



# Probability Distributions and Moment Matching

## Models for Socio-Environmental Data

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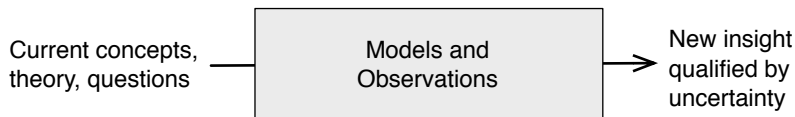
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# Roadmap

- ▶ The rules of probability
  - ▶ conditional probability
  - ▶ independence
  - ▶ the law of total probability
- ▶ Factoring joint probabilities
- ▶ Probability distributions for discrete and continuous random variables
- ▶ Marginal distributions
- ▶ Moment matching

# Motivation: A general approach to scientific research





# Motivation: Why do we need to know this stuff?

| Concept to be taught          | Why do you need to understand this concept?                                     |
|-------------------------------|---|
| Conditional probability       | It is the foundation for Bayes' Theorem and all inferences we will make.        |
| The law of total probability  | Basis for the denominator of Bayes' Theorem $[y]$                               |
| Factoring joint distributions | This is the procedure we will use to build models.                              |
| Independence                  | Allows us to simplify fully factored joint distributions.                       |
| Probability distributions     | Our toolbox for fitting models to data and representing uncertainty             |
| Moments                       | The way we summarize distributions.   |
| Marginal distributions        | Bayesian inference is based on marginal distributions of unobserved quantities. |
| Moment matching               | Allows us to embed the predictions of models into any statistical distribution. |

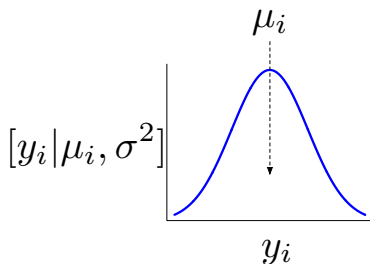


## Motivation: The essence of Bayes

Bayesian analysis is the *only* branch of statistics that treats all unobserved quantities as random variables. We seek to understand the characteristics of the probability distributions governing the behavior of these random variables.

## Motivation: models of data

$$\mu_i = g(\theta, x_i)$$



A model of the data describes our ideas about how the data arise.

## Motivation: flexibility in analysis

### Deterministic models

general linear  
nonlinear  
differential equations  
difference equations  
auto-regressive  
occupancy  
state-transition  
integral-projection

### Types of data

real numbers  
non-negative real numbers  
counts  
0 to 1  
0 or 1  
counts in categories  
proportions in categories

univariate and  
multivariate



## Motivation: flexibility in analysis

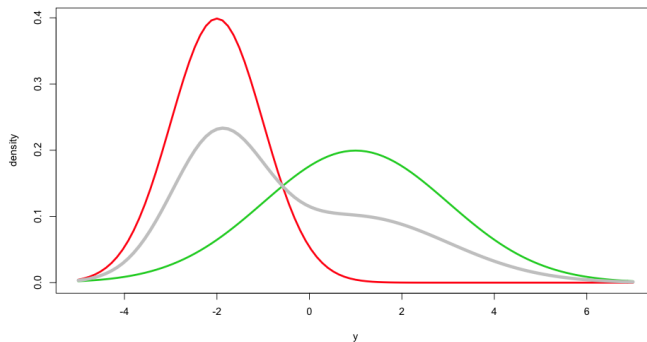
| Probability model | Support for random variable        |
|-------------------|------------------------------------|
| normal            | real numbers                       |
| lognormal         | non-negative real numbers          |
| gamma             | non-negative real numbers          |
| beta              | 0 to 1 real numbers                |
| Bernoulli         | 0 or 1                             |
| binomial          | counts in 2 categories             |
| Poisson           | counts                             |
| multinomial       | counts in $> 2$ categories         |
| negative binomial | counts                             |
| Dirichlet         | proportions in $\geq 2$ categories |
| Cauchy            | real numbers                       |



# Motivation: flexibility in analysis



$p = 0.5$



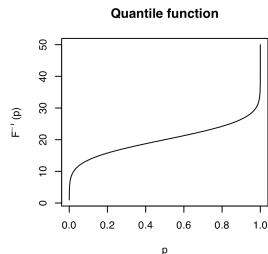
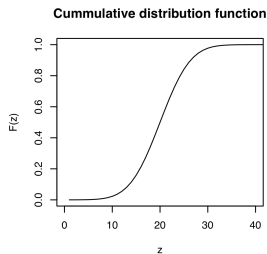
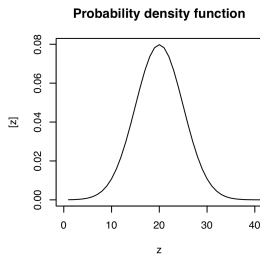


## Work flow: probability distributions

- ▶ General properties and definitions
  - ▶ discrete random variables
  - ▶ continuous random variables
- ▶ Specific distributions
- ▶ Marginal distributions
- ▶ Moment matching



# How will we use probability distributions?



Used to fit models to data, to represent uncertainty in processes and parameters, and to portray prior information

Used to make inferences about models.



