

# Dynamic Factor Models

Francis J. DiTraglia

University of Pennsylvania

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# Survey Articles on Dynamic Factor Models

## Stock & Watson (2010)

Best general overview of dynamic factor models and applications.

## Bai & Ng (2008)

Comprehensive review of large-sample results for high-dimensional factor models estimated via PCA.

## Stock & Watson (2006)

Handbook chapter on forecasting with many predictors. One section is devoted to dynamic factor models.

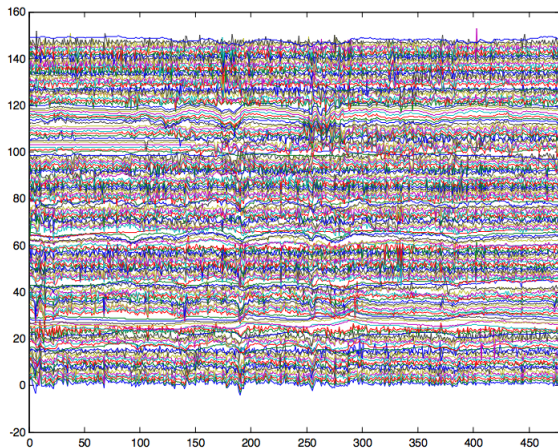
## Breitung & Eickmeyer (2006)

Brief overview with an application to Euro-area business cycles.

# The Basic Idea

We're interested in settings with a large number of time series  $N$  and a comparable number of time periods  $T$ .

## Example: Stock and Watson Dataset



Monthly Macroeconomic Indicators:  $N > 200$ ,  $T > 400$

# Why Factor Models?

1. Factors could be intrinsically interesting if they arise from a theoretical model (e.g. Financial Economics)
2. Many variables without running out of degrees of freedom
  - ▶ More information could improve forecasts/macro analysis
  - ▶ Mimic central banks “looking at everything”
3. Eliminate measurement error and idiosyncratic shocks to provide more reliable information for policy
4. “Remain Agnostic about the Structure of the Economy”
  - ▶ Advantages over SVARs: don't have to choose variables to control degrees of freedom, and can allow fewer underlying shocks than variables.

## Last Time: Classical Factor Analysis Model

I've eliminated the mean  $\mu$  and renamed the factor  $F_t$

$$\underset{(N \times 1)}{X_t} = \underset{(k \times 1)}{\Lambda} F_t + \epsilon_t$$

$$\begin{bmatrix} F_t \\ \epsilon_t \end{bmatrix} \stackrel{iid}{\sim} \mathcal{N} \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} I_k & 0 \\ 0 & \Psi \end{bmatrix} \right)$$

$\Lambda$  = matrix of factor loadings

$\Psi$  = diagonal matrix of idiosyncratic variances.

## Adding Time-Dependence

$$\underset{(N \times 1)}{X_t} = \underset{(k \times 1)}{\Lambda} \underset{(k \times 1)}{F_t} + \epsilon_t$$

$$\underset{(k \times 1)}{F_t} = A_1 F_{t-1} + \dots + A_p F_{t-p} + u_t$$

$$\begin{bmatrix} u_t \\ \epsilon_t \end{bmatrix} \stackrel{iid}{\sim} \mathcal{N} \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} I_k & 0 \\ 0 & \Psi \end{bmatrix} \right)$$

## Some Terminology

**Static**  $X_t$  depends only on  $F_t$

**Dynamic**  $X_t$  depends on lags of  $F_t$  as well

**Exact**  $\Psi$  is diagonal and  $\epsilon_t$  independent over time

**Approximate** Some cross-sectional & temporal dependence in  $\epsilon_t$

The model I wrote down on the previous slide is sometimes called an “exact, static factor model” even though it has dynamics! I’ll still call it a dynamic factor model...



