

# Lecture 2: Various Model Selection Criteria

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## 1 The Corrected AIC

To derive the TIC and AIC we used asymptotic theory to derive an analytical bias correction. These approximations tend to work well as long  $n$  is fairly large relative to  $p$  but when this is not the case, they can break down. We'll now consider an alternative that makes stronger assumptions and relies on *exact* small-sample theory rather than asymptotics: the “Corrected” AIC, or  $AIC_c$ , of Hurvich and Tsai (1989). Suppose that the true DGP is a linear regression model:

$$\mathbf{y} = X\beta_0 + \epsilon$$

where  $\epsilon \sim N(\mathbf{0}, \sigma_0^2 \mathbf{I}_T)$ . Then  $\mathbf{y}|X \sim N(X\beta_0, \sigma_0^2 \mathbf{I}_T)$  so the likelihood is

$$g(\mathbf{y}|X; \beta_0, \sigma_0^2) = (2\pi\sigma_0^2)^{-T/2} \exp \left\{ -\frac{1}{2\sigma_0^2} (\mathbf{y} - X\beta_0)' (\mathbf{y} - X\beta_0) \right\}$$

and the log-likelihood is

$$\log [g(\mathbf{y}|X; \beta_0, \sigma_0^2)] = -\frac{T}{2} \log(2\pi) - \frac{T}{2} \log(\sigma_0^2) - \frac{1}{2\sigma_0^2} (\mathbf{y} - X\beta_0)' (\mathbf{y} - X\beta_0)$$

Now suppose we evaluated the log-likelihood at some *other* parameter values  $\beta_1$  and  $\sigma_1^2$ . The vector  $\beta_1$  might, for example, correspond to dropping some regressors from the model by setting their coefficients to zero, or perhaps

adding in some additional regressors. We have

$$\log[f(\mathbf{y}|X; \beta_1, \sigma_1^2)] = -\frac{T}{2} \log(2\pi) - \frac{T}{2} \log(\sigma_1^2) - \frac{1}{2\sigma_1^2} (\mathbf{y} - X\beta_1)' (\mathbf{y} - X\beta_1)$$

Since we've specified the density from which the data were generated as well as the density of the approximating model, we can *directly calculate* the KL divergence rather than trying to find a reasonable large sample approximation. It turns out that for this example

$$KL(g; f) = \frac{T}{2} \left[ \frac{\sigma_0^2}{\sigma_1^2} - \log \left( \frac{\sigma_0^2}{\sigma_1^2} \right) - 1 \right] + \left( \frac{1}{2\sigma_1^2} \right) (\beta_0 - \beta_1)' X'X (\beta_0 - \beta_1)$$

as you will demonstrate on the problem set. We need to estimate this quantity for it to be of any use in model selection. If let  $\hat{\beta}$  and  $\hat{\sigma}^2$  be the maximum likelihood estimators of  $\beta_1$  and  $\sigma_1^2$  and substitute them into the expression for the KL divergence, we have

$$\widehat{KL}(g; f) = \frac{T}{2} \left[ \frac{\sigma_0^2}{\hat{\sigma}^2} - \log \left( \frac{\sigma_0^2}{\hat{\sigma}^2} \right) - 1 \right] + \left( \frac{1}{2\hat{\sigma}^2} \right) (\beta_0 - \hat{\beta})' X'X (\beta_0 - \hat{\beta})$$

We still have two problems. First, we haven't been entirely clear about what  $\beta_1$  and  $\sigma_1$  are. At the moment, they seem to be something like "pseudo-true" values. Second, and more importantly, we don't know  $\beta_0$  and  $\sigma_0^2$  so we can't use the preceding expression to compare models.

Hurvich and Tsai (1989) address both of these problems with the assumption that all models under consideration are *at least correctly specified*. That is, while they may include a regressor whose coefficient is in fact zero, they do not exclude any regressors with a non-zero coefficient. This is the same assumption that we used above to reduce TIC to AIC. Under this assumption,  $\beta_1$  and  $\sigma_1^2$  are *precisely the same* as  $\beta_0$  and  $\sigma_0^2$ . More importantly, we can use all of the standard results for the exact finite sample distribution of regression estimators to help us. The idea is to construct an *unbiased* estimator of the

KL divergence. Taking expectations and rearranging slightly, we have

$$\begin{aligned} E \left[ \widehat{KL}(g; f) \right] &= \frac{T}{2} \left\{ E \left[ \frac{\sigma_0^2}{\widehat{\sigma}^2} \right] - \log(\sigma_0^2) + E \left[ \log(\widehat{\sigma}^2) \right] - 1 \right\} \\ &\quad + \frac{1}{2} E \left[ \left( \frac{1}{\widehat{\sigma}^2} \right) (\widehat{\beta} - \beta_0) X' X (\widehat{\beta} - \beta_0) \right] \end{aligned}$$

