

Gradient Descent (proofs techniques)

Saturday, March 21, 2020

5:23 PM

There are many different types of results. Here, I try to unify some of them.

Algorithm / notation

Algo	$\left\{ \begin{array}{l} X_1 \text{ arbitrary} \\ \text{for } t=1, 2, \dots, T \\ X_t = X_{t-1} - \eta V_t \end{array} \right.$	\uparrow TBD $\text{or } V_t = \nabla f(X_t)$ $\text{or } V_t \in \partial f(X_t)$

Lemma 14.1 (Shalev-Shwartz, Ben-David)

Let $\{V_t\}_{t=1}^T$ be arbitrary, f need not be convex nor smooth
 then Algo produces a sequence satisfying

$$\sum_{t=1}^T \langle X_t - x^*, V_t \rangle \leq \frac{\|x^* - x_1\|^2}{2\eta} + \frac{\eta}{2} \sum_{t=1}^T \|V_t\|^2$$

Corollary

If $\|V_t\| \leq \rho \forall t$ (eg: f is ρ -Lipschitz) and $\|x^* - x_1\| \leq B$
 choosing $\eta = \sqrt{\frac{B^2}{\rho^2 T}}$ gives $\frac{1}{T} \sum_{t=1}^T \langle X_t - x^*, V_t \rangle \leq \rho \frac{B}{\sqrt{T}}$

(x^* denotes any minimizer of f)

proof sketch of lemma (just the good parts)

$$\begin{aligned} \sum_{t=1}^T \langle X_t - x^*, V_t \rangle &= \frac{1}{2\eta} \sum_{t=1}^T \left(-\|X_{t+1} - x^*\|^2 + \|X_t - x^*\|^2 + \|V_t\|^2 \right) \\ &\quad \text{(via completing-the-square and algebra)} \\ &= \frac{1}{2\eta} \left(\|X_1 - x^*\|^2 - \|X_{T+1} - x^*\|^2 \right) + \frac{\eta}{2} \sum_{t=1}^T \|V_t\|^2 \\ &\quad \text{since sum telescoped} \quad \mathbb{R} \quad \|\cdot\| \geq 0 \\ &\leq \frac{1}{2\eta} \|X_1 - x^*\|^2 + \frac{\eta}{2} \sum_{t=1}^T \|V_t\|^2 \quad \square \end{aligned}$$

How to use this result?

Case: f is convex (and ρ -Lipschitz, so corollary applies)

Choose $V_t \in \partial f(X_t)$ $\nwarrow = \min_x f(x) = f(x^*)$

then by convexity, $f(X_t) - f^* \leq \langle X_t - x^*, V_t \rangle$

So

Corollary 1: If f is convex and ρ -Lipschitz, running subgradient descent gives

$$\frac{1}{T} \sum_{t=1}^T (f(X_t) - f^*) \leq \frac{B\rho}{\sqrt{T}} \quad \text{if } \|X_1 - x^*\| \leq B$$

and stepsize $\eta = \sqrt{\frac{B^2}{\rho^2 T}}$

How to apply this?

If we can easily evaluate $f(X_t)$, then

let $X_{\text{best}} = \arg \min_{x \in \{X_1, \dots, X_T\}} f(x)$

and

Corollary 1a: $f(X_{\text{best}}) - f^* \leq \frac{B\rho}{\sqrt{T}}$

However, sometimes it's not easy to evaluate $f(x)$

ex: $f(w) = L_D(w)$ (we can only sample from it...

as may be the case in SGD)

In that case, define $\bar{X} = \frac{1}{T} \sum_{t=1}^T X_t$

then

$f(\bar{X}) \leq \frac{1}{T} \sum_{t=1}^T f(X_t)$ by Jensen's ineq., hence

Corollary 1b: $f(\bar{X}) - f^* \leq \frac{B\rho}{\sqrt{T}}$

Case: f is smooth (ie. ∇f is β -Lipschitz)

Descent lemma: $f(X_{t+1}) \leq f(X_t) + \langle \nabla f(X_t), X_{t+1} - X_t \rangle + \frac{\beta}{2} \|X_{t+1} - X_t\|^2$
(no convexity needed just smoothness)

and if we run gradient descent w/ stepsize $\eta = \frac{1}{\beta}$ then via some algebra,

$$(*) \quad f(x_{t+1}) \leq f(x_t) - \frac{1}{2\beta} \underbrace{\|\nabla f(x_t)\|^2}_{\text{"V}_k \text{ in Algo"}}$$

Case, part 1: f is smooth but not convex

Thm If f is β -smooth, then gradient descent w/ $\eta = \frac{1}{\beta}$ gives $\min_{t \in [T]} \|\nabla f(x_t)\|^2 \leq \frac{2\beta}{T} (f(x_1) - f^*)$

