Consider the panel LRM

$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + \iota \alpha_i + \varepsilon_{it}.$$

 $y_{it}$ : an observation for individual i at time t.

 $\mathbf{x}'_{it}$ : K observations for K regressors for individual i at time t.  $1 \times K$ .

 $\beta$ : vector of true coefficients.  $K \times 1$ .

 $\iota$ : scalar with a value of 1. Greek letter 'iota'.

 $\alpha_i$ : time invariant constant term specific to individual i in the panel. Potentially correlated with  $\mathbf{x}'_{it}$ . It captures individual heterogeneity.

 $\varepsilon_{it}$ : error term. It meets the OLS assumptions.

There are T observations available for each i. If we stack the T observations, we obtain

$$\mathbf{y}_i = \mathbf{X}_i' \boldsymbol{\beta} + \iota \alpha_i + \boldsymbol{\varepsilon}_i.$$

 $\mathbf{y}_i$ :  $T \times 1$ .

 $\mathbf{X}_{i}^{\prime}$ : T observations for i for K independent variables.  $T \times K$ .

 $\mathbf{x}'_{it}$ : row vector in row t of  $\mathbf{X}'_i$ .  $1 \times K$ . It contains k observations for k regressors for individual i at time t.

 $\iota$ : column vector containing 1 in every row.  $T \times 1$ .

$$\varepsilon_i$$
:  $T \times 1$ .

There are N individuals. If we stack the N individuals, we obtain

$$y = X\beta + D\alpha + \varepsilon.$$

y:  $NT \times 1$ .

 $X: NT \times K.$ 

**D**: has N diagonal elements. Each element of the diagonal is a vector, is the same, and is given by the column vector  $\iota$ . All of the off-diagonal elements are  $\mathbf{0}$  column vectors of size  $T \times 1$ . Hence,  $\mathbf{D}$  is  $NT \times N$ .

 $\alpha$ :  $N \times 1$  since there are N different  $\alpha_i$ s.

This is the Least Squares Dummy Variable (LSDV) model.

For individual i, T = 3, and K = 3,

$$\begin{bmatrix} y_{i1} \\ y_{i2} \\ y_{i3} \end{bmatrix} = \begin{bmatrix} k_{i1} & l_{i1} & m_{i1} \\ k_{i2} & l_{i2} & m_{i2} \\ k_{i3} & l_{i3} & m_{i3} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \alpha_i + \begin{bmatrix} \varepsilon_i \\ \varepsilon_i \\ \varepsilon_i \end{bmatrix}$$

where k, l, m represent three different regressors. Putting them into row vector  $\mathbf{x}'_{it}$ ,

$$\begin{bmatrix} y_{i1} \\ y_{i2} \\ y_{i3} \end{bmatrix} = \begin{bmatrix} \mathbf{x}'_{i1} \\ \mathbf{x}'_{i2} \\ \mathbf{x}'_{i3} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \alpha_i + \begin{bmatrix} \varepsilon_i \\ \varepsilon_i \\ \varepsilon_i \end{bmatrix} \\ \mathbf{x}'_i \\ \beta_i \end{bmatrix}$$

Assume N = 3. Stack N individuals to obtain

$$\begin{bmatrix} \mathbf{y}_1 \\ \mathbf{y}_2 \\ \mathbf{y}_3 \end{bmatrix} = \begin{bmatrix} \mathbf{X}_1' \\ \mathbf{X}_2' \\ \mathbf{X}_3' \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{bmatrix} + \begin{bmatrix} \iota & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \iota & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \iota \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix}$$

$$\mathbf{y}_{NT \times 1} \quad \mathbf{x}_{NT \times K} \quad \mathbf{x}_{N \times 1} \quad \mathbf{x}_{N \times 1} \quad \mathbf{x}_{N \times 1}$$

where

$$m{D} = egin{bmatrix} 1 & 0 & 0 \ 1 & 0 & 0 \ 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \ 0 & 0 & 1 \ 0 & 0 & 1 \ \end{bmatrix}$$

The LSDV model has two problems. First, it requires the inversion of a very large matrix due to D. Second, it requires estimation of the large number of intercept terms contained in  $\alpha$ . Could we avoid these problems?

Consider again the panel model for individual i at time t

$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + \iota \alpha_i + \varepsilon_{it}.$$

Take the average over all t for individual i to obtain

$$\bar{\mathbf{y}}_i = \bar{\mathbf{x}}_i' \boldsymbol{\beta} + \iota \alpha_i + \bar{\varepsilon}_i,$$

where

$$\bar{y}_i = \frac{1}{T} \sum_{t=1}^I y_{it}.$$

Subtract the second equation from the first to obtain

$$y_{it} - \bar{y}_i = (\mathbf{x}'_{it} - \bar{\mathbf{x}}'_i)\boldsymbol{\beta} + \varepsilon_{it} - \bar{\varepsilon}_i.$$

The is the fixed effects transformation. The time invariant individual specific constant term  $\alpha_i$  disappeared!

