Sample (n)  $T_n = X_1 + \dots + X_n$ + X Hypergeometric dist.  $P(T_n = t) = \frac{x}{n-t} \frac{(x)(n-x)}{(n-t)}$  (n, x, N)  $\bar{X} = [1(\sqrt{\alpha}) \circ J = 0 \quad \hat{G} = C \cdot A \Rightarrow C \cdot A$ Dealing w/ the hypergeometric is complicated (but doable). What can we assume to make this gravay?= 9 V 9 of mont noites last is si & called By "Statistical estimation and just "Estimator" Let X, N-> contbut 10 = N+2) simplifying assumption is a realization from the estimation. The distribution lim P(X2=X,=1)= lim N-1=0=>X, , ... X\_~ Ben(0) This sampling dist and its properties whe hap Pretend you work at the iphone factory, they sample new iphones to ensure they work to ensure the manufacturing is working properly. You check the first one X = 1, X2 = 1, ..., X100 = 1 ·EXIBNABERALIS (XH HX) 引きに合いま What population are you sampling from? What's N? When you estimate &, you're estimating & in a "process," i.e. a "data generating process" (DGP), i.i.d. Bern (0).

DGPs and so population sampling is the same thing.

"real", we just assume an i.i.d. DGP from now on. Returning to our main goal: inference i.e. knowing Something about 0 from the data. First subgoal: pt estimation.  $\hat{\theta} = \frac{1}{n} (X_1 + \dots + X_n) \times \dots \times n$  are random realizations From X, X, ~ Bern(0) e.g.  $\overline{X} = \begin{bmatrix} 10010 \end{bmatrix} = > \hat{\theta} = 0.4 = > \Theta$  random but e.g.  $\overline{X} = \begin{bmatrix} 11101 \end{bmatrix} = > \hat{\theta} = 0.8$  (could be any thing) ("Xim, Yu dookle) what are or one to make the B is a realization from the R.V. B= TEXi is called a "Statistical estimator" or just "estimator". The Statistic (Statistical estimate, estimate) is a realization from the estimator. The distribution of the estimator, & is called the "sampling dist" This sampling dist and its properties are very important blo it tells us a lot about our estimates. Sample new ighones to ensure they work to One property is the estimator's expectation, the mean arrall manufacture Samples of size n. WY ECÔ] = E[ (X, + . . + X, )] = - SE[X;] = - = E[X;] = => What pupil besoid is is in Single from the will se will over all Bias [ê] = E[ê]-O. If i.i.d. Bern(0) setting X.,.., Xn Bias [0]=0=> 0 is unbiased to=> biased"

We no longer care about whether the population is

How far is  $\hat{\theta}$  from  $\Theta$ ?

We define a distance fn a.k.a. "loss function", ("error fn")  $\ell(\hat{\theta}, \theta)$ .  $\ell(\hat{\theta}, \theta)$  absolute error loss (L. loss)  $\ell(\hat{\theta}, \theta)$ :  $\ell(\hat{\theta$ 

 $\mathcal{L}(\hat{\theta}, \theta) = \int \mathcal{L}_{n}(\frac{f(x; \theta)}{f(x; \theta)}) f(x; \theta) dx$  Kullblack - Leibler (KL)  $x \in X$  loss for continuous R.V.S.

How far away on average are we? [9]  $\mathbb{R}(\hat{\theta}, \theta) = \mathbb{E}[L(\theta, \hat{\theta})] / \mathbb{E}[\Psi \text{ used squared error loss,}$ Risk of an Jover,  $\mathbb{X}_1, \ldots, \mathbb{X}_n / \mathbb{R}(\hat{\theta}, \theta) = \mathbb{M} \mathbb{E}[\hat{\theta}] = \mathbb{E}[(\hat{\theta} - \theta)^2]$ estimator "mean squared error" (MSE)

## Coal #31 of interface: theory terring (hyp their testing)

If the estimator is unbiased, what is its MSE simplify?

MSE  $[\hat{\theta}] = E[(\hat{\theta} + \theta)^2] = E[(\hat{\theta} - E[\hat{\theta}])^2] = Var[\hat{\theta}]$ if  $\hat{\theta}$  is unbiased,  $E[\hat{\theta}] = \theta$ 

MSE = variance

For a biased estimator (i.e. the general case),  $MSEH = E[(\hat{\theta} - \theta)^2] = E[\theta^2 - 2\hat{\theta}\theta + \theta^2]$   $= E[\hat{\theta}^2](-2\theta E[\hat{\theta}] + \theta^2]$  Recall var[ $\hat{\theta}$ ] =  $E[\theta^2]$ - $E[\hat{\theta}]$ 

=  $\sqrt{\alpha}$   $C\hat{\theta}$  +  $C\hat{\theta}$  =  $2\theta$   $C\hat{\theta}$  +  $\theta$ 

Marchalle Bias [0] Bias - Nar decomposition

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SE[ê] i = Jvar[ê] "Std error of the estimation"