Now, under our assumptions  $T\widehat{\sigma}^2/\sigma_0^2 \sim \chi_{T-k}^2$  where  $k$  is the number of estimated coefficients in  $\widehat{\beta}$ . Further, if  $Z \sim \chi_\nu^2$  then  $E[1/Z] = 1/(\nu - 2)$ . It follows that

$$E \left[ \frac{\sigma_0^2}{\widehat{\sigma}^2} \right] = E \left[ \frac{T}{T\widehat{\sigma}^2/\sigma_0^2} \right] = \frac{T}{T - k - 2}$$

We can rewrite the final term similarly:

$$E \left[ \left( \frac{1}{\widehat{\sigma}^2} \right) (\widehat{\beta} - \beta_0) X' X (\widehat{\beta} - \beta_0) \right] = E \left[ \left( \frac{T}{T\widehat{\sigma}^2/\sigma_0^2} \right) \frac{(\widehat{\beta} - \beta_0) X' X (\widehat{\beta} - \beta_0)}{\sigma_0^2} \right]$$

Under our assumptions the two terms in the product are independent, so we can break apart the expectation. First, we have

$$E \left[ \frac{T}{T\widehat{\sigma}^2/\sigma_0^2} \right] = \frac{T}{T - k - 2}$$

as above. For the second part,

$$\frac{(\widehat{\beta} - \beta_0) X' X (\widehat{\beta} - \beta_0)}{\sigma_0^2} \sim \chi_k^2$$

and hence

$$E \left[ \frac{(\widehat{\beta} - \beta_0) X' X (\widehat{\beta} - \beta_0)}{\sigma_0^2} \right] = k$$

Putting all the pieces together,

$$\begin{aligned}
E \left[ \widehat{KL}(g; f) \right] &= \frac{T}{2} \left\{ E \left[ \frac{\sigma_0^2}{\widehat{\sigma}^2} \right] + \log(\sigma_0^2) - E \left[ \log(\widehat{\sigma}^2) \right] - 1 \right\} \\
&\quad + \frac{1}{2} E \left[ \left( \frac{1}{\widehat{\sigma}^2} \right) (\widehat{\beta} - \beta_0)' X' X (\widehat{\beta} - \beta_0) \right] \\
&= \frac{T}{2} \left( \frac{T}{T-k-2} - \log(\sigma_0^2) + E \left[ \log(\widehat{\sigma}^2) \right] - 1 \right) + \frac{T}{2} \left( \frac{k}{T-k-2} \right) \\
&= \frac{T}{2} \left( \frac{T+k}{T-k-2} - \log(\sigma_0^2) + E \left[ \log(\widehat{\sigma}^2) \right] - 1 \right)
\end{aligned}$$

Since  $\log(\widehat{\sigma}^2)$  is an unbiased estimator of  $E[\log(\widehat{\sigma}^2)]$ , substituting this give us an unbiased estimator of  $E \left[ \widehat{KL}(g; f) \right]$  as desired. The only terms that vary across candidate models are the first and the third. Moreover, the multiplicative factor of  $T/2$  does not affect model selection. Hence, the criterion is

$$AIC_c = \log(\widehat{\sigma}^2) + \frac{T+k}{T-k-2}$$

Note that the way this expression is written, *smaller* values indicate a better model. So how does this compare to the plain-vanilla AIC for normal linear regression? The maximum likelihood estimators for this problem are

$$\begin{aligned}
\widehat{\beta} &= (X'X)^{-1} X' \mathbf{y} \\
\widehat{\sigma}^2 &= \frac{(\mathbf{y} - X\widehat{\beta})'(\mathbf{y} - X\widehat{\beta})}{T}
\end{aligned}$$

It follows that the maximized log-likelihood is

$$\begin{aligned}
\log \left[ f(\mathbf{y}|X; \widehat{\beta}) \right] &= -\frac{T}{2} \log(\widehat{\sigma}^2) - \frac{1}{2\widehat{\sigma}^2} (\mathbf{y} - X\widehat{\beta})'(\mathbf{y} - X\widehat{\beta}) \\
&= -\frac{T}{2} \log(\widehat{\sigma}^2) - \frac{T}{2}
\end{aligned}$$

by substituting  $T\widehat{\sigma}^2$  for the numerator of the second term. Hence, the AIC for

this problem is

$$AIC = 2 \left( \ell(\hat{\beta}) - k \right) = -T \log(\hat{\sigma}^2) - T - 2k$$

But this way of writing things uses the *opposite* sign convention from  $AIC_c$ . It's important to keep track of this, since different authors use different sign conventions for information criteria. To make the AIC comparable with our scaling of the  $AIC_c$ , we multiply through by  $-1/T$  yielding

$$AIC = \log(\hat{\sigma}^2) + \frac{T + 2k}{T}$$

where *smaller* values now indicate a better model.

