#### Frank-Wolfe / Conditional Gradient algorithm

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#### Constrained optimization problem

We consider the constrained optimization problem (P):

$$\min_{x \in \mathcal{D}} f(x)$$

- where  $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$  is the **objective function**
- $\mathcal{D}$  is the **domain** which we assume is a **convex set**.
- $\rightarrow$  Assuming f is smooth how would you solve this?
- $\rightarrow$  Give me examples in machine learning of such a problem.

## Constrained optimization problem



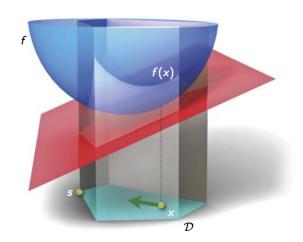


Image courtesy of Martin Jaggi (cf. [Jag13]).



# Many applications

- network flows / transportation problems
- greedy selection and sparse optimization
- low-rank matrix factorizations, many other matrices
- wavelets (infinite-dimensional)
- structured sparsity and structured prediction
- total-variation-norm for image de-noising
- submodular optimization
- boosting
- training deep networks

#### LMO and linearization

The Linear Minimization Oracle

$$LMO_{\mathcal{D}}(d) = \operatorname*{arg\,min}_{s \in \mathcal{D}} \langle d, s \rangle$$

Linearization

$$\min_{s\in\mathcal{D}}f(x)+\langle\nabla f(x),s-x\rangle$$

Idea:

$$x^{k+1} \approx \underset{s \in \mathcal{D}}{\operatorname{arg\,min}} \operatorname{LMO}_{\mathcal{D}}(\nabla f(x^k))$$

• Step depends on domain  $\mathcal{D}$  and  $\nabla f(x^k)$ , hence the name conditional gradient.

#### Convergence

• Marguerite Frank and Philip Wolfe showed in [FW56] that:

$$f(x^k) - f(x^*) \le \mathcal{O}(1/k)$$

- Provided that:
  - f is smooth and convex
  - ullet  $\mathcal D$  is bounded and convex

Rem: Same rates as projected gradient method but with simpler iterations. It is a projection free algorithm.

### Frank-Wolfe / Conditional Gradient algorithm

- 1:  $x^0 \in \mathbf{D}$
- 2: **for** k = 0 to n **do**
- 3:  $s = \text{LMO}_{\mathcal{D}}(\nabla f(x^k))$
- 4:  $\gamma = \frac{2}{k+2}$
- 5:  $x^{k+1} = (1-\gamma)x^k + \gamma s$
- 6: end for
- 7: return  $x^{k+1}$

With line search:

$$\gamma = \operatorname*{arg\,min}_{\gamma \in [0,1]} f((1-\gamma)x^k + \gamma s)$$

### Convergence proof

#### Theorem

For each  $k \ge 1$ , the iterates  $x^k$  of the Frank-Wolfe algorithm satisfy

$$f(x^k) - f(x^*) \le \frac{2C_f}{t+2} .$$

#### Convergence proof

PROOF. Let  $C_f$  a "curvature" constant such that:

$$f(y) \le f(x) + \gamma \underbrace{\langle s - x, \nabla f(x) \rangle}_{-g(x)} + \frac{\gamma^2}{2} C_f$$

for all  $x, s \in \mathcal{D}$ ,  $y = x + \gamma(s - x)$ ,  $\gamma \in [0, 1]$ . Writing  $h(x^k) = f(x^k) - f(x^*)$  for the error on objective, we have:

$$h(x^{k+1}) \le h(x^k) - \gamma g(x^k) + \frac{\gamma^2}{2} C_f \qquad \text{(Definition of } C_f)$$

$$\le h(x^k) - \gamma h(x^k) + \frac{\gamma^2}{2} C_f \quad (h \le g \text{ by convexity})$$

$$= (1 - \gamma)h(x^k) + \frac{\gamma^2}{2} C_f.$$

From here, the decrease rate follows from a simple lemma.



### Convergence proof

#### Lemma

Suppose a sequence of numbers  $(h_k)_k$  satisfies

$$h_{k+1} \le (1 - \gamma^k)h_k + (\gamma^k)^2 C$$

for  $\gamma^k = \frac{2}{k+1}$ , and  $k = 0, 1, \dots$ , and a constant C. Then

$$h_k \leq \frac{4C}{k+2}, \ k=0,1,\ldots$$

PROOF. Trivial by induction.

Rem: [LJJ13] shows a linear convergence if f strongly convex and use line-search.



#### Curvature constant vs. L-Liptschitz gradient

The curvature constant  $C_f$  is defined by:

$$C_f = \sup_{\substack{x,s \in \mathcal{D}, \\ \gamma \in [0,1] \\ y = x + \gamma(s-x)}} \frac{2}{\gamma^2} (f(y) - f(x) - \langle y - x, \nabla f(x) \rangle) .$$

#### Lemma

Let f be a convex and differentiable function with its gradient  $\nabla f$  being Lipschitz-continuous w.r.t. some norm  $\|\cdot\|$  over the domain  $\mathcal D$  with Lipschitz-constant  $L_{\|\cdot\|}>0$ . Then:

$$C_f \leq \operatorname{diam}_{\|\cdot\|}(\mathcal{D})^2 L_{\|\cdot\|}$$
.

PROOF. Give it a try!

Rem: For L-smooth convex function, with a bounded convex domain with have the  $\mathcal{O}(1/k)$  convergence rate.



# Optimality certificate (almost for free)

We solve:

$$\min_{x \in \mathcal{D}} f(x)$$

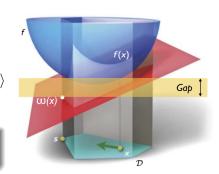
Let:

$$\omega(x) = \min_{s \in \mathcal{D}} f(x) + \langle \nabla f(x), s - x \rangle$$

#### Lemma (Weak duality)

$$\omega(x) \le f(x^*) \le f(x)$$

So if  $f(x) - \omega(x) \le \epsilon$  we have an  $\epsilon$ -solution.



### Special case of Atomic Sets

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$$\mathcal{D} = \operatorname{conv}(\mathcal{A})$$

where A is a set (possibly infinite) of atoms/vectors.

Then we have that for every FW step  $s \in A$ .

Example of  $\ell_1$  ball:

$$\mathcal{D} = \operatorname{conv}(\{e_i|i \in [n]\} \cup \{-e_i|i \in [n]\})$$



So 
$$s = \text{LMO}_{\mathcal{D}}(\nabla f(x^k)) \in \{e_i | i \in [n]\} \cup \{-e_i | i \in [n]\}.$$



### Let's practice

 $\rightarrow$  frank\_wolfe.ipynb notebook.

#### References



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