## A bit about notation

| Ours                                | Others                                   | Meaning  |
|-------------------------------------|--|--|
| $[z]$                               | $f(Z = z)$                               | The probability or probability density of $z$ .  |
| $[z \alpha, \beta]$                 | $p(z \alpha, \beta), P(z \alpha, \beta)$ | The probability or probability density of $z$ conditional on $\alpha$ and $\beta$ .                      |
| $[z]$                               | $p(z), P(z)$                             | The probability or probability density of $z$ where its parameters are <i>numeric</i> . Used for priors. |
| $z \sim \text{Poisson}(\lambda)$    | $z \sim \text{Poisson}(\lambda)$         | $z$ is distributed Poisson with mean $\lambda$   |
| $z \sim \text{beta}(\alpha, \beta)$ | $z \sim \text{beta}(\alpha, \beta)$      | $z$ is distributed beta with parameters $\alpha$ and $\beta$ .   |



# Board work on probability distributions for discrete random variables

- ▶ Probability mass function,  $z$ , PMF (also called probability function, discrete destiny function)
  - ▶ notation  $[z], f(z)$
  - ▶  $[z]$  is a function that returns the probability of a specific value of the random variable  $= z$
  - ▶ Support of random variable  $z$  is defined as all values of  $z$  for which  $[z] > 0$  and defined.
  - ▶ requirements to be a PMF
    - ▶  $[z] \geq 0$
    - ▶  $\sum_{z \in s} z = 1$ , where  $s$  is the support of the random variable
  - ▶ moments of PMF
    - ▶ first moment, the expected value (or mean)  $= E(z) = \mu = \sum_{z \in s} z[z]$ , approximated from many ( $n$ ) random draws from  $[z]$  using  $E(z) \simeq \frac{1}{n} \sum_{i=1}^n z_i$
    - ▶ second central moment, the variance  $= E((z - \mu)^2) = \sigma^2 = \sum_{z \in s} (z - \mu)^2 [z]$ , approximated from many ( $n$ ) random draws from  $[z]$  using  $E((z - \mu)^2) \simeq \frac{1}{n} \sum_{i=1}^n (z_i - \mu)^2$
- ▶ cumulative distribution function for  $z$
- ▶ quantile function for  $z$



# Board work on probability distributions for continuous random variables

- ▶ Probability density function, PDF,  $[z]$ 
  - ▶ notation  $[z], f(z), z \sim \text{normal}()$
  - ▶  $[z]$  gives the *probability density* of a specific value of the random variable  $= z$ .
  - ▶ Support of random variable  $z$  is defined as all values of  $z$  for which  $[z] > 0$  and defined.
  - ▶ requirements
    - ▶  $[z] \geq 0$
    - ▶  $\int_{-\infty}^{\infty} [z] dz = 1$
    - ▶  $\Pr(a < z < b) = \int_a^b [z] dz$
  - ▶ What is probability density?
  - ▶ moments
    - ▶ first moment, the expected value (or mean)  $= E(z) = \mu = \int_{-\infty}^{\infty} z [z] dz$ , approximated from many ( $n$ ) random draws from  $[z]$  using  $E(z) \simeq \frac{1}{n} \sum_{i=1}^n z_i$
    - ▶ second central moment, the variance  $= E((z - \mu)^2) = \sigma^2 = \int_{-\infty}^{\infty} (z - \mu)^2 [z] dz$ , approximated from many ( $n$ ) random draws from  $[z]$  using  $E((z - \mu)^2) \simeq \frac{1}{n} \sum_{i=1}^n (z_i - \mu)^2$
- ▶ cumulative distribution function, CDF
- ▶ quantile function



# Problems

1. Introduce cheat sheet
2. Do Probability distributions problems in lab (section VI)



# Work flow: probability distributions

- ▶ General properties and definitions
  - ▶ discrete random variables
  - ▶ continuous random variables
- ▶ Specific distributions
- ▶ Marginal distributions
- ▶ Moment matching