## 2 Cross-Validation

In the last lecture, we learned that choosing a model by minimizing the KL divergence is equivalent to choosing a model by maximizing the expected log likelihood. We also learned that the sample analogue

$$E_{\hat{G}} \left[ \log f(\mathbf{y}|\hat{\theta}) \right] = \frac{\ell(\hat{\theta})}{T} = \frac{1}{T} \sum_{t=1}^T \log f(y_t|\hat{\theta})$$

provides a biased estimator of this quantity. Intuitively, the problem is that it uses the data twice: first to estimate  $\hat{\theta}$  and then to approximate the integral

$$\int g(y) \log f(y|\hat{\theta}) dy = E_G \left[ \log f(Y_{new}|\hat{\theta}) \right]$$

using the empirical CDF constructed from the sample observations. If the problem is that we've used the data twice, then an obvious idea is to find some way to use *different* data for estimating  $\theta$  than we use to approximate the integral. This is the idea behind cross-validation. We split the data into two parts, use one for estimation and the *other* for model evaluation. To avoid

“wasting data” we repeat this process sucessively for *different* splits, so each observation has a chance to be used for for estimation and evaluation but *never* for both at the same time.

To make this more concrete, we’ll consider what is perhaps the most common form of cross-validation: “leave-one-out” cross-validation. For simplicity, suppose we have iid observations  $Y_1, \dots, Y_T$  and let  $\hat{\theta}_{(t)}$  denote the ML estimator for  $\theta$  using all observations *except*  $Y_t$ . The leave-one-out cross-validation estimator of the expected log likelihood is

$$CV(1) = \frac{1}{T} \sum_{t=1}^T \log f(y_t | \hat{\theta}_{(t)})$$

The idea is that, since the data are iid,  $\hat{\theta}_{(t)}$  is *independent* of  $Y_t$ . Accordingly, the cross-validation estimate of the expected log-likelihood should *not* be subject the the over-optimism problem that plagues the maximized log-likelihood. To use cross-validation for model selection, we simply calculate  $CV(1)$  for the various models under consideration, and choose the one with the *highest* value.

As it turns out, leave-one-out cross-validation is intimately connected with the TIC. In fact the two are *asymptotically equivalent* as we’ll now show. To begin note that, by a first-order Taylor Expansion of the leave-one-out estimator around the full-sample MLE we have

$$\begin{aligned} CV(1) &= \frac{1}{T} \sum_{t=1}^T \log f(y_t | \hat{\theta}_{(t)}) \\ &= \frac{1}{T} \sum_{t=1}^T \left[ \log f(y_t | \hat{\theta}) + \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} (\hat{\theta}_{(t)} - \hat{\theta}) \right] + o_p(1) \\ &= \frac{\ell(\hat{\theta})}{T} + \frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} (\hat{\theta}_{(t)} - \hat{\theta}) + o_p(1) \end{aligned}$$

so we simply need to show that

$$\frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} \left( \hat{\theta}_{(t)} - \hat{\theta} \right) = -\frac{1}{T} \text{trace} \left( \hat{J}^{-1} \hat{K} \right) + o_p(1)$$

***Everything that follows amounts to proving this statement.***

To understand the preceding assertion, we'll need to take a slight detour and talk about *influence functions*, an idea from the robust estimation literature. Let  $\mathbb{T} = \mathbb{T}(G)$  be a functional and  $G$  be some probability distribution. Then the influence function of  $\mathbb{T}$  at a point  $y$  is defined as

$$\text{infl}(G, y) = \lim_{\epsilon \rightarrow 0} \frac{\mathbb{T}((1 - \epsilon)G + \epsilon \delta_y) - \mathbb{T}(G)}{\epsilon}$$

where  $\delta_y$  is a *point mass* at  $y$ , that is

$$\delta_y(a) \begin{cases} 0, & a < y \\ 1, & a \geq y \end{cases}$$

All kinds of quantities that we know and love can be viewed as functionals of a distribution, for example the mean and variance. Here we're going to be concerned with a particular functional that should look familiar from our last lecture:

$$\theta_0 = \mathbb{T}(G) = \arg \min_{\theta \in \Theta} E_G \left[ \log \left\{ \frac{g(Y)}{f(Y|\theta)} \right\} \right]$$

What this says is that we can view  $\theta_0$  as the result of applying an *operator*  $\mathbb{T}$  to the distribution  $G$ . In this case  $\theta_0$  is simply the pseudo-true value: the probability limit of the maximum likelihood estimator of  $\theta$  based on  $f(y|\theta)$ . Clearly the pseudo-true value depends on the DGP, namely  $G$ . Different distributions  $G$  would yield different pseudo-true values for the *same* likelihood  $f$ . If we evaluate  $\mathbb{T}$  at the *empirical* distribution  $\hat{G}$  we get the maximum likelihood estimator  $\hat{\theta}$  rather than the pseudo-true value  $\theta_0$ .

