Y_n can be modelled as approximately exchangeable;

►► Next lecture: Robert (2007) Ch. 3.

Priors: a curse and a blessing

- Priors are the main point of contention between Bayesians and non-Bayesians;
- As we shall see, there is usually no unique way of constructing a prior measure;
- Moreover, in many situations the choice of prior is not inconsequential.
- There is always a question of when to stop adding uncertainty...



Determination of priors: existence

It is usually quite hard to determine a (unique) prior even when substantial knowledge. Why? One reason is that a prior measure is guaranteed to exist only when there is a **coherent ordering** of the Borel sigma-algebra $\mathcal{B}(\Theta)$. This entails that the following axioms hold:

(A1) Total ordering: For all measurable $A, B \in \mathcal{B}(\Theta)$ one and only one of these can hold:

$$A < B, B < A \text{ or } A \sim B.$$

(A2) Transitivity: For measurable $A_1, A_2, B_1, B_2 \in \mathcal{B}(\Theta)$ such that $A_1 \cap A_2 = \emptyset = B_1 \cap B_2$ and $A_i \leq B_i, i = 1, 2$ then the following holds:

$$\diamond A_1 \cup A_2 \leq B_1 \cup B_2;$$

$$\diamond \text{ If } A_1 < B_1 \text{ then } A_1 \cup A_2 < B_1 \cup B_2;$$

(A3) For any measurable $A, \emptyset \leq A$ and also $\emptyset < \Theta$;

(A4) Continuity: If $E_1 \supset E_2 \dots$ is a decreasing sequence of measurable sets and B is such that $B \leq E_i$ for all i , then

$$B \leq \bigcap_{i=1}^{\infty} E_i.$$

Approximation I: marginalisation

One way to approach the problem of determining a prior measure is to consider the marginal distribution of the data:

$$m(x) = \int_{\Theta} f(x | \theta) \pi(\theta) d\theta. \quad (7)$$

In other words we are trying to solve an inverse problem in the form of an integral equation by placing restrictions on $m(x)$ and calibrating π to satisfy them.

Approximation II: moments

Another variation on the integral-equation-inverse-problem theme is to consider expectations of measurable functions. Suppose

$$E_{\pi}[g_k] := \int_{\Theta} g_k(t) \pi(t) dt = w_k. \quad (8)$$

For instance, if the analyst knows that $E_{\pi}[\theta] = \mu$ and $\text{Var}_{\pi}(\theta) = \sigma^2$, then this restricts the class of functions in $\mathcal{L}_1(\Theta)$ that can be considered as prior density⁴. One can also consider *order statistics* by taking $g_k(x) = \mathbb{I}_{(-\infty, a_k]}(x)$.

⁴As we shall see in the coming lectures, π needs not be in $\mathcal{L}_1(\Theta)$, i.e., needs not be **proper**. But this “method-of-moments” approach is then complicated by lack of integrability.

Maximum entropy priors

The moments-based approach is not complete in the sense that it does not lead to a unique prior measure π .

Definition 9 (Entropy)

The entropy of a probability distribution P is defined as

$$H(P) := E_P[-\log p] = - \int_{\mathcal{X}} \log p(x) dP(x). \quad (9)$$

When θ has finite support, we get the familiar

$$H(P) = - \sum_i p(\theta_i) \log(p(\theta_i)).$$

We can leverage this concept in order to pick π .

