Lecture notes, Oct 13th, 2020

The alternative way I provided for McCall (general dynamic prog. pol)

(general dynamic prog. pol)

$$V(s) = \max_{s \in S} |V_s(s)| \le |V_s(s)| |V_s(s)| = |V_s(s)| |V_s(s)| |V_s(s)| = |V_s(s)| |V_s(s)| |V_s(s)| = |V_s(s)| |V_s(s)| |V_s(s)| = |V_s(s)| |V_s(s$$

 $\bigvee_{\tau}^{\mathsf{U}}(s) = \mathsf{MPX} \setminus \bigvee_{\tau}^{\mathsf{E}}(s), \; \; \; \; \; \; \; \bigvee_{\tau}^{\check{\mathsf{E}}}(s) = \mathsf{W}(s)$