The influence function is in fact a *functional derivative*. It allows us to evaluate, for example, how the pseudo-true value  $\theta_0$  would change if we *slightly*

changed the distribution  $G$  that generated the data by “polluting” it with a tiny mass point located at  $y$ . We could also consider how the maximum likelihood estimator,  $\hat{\theta}$ , would change if we slightly changed the dataset, represented by empirical distribution function. Now, since the empirical distribution is given by

$$\hat{G}(a) = \frac{1}{T} \sum_{t=1}^T \mathbf{1}\{y_t \leq a\} = \frac{1}{T} \sum_{t=1}^T \delta_{y_t}(a)$$

we can re-write it as

$$\hat{G} = (1 - 1/T)\hat{G}_{(t)} + \delta_{y_t}/T$$

where  $\hat{G}_{(t)}$  is the empirical distribution with  $y_t$  excluded from the dataset.

Which means that we can express the leave-one-out estimator  $\hat{\theta}_{(t)}$  as follows

$$\begin{aligned} \hat{\theta}_{(t)} &= \hat{\theta} - \frac{1}{T} \text{infl}\left(\hat{G}_{(t)}, y_t\right) + o_p(1) \\ &= \hat{\theta} - \frac{1}{T} \text{infl}\left(\hat{G}, y_t\right) + o_p(1) \end{aligned}$$

Now, it can be shown that the influence function for maximum likelihood estimation is

$$\text{infl}(G, y) = J^{-1} \left( \frac{\partial \log f(y|\theta_0)}{\partial \theta} \right)$$

where  $\theta_0 = \mathbb{T}(G)$ . Hence, evaluating this expression at  $\hat{G}$  and  $y_t$  and substituting into our expression for  $\hat{\theta}_{(t)}$

$$\hat{\theta}_{(t)} = \hat{\theta} - \frac{1}{T} \hat{J}^{-1} \left( \frac{\partial \log f(y_t|\hat{\theta})}{\partial \theta} \right) + o_p(1)$$

In other words,

$$\left(\hat{\theta}_{(t)} - \hat{\theta}\right) = -\frac{1}{T} \hat{J}^{-1} \left( \frac{\partial \log f(y_t|\hat{\theta})}{\partial \theta} \right) + o_p(1)$$



Finally, substituting this back into the expression we initially set out to prove,

$$\begin{aligned}
\frac{1}{T} \sum_{t=1}^T \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta'} (\hat{\theta}_{(t)} - \hat{\theta}) &= -\frac{1}{T} \sum_{t=1}^T \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right)' \hat{J}^{-1} \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right) + o_p(1) \\
&= -\frac{1}{T} \text{trace} \left\{ \hat{J}^{-1} \left[ \frac{1}{T} \sum_{t=1}^T \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right) \left( \frac{\partial \log f(y_t | \hat{\theta})}{\partial \theta} \right)' \right] \right\} \\
&\quad + o_p(1) \\
&= -\frac{1}{T} \text{trace} \left\{ \hat{J}^{-1} \hat{K} \right\}
\end{aligned}$$

So it works as advertised!

**Other Loss Functions** Although we’ve used cross-validation to evaluate the KL divergence here, it’s actually a very general idea and can be used with *any* loss function. For example, we could use a zero-one loss function for binary predictions, or a quadratic loss function for continuous predictions. The idea is the same in any case: we create “pseudo-out-of-sample observations” by withholding one observation at a time, and use these to evaluate the loss. While cross-validation can be computationally intensive, it turns out that there’s a shortcut for models that can be expressed as linear smoothers. You’ll examine a simple case of this on the problem set. It’s also worth pointing out that there are varieties of cross-validation other than leave-one-out, but these have different properties.

### 3 Mallow’s $C_p$

Suppose that we want to predict  $y$  from  $\mathbf{x}$  using a linear regression model:

$$\underset{(T \times 1)}{\mathbf{y}} = \underset{(T \times K)}{X} \underset{(K \times 1)}{\beta} + \underset{(T \times 1)}{\epsilon}$$

Where  $E[\epsilon|X] = 0$  and  $\text{Var}(\epsilon|X) = \sigma^2 \mathbf{I}$ . We know that the conditional mean is the minimum mean-squared error predictor. This means that if  $\beta$

were *known*, we could never improve upon simply using all the regressors for prediction. But since  $\beta$  must be *estimated* from the data, a bias-variance tradeoff arises. In particular, we might be better off *excluding* a regressor with small coefficient, since it adds very little predictive power compared but introduces additional estimation uncertainty.

