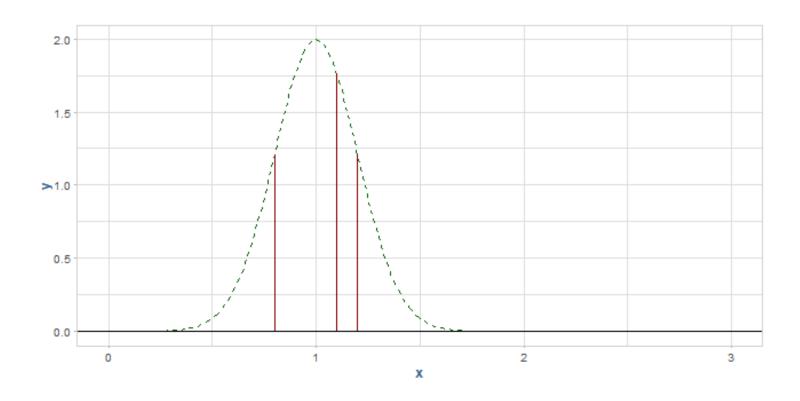
Likelihood

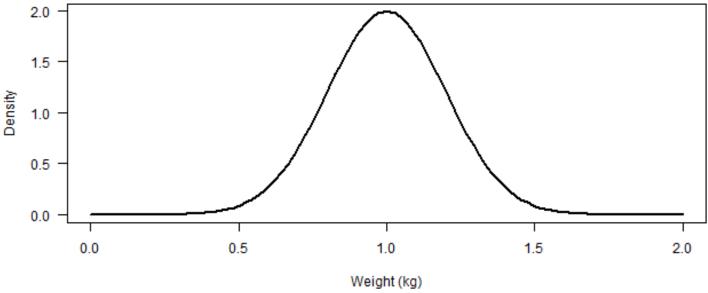
Theory

```
Given 3 observations .8, 1.2, 1.1 and a model y_i \sim Norm(1,.2)
obs <- c(0.8, 1.2, 1.1) # observations
# probability of seeing these in n(1, .2)
p1 \leftarrow prod(dnorm(obs, mean = 1, sd = 0.2))
р1
[1] 2.576671
# probability of seeing these in n(1.2, .4)
p2 \leftarrow prod(dnorm(obs, mean = 1.2, sd = 0.4))
p2
[1] 0.5832185
p1/p2 # 4x liklier to see under model 1 than model 2
[1] 4.41802
# graphically
xs \leftarrow seq(from=0, to=3, by = .01)
ys \leftarrow dnorm(xs, mean = 1, sd = .2)
dat <- data.table(x = xs, y = ys)</pre>
obs marks \leftarrow data.table(x = obs, y = dnorm(obs, mean = 1, sd = .2))
ggplot(dat) +
   geom_line(aes(x,y), col = "darkgreen", lty=2) +
   geom_hline(yintercept = 0) +
   geom_segment(data = obs_marks, aes(x, y, xend=x, yend=0), col="darkred")
```



Quick Look at the Normal Distribution

```
x <- seq(0, 2, length = 100)
dx <- dnorm(x, mean = 1, sd = 0.2)
plot(x, dx, type = "l", xlab = "Weight (kg)", ylab = "Density", lwd = 2, las = 1)</pre>
```



```
rnorm(5, 1, 0.2) # draws 5 random numbers from Norm(1, 0.2)  
[1] 1.1477332 1.0755553 0.8027062 1.3199443 0.9106785  
pnorm(q = .8, 1, 0.2)  
[1] 0.1586553  
L(\mu, \sigma | y) = \prod_{i=1}^{n} p(y_i, | \mu, \sigma) 
y <- c(0.8, 1.2, 1.1)  
1f <- function(mu, sigma) prod(dnorm(y, mu, sigma))  
1f(1, .2)  
[1] 2.576671
```

The Maximum Likelihood Method

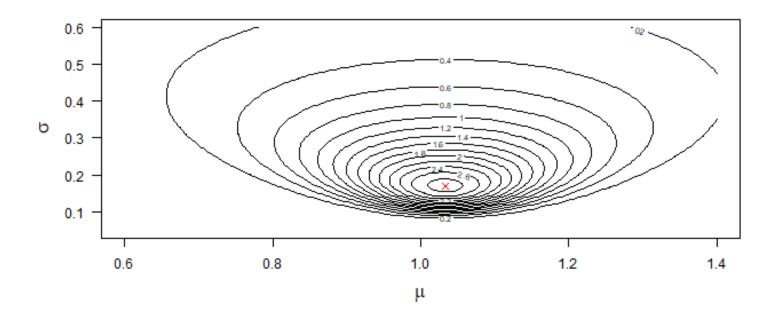
```
mu <- seq(0.6, 1.4, length=100)
sigma <- seq(0.05, 0.6, length=100)

lik <- matrix(nrow=length(mu), ncol = length(sigma))

for(i in 1:length(mu)) {
   for(j in 1:length(sigma)) {</pre>
```

[1] 1.0333272 0.1699747

```
# optimal values
points(MLest$par[1], MLest$par[2], col="red", pch=4)
```



Likelihood ratio = p1/p2

The Log Pointwise Predictive Density

```
llpd = \sum_{i=1}^n log \int p(y_i|\theta) p(\theta|y) d\theta \mod <- \ln(y-1) \text{ \# fit model by LS method} nsim <- 2000 bsim <- \sin(\bmod, n.sim=nsim) \text{ \# simulate from posterior dist. of parameters}
```

[1] 0.1595696

The log posterior density can be used as a measure of model fit.