Definition 10 (Maximum entropy prior)

Let \mathcal{P}_r be a class of probability measures on $\mathcal{B}(\Theta)$. A maximum entropy prior in \mathcal{P}_r is a distribution that satisfies

$$\arg \max_{P \in \mathcal{P}_r} H(P).$$

Finding a maxent prior

When Θ is finite, we can write

$$\pi^*(\theta_i) = \frac{\exp \{ \sum_{k=1} \lambda_k g_k(\theta_i) \}}{\sum_j \exp \{ \sum_{k=1} \lambda_k g_k(\theta_j) \}},$$

where the λ_k are Lagrange multipliers. In the uncountable case things are significantly more delicate, but under regularity conditions there exists a reference measure Π_0 such that

$$\begin{aligned} H_{\Pi} &= E_{\pi_0} \left[\log \left(\frac{\pi(\theta)}{\pi_0(\theta)} \right) \right], \\ &= \int_{\Theta} \log \left(\frac{\pi(\theta)}{\pi_0(\theta)} \right) \Pi_0(d\theta). \end{aligned}$$

Exercise 2 (Maximum entropy Beta prior)

Find the maximum entropy Beta distribution under the following constraints:

- $E[\theta] = 1/2$;
- $E[\theta] = 9/10$.

Hint: If P is a Beta distribution with parameters α and β , then

$$H_P = \log B(\alpha, \beta) - (\alpha - 1)\psi(\alpha) - (\beta - 1)\psi(\beta) + (\alpha + \beta - 2)\psi(\alpha + \beta),$$

where $B(x, y) = \frac{\Gamma(x)\Gamma(y)}{\Gamma(x+y)}$ is the Beta function and $\psi(x) = \frac{d}{dx} \log(\Gamma(x))$ is the digamma function.

Parametric approximations: easy-peasy

In some situations, the “right” parametric family presents itself naturally.

Example 6 (Eliciting Beta distributions)

Let $x_i \sim \text{Binomial}(n_i, p_i)$ be the number of Flamengo supporters out of n_i people surveyed. Over the years, the average of p_i has been 0.70 with variance 0.1. If we assume $p_i \sim \text{Beta}(\alpha, \beta)$ we can elicit an informative distribution based on historical data by solving the system of equations

$$E[\theta] = \frac{\alpha}{\alpha + \beta} = 0.7,$$

$$\text{Var}(\theta) = \frac{\alpha\beta}{(\alpha + \beta)^2(\alpha + \beta + 1)} = 0.1.$$

Parametric approximations: difficulties

Other times we may have a hard time narrowing down the prior to a specific parametric family. Consider the following example.

Example 7 (Normal or Cauchy?)

Suppose $x_i \sim \text{Normal}(\theta, 1)$ and we are informed that $\Pr(\theta \leq -1) = 1/4$, $\Pr(\theta \leq 0) = 1/2$ and $\Pr(\theta \leq 1) = 3/4$. Seems like plenty of information. It can be shown that

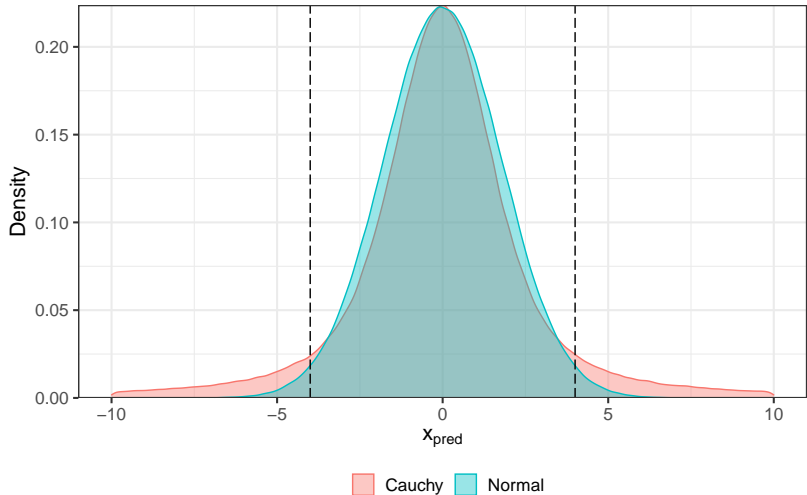
$$\pi_1(\theta) = \frac{1}{\sqrt{2\pi}2.19} \exp\left(-\frac{\theta^2}{2 \times 2.19}\right) \text{ (Normal),}$$

$$\pi_2(\theta) = \frac{1}{\pi(1 + \theta^2)} \text{ (Cauchy),}$$

both satisfy the requirements. Unfortunately, under quadratic loss we get $\delta_1(4) = 2.75$ and $\delta_2(4) = 3.76$ and differences are exacerbated for $|x| \geq 4$.