# Marginal distributions of discrete random variables

|                      | $a_1$          | $a_2$          | $a_3$          | $a_4$           | $\Pr(B) \downarrow$ |
|----------------------|----------------|----------------|----------------|-----------------|---------------------|
| $b_1$                | $\frac{2}{20}$ | 0              | $\frac{1}{20}$ | $\frac{3}{20}$  | $\frac{6}{20}$      |
| $b_2$                | 0              | $\frac{4}{20}$ | 0              | $\frac{6}{20}$  | $\frac{10}{20}$     |
| $b_3$                | $\frac{1}{20}$ | $\frac{1}{20}$ | $\frac{1}{20}$ | 0               | $\frac{3}{20}$      |
| $b_4$                | 0              | 0              | 0              | $\frac{1}{20}$  | $\frac{1}{20}$      |
| $\Pr(A) \rightarrow$ | $\frac{3}{20}$ | $\frac{5}{20}$ | $\frac{2}{20}$ | $\frac{10}{20}$ | $\frac{20}{20}$     |



## Marginal distributions of discrete random variables

If we have a function  $[A, B]$  specifying the joint probability of the discrete random variables A and B, then

$\sum_A [A, B]$  is the marginal probability of B  
and

$\sum_B [A, B]$  is the marginal probability of A.

This same idea applies to any number of jointly distributed random variables. We simply sum over all but one.



# Marginal distributions of continuous random variables

Exercise: If  $A$  and  $B$  are continuous random variables and we have a function  $[A,B]$  that gives their joint probability density, what is the marginal distribution of  $A$ ? Of  $B$ ?



## Marginal distributions of continuous random variables

If we have a function  $[A, B]$  specifying the joint probability of the discrete random variables A and B, then

$\int_A [A, B] dA$  is the marginal probability of B

and

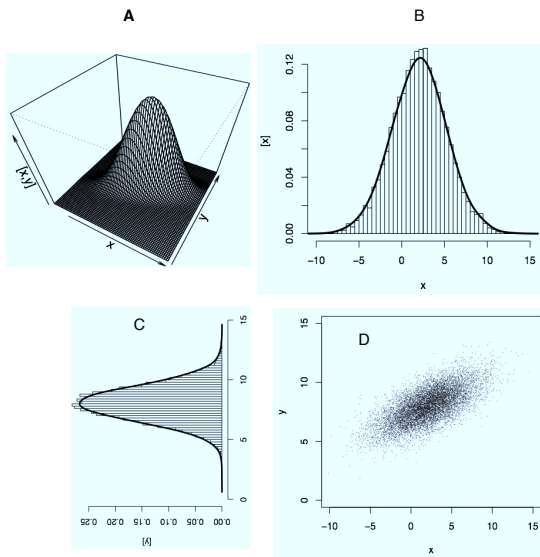
$\int_B [A, B] dB$  is the marginal probability of A.

This same idea applies to any number of jointly distributed random variables. We simply integrate over all but one.

Integrating over all but one random variable is often referred to as “integrating out.”



# Marginal distributions of continuous random variables





Do marginal distribution problems

## Motivation: flexibility in analysis

### Deterministic models

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### Types of data

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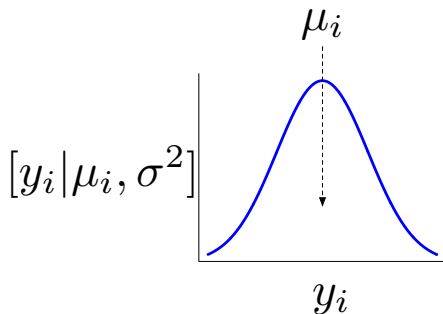
## Motivation: flexibility in analysis

| Probability model | Support for random variable        |
|-------------------|------------------------------------|
| normal            | all real numbers                   |
| lognormal         | non-negative real numbers          |
| gamma             | non-negative real numbers          |
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| binomial          | counts in 2 categories             |
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## Motivation: linking models to data

$$\mu_i = g(\boldsymbol{\theta}, x_i)$$





## A familiar approach

$$\begin{aligned}y_i &= \beta_0 + \beta_1 x_i + \varepsilon_i \\ \varepsilon_i &\sim \text{normal}(0, \sigma^2)\end{aligned}$$

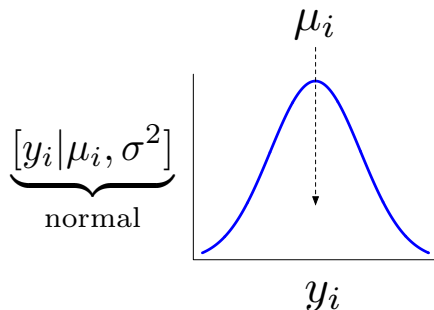
which is identical to

$$\begin{aligned}\mu_i &= \beta_0 + \beta_1 x_i \\ y_i &\sim \text{normal}(\mu_i, \sigma^2)\end{aligned}$$

## A familiar approach

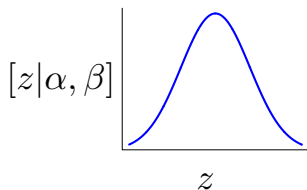
$$\boldsymbol{\theta} = (\beta_0, \beta_1)'$$

$$\mu_i = g(\boldsymbol{\theta}, x_i) = \beta_0 + \beta_1 x_i$$



# The problem

All distributions have parameters:



$\alpha$  and  $\beta$  are parameters of the distribution of the random variable  $z$ .