We'll now consider using *subsets* of  $X$  rather than the full data matrix. Let  $X_M$  denote a design matrix that possibly excludes some columns of  $X$ . The index  $M$  refers to a particular *model*. Accordingly, let  $\hat{\beta}_M$  be the least-squares estimator based on the design matrix  $X_M$ . We'll adopt the convention that  $\hat{\beta}_M$  is padded out with zeros for the elements of  $\beta$  that are *not estimated* under model  $M$ . This way we can write

$$X\hat{\beta}_M = X_{(-M)}\mathbf{0} + X_M(X_M'X_M)^{-1}X_M'\mathbf{y} = P_M\mathbf{y}$$

Now, suppose we want to compare the predictive power of the competing estimators  $\hat{\beta}_M$  using mean-squared error. A naïve idea would be to use in-sample prediction error to compare models:

$$RSS(M) = (\mathbf{y} - X\hat{\beta}_M)'(\mathbf{y} - X\hat{\beta}_M)$$

As is well-known, however, the residual sum of squares can *never* decrease even as we add irrelevant predictors to our model. In contrast, out-of-sample predictive ability can easily decrease when we add more predictors: there's a bias-variance tradeoff that arises from estimation uncertainty. Somehow or other we need to develop a criterion to take this into account.

We'll start off by calculating the predictive mean-squared error of  $X\hat{\beta}_M$  relative to the infeasible optimum, namely  $X\beta$ . Let  $P_M = X_M(X_M'X_M)^{-1}X_M'$ . Then, using the properties of projection matrices that we learned in Econ 705, in particular that they are symmetric and idempotent and the same goes from

their orthogonal complements,

$$\begin{aligned}
(X\hat{\beta}_M - X\beta)'(X\hat{\beta}_M - X\beta) &= (P_M\mathbf{y} - X\beta)'(P_M\mathbf{y} - X\beta) \\
&= \{P_M(Y - X\beta) + (\mathbf{I} - P_M)X\beta\}'\{P_M(Y - X\beta) + (\mathbf{I} - P_M)X\beta\} \\
&= \{P_M\epsilon + (\mathbf{I} - P_M)X\beta\}'\{P_M\epsilon + (\mathbf{I} - P_M)X\beta\} \\
&= \epsilon'P_M'P_M\epsilon + \beta'X'(\mathbf{I} - P_M)'P_M\epsilon \\
&\quad + \epsilon'P_M'(\mathbf{I} - P_M)X\beta + \beta'X'(\mathbf{I} - P_M)(\mathbf{I} - P_M)X\beta \\
&= \epsilon'P_M\epsilon + \beta'X'(\mathbf{I} - P_M)X\beta
\end{aligned}$$

Thus, evaluating the predictive mean-squared error conditional on  $X$ , we have

$$\begin{aligned}
\text{MSE}(M|X) &= E[(X\hat{\beta}_M - X\beta)'(X\hat{\beta}_M - X\beta)|X] \\
&= E[\epsilon'P_M\epsilon|X] + E[\beta'X'(\mathbf{I} - P_M)X\beta|X] \\
&= E[\text{trace}\{\epsilon'P_M\epsilon\}|X] + \beta'X'(\mathbf{I} - P_M)X\beta \\
&= \text{trace}\{E[\epsilon\epsilon'|X]P_M\} + \beta'X'(\mathbf{I} - P_M)X\beta \\
&= \text{trace}\{\sigma^2P_M\} + \beta'X'(\mathbf{I} - P_M)X\beta \\
&= \sigma^2k_M + \beta'X'(\mathbf{I} - P_M)X\beta
\end{aligned}$$

where  $k_M$  denotes the number of regressors included in  $X_M$  and we have used the fact that the trace of a projection matrix equals its dimension.

The problem with the proceeding expression is that we don't know  $\theta$  or  $\sigma^2$  so we can't compare MSE across models. To get around this, we'll construct an unbiased estimator. Let  $\hat{\beta}$  be the estimator based on the full set of regressors, i.e.  $\hat{\beta} = (X'X)^{-1}X'\mathbf{y}$  and let  $P_X$  be the corresponding projection matrix so that we have