Why, though?

Remember the marginal approach? It is illuminating in this case. Heres $m(x)$:



Prior predictive distributions of x under Normal and Cauchy priors.

Conjugacy

Conjugacy is a central concept in Bayesian statistics. It provides a functional view of the prior-posterior mechanic that emphasises tractability over coherence.

Definition 11 (Conjugate)

*A family \mathcal{F} of distributions on Θ is called **conjugate** or closed under sampling for a likelihood $f(x | \theta)$ if, for every $\pi \in \mathcal{F}$, $p(\theta | x) \in \mathcal{F}$.*

Arguments for using conjugate priors

- “Form-preservation”: in a limited-information setting it makes sense that $p(\theta | x)$ and $\pi(\theta)$ lie on the same family, since the information in x might not be enough to change the structure of the model, just its parameters;
- Simplicity: when you do not know a whole lot, it makes sense to KISS⁵;
- Sequential learning: since \mathcal{F} is closed under sampling, one can update a sequence of posteriors $p_i(\theta | x_1, \dots, x_i)$ as data comes in.

⁵Keep it simple, stupid!

Exponential families

The exponential family of distributions is a cornerstone of statistical practice, underlying many often-used models. Here are a few useful definitions.

Definition 12 ((Natural) Exponential family)

Let μ be a σ -finite measure on \mathcal{X} and let Θ be a non-empty set serving as the parameter space. Let $C : \Theta \rightarrow (0, \infty)$ and $h : \mathcal{X} \rightarrow (0, \infty)$ and let $R : \Theta \times \mathcal{X} \rightarrow \mathbb{R}^k$ and $T : \Theta \times \mathcal{X} \rightarrow \mathbb{R}^k$. The family of distributions with density

$$f(x \mid \theta) = C(\theta) h(x) \exp(R(\theta) \cdot T(x))$$

w.r.t. μ is called an **exponential family**. Moreover, if $R(\theta) = \theta$, the family is said to be **natural**.

Definition 13 (Regular exponential family)

We say a natural exponential family $f(x \mid \theta)$ is **regular** if the natural parameter space

$$N := \left\{ \theta : \int_{\mathcal{X}} \exp(\theta \cdot x) h(x) d\mu(x) < \infty \right\}, \quad (10)$$

is an open set of the same dimension as the closure of the convex hull of $\text{supp}(\mu)$.

Conjugacy and sufficiency

There is an intimate link between sufficiency (i.e. the existence of sufficient statistics) and conjugacy. The following is a staple of Bayesian theory.

Theorem 4 (Pitman-Koopman-Darmois)

If a family of distributions $f(\cdot | \theta)$ whose support does not depend on θ is such that, for a sample size large enough, there exists a sufficient statistic of fixed dimension, then $f(\cdot | \theta)$ is an exponential family.

The support condition is not a complete deal breaker, however:

Remark 3 (Quasi-exponential)

The $\text{Uniform}(-\theta, \theta)$ and $\text{Pareto}(\theta, \alpha)$ families are called quasi-exponential due to the fact that there do exist sufficient statistics of fixed dimension for these families, even though their supports depend on θ .

Conjugacy in the exponential family

I hope you are convinced of the utility of the exponential family by now. It would be nice to have an automated way to deduce a conjugate prior for $f(x | \theta)$ when it is in the exponential family. This is exactly what the next result gives us.

Remark 4 (Conjugate prior for the exponential family)

A conjugate family for $f(x | \theta)$ is given by

$$\pi(\theta | \mu, \lambda) = K(\mu, \lambda) \exp(\theta \cdot \mu - \lambda g(\theta)), \quad (11)$$

such that the posterior is given by $p(\theta | \mu + x, \lambda + 1)$.