## Types of parameters

| Parameter name                  | Function                     |
|---------------------------------|------------------------------|
| intensity, centrality, location | sets position on x axis      |
| shape                           | controls dispersion and skew |
| scale, dispersion parameter     | shrinks or expands width     |
| rate                            | scale <sup>-1</sup>          |



## The problem

The normal and the Poisson are the only distributions for which the parameters of the distribution are the *same* as the moments. For all other distributions, the parameters are *functions* of the moments.

$$\alpha = m_1(\mu, \sigma^2)$$

$$\beta = m_2(\mu, \sigma^2)$$

We can use these functions to “match” the moments to the parameters.



# Moment matching

$$\begin{aligned}\mu_i &= g(\theta, x_i) \\ \alpha &= m_1(\mu_i, \sigma^2) \\ \beta &= m_2(\mu_i, \sigma^2) \\ &\quad [y_i | \alpha, \beta]\end{aligned}$$

## Moment matching the gamma distribution

The gamma distribution:  $[z|\alpha, \beta] = \frac{\beta^\alpha z^{\alpha-1} e^{-\beta z}}{\Gamma(\alpha)}$

The mean of the gamma distribution is

$$\mu = \frac{\alpha}{\beta}$$

and the variance is

$$\sigma^2 = \frac{\alpha}{\beta^2}.$$

Discover functions for  $\alpha$  and  $\beta$  in terms of  $\mu$  and  $\sigma^2$ .

Note:  $\Gamma(\alpha) = \int_0^\infty t^{\alpha-1} e^{-t} \frac{dt}{t}$





# Answer

$$1) \mu = \frac{\alpha}{\beta}$$

$$2) \sigma^2 = \frac{\alpha}{\beta^2}$$

Solve 1 for  $\beta$ , substitute for  $\beta$  in 2), solve for  $\alpha$  :

$$3) \alpha = \frac{\mu^2}{\sigma^2}$$

Substitute rhs 3) for  $\alpha$  in 2), solve for  $\beta$  :

$$4) \beta = \frac{\mu}{\sigma^2}$$



## Moment matching the beta distribution

The beta distribution gives the probability density of random variables with support on  $0, \dots, 1$ .

$$[z|\alpha, \beta] = \frac{z^{\alpha-1}(1-z)^{\beta-1}}{B(\alpha, \beta)}$$

$$B = \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)}$$

$$\mu = \frac{\alpha}{\alpha + \beta}$$

$$\sigma^2 = \frac{\alpha \beta}{(\alpha + \beta)^2 (\alpha + \beta + 1)}$$

$$\alpha = \frac{\mu^2 - \mu^3 - \mu \sigma^2}{\sigma^2}$$

$$\beta = \frac{\mu - 2\mu^2 + \mu^3 - \sigma^2 + \mu \sigma^2}{\sigma^2}$$

oooooo  
oooooo

## You need some functions...

```
#BetaMomentMatch.R
# Function for parameters from moments
shape_from_stats <- function(mu, sigma){
  a <- (mu^2-mu^3-mu*sigma^2)/sigma^2
  b <- (mu-2*mu^2+mu^3-sigma^2+mu*sigma^2)/sigma^2
  shape_ps <- c(a,b)
  return(shape_ps)
}
# Functions for moments from parameters
beta.mean=function(a,b)a/(a+b)
beta.var = function(a,b)a*b/((a+b)^2*(a+b+1))
```

## Moment matching for a single parameter

We can solve for  $\alpha$  in terms of  $\mu$  and  $\beta$ ,

$$\mu = \frac{\alpha}{\alpha + \beta} \quad (1)$$

$$\alpha = \frac{\mu\beta}{1 - \mu}, \quad (2)$$

which allows us to use

$$\mu_i = g(\theta, x_i) \quad (3)$$

$$y_i \sim \text{beta}\left(\frac{\mu_i\beta}{1 - \mu_i}, \beta\right) \quad (4)$$

to moment match the mean alone.



## Moment matching for a single parameter

The first parameter of the lognormal =  $\alpha$ , the mean of the random variable on the log scale. The second parameter =  $\sigma_{\log}^2$ , the variance of the random variable on the log scale

We often moment match the median the lognormal distribution:

$$\text{median} = \mu_i = g(\theta, x_i) \quad (5)$$

$$\mu_i = e^{\alpha} \quad (6)$$

$$\alpha = \log(\mu_i) \quad (7)$$

$$y_i \sim \text{lognormal}(\log(\mu_i), \sigma_{\log}^2) \quad (8)$$

In this case,  $\sigma^2$  remains on log scale.

## Problems continued

Do section on Moment Matching