$$X\hat{\theta} = X(X'X)^{-1}X'\mathbf{y} = P_X\mathbf{y}$$

Then, using the fact that  $P_M P_X = P_X P_M = P_M$ , we have

$$\begin{aligned}
E \left[ \widehat{\theta}' X' (\mathbf{I} - P_M) X \widehat{\theta} | X \right] &= E \left[ \mathbf{y}' P_X' (\mathbf{I} - P_M) P_X \mathbf{y} | X \right] \\
&= E \left[ \mathbf{y}' (P_X' P_X - P_X' P_M P_X) \mathbf{y} | X \right] \\
&= E \left[ \mathbf{y}' (P_X - P_M) \mathbf{y} | X \right] \\
&= E \left[ (X\beta + \epsilon)' (P_X - P_M) (X\beta + \epsilon) \mathbf{y} | X \right] \\
&= E \left[ \beta' X (P_X - P_M) X \beta | X \right] + E \left[ \epsilon' (P_X - P_M) X \beta | X \right] \\
&\quad + E \left[ \beta' X' (P_X - P_M) \epsilon | X \right] + E \left[ \epsilon' (P_X - P_M) \epsilon | X \right] \\
&= \beta' X (P_X - P_M) X \beta + E \left[ \epsilon' (P_X - P_M) \epsilon | X \right] \\
&= \beta' X (P_X - P_M) X \beta + E \left[ \text{trace} \{ \epsilon' (P_X - P_M) \epsilon \} | X \right] \\
&= \beta' X (P_X - P_M) X \beta + \text{trace} \{ E \left[ \epsilon \epsilon' | X \right] (P_X - P_M) \} \\
&= \beta' X (P_X - P_M) X \beta + \text{trace} \{ \sigma^2 (P_X - P_M) \} \\
&= \beta' X (P_X - P_M) X \beta + \sigma^2 (\text{trace} \{ P_X \} - \text{trace} \{ P_M \}) \\
&= \beta' X (P_X - P_M) X \beta + \sigma^2 (K - k_M)
\end{aligned}$$

Rearranging, and comparing to our expression from above, we have

$$E \left[ \widehat{\theta}' X' (\mathbf{I} - P_M) X \widehat{\theta} + \sigma^2 (2k_M - K) | X \right] = \text{MSE}(M | X)$$

We still don't know  $\sigma^2$ , but we can construct an unbiased estimate from the residuals of the full model as follows

$$\widehat{\sigma}^2 = \frac{\mathbf{y}' (\mathbf{I} - P_X) \mathbf{y}}{(T - K)}$$

Now, as we calculated above,

$$\widehat{\theta}' X' (\mathbf{I} - P_M) X \widehat{\theta} = \mathbf{y}' (P_X - P_M) \mathbf{y}$$

Hence, the following is an unbiased estimator of  $\text{MSE}(M|X)$

$$\text{MC}_M = \hat{\theta}' X' (\mathbf{I} - P_M) X \hat{\theta} + \hat{\sigma}^2 (2k_M - K)$$

To get Mallows's  $C_p$  we rearrange this quantity. First, we have

$$\begin{aligned} \text{MC}_M - 2\hat{\sigma}^2 k_M &= \hat{\theta}' X' (\mathbf{I} - P_M) X \hat{\theta} - K\hat{\sigma}^2 \\ &= \mathbf{y}' P_X' (\mathbf{I} - P_M) P_X \mathbf{y} K \hat{\sigma}^2 \\ &= \mathbf{y}' (P_X' P_X - P_X' P_M P_X) \mathbf{y} K \hat{\sigma}^2 \\ &= \mathbf{y}' (P_X - P_M) \mathbf{y} - \left( \frac{K}{T-K} \right) \mathbf{y}' (\mathbf{I} - P_X) \mathbf{y} \\ &= \left( \frac{T-K}{T-K} \right) (\mathbf{y}' P_X \mathbf{y} - \mathbf{y}' P_M \mathbf{y}) - \left( \frac{K}{T-K} \right) (\mathbf{y}' \mathbf{y}' - \mathbf{y}' P_X \mathbf{y}) \\ &= \left( \frac{T-K}{T-K} + \frac{K}{T-K} \right) \mathbf{y}' P_X \mathbf{y} - \left( \frac{T-K}{T-K} \right) \mathbf{y}' P_M \mathbf{y} - \left( \frac{K}{T-K} \right) \mathbf{y}' \mathbf{y} \\ &= \left( \frac{T}{T-K} \right) \mathbf{y}' P_X \mathbf{y} - \mathbf{y}' P_M \mathbf{y} - \left( \frac{K}{T-K} \right) \mathbf{y}' \mathbf{y} \\ &= \left( \frac{T}{T-K} \right) \mathbf{y}' P_X \mathbf{y} - \mathbf{y}' P_M \mathbf{y} + \left( \frac{T-K-T}{T-K} \right) \mathbf{y}' \mathbf{y} \\ &= \left( \frac{T}{T-K} \right) \mathbf{y}' P_X \mathbf{y} - \mathbf{y}' P_M \mathbf{y} + \left( 1 - \frac{T}{T-K} \right) \mathbf{y}' \mathbf{y} \\ &= \left( \frac{T}{T-K} \right) \mathbf{y}' P_X \mathbf{y} - \mathbf{y}' P_M \mathbf{y} + \mathbf{y}' \mathbf{y} - \left( \frac{T}{T-K} \right) \mathbf{y}' \mathbf{y} \\ &= \mathbf{y}' \mathbf{y} - \mathbf{y}' P_M \mathbf{y} - \left( \frac{T}{T-K} \right) (\mathbf{y}' \mathbf{y} - \mathbf{y}' P_M \mathbf{y}) \\ &= \mathbf{y}' (\mathbf{I} - P_M) \mathbf{y} - \left( \frac{T}{T-K} \right) \mathbf{y}' (\mathbf{I} - P_X) \mathbf{y} \\ &= \mathbf{y}' (\mathbf{I} - P_M) \mathbf{y} - T\hat{\sigma}^2 \\ &= \text{RSS}(M) - T\hat{\sigma}^2 \end{aligned}$$

