Rules of Probability

Bayesian Modeling for Socio-Environmental Data

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Road map

- Rules of probability
 - Conditional probability
 - ► Chain rule
 - Independence
 - The law of total probability
- Factoring joint probabilities

Why do we need to know this stuff?

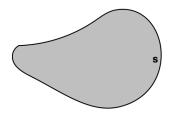
- Conditional probability foundational for all the inferences that we make.
- **② The law of total probability** is the denominator of Bayes' Theorem.
- Factoring joint distributions is how we deal with complexity, reducing high dimensional problems (the chain rule allows us to do this).
- **Independence** allows us to simplify fully factored joint distributions.

Random variables

- are quantities governed by chance.
- have a specific value called an events or outcomes.
- are summarized by probability distributions.
- Bayesians treat every unobserved quantity as a random variable.

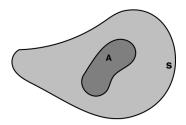
S=Sample Space

- The set of all possible events or outcomes of an experiment or survey.
- The sample space, S has a specific area.

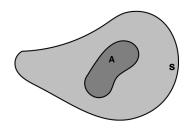


Events in S

- Can define and event, A.
- The area of event A is less than S.



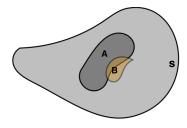
What is the probability of event A?



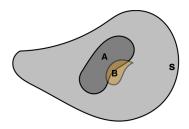
$$\Pr(A) = \frac{\text{Area of } A}{\text{Area of } S}$$

Conditional Probability

Conditional probability: the probability of an event given that we know another event has occurred.

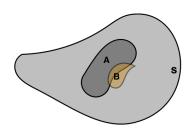


What is the probability of event B, given that event A has occurred?



Pr(B|A) = probability of B conditional on knowing A has occurred

What is the probability of event B, given that event A has occurred?



$$Pr(B|A) = \frac{\text{Joint Probability}}{\text{Probability of A}} = \frac{Pr(A,B)}{Pr(A)}$$

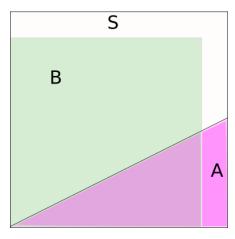


In this case, events A and B are said to be **independent**

Events are independent if and only if...

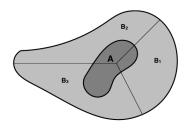
$$Pr(A|B) = Pr(A)$$

Assuming independence, the joint probability of event A and event B



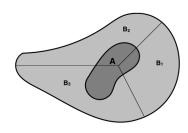
Pr(A, B) = Pr(A)Pr(B)

The Law of Total Probability



We can define a set of events $\{B_n : n = 1, 2, 3, ...\}$, which taken together define the entire sample space, $\sum_n B_n = S$.

What is the probability of event A?



$$Pr(A) = \sum_{n} Pr(A|B_n) Pr(B_n)$$
 (discrete case)

$$Pr(A) = \int Pr(A|B) Pr(B) dB$$
 (continuous case)

The Chain Rule of Probability

The chain rule of probability allows us to calculate any number of joint distributions using only conditional probabilities.

$$Pr(z_1, z_2, ..., z_n) = Pr(z_n|z_{n-1}, ..., z_1)...Pr(z_3|z_2, z_1)Pr(z_2|z_1)Pr(z_1)$$

Notice the pattern here.

- z's can be scalars or vectors.
- Sequence of conditioning doesn't matter.
- When we build models, we choose a sequence that makes sense.

Chain rule of probability board work and independence	

Factoring joint probabilities

Why is factoring useful?

- The rules of probability allow us to simplify complicated joint distributions, breaking them down into chunks.
- Chunks can be analyzed one at a time.
- Provide a usable graphical and mathematical foundation, *critical* for the model specification step.

Consider a Bayesian Network (represented by a directed acyclic graph or DAG)



- Bayesian networks specify how joint distributions are factored into conditional distributions using nodes to represent RV's and arrows to represent dependencies.
- Nodes at the heads of arrows must be on the left hand side of the conditioning symbols;
- Nodes at the tails of arrows are on the right hand side of the conditioning symbols.
- Any node at the tail of an arrow without and arrow leading into it must be expressed unconditionally.

Factoring with DAGs at the board



$$Pr(A, B) =$$



$$Pr(A,B) = Pr(A|B)Pr(B)$$



$$Pr(A, B, C) =$$



$$Pr(A,B,C) = Pr(A|B,C) Pr(B|C) Pr(C)$$

Work on lab

Complete parts I-VI