

Benjamin Nguyen

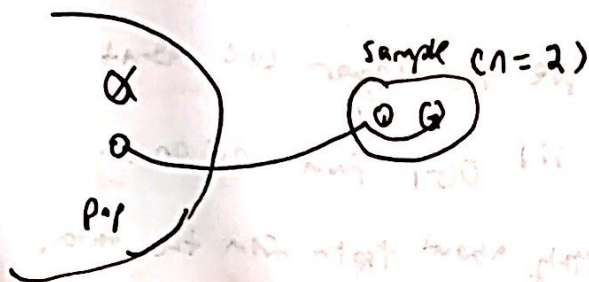
MATH 369

8/31/20

Lecture #2

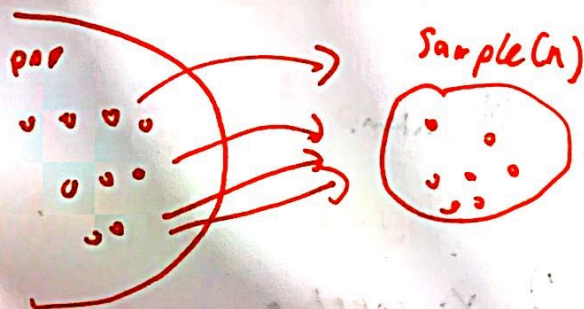
$$X_1 \sim \text{Bern}(\theta) = \text{Bern}\left(\frac{K}{N}\right)$$

Let's draw a second sample from the population assuming $X_1 = 1$



$$P(X_2 = 1 | X_1 = 1) = \frac{K-1}{N-1} < \frac{K}{N} = \theta$$

$$\Rightarrow X_2 | X_1 = 1 \sim \text{Bern}\left(\frac{K-1}{N-1}\right)$$



$$T_n = X_1 + \dots + X_n \sim \text{Hypergeo}(N, K, n)$$

$$P(T_n = t) = \frac{\binom{K}{t} \binom{N-K}{n-t}}{\binom{N}{n}}$$

Dealing with the hypergeo is complicated. What can we assume to get rid of this problem?

$$\text{Let } K, N \rightarrow \infty \text{ but } \theta = \frac{K}{N} \Rightarrow X_1, \dots, X_n \stackrel{iid}{\sim} \text{Bern } \theta$$

$$\lim P(X_2 = 1 | X_1 = 1) = \lim \frac{K-1}{N-1} = \theta$$

Pretend you work at the iPhone factory, they sample new iPhones to ensure they work properly to ensure the manufacturing is working properly. You check the first one $x_1 = 1$, $x_2 = 1$.

What population are you sampling from? What is N ?

When you estimate θ , you're estimating θ in a "process" i.e. a "data generating process" (DGP), iid $\text{Bern}(\theta)$...

DGPs are infinite population sampling. It's the same thing. We no longer care about whether the population is "real", we just assume an iid DGP from now on...

Returning to our main goal: inference i.e. knowing something about θ from the data.

First subgoal: point estimator. Recall,

$$\hat{\theta} = \frac{1}{n}(x_1 + \dots + x_n). \quad x_1, \dots, x_n \text{ are random realizations from } x_1, \dots, x_n \stackrel{\text{iid}}{\sim} \text{Bern}(\theta)$$

$\hat{\theta}$ e.g. $\vec{x} = [1, 0, 0, 1, 0] \Rightarrow \hat{\theta} = 0.4 \Rightarrow \hat{\theta}$ random.

$$\vec{x} = [1, 1, 0, 1] \Rightarrow \hat{\theta} = 0.75$$

$\hat{\theta}$ is a realization from the r.v. $\hat{\theta} := \frac{1}{n} \sum_{i=1}^n X_i$ called $\hat{\theta}$

"Statistical estimator" or just "estimator". The statistic (statistical estimate, estimate) is a realization from the estimator. The distribution of the estimator, $\hat{\theta}$, is called the "sampling distribution". This sampling distribution and its properties are very important because it tells us a lot about our estimator.

One property is the estimator's expectation, the mean over all samples n size n .

$$E[\hat{\theta}] = \theta$$

\nearrow overall
 x_1, \dots, x_n

$E[\hat{\theta}] = E\left[\frac{1}{n}(x_1 + \dots + x_n)\right] = \frac{1}{n} \sum E[x_i] = \frac{1}{n} n E[x_1] = \theta$ In our case $Bias(\theta) = 0$ set.

$\Rightarrow \theta$ is unbiased.

$Bias[\hat{\theta}] := E[\hat{\theta}] - \theta$. If $Bias[\hat{\theta}] = 0 \Rightarrow \theta$ is unbiased.
 $Bias[\hat{\theta}] \neq 0 \Rightarrow \theta$ is biased.

How far is $\hat{\theta}$ from θ ?

We define a distance function AKA "loss function". ("error function")

$l(\hat{\theta}, \theta)$, $l: \Theta \times \Theta \rightarrow [0, \infty)$. $l = 0$ only if $\hat{\theta} = \theta$

There are many ways to define a loss function e.g.

$l(\hat{\theta}, \theta) := |\hat{\theta} - \theta|$ absolute error loss (L_1 , loss)

* $l(\hat{\theta}, \theta) := |\hat{\theta} - \theta|^2$ squared error loss (L_2 , loss)

$l(\hat{\theta}, \theta) := |\hat{\theta} - \theta|^p$, $p > 0$ L_p loss

$l(\hat{\theta}, \theta) := \int \ln\left(\frac{p(x; \theta)}{p(x; \hat{\theta})}\right) p(x; \theta) dx$ Kullback-Leibler (KL) loss for continuous r.v.'s

How far away on average are we?

Risk: $R(\hat{\theta}, \theta) = E[l(\hat{\theta}, \theta)]$

Risk of an estimator.

If we use squared error loss,
 $R(\hat{\theta}, \theta) = MSE[\hat{\theta}] = E[(\hat{\theta} - \theta)^2]$
 "mean squared error".

~~under random error / off diag / off diag / off diag~~

Is the estimator unbiased, does its MSE simplify?
 $MSE[\hat{\theta}] = E[(\hat{\theta} - \theta)^2] = E[(\hat{\theta} - E[\hat{\theta}])^2] = \text{var. or } \text{Var}[\hat{\theta}]$.
 IF θ is unbiased, $E[\hat{\theta}] = \theta$

For a biased estimator (ie the general case),

$$\begin{aligned} MSE[\hat{\theta}] &= E[(\hat{\theta} - \theta)^2] = E[\hat{\theta}^2 - 2\hat{\theta}\theta + \theta^2] \\ &= E[\hat{\theta}^2] - 2\theta E[\hat{\theta}] + \theta^2 \quad \text{Recall } \text{var}[\hat{\theta}] = E[\hat{\theta}^2] - E[\hat{\theta}]^2 \\ &= \text{var}[\hat{\theta}] + E[\hat{\theta}]^2 - 2\theta E[\hat{\theta}] + \theta^2 \\ &= \text{var}[\hat{\theta}] + (E[\hat{\theta}] - \theta)^2 \\ &= \text{var}[\hat{\theta}] + \text{Bias}[\hat{\theta}]^2 \quad \text{Bias-variance decomp of MSE.} \end{aligned}$$

$SE[\hat{\theta}] := \sqrt{\text{var}[\hat{\theta}]}$ "Standard error of the estimator"