(for nonconvex, we don't show convergence to a global or even local minimizer, just $\|\nabla f(x_t)\| \rightarrow 0$, i.e., a stationary pt. where $\nabla f(x) = 0$)

proof Sum $(*)$ from $t=1, \dots, T$

$$\begin{aligned} \frac{1}{2\beta} \sum_{t=1}^T \|\nabla f(x_t)\|^2 &\leq \sum_{t=1}^T f(x_t) - f(x_{t+1}) \\ &\quad \text{(telescopes)} \\ &= f(x_1) - f(x_{T+1}) \leq f(x_1) - f^* \end{aligned}$$

$$\text{and } \min_{t \in [T]} \|\nabla f(x_t)\|^2 \leq \frac{1}{T} \sum_{t=1}^T \|\nabla f(x_t)\|^2 \quad (\min \leq \text{avg}) \quad \square$$

Case, part 2: f is β -smooth and convex

As we already saw above, when f is convex, combined w/ Lemma 14.1 (but don't use the corollary yet)

$$\sum_{t=1}^T f(x_t) - f^* \leq \frac{\|x_1 - x^*\|^2}{2\eta} + \frac{\eta}{2} \sum_{t=1}^T \underbrace{\|\nabla f(x_t)\|^2}_{V_t}$$

and by smoothness, descent lemma gives

$$f(x_{t+1}) + \frac{1}{2\beta} \|\nabla f(x_t)\|^2 \leq f(x_t). \quad \text{Choose } \eta = \frac{1}{\beta}$$

then

$$\begin{aligned} \sum_{t=1}^T \left(f(x_{t+1}) + \frac{\eta}{2} \|\nabla f(x_t)\|^2 - f^* \right) &\leq \sum_{t=1}^T (f(x_t) - f^*) \\ &\leq \|x_1 - x^*\|^2 \cdot \eta \cdot T \dots \end{aligned}$$

So (using $\eta = 1/\beta$)

$$\frac{1}{2\eta} + \frac{1}{2} \sum_{t=1}^T \|\nabla f(x_t)\|^2$$

Thm: $f(x_T) - f^* \leq \frac{1}{T} \sum_{t=1}^T (f(x_t) - f^*) \leq \frac{1}{T} \frac{\beta}{2} \|x_1 - x^*\|^2$

↑ since $x_T = x_{\text{best}}$ in this case (descent lemma $\Rightarrow f(x_{t+1}) \leq f(x_t)$)

Case, part 3: f is β smooth and λ -strongly convex

First, define

"Polyak-Łojasiewicz inequality" or just "PL"

$$\forall x, \frac{1}{2} \|\nabla f(x)\|^2 \geq \lambda (f(x) - f^*)$$

then f λ -strongly convex $\Rightarrow f$ is λ -PL

Then to analyze, start at descent lemma again

$$\begin{aligned} f(x_{t+1}) - f(x_t) &\leq -\frac{1}{2\beta} \|\nabla f(x_t)\|^2 \quad (\text{by } \beta\text{-smoothness}) \\ &\leq -\frac{\lambda}{\beta} (f(x_t) - f^*) \quad (\text{by PL}) \end{aligned}$$

So re-arrange

$$\begin{aligned} f(x_{t+1}) - f^* &\leq \left(1 - \frac{\lambda}{\beta}\right) (f(x_t) - f^*) \\ &\leq \left(1 - \frac{\lambda}{\beta}\right)^t (f(x_0) - f^*) \end{aligned}$$

So

Thm $f(x_{t+1}) - f^* \leq c^t (f(x_0) - f^*)$
 $c = (1 - \lambda/\beta) < 1$ "linear convergence"

Discussion of convergence rates

Error e_t . How many more iterations needed to go from $\epsilon=1$ accuracy to $\epsilon=0.01$ accuracy?

	<u>Rate</u>	<u>Iter.</u>	<u>Examples</u>
-linear	1. $e_T \propto \frac{1}{\sqrt{T}}$ ($T = O(\epsilon^{-2})$)	10,000 <small>times more</small>	subgradient or gradient descent (not smooth); SGD
	2. $e_T \propto \frac{1}{T}$ ($T = O(\epsilon^{-1})$)	100 <small>times more</small>	gradient descent (smooth)

- sub: 3. $e_T \propto \frac{1}{T^2}$ ($T = O(\epsilon^{-1/2})$) 10 times more accelerated gradient descent
- linear: 4. $e_T \propto c^T$ ($T = \log(\epsilon^{-1})$) 2 const more gradient descent (smooth and strongly convex)
 $e_{t+1} \leq c e_t$
- superlinear: 5. $e_{t+1} \leq c_t e_t$, $c_t < 1$, $c_t \rightarrow 0$
- quadratic: 6. $e_{t+1} \leq c e_t^2$ ($T = \log(\log(\epsilon^{-1}))$) 1 more Newton's method near a solution
 $c > 0$

Geometric Picture