Please do note that (11) is only a valid density when $\lambda > 0$ and μ/λ belongs to the interior of the natural space parameter. Then, it is a σ -finite measure. See [Diaconis and Ylvisaker \(1979\)](#) for more details.

Conjugacy: common families

Table 3.3.1. *Natural conjugate priors for some common exponential families*

$f(x \theta)$	$\pi(\theta)$	$\pi(\theta x)$
Normal $\mathcal{N}(\theta, \sigma^2)$	Normal $\mathcal{N}(\mu, \tau^2)$	$\mathcal{N}(\varrho(\sigma^2\mu + \tau^2x), \varrho\sigma^2\tau^2)$ $\varrho^{-1} = \sigma^2 + \tau^2$
Poisson $\mathcal{P}(\theta)$	Gamma $\mathcal{G}(\alpha, \beta)$	$\mathcal{G}(\alpha + x, \beta + 1)$
Gamma $\mathcal{G}(\nu, \theta)$	Gamma $\mathcal{G}(\alpha, \beta)$	$\mathcal{G}(\alpha + \nu, \beta + x)$
Binomial $\mathcal{B}(n, \theta)$	Beta $\mathcal{B}e(\alpha, \beta)$	$\mathcal{B}e(\alpha + x, \beta + n - x)$
Negative Binomial $\mathcal{N}eg(m, \theta)$	Beta $\mathcal{B}e(\alpha, \beta)$	$\mathcal{B}e(\alpha + m, \beta + x)$
Multinomial $\mathcal{M}_k(\theta_1, \dots, \theta_k)$	Dirichlet $\mathcal{D}(\alpha_1, \dots, \alpha_k)$	$\mathcal{D}(\alpha_1 + x_1, \dots, \alpha_k + x_k)$
Normal $\mathcal{N}(\mu, 1/\theta)$	Gamma $\mathcal{G}a(\alpha, \beta)$	$\mathcal{G}(\alpha + 0.5, \beta + (\mu - x)^2/2)$

Taken from Robert (2007), page 121.

Conjugacy: drawbacks

Conjugate modelling is certainly useful, but has its fair share of pitfalls.

Arguments against using conjugate priors

- Conjugate priors are restrictive *a priori*: in many settings, specially in high dimensions, the set of conjugate priors that retain tractability is so limited so as to not be able to encode all prior information available;
- Conjugate priors are not truly subjective: they limit the analyst's input to picking values for the hyperparameters;
- Conjugate priors are restrictive *a posteriori*: you are stuck with a given structure forever, no matter how much data you run into.

The principle of insufficient reason

Also called principle of indifference by Keynes⁶.

...if there is no known reason for predicating of our subject one rather than another of several alternatives, then relatively to such knowledge the assertions of each of these alternatives have an equal probability." (Keynes, 1921, Ch4 pg. 52-53).

The idea dates back to Laplace and even Bayes himself and usually leads to

$$\pi(\theta) \propto 1.$$

⁶John Maynard Keynes (1883–1946) was an English economist.

Invariance

In many applications we might want some sort of *invariance* in our prior model.

Definition 14 (Invariant model)

A statistical model is said to be **invariant** (or closed) under the action of a group \mathcal{G} if $\forall g \in \mathcal{G} \exists \theta^* \in \Theta$ such that $y = g(x)$ is distributed with density $f(y \mid \theta^*)$, denoting $\theta^* = \bar{g}(\theta)$.

Consider two types of invariance

- *Translation* invariance: A model $f(x - \theta)$ such that $x - x_0$ has a distribution in the same family for every x_0 leads to

$$\pi(\theta) = \pi(\theta - \theta_0), \forall \theta_0 \in \Theta.$$

- *Scale* invariance: Similarly, a model of the form $\sigma^{-1}f(x/\sigma)$, $\sigma > 0$ is *scale-invariant* and leads to

$$\pi(A/c) = \pi(A),$$

for any measurable A .

