Equations for possible use.

$$\frac{\partial x^*}{\partial p_x} = \frac{\partial x^c}{\partial p_x} - \frac{\partial x^*}{\partial I} x^c$$

$$MR = P(1 + \frac{1}{e_{q,P}})$$

$$\frac{dlnx}{dx} = \frac{1}{x}$$

$$\frac{d(ax^b)}{dx} = bax^{b-1}$$

$$E(U(x)) = \pi_1 U(w_1) + \pi_2 U(w_2)$$

$$TaxRevanue = t * x^*(p_x - t, p_y, I)$$

$$\frac{-dK}{dL}|_{q_0} = \frac{MP_L}{MP_K}$$

$$\frac{\partial e(p_x, p_y, I)}{\partial p_x} = x^c(p_x, p_y, I)$$

$$x^*(p_x, p_y, I) = -\frac{\frac{\partial V(p_x, p_y, I)}{\partial p_x}}{\frac{\partial V(p_x, p_y, I)}{\partial I}}$$

$$\frac{\partial C(q,w,v)}{\partial v} = k^c(q,w,v)$$

$$-\frac{\partial \pi(q, w, v)}{\partial w} = l^*(P, w, v)$$

$$-\frac{\partial \pi(q,w,v)}{\partial v} = k^*(P,w,v)$$

$$\frac{\partial \pi(q, w, v)}{\partial P} = q(P, w, v)$$

$$Q = nq$$

$$E[x] = \sum_{i=1}^{n} \pi_i x_i$$

$$\sigma = \frac{\%\Delta(k/l)}{\%\Delta RTS} = \frac{d(k/l)}{dRTS} * \frac{RTS}{k/l}$$