We have carried out the fixed effects transformation for individual i using his T observations. We need to take account of the fact that we have n individuals in the panel data.

The panel model for N individuals described above is

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{D}\boldsymbol{\alpha} + \boldsymbol{\varepsilon}.$$

Consider the model

$$\mathbf{y} = \mathbf{M}_D \mathbf{X} \boldsymbol{\beta} + \boldsymbol{v}.$$

where

$$\mathbf{M}_D = \mathbf{I} - \mathbf{P}_D$$
.

and

$$\mathbf{P}_D = \mathbf{D}(\mathbf{D}'\mathbf{D})^{-1}\mathbf{D}'.$$

FWL theorem: OLS estimator of  $oldsymbol{eta}$  in the stated two models is the same and given by

$$\begin{aligned} \mathbf{b}_{OLS} &= ((\mathbf{M}_D \mathbf{X})'(\mathbf{M}_D \mathbf{X}))^{-1} (\mathbf{M}_D \mathbf{X})' \mathbf{y} = (\mathbf{X}' \mathbf{M}_D \mathbf{X})^{-1} \mathbf{X}' \mathbf{M}_D \mathbf{y} \\ &= \mathbf{b}_{FE}. \end{aligned}$$

This is the fixed effects estimator.

Why does  $M_D$  demeans the data? Take a closer look at

$$\mathbf{M}_D = \mathbf{I} - \mathbf{D}(\mathbf{D}'\mathbf{D})^{-1}\mathbf{D}'.$$

Realise that

$$D'D = T$$
.

and hence

$$\mathbf{M}_D = \mathbf{I} - \frac{1}{\tau} \mathbf{D} \mathbf{D}'$$

which is called the centering matrix.

If 
$$T=3$$
 and  $N=2$ .

$$\mathbf{M}_D = \begin{bmatrix} 1 - \frac{1}{T} & -\frac{1}{T} & -\frac{1}{T} & 0 & 0 & 0 \\ -\frac{1}{T} & 1 - \frac{1}{T} & -\frac{1}{T} & 0 & 0 & 0 \\ -\frac{1}{T} & -\frac{1}{T} & 1 - \frac{1}{T} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 - \frac{1}{T} & -\frac{1}{T} & -\frac{1}{T} \\ 0 & 0 & 0 & -\frac{1}{T} & 1 - \frac{1}{T} & -\frac{1}{T} \\ 0 & 0 & 0 & -\frac{1}{T} & 1 - \frac{1}{T} & 1 - \frac{1}{T} \end{bmatrix}$$

Then, assuming values for X, X in deviation form is

$$\begin{aligned} \boldsymbol{M}_{D}\boldsymbol{X} &= \begin{bmatrix} 1 - \frac{1}{T} & -\frac{1}{T} & -\frac{1}{T} & 0 & 0 & 0 \\ -\frac{1}{T} & 1 - \frac{1}{T} & -\frac{1}{T} & 0 & 0 & 0 \\ -\frac{1}{T} & -\frac{1}{T} & 1 - \frac{1}{T} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 - \frac{1}{T} & -\frac{1}{T} & -\frac{1}{T} \\ 0 & 0 & 0 & -\frac{1}{T} & 1 - \frac{1}{T} & -\frac{1}{T} \\ 0 & 0 & 0 & -\frac{1}{T} & 1 - \frac{1}{T} & 1 - \frac{1}{T} \end{bmatrix} \begin{bmatrix} 1 & 12 \\ 1 & 13 \\ 1 & 11 \\ 3 & 43 \\ 4 & 46 \\ 4 & 41 \end{bmatrix} \\ &= \begin{bmatrix} 1 - \frac{1+1+1}{3} & 12 - \frac{12+13+11}{3} \\ 1 - \frac{1+1+1}{3} & 13 - \frac{12+13+11}{3} \\ 1 - \frac{1+1+1}{3} & 11 - \frac{12+13+11}{3} \\ 3 - \frac{3+4+4}{3} & 43 - \frac{43+46+41}{3} \\ 4 - \frac{3+4+4}{3} & 46 - \frac{43+46+41}{3} \\ 4 - \frac{3+4+4}{3} & 41 - \frac{43+46+41}{3} \end{bmatrix} \end{aligned}$$