

Time-Series-Cross-Section Data 2

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Fixed Effects

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$$y_{it} = \alpha + \beta x_{it} + \delta u_i + \epsilon_{it}, i = 1, \dots, N, t = 1, \dots, T$$

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- LSDV representation: $\mathbf{Y} = \beta \mathbf{X} + \delta_{\mathbf{u}} \mathbf{u} + \epsilon$, where

$$\mathbf{X} = \begin{bmatrix} x_{11}^{(1)} & x_{11}^{(2)} & \dots & x_{11}^{(K)} \\ \vdots & \vdots & \vdots & \vdots \\ x_{1T}^{(1)} & x_{1T}^{(2)} & \dots & x_{1T}^{(K)} \\ x_{21}^{(1)} & x_{21}^{(2)} & \dots & x_{21}^{(K)} \\ \vdots & \vdots & \vdots & \vdots \\ x_{2T}^{(1)} & x_{2T}^{(2)} & \dots & x_{2T}^{(K)} \\ \dots & \dots & \dots & \dots \\ x_{N1}^{(1)} & x_{N1}^{(2)} & \dots & x_{N1}^{(K)} \\ \vdots & \vdots & \vdots & \vdots \\ x_{NT}^{(1)} & x_{NT}^{(2)} & \dots & x_{NT}^{(K)} \end{bmatrix}_{NT \times K} \quad \text{and } \delta_{\mathbf{u}} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ \vdots & \vdots & & \vdots \\ 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 1 & \dots & 0 \\ 0 & 0 & \dots & 1 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}_{NT \times N}$$

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- There are in total $(N + K)$ parameters to be estimated, and as a result the estimation is inefficient when T is small

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- ▶ Demeaned estimation: Regress Y and X on δ_u and then regress the residuals \tilde{Y} and the residuals \tilde{X} , where

$$\tilde{Y} = \begin{pmatrix} y_{11} - \bar{y}_1 \\ \vdots \\ y_{it} - \bar{y}_i \\ \vdots \\ y_{NT} - \bar{y}_N \end{pmatrix} \text{ and } \tilde{X} = \begin{pmatrix} x_{11} - \bar{x}_1 \\ \vdots \\ x_{it} - \bar{x}_i \\ \vdots \\ x_{NT} - \bar{x}_N \end{pmatrix}$$

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- ▶ Then $\hat{\beta}_{FE} = (\tilde{X}'\tilde{X})^{-1}\tilde{X}'\tilde{Y} = \hat{\tau}_{FE}$, the within-group estimator

Random Effects

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- The critical step is to derive the variance-covariance matrix of the augmented errors $(u + \epsilon)$, and we have $V = \Omega \otimes \mathbf{I}_N$ where

$$\Omega = \begin{pmatrix} \sigma_u^2 + \sigma_e^2 & \sigma_u^2 & \dots & \sigma_u^2 \\ \sigma_u^2 & \sigma_u^2 + \sigma_e^2 & \dots & \sigma_u^2 \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_u^2 & \sigma_u^2 & \dots & \sigma_u^2 + \sigma_e^2 \end{pmatrix}_{T \times T}$$

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- MLE now can be implemented with $Y|X \sim N(Z\gamma, \Omega)$ where $Z = [1X]_{NT \times K}$ and $\gamma = [\alpha\beta]_{K \times 1}^T$

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- ▶ Eventually, we can show that

$$\hat{\beta}_{RE} = (\tilde{X}'\tilde{X} + \frac{\sigma_e^2}{\sigma_e^2 + \sigma_u^2}T'\tilde{X})^{-1}(\tilde{X}'\tilde{X}\hat{\beta}_W + \frac{\sigma_e^2}{\sigma_e^2 + \sigma_u^2}T'\tilde{X}\hat{\beta}_B)$$

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- ▶ $\beta_B = (\dot{X}'\dot{X})^{-1}\dot{X}'\dot{Y}$, where $\dot{Y}_i = \bar{y}_i - \bar{y}$, $\dot{X}_i = \bar{x}_i - \bar{x}$, and

$$\dot{Y}_{NT \times 1} = \begin{pmatrix} 1_T(\bar{y}_1 - \bar{y}) \\ \vdots \\ 1_T(\bar{y}_N - \bar{y}) \end{pmatrix} \text{ and } \dot{X}_{NT \times 1} = \begin{pmatrix} 1_T(\bar{x}_1 - \bar{x}) \\ \vdots \\ 1_T(\bar{x}_N - \bar{x}) \end{pmatrix}$$

. We call it between-group estimator

- ▶ Clearly, we can see that the random effects estimator is just a weighted average of within-in group estimator and between-group estimator. If $T \rightarrow \infty$ or $\sigma_u^2 \rightarrow \infty$, then it is the case of fixed effects. If $\sigma_u^2 = 0$, then it becomes a pooled OLS estimator. (Will come back to this again when we study Bayesian!)

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- ▶ But for non-linear case we have a big problem (bivariate dependent variable panel data)
- ▶ Assume a logit model with two independent time periods, fixed effects and one explanatory variable x_{it} s.t. $\forall i, x_{i1} = 0$ and $x_{i2} = 1$

$$P(y_{it=1} | x, \alpha) = \frac{e^{\alpha_i + x_{it}\beta}}{1 + e^{\alpha_i + x_{it}\beta}}$$

if $y_{i1} = 0$ and $y_{i2} = 0$ then $\hat{\alpha}_i = -\infty$

if $y_{i1} = 1$ and $y_{i2} = 1$ then $\hat{\alpha}_i = \infty$

if $y_{i1} + y_{i2} = 1$ then $\hat{\alpha}_i = -\hat{\beta}/2$ and $\hat{\beta} \xrightarrow{P} 2\beta$

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$$f(y_{i1}, \dots, y_{iT} | X, \beta, \sigma_u^2) = \int \left[\prod_{t=1}^T f(y_{it} | X, u_i, \beta) \right] \frac{1}{\sigma_u} \phi\left(\frac{u}{\sigma_u}\right) du$$

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- ▶ Already implemented in R and Stata
- ▶ The independence assumption of u_i and x_i is very strong

Conditional logit: removing the fixed effects

- ▶ Example with $T = 2$:

$$\Lambda_i = \begin{cases} 1 & \text{if } y_{i1} = 1, y_{i2} = 0 \\ 0 & \text{if } y_{i1} = 0, y_{i2} = 1 \end{cases}$$

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- ▶ So we have $L = \prod_{i=1}^N \text{logit}^{-1}(\beta(x_{i1} - x_{i2}))^{\Lambda_i} [1 - \text{logit}^{-1}(\beta(x_{i1} - x_{i2}))]^{1-\Lambda_i}$, and u_i disappears from the estimation.

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$$\prod_{i=1}^N \frac{\exp(\beta \sum_{t=1}^T x_{it} y_{it})}{\sum_{d \in D_i} \exp(\beta \sum_{t=1}^T x_{it} d_t)}$$

where $D_i = \{d = (d_1, \dots, d_T) | d_t = 0 \text{ or } 1, \text{ and } \sum_{t=1}^T d_t = \sum_{t=1}^T y_{it}\}$

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- ▶ Equivalent to the partial likelihood function of the stratified Cox model in discrete time
 - ▶ single discrete time period
 - ▶ $y_{it} = 1$ observations are taken as failures at time 1
 - ▶ $y_{it} = 0$ observations are taken as alive/censored at time 1
 - ▶ units correspond to strata

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- ▶ Heavily relies on functional form (does not work for Probit)
- ▶ Although $\hat{\beta}$ is fine, predicted probabilities, odds ratio and other quantities of interest can not be obtained