Rules of Probability

ESS 575 Models for Ecoloical Data

N. Thompson Hobbs

January 2019



A line of inference



tobbs Rules of Probability, January 2019 1 / 24 Hobbs Rules of Probability, January 2019 2 / 24

Insight in science

Probability model

Observations (data)

Deterministic model

Idea!

What is the probability that I would observe the data if my model is a faithful representation of the processes that gave rise to the data?

Road map for today

- Rules of probability
- Factoring joint probabilities
- Directed acyclic graphs (a.k.a. Bayesian networks)

Hobbs Rules of Probability, January 2019 3 / 24 Hobbs Rules of Probability, January 2019 4 / 24

All of Bayesian inference extends from three rules of probability

- Conditional probability (and independence)
- The law of total probability
- The chain rule of probability

Random variables

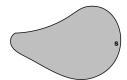
The world can be divided into things that are observed and things that are unobserved.

- Bayesians treat all unobserved quantities as random varialbes.
- The values of random variables are governed by chance.
- Probability distributions describe "governed by chance."
- A specific value of a random variable is called an event or an outcome.

Hobbs Rules of Probability, January 2019 5 / 24 Hobbs Rules of Probability, January 2019 6 / 24

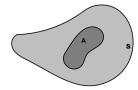
S=Sample Space

- The set of all possible values of a random variable.
- The sample space, S has a specific area.



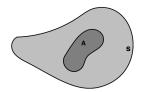
Events in S

- Can define and event, A.
- The area of event A is less than or equal to S.



Hobbs Rules of Probability, January 2019 7 / 24 Hobbs Rules of Probability, January 2019 8 / 24

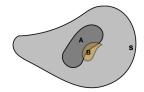
What is the probability of event A?



 $Pr(A) = \frac{Area \text{ of } A}{Area \text{ of } S}$

Conditional Probability

Conditional probability: the probability of an event given that we know another event has occurred.



Hobbs

Rules of Probability, January 2019

/ 24

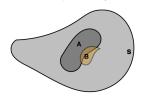
Rules

f Probability, January 2019

10 / 24

Conditional Probability

What is the probability of event B, given that event A has occurred?

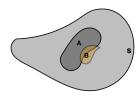


Pr(B|A) = probability of B conditional on knowing A has occurred

$$Pr(B|A) = \frac{\text{Joint Probability}}{\text{Probability of A}} = \frac{Pr(A,B)}{Pr(A)}$$

Conditional Probability

What is the probability of event A, given that event B has occurred?



Independence

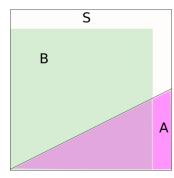
Event A and B are independent If the occurrence of event A does not tell us anything about event B.

Events are independent if and only if:

$$Pr(A|B) = Pr(A)$$

$$Pr(B|A) = Pr(B)$$

Independence



 $Pr(A|B) = \frac{area \text{ of A and B}}{area \text{ of B}} = \frac{area \text{ of A}}{area \text{ of S}}$

Hobbs

Rules of Probability, January 2019

13 / 24

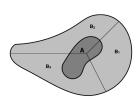
Rules of Probability, Ja

14 / 24

Independence

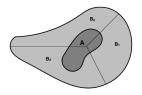
Show that Pr(A, B) = Pr(A)Pr(B) using the definition of conditional probability and independence.

The Law of Total Probability



We can define a set of events $\{B_n: n=1,2,3,...\}$, which taken together define the entire sample space, $\sum_n B_n = S$.

What is the probability of event A?



 $\Pr(A) = \sum_{n} \Pr(A|B_n) \Pr(B_n)$ (discrete case)

 $Pr(A) = \int Pr(A|B) Pr(B) dB$ (continuous case)

Chain rule of probability

Board work

 Hobbs
 Rules of Probability, January 2019
 17 / 24
 Hobbs
 Rules of Probability, January 2019
 18 / 24

The Chain Rule of Probability

The chain rule of probability allows us to calculate any number of joint distributions using only conditional probabilities.

$$Pr(z_1, z_2, ..., z_n) = Pr(z_n|z_{n-1}, ..., z_1)...Pr(z_3|z_2, z_1)Pr(z_2|z_1)Pr(z_1)$$

Notice the pattern here.

- z's can be scalars or vectors.
- Sequence of conditioning does not matter.
- When we build models, we choose a sequence that makes sense.

Factoring joint probabilities

Why is factoring useful?

- Factoring joint distributions is how we build Bayesian models.
- The rules of probability allow us to simplify complicated joint. distributions, breaking them down into chunks.
- Chunks can be analyzed one at a time.

Consider a factored joint distribution represented by a directed acvclic graph (DAG)

Represents [A | B, C] [B] [C] The is one way to factor [A, B, C].

- Directed acyclic graphs (aka Bayesian networks) specify how joint distributions are factored into conditional distributions using nodes to represent RV's and arrows to represent dependencies.
- Nodes at the heads of arrows must be on the left hand side of the conditioning symbols;
- Nodes at the tails of arrows are on the right hand side of the conditioning symbols.
- Any node at the tail of an arrow without and arrow leading into it
 must be expressed unconditionally.
- Nodes at heads of arrows are called "children"; at tails, "parents."

Factoring with DAGs at the board

 Hobbs
 Rules of Probability, January 2019
 21 / 24
 Hobbs
 Rules of Probability, January 2019
 22 / 24

Factoring joint probabilities

Illustrate with simple regression model on board.

Work on lab

Complete parts I-VI

Hobbs Rules of Probability, January 2019 23 / 24 Hobbs Rules of Probability, January 2019 24 / 24