Jeffreys's prior

One can try to build a prior that captures only the essential structural information about the problem by deriving an invariant distribution from the Fisher information:

$$I(\theta) = E \left[\left(\frac{\partial \log f(X | \theta)}{\partial \theta} \right)^2 \right].$$

Under regularity conditions, we can usually also write

$$I(\theta) = -E \left[\frac{\partial^2 \log f(X | \theta)}{\partial \theta^2} \right].$$

Jeffreys showed that

$$\pi_J(\theta) \propto \sqrt{I(\theta)},$$

is invariant. There are straightforward generalisations when θ is multidimensional.

Jeffreys's priors: examples

A good exercise is to show that

- If $x \sim \text{Normal}(0, \theta)$, $\pi_J(\theta) \propto 1/\theta^2$;
- If $x \sim \text{Normal}_d(\theta, \mathbf{I}_d)$, $\pi_J(\theta) \propto 1$;
- If $x \sim \text{Binomial}(n, \theta)$, $\pi_J(\theta) \equiv \text{Beta}(1/2, 1/2)$;
- If $f(x | \theta) = h(x) \exp(\theta \cdot x - \psi(\theta))$, then

$$\pi_J(\theta) \propto \sqrt{\prod_{i=1}^k \psi''(\theta)}.$$

Beware!

One important caveat of Jeffreys's priors is that they violate the Likelihood Principle. To see why, consider the following exercise.

Exercise 3 (Poisson process)

Suppose one is interested in estimating the rate, θ , of a Poisson process:

$$Y(t) \sim \text{Poisson}(t\theta).$$

There are two possible experimental designs:

- a) Fix a number n of events to be observed and record the time X to observe them, or;*
- b) Wait a fixed amount of time, t , and count the number Y of occurrences of the event of interest. Show that*

$$a) l_X(\theta) = \frac{n}{\theta^2},$$

$$b) l_Y(\theta) = \frac{t}{\theta}.$$

Which conclusions can we draw from this example?

See also example 3.5.7 in **Robert (2007)**.

Reference priors

Jeffreys's approach can sometimes lead to marginalisation paradoxes and calibration issues (see exercise 4.47 in [Robert \(2007\)](#)). [Bernardo \(1979\)](#) proposes a modification that avoids these difficulties by explicitly separating parameters in *nuisance* and *interest*. It works like this: take $f(x | \theta)$, with $\theta = (\theta_1, \theta_2)$ and let θ_1 be the parameter of interest. We must first compute⁷

$$\tilde{f}(x | \theta_1) = \int_{\Theta_2} f(x | \theta_1, t_2) \pi(t_2 | \theta_1) dt_2,$$

and then compute the Jeffreys's prior associated with this marginalised likelihood. Notice that this entails first deriving $\pi(\theta_2 | \theta_1)$.

⁷Notice that this need not be well-defined. One common way of dealing with difficulties is to integrate on a sequence of measurable compact sets and take the limit.

Reference priors: example

Suppose we have $x_{ij} \sim \text{Normal}(\mu_j, \sigma^2)$, $i = 1, \dots, n$, $j = 1, 2$ and consider making inferences about $\theta = (\sigma^2, \mu)$. Here $\theta_1 = \sigma$ is a nuisance parameter and we're interested in the location $\theta_2 = \mu$. The Jeffreys's prior is

$$\pi_J(\theta) \propto 1/\sigma^{n+1},$$

leading to a Bayes estimator under quadratic loss:

$$\hat{\sigma}_J := E[\sigma^2 \mid \mathbf{x}] = \frac{\sum_{i=1}^n (x_{i1} - x_{i2})^2}{4n - 4},$$

which is not consistent. The reference approach gives $\pi(\theta_1 \mid \theta_2)$ as a flat prior - because θ_2 is a location parameter. Marginalising the likelihood against this flat density over $(0, \infty)$ gives $\pi_R(\sigma^2) \propto 1/\sigma^2$, leading to

$$\hat{\sigma}_R = \frac{\sum_{i=1}^n (x_{i1} - x_{i2})^2}{2n - 4},$$

which is consistent. Phew!