In other words,

$$\text{MC}_M = \text{RSS}(M) + \hat{\sigma}^2 (2k_M - T)$$

is an unbiased estimator of the predictive mean-squared error of model  $M$

conditional on  $X$ . Dividing through by  $\hat{\sigma}^2$  gives Mallows's  $C_p$

$$C_p(M) = \frac{RSS(M)}{\hat{\sigma}^2} + 2k_M - T$$

This expression tells us how we need to *adjust* the residual sum of squares to account for the fact that in-sample fit is a misleading guide to out-of-sample predictive performance.

## 4 Bayesian Information Criterion

Since Frank2 talked about this in his part of the course, I won't discuss this derivation in class but I wanted to provide the details for completeness. As in our derivation of TIC and AIC, we'll consider a setting with an iid sample of scalar random variables  $Y_1, \dots, Y_T$ . The results still hold in the more general case, but this simplifies the notation.

### 4.1 Overview of the BIC

Despite its name, the BIC is *not* a Bayesian procedure. It is a large-sample Frequentist *approximation* to Bayesian model selection:

1. Begin with a uniform prior on the set of candidate models so that it suffices to maximize the Marginal Likelihood.
2. The BIC is a large sample approximation to the Marginal Likelihood:

$$\int \pi(\beta_i) f_i(\mathbf{y}|\beta_i) d\beta_i$$

where  $i$  indexes models  $M_i$  in a set  $\mathcal{M}$ .

3. As usual when Bayesian procedures are subjected to Frequentist asymptotics, the priors on parameters vanish in the limit.
4. We proceed by a *Laplace Approximation* to the Marginal Likelihood

## 4.2 Laplace Approximation

For the moment simplify the notation by suppressing dependence on  $M_i$ . We want to approximate:

$$\int \pi(\beta)f(\mathbf{y}|\beta)d\beta$$

This is actually a common problem in applications of Bayesian inference:

- Notice that  $\pi(\beta)f(\mathbf{y}|\beta)$  is the *kernel* of some probability density, i.e. the density without its normalizing constant.
- *How do we know this?* By Bayes' Rule

$$\pi(\beta|\mathbf{y}) = \frac{\pi(\beta)f(\mathbf{y}|\beta)}{\int \pi(\beta)f(\mathbf{y}|\beta)d\beta}$$

is a proper probability density and the denominator is *constant* with respect to  $\beta$ . (The parameter has been “integrated out.”)

- In Bayesian inference, we specify  $\pi(\beta)$  and  $f(\mathbf{y}|\beta)$ , so  $\pi(\beta)f(\mathbf{y}|\beta)$  is known. But to calculate the posterior we need to *integrate* to find the normalizing constant.
- Only in special cases (e.g. conjugate families) can we find the exact normalizing constant. Typically some kind of approximation is needed:
  - Importance Sampling
  - Markov-Chain Monte Carlo (MCMC)
  - *Laplace Approximation*

The Laplace Approximation is an *analytical approximation* based on Taylor Expansion arguments. In Bayesian applications, the expansion is carried out around the posterior mode, i.e. the mode of  $\pi(\beta)f(\mathbf{y}|\beta)$ , but we will expand around the Maximum likelihood estimator.

**Proposition 4.1** (Laplace Approximation).

$$\int \pi(\beta) f(\mathbf{y}|\beta) d\beta \approx \frac{\exp \left\{ \ell(\hat{\beta}) \right\} \pi(\hat{\beta}) (2\pi)^{p/2}}{n^{p/2} \left| J(\hat{\beta}) \right|^{1/2}}$$

Where  $\hat{\beta}$  is the maximum likelihood estimator,  $p$  the dimension of  $\beta$  and

$$J(\hat{\beta}) = -\frac{1}{n} \frac{\partial^2 \log f(\mathbf{y}|\hat{\beta})}{\partial \beta \partial \beta'}$$

*Proof.* A rigorous proof of this result is complicated. The following is a sketch.

