Multiple Linear Regression: Model Checking and Diagnostics

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Today's Lecture

- Model checking and diagnostics
- Variable transformations

Model selection vs. model checking

Assume
$$y|\mathbf{x} = f(\mathbf{x}) + \epsilon$$

- model selection focuses on how you construct $f(\cdot)$;
- lacktriangleright model checking asks whether the ϵ match the assumed form.

Model checking: possible challenges

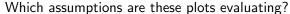
Two major areas of concern

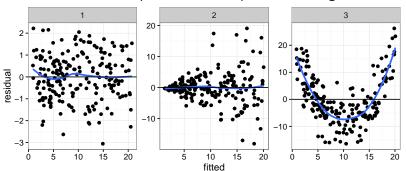
- Global lack of fit, or general breakdown of model assumptions
 - Linearity
 - ▶ Unbiased, uncorrelated errors $E(\epsilon|x) = E(\epsilon) = 0$
 - Constant variance $Var(y|x) = Var(\epsilon|x) = \sigma^2$
 - ► Independent errors
 - Normality of errors
- Effect of influential points and outliers

Model checking: possible solutions and strategies

- Global lack of fit, or general breakdown of model assumptions
 - Residual analysis QQ plots, residual plots against fitted values and predictors
 - Adjusted variable plots
- Effect of influential points and outliers
 - ► Measure of leverage, influence, outlying-ness

Residual plots: verifying assumptions





Assumption violations are not often this obvious (but sometimes they are!).

QQ-plots for checking Normality of residuals

QQ plot defined

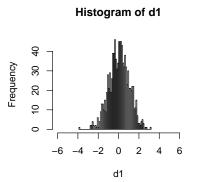
QQ-plot stands for quantile-quantile plot, and is used to compare two distributions. If the two distributions are the same, then each point (which represents a quantile from each distribution) should lie along a line.

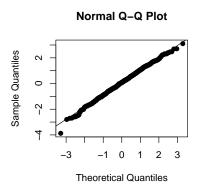
For a single (x, y) point

- x = a specific quantile for the N(0,1) distribution
- y = the same quantile from the sample of data

example: Gaussian or Normal(0,1) distribution

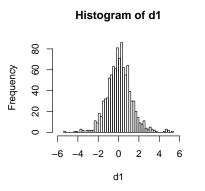
```
d1 <- rnorm(1000)
layout(matrix(1:2, nrow=1))
hist(d1, breaks=50, xlim=c(-6, 6))
qqnorm(d1, pch = 19)
qqline(d1)</pre>
```

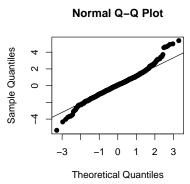




example: Student's T-distribution with 6 d.f.

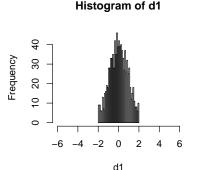
```
d1 <- rt(1000, df=5)
layout(matrix(1:2, nrow=1))
hist(d1, breaks=50, xlim=c(-6, 6))
qqnorm(d1, pch = 19)
qqline(d1)</pre>
```

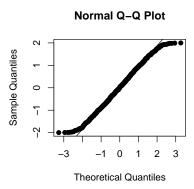




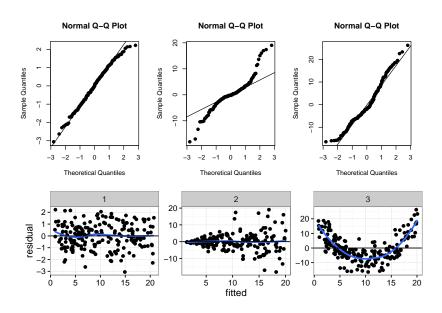
example: Truncated Gaussian

```
d1 <- rnorm(1000)
d1 <- subset(d1, abs(d1)<2)
layout(matrix(1:2, nrow=1))
hist(d1, breaks=50, xlim=c(-6, 6))
qqnorm(d1, pch = 19)
qqline(d1)</pre>
```



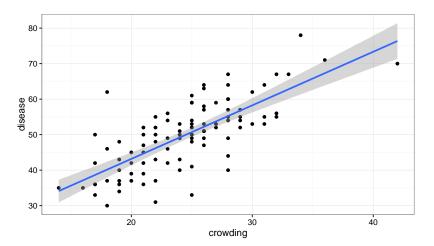


QQ-plots for our three fits from earlier



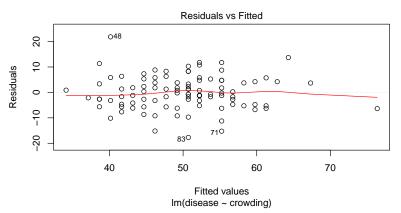
Typical regression plot: fitted line

```
ggplot(data, aes(crowding, disease)) +
   geom_point() + geom_smooth(method="lm")
```