Frequentist considerations

If you are a bit greedy and want to please Greeks and Troyans, you might also try to construct your prior so that it attains good frequency properties. One such way is to construct **matching priors**:

Definition 15 (Matching prior)

We say $\pi(\theta)$ is a **matching prior** for a confidence level α if it is constructed in such a way that

$$\Pr(g(\theta) \in C_x \mid x) = \frac{1}{m(x)} \int_{C_x} f(x \mid t) \pi(t) dt = 1 - \alpha,$$

holds for a given confidence set $C_x(\alpha)$ for $g(\theta)$.

In other words, if the posterior matches the confidence set. It can be shown that, in unidimensional families, the Jeffreys's prior gives

$$\Pr(\theta \leq k_\alpha(x)) = 1 - \alpha + O(n^{-1}),$$

where $C_x = (-\infty, k_\alpha(x))$ is a one-sided confidence interval.

Prior classes

Robert (2007) gives a classification of priors in classes:

i) Conjugate classes:

$$\Gamma_C = \{\pi \in \mathcal{F} : p \in \mathcal{F}\},$$

ii) Determined moment(s) classes:

$$\Gamma_M = \{\pi : a_i \leq E_\pi[\theta] \leq b_i, i = 1, \dots, k\},$$

iii) Neighbourhood (or ϵ -contamination) classes:

$$\Gamma_{\epsilon, Q} = \{\pi = (1 - \epsilon)\pi_0 + q, q \in Q\},$$

iv) Underspecified classes:

$$\Gamma_U = \{\pi : \int_{I_i} \pi(t) dt \leq \mu_i, i = 1, \dots, k\},$$

v) Ratio of density classes:


$$\Gamma_R = \{\pi : L(\theta) \leq \pi(\theta) \leq U(\theta)\}.$$

Prior sensitivity analysis

General recommendations about building priors:

- Check the **observable consequences** of your priors :what kinds of data does this produce?
- Check the inferential consequences of your priors: how do my estimators change under different priors?
- Make sure you know what your restrictions do to the tail of your prior;
- It is usually a good idea to understand what the prior **does** to the model, as opposed to only which values θ can plausibly take;
- Sometimes it may be useful to think of priors as *penalisations* that **regularise** inference.

Recommended reading

-  **Robert (2007)** Ch. 3;
- ▶▶ Next lecture: **Robert (2007)** Ch. 3.6, **Seaman III et al. (2012)**, **Gelman et al. (2017)** and **Simpson et al. (2017)**.

The maximum *a posteriori* (MAP) estimator

Definition 16 (Maximum *a posteriori*)

The posterior mode or maximum *a posteriori* (MAP) estimator of a parameter θ is given by

$$\delta_{\pi}^{\text{MAP}}(x) := \arg \max_{\theta \in \Theta} p(\theta | x). \quad (12)$$

Example 8 (MAP for the binomial case)

Suppose $x \sim \text{Binomial}(n, p)$. Now consider the following three priors for p :

- $\pi_0(p) = \frac{\sqrt{p(1-p)}}{B(1/2, 1/2)}$ [Jeffreys];
- $\pi_1(p) = 1$ [Beta(1,1)/Uniform];
- $\pi_2(p) = (p(1-p))^{-1}$ [Haldane (1932)].

These lead to

- $\delta_0^{\text{MAP}}(x) = \max\{(x - 1/2)/(n - 1), 0\}$;
- $\delta_1^{\text{MAP}}(x) = x/n$;
- $\delta_2^{\text{MAP}}(x) = \max\{(x - 1)/(n - 2), 0\}$.