First write  $\ell(\beta)$  for  $\log f(\mathbf{y}|\beta)$  so that

$$\pi(\beta) f(\mathbf{y}|\beta) = \pi(\beta) \exp \{ \log f(\mathbf{y}|\beta) \} = \pi(\beta) \exp \{ \log \ell(\beta) \}$$

By a second-order Taylor Expansion around the MLE  $\hat{\beta}$

$$\ell(\beta) = \ell(\hat{\beta}) + \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) + R_\ell \quad (1)$$

since the derivative of  $\ell(\beta)$  is zero at  $\hat{\beta}$  by the definition of MLE. A first-order expansion is sufficient for  $\pi(\beta)$  because the derivative does not vanish at  $\hat{\beta}$

$$\pi(\beta) = \pi(\hat{\beta}) + \frac{\partial \pi(\hat{\beta})}{\partial \beta'} (\beta - \hat{\beta}) + R_\pi \quad (2)$$

Substituting Equations 1 and 2,

$$\begin{aligned} \int \pi(\beta) f(\mathbf{y}|\beta) d\beta &= \int \exp \left\{ \ell(\hat{\beta}) + \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) + R_\ell \right\} \\ &\quad \times \left[ \pi(\hat{\beta}) + (\beta - \hat{\beta})' \frac{\partial \pi(\hat{\beta})}{\partial \beta} + R_\pi \right] d\beta \\ &= \exp \left\{ \ell(\hat{\beta}) \right\} (I_1 + I_2 + I_3) \end{aligned}$$



where

$$\begin{aligned}
I_1 &= \pi(\hat{\beta}) \int \exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) + R_\ell \right\} d\beta \\
I_2 &= \frac{\partial \pi(\hat{\beta})}{\partial \beta'} \int (\beta - \hat{\beta}) \exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) + R_\ell \right\} d\beta \\
I_3 &= \int R_\pi \exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) + R_\ell \right\} d\beta
\end{aligned}$$

Under certain regularity conditions (not the standard ones!) we can treat  $R_\ell$  and  $R_\pi$  as approximately equal to zero for large  $n$  uniformly in  $\beta$ , so that

$$\begin{aligned}
I_1 &\approx \pi(\hat{\beta}) \int \exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) \right\} d\beta \\
I_2 &\approx \frac{\partial \pi(\hat{\beta})}{\partial \beta'} \int (\beta - \hat{\beta}) \exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) \right\} d\beta \\
I_3 &\approx 0
\end{aligned}$$

Because  $\hat{\beta}$  is the MLE,

$$\frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'}$$

must be negative definite, so

$$-\frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'}$$

is positive definite. It follows that

$$\exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) \right\} = \exp \left\{ -\frac{1}{2} (\beta - \hat{\beta})' \left[ \left( -\frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} \right)^{-1} \right]^{-1} (\beta - \hat{\beta}) \right\}$$

can be viewed as the kernel of a Normal distribution with mean  $\hat{\beta}$  and variance

matrix

$$\left( -\frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} \right)^{-1}$$

Thus,

$$\int \exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) \right\} d\beta = (2\pi)^{p/2} \left| \left( -\frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} \right)^{-1} \right|^{1/2}$$

and

$$\int (\beta - \hat{\beta}) \exp \left\{ \frac{1}{2} (\beta - \hat{\beta})' \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} (\beta - \hat{\beta}) \right\} d\beta = 0$$

Therefore,

$$\begin{aligned} \int \pi(\beta) f(\mathbf{y}|\beta) d\beta &\approx \exp \left\{ \ell(\hat{\beta}) \right\} \pi(\hat{\beta}) (2\pi)^{p/2} \left| \left( -\frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} \right)^{-1} \right|^{1/2} \\ &= \exp \left\{ \ell(\hat{\beta}) \right\} \pi(\hat{\beta}) (2\pi)^{p/2} \left| n \left( -\frac{1}{n} \frac{\partial^2 \ell(\hat{\beta})}{\partial \beta \partial \beta'} \right) \right|^{-1/2} \\ &= \frac{\exp \left\{ \ell(\hat{\beta}) \right\} \pi(\hat{\beta}) (2\pi)^{p/2}}{n^{p/2} |J(\hat{\beta})|^{1/2}} \end{aligned}$$

□

### 4.3 Finally the BIC

Now we re-introduce the dependence on the model  $M_i$ . Taking logs of the Laplace Approximation and multiplying by two (again, this is traditional but has no effect on model comparisons)

$$\begin{aligned} 2 \log f(y|M_i) &= 2 \log \left\{ \int f_i(y|\beta_i) \pi(\beta_i) d\beta_i \right\} \\ &\approx 2\ell(\hat{\beta}_i) - p \log(n) + p \log(2\pi) - \pi(\hat{\beta}_i) - \log |J(\hat{\beta}_i)| \end{aligned}$$

The first two terms are  $O_p(n)$  and  $O_p(\log n)$ , while the last three are  $O_p(1)$ , hence negligible as  $n \rightarrow \infty$ . This gives us Schwarz's BIC

$$BIC(M_i) = 2 \log f_i(\mathbf{y}|\hat{\beta}_i) - p \log n$$

We choose the model  $M_i$  for which  $BIC(M_i)$  is largest. Notice that the prior on the parameter,  $\pi(\beta)$ , drops out in the limit, and recall that we began by putting a uniform prior on the *models* under consideration.