Typical residual plot: fitted vs. residuals

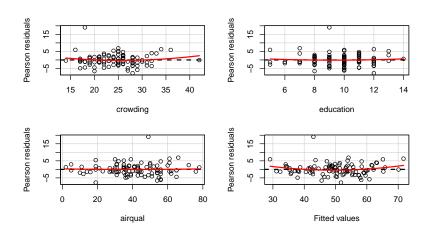
```
slr1 <- lm(disease ~ crowding, data=data)
plot(slr1, which=1)</pre>
```



But this is more complicated with MLR: how do we visualize adjusted multivariable relationships?

Predictor vs. residual plots

```
library(car)
mlr1 <- lm(disease ~ crowding + education + airqual, data=data)
residualPlots(mlr1, tests=FALSE)</pre>
```



Checking model structure: adjusted variable plots!

- You can plot residuals against each of the predictors, or plot outcomes against predictors, BUT...
- Keep in mind the MLR uses adjusted relationships; scatterplots don't show that adjustment!

Adjusted variable plots (partial regression plots, added variable plots) can be useful.

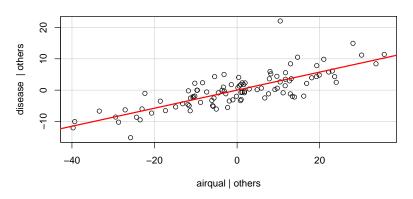
Adjusted (or added) variable plots

- Regress y on everything but x_j ; take residuals $r_{y|-x_j}$
- Regress x_j on everything but x_j ; take residuals $r_{x_j|-x_j}$
- Regress $r_{y|-x_j}$ on $r_{x_j|-x_j}$; slope of this line will match β_j in the full MLR
- Plot of $r_{y|-x_i}$ against $r_{x_i|-x_i}$ shows the "adjusted" relationship
- This figure can be used to diagnose violations of linearity in MLR models.

AV plots

avPlot(mlr1, variable="airqual")

Added-Variable Plot: airqual



Model checking: possible solutions

- Global lack of fit, or general breakdown of model assumptions
 - Residual analysis QQ plots, residual plots against fitted values and predictors
 - Adjusted variable plots
- Effect of influential points and outliers
 - Measure of leverage, influence, outlying-ness

Isolated points

Points can be isolated in three ways

- Leverage point outlier in x, measured by hat matrix
- Outlier outlier in y, measured by residual
- Influential point a point that largely affects β
 - ▶ Deletion influence; $|\hat{\beta} \hat{\beta}_{(-i)}|$
 - Basically, a high-leverage outlier

Quantifying leverage

We measure leverage (the "distance" of \mathbf{x}_i from the distribution of \mathbf{x}) using

$$h_{ii} = \mathbf{x}_i^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_i$$

where h_{ii} is the $(i,i)^{th}$ entry of the hat matrix. Where, recall

$$\mathbf{H} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T$$

Quantifying Leverage via the Hat Matrix

Note that

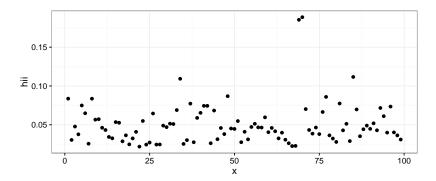
$$\sum_{i} h_{ii} \stackrel{def}{=} tr(\mathbf{H}) = p$$

where p is the total number of independent predictors (i.e. β s) in your model (including a β_0 if you have one).

What counts as "big" leverage?

- Average leverage is p/n
- Typical rules of thumb are 2p/n or 3p/n
- Leverage plots can be useful as well

Example Leverage plot with lung data



Outliers

- When we refer to "outliers" we typically mean "points that don't have the same mean structure as the rest of the data"
- Residuals give an idea of "outlying-ness", but we need to standardize somehow
- We can use the fact that $Var(\hat{\epsilon}_i) = \sigma^2(1 h_{ii})$...

Outliers

The standardized residual is given by

$$\hat{\epsilon}_i^* = rac{\hat{\epsilon}_i}{\sqrt{Var(\hat{\epsilon}_i)}} = rac{\hat{\epsilon}_i}{\hat{\sigma}\sqrt{(1-h_{ii})}}$$

The Studentized residual is given by

$$t_{i} = \frac{\hat{\epsilon}_{(-i)}}{\hat{\sigma}_{(-i)}\sqrt{(1-h_{ii})}} = \hat{\epsilon}_{i}^{*} \left(\frac{n-p}{n-p-\hat{\epsilon}_{i}^{*2}}\right)^{1/2}$$

Studentized residuals follow a t_{n-p-1} distribution.