We end this discussion with the following warning:

Idea 6 (Marginalise, not maximise)

Bayesian approaches to estimation and prediction usually focus on marginalisation rather than optimisation. This is because, following the Likelihood Principle, all of the information available about the unknowns is contained in the posterior distribution, and thus all inferences must be made using this probability measure, usually by finding suitable expectations of functionals of interest.

In particular, for higher dimensions, **concentration of measure**⁸ ensures that the posterior mode has less and less relevance as a summary, at least so far as the barycentre of the distribution is concerned.

⁸See these excellent notes by Terence Tao: <https://terrytao.wordpress.com/2010/01/03/254a-notes-1-concentration-of-measure/> .

Precision of Bayes estimators

A central quantity in the evaluation of Bayesian estimators is

$$E_p [(\delta_\pi - h(\theta))^2] = E_\pi [(\delta_\pi - h(\theta))^2 | x] \quad (13)$$

for measurable h .

Example 9 (Bayes versus frequentist risk)

Take $x \sim \text{Binomial}(n, \theta)$ with n known and place a Jeffreys's prior on θ . Consider the MLE: $\delta_1(x) = x/n$. It can be shown that:

$$E_\pi [(\delta_1 - \theta)^2 | x] = \left(\frac{x - n/2}{n(n+1)} \right)^2 + \frac{(x+1/2)(n-x+1/2)}{(n+1)^2(n+2)}.$$

Moreover,

$$\arg \max_{\theta \in (0,1)} E_\pi [(\delta_1 - \theta)^2 | x] = [4(n+2)]^{-1},$$

and

$$\arg \max_{\theta \in (0,1)} E_\theta [(\delta_1 - \theta)^2] = [4n]^{-1}.$$

A brief aside about prediction

Prediction is an important inferential task and is somewhat related to the previous discussion on precision. Consider predicting a quantity z **conditional** on data x . For that we need $g(z | x, \theta)$, $f(x | \theta)$ and $\pi(\theta)$. Then,

$$g_{\pi}(z | x) = \int_{\Theta} g(z | x, t) p(t | x) dt \quad (14)$$

encodes all of the information brought by the posterior about z . A special case is i.i.d prediction:

$$g(\tilde{x} | x) = \int_{\Theta} f(\tilde{x} | t) p(t | x) dt \quad (15)$$

is the posterior predictive of the new data \tilde{x} .

Idea 7 (Calibrated priors for prediction)

The prior, π , can be constructed so as to minimise error in a prediction task.

A neat trick

Computing expectations all the time means we have to become familiar with a few tricks to facilitate obtaining approximate answers.

Example 10 (Mixture representation of the Student-t)

Take $x \sim \text{Normal}_p(\theta, I_p)$ and put $\theta \sim \text{Student-t}_p(\alpha, 0, \tau^2 I_p)$. Then $p(\theta | x)$ does not have a closed-form normalising constant and computing the Bayes estimator under quadratic loss is a chore. However, we can use the representation

$$\begin{aligned}\theta | z &\sim \text{Normal}_p(0, \tau^2 z I_p), \\ z &\sim \text{InverseGamma}(\alpha/2, \alpha/2),\end{aligned}$$

to get

$$\theta | x, z \sim \text{Normal}_p\left(\frac{x}{1 + \tau^2 z}, \frac{\tau^2 z}{1 + \tau^2 z} I_p\right)$$

Thus, the Bayes estimator $\delta_\pi(x) = \int_0^\infty E_\pi[\theta | x, z] p(z | x) dz$ can be computed with a single integral for any dimension p .

Conjugacy is handy!

Table 4.2.1. *The Bayes estimators of the parameter θ under quadratic loss for conjugate distributions in the usual exponential families.*

Distribution	Conjugate prior	Posterior mean
Normal	Normal	
$\mathcal{N}(\theta, \sigma^2)$	$\mathcal{N}(\mu, \tau^2)$	$\frac{\mu\sigma^2 + \tau^2 x}{\sigma^2 + \tau^2}$
Poisson	Gamma	
$\mathcal{P}(\theta)$	$\mathcal{G}(\alpha, \beta)$	$\frac{\alpha + x}{\beta + 1}$
Gamma	Gamma	
$\mathcal{G}(\nu, \theta)$	$\mathcal{G}(\alpha, \beta)$	$\frac{\alpha + \nu}{\beta + x}$
Binomial	Beta	
$\mathcal{B}(n, \theta)$	$\mathcal{B}e(\alpha, \beta)$	$\frac{\alpha + x}{\alpha + \beta + n}$
Negative binomial	Beta	
$\mathcal{N}eg(n, \theta)$	$\mathcal{B}e(\alpha, \beta)$	$\frac{\alpha + n}{\alpha + \beta + x + n}$
Multinomial	Dirichlet	
$\mathcal{M}_k(n; \theta_1, \dots, \theta_k)$	$\mathcal{D}(\alpha_1, \dots, \alpha_k)$	$\frac{\alpha_i + x_i}{(\sum_j \alpha_j) + n}$
Normal	Gamma	
$\mathcal{N}(\mu, 1/\theta)$	$\mathcal{G}(\alpha/2, \beta/2)$	$\frac{\alpha + 1}{\beta + (\mu - x)^2}$

⁹Taken from Robert (2007).

A worked example

We will stretch our Bayesian muscles with the next problem.

Exercise 4 (Inference for the rate of a Gamma)

Let $x \sim \text{Gamma}(\nu, \theta)$ with $\nu > 0$ known. A natural choice of prior is $\theta \sim \text{Gamma}(\alpha, \beta)$. Find the Bayes estimator under

$$L_1(\delta, \theta) = \left(\delta - \frac{1}{\theta} \right)^2,$$

and the scale-invariant loss

$$L_2(\delta, \theta) = \theta^2 \left(\delta - \frac{1}{\theta} \right)^2$$

Hint: If $X \sim \text{Gamma}(\alpha, \beta)$, $Y = 1/X \sim \text{InverseGamma}(\alpha, \beta)$ and $E[Y^k] = \frac{\beta}{(\alpha-1) \cdots (\alpha-k)}$

A quick note on quadratic loss

Exercise 4 is a special case of the general situation where

$$L(\delta, \theta) = w(\theta) \|\delta - \theta\|_G^2,$$

for G a $p \times p$ non-negative symmetric matrix. In this case, we get

$$\delta_\pi = \frac{E_p[w(\theta)\theta]}{E_p[w(\theta)]}.$$

Please **note** that there is no universal justification for quadratic loss other than (sometimes leading to increased) mathematical tractability

Loss estimation

Since the loss function, $L(\delta(x), \theta)$ is usually measurable w.r.t the posterior, it can be estimated much the same way as other functionals. In particular, if you are feeling particularly eclectic, you can always constructed π such that

$$E \left[E_p[L(\delta_\pi(x), \theta)] \right] \geq R(\delta_\pi(x), \theta), \theta \in \Theta,$$

i.e. that the estimated loss never underestimates the error resulting from the use of δ_π , at least in the long run. This is called **frequentist validity**.

A nice little problem by Neyman

The following problem is described by Jeffreys as originating with Jerzy Neyman¹⁰.

Exercise 5 (The tramcar problem)

A person travelling in a foreign country has to change trains at a junction, and goes into the town, the existence of which they have only just heard. They have no idea of its size. The first thing they see is a tramcar numbered 100. Assuming tramcars are numbered consecutively from 1 onwards, what could one infer about the number N of tramcars in this town?

¹⁰Jerzy Neyman (1894-1981) was a Polish-American statistician, known for his work with Egon Pearson (1895-1980) on the foundations of the null hypothesis significance testing (NHST) framework.

Recommended reading

 Robert (2007), Ch4.

▶▶ Next lecture: Robert (2007) Ch. 5.

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