Influence

Intuitively, "influence" is a combination of outlying-ness and leverage. More specifically, we can measure the "deletion influence" of each observation: quantify how much $\hat{\boldsymbol{\beta}}$ changes if an observation is left out.

- $|\hat{\boldsymbol{\beta}} \hat{\boldsymbol{\beta}}_{(-i)}|$
- Cook's distance is

$$D_{i} = \frac{(\hat{\boldsymbol{\beta}} - \hat{\boldsymbol{\beta}}_{(i)})^{T}(\mathbf{X}^{T}\mathbf{X})(\hat{\boldsymbol{\beta}} - \hat{\boldsymbol{\beta}}_{(i)})}{\rho\hat{\sigma}^{2}}$$

$$= \frac{(\hat{\mathbf{y}} - \hat{\mathbf{y}}_{(-i)})^{T}(\hat{\mathbf{y}} - \hat{\mathbf{y}}_{(-i)})}{\rho\hat{\sigma}^{2}}$$

$$= \frac{1}{\rho}\hat{\epsilon}_{i}^{2}\frac{h_{ii}}{1 - h_{ii}}$$

Handy R functions

Suppose you fit a linear model in R;

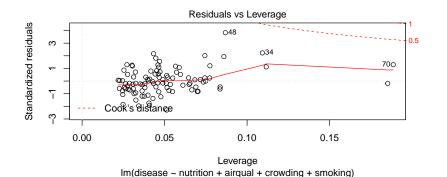
- hatvalues gives the diagonal elements of the hat matrix h_{ii} (leverages)
- rstandard gives the standardized residuals
- rstudent gives the studentized residuals
- cooks.distance gives the Cook's distances

Built-in R plots for 1m objects

You can also use the plot.lm() function to look at leverage, outlying-ness, and influence all together. Recall that

$$D_i = \frac{1}{p} \hat{\epsilon^*}_i^2 \frac{h_{ii}}{1 - h_{ii}}$$

plot(mlr, which=5)



Back to the outline

- Model checking and diagnostics
- Variable transformations

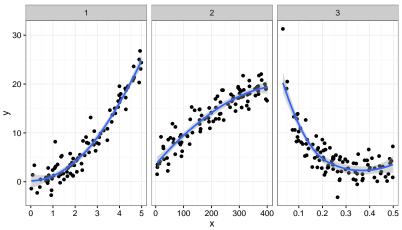
Overview of variable transformations

The problems

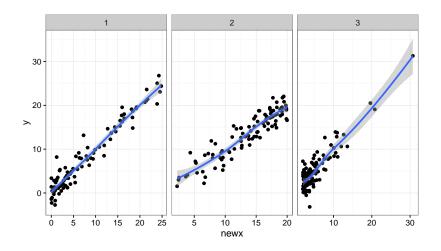
- Non-linearity between X and $Y \longrightarrow \text{transform } X$
- lacksquare Skewed distribution of Xs/points with high leverage \longrightarrow transform X
- Non-constant variance \longrightarrow transform Y

Transforming your *X* variables

Transforming predictor variables can help with constant-variance non-linear relationships.



Transforming your *X* variables



β interpretations with transformed Xs

Transforming predictor variables can help with non-linearities, but can make coefficient interpretations hard.

Possible solutions

- Interpret β s qualitatively across a region of interest: "We found strong evidence for an inverse association, where values of Y decreased inversely proportional to X across the observed range (a, b).
- Occasionally, a "one unit change in X" can be meaningful:
 e.g. log_a X. A one unit change in log_a X indicates a a-fold increase in X.

 β interpretations with transformed Xs

Transforming predictor variables can help with non-linearities, but can make coefficient interpretations hard.

Transforming Ys for non-constant variance

What to do ...

- Nothing; just use least squares and bootstrap
- Use weighted LS, GLS (Methods 3?)
- Use a variance stabilizing transformation
- Consider a generalized linear model (more soon)

Box-Cox Transformations

Outcome is raised to the λ power:

$$y_i^{\lambda} = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i$$

- **E**stimate λ , a new parameter, by maximum likelihood.
- Some well-known choices of λ : 2, -1, 1/2
- By definition, when $\lambda = 0$, we specify $y_i^{\lambda} = \log_e y_i$

Today's big ideas

- Model checking
- Variable transformations
- Next up: inference about MLR parameters