## Editorial: This is all a bit confused...

1. The difference between “static” and “dynamic” is unclear
  - ▶ Can write dynamic model as a static one with more factors
  - ▶ Static representation involves “different” factors, but we may not care: are the factors “real” or just a data summary?
2. Not really possible to allow cross-sectional dependence in  $\epsilon_t$ 
  - ▶ Unless the off-diagonal elements of  $\Psi$  are close to zero we can't tell them apart from the common factors
  - ▶ “Approximate” factor models basically assume conditions under which the off-diagonal elements of  $\Psi$  are negligible
  - ▶ Similarly, time series dependence in  $\epsilon_t$  can't be very strong (stationary ARMA is ok)

# Methods of Estimation for Dynamic Factor Models

1. Bayesian Estimation
2. Maximum Likelihood: EM-Algorithm + Kalman Filter
  - ▶ Watson & Engle (1983)
  - ▶ Ghahramani & Hinton (1996)
  - ▶ Jungbacker & Koopman (2008)
  - ▶ Doz, Giannone & Reichlin (2012)
3. “Nonparametric” Estimation
  - ▶ Just carry out PCA on  $X$  and ignore the time-series element

PCA stuff, when and why it works, what the basic conditions are, and when it fails.

# Doz, Giannone & Reichlin (2012)

## Typical Justifications for PCA Approach

- ▶ Consistent estimation of factors under very weak assumptions
- ▶ MLE is computationally infeasible for large  $N$

## But Neither is True!

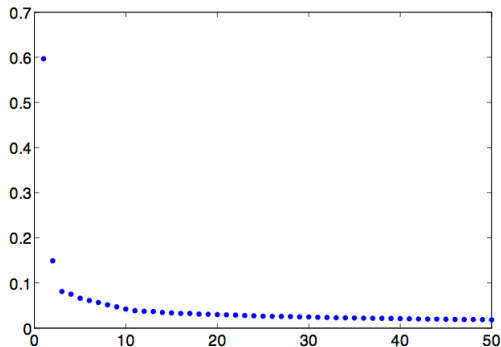
- ▶ EM-algorithm + Kalman Filter is *very efficient* – complexity depends on number of *factors*, not number of series
- ▶ Treat exact, static factor model (the one I wrote out) as a mis-specified *approximating model* (Quasi-MLE)
- ▶ Identical large-sample results as PC under similar assumptions, but better finite-sample properties and temporal smoothing

## Choosing the Number of Factors

If we use Likelihood-based or Bayesian estimation, we could try to resort to the familiar tools from earlier in the semester. There are a lot of parameters in factor models, however, so the asymptotic approximations (I'm looking at you, AIC) could be poor.

## Choosing the Number of Factors – Scree Plot

If we use PC estimation, we can look at something called a “scree plot” to help us decide how many PCs to include:



This figure depicts the eigenvalues for an  $N = 1148$ ,  $T = 252$  dataset of excess stock returns

# Choosing the Number of Factors – Bai & Ng (2002)

## Onatski (2013)

Nobody volunteered to present this paper! Unlike Bai & Ng (2002), the idea here is *not* to consistently estimate the number of factors. Instead, and in the spirit of AIC and  $C_p$ , we try to reconstruct the factors with minimum quadratic loss. The results in the paper apply both to “strong” and “weak” factor asymptotics.



# What Can We Do with Factors?

Among other possibilities:

1. Use them as Instrumental Variables
2. Use them to construct Forecasts
3. Use them to “Augment” a VAR

# Factors as Instruments – Bai & Ng (2010)

Endogenous Regressors  $x_t$

$$y_t = x_t' \beta + \epsilon_t \quad E[x_t \epsilon_t] \neq 0$$

Unobserved Variables  $F_t$  are Strong IVs

$$\underset{(k \times 1)}{x_t} = \underset{(r \times 1)}{\Psi' F_t} + u_t \quad E[F_t \epsilon_t] = 0$$

Observe Large Panel  $(z_{1t}, \dots, z_{Nt})$

$$z_{it} = \lambda_i' F_t + e_{it}$$

# Factors as Instruments – Bai & Ng (2010)

$$y_t = x_t' \beta + \epsilon_t, \quad x_t = \Psi' F_t + u_t, \quad z_{it} = \lambda_i' F_t + e_{it}$$

## Procedure

1. Calculate the PCs of  $Z$
2. Calculate  $\tilde{F}_t$  using the first  $r$  PCs of  $Z$
3. Use  $\tilde{F}_t$  in place of  $F_t$  for IV estimation

## Main Result

Under certain assumptions, as  $(N, T) \rightarrow \infty$  “estimation and inference can proceed as though  $F_t$  were known.” The resulting estimator is consistent and asymptotically normal.

# Forecasting with Dynamic Factors

- ▶ Similar to Principal Components Regression (PCR)
- ▶ Estimate factors  $\hat{F}_t$  from a large number of regressors  $X_t$
- ▶ Run a regression to forecast  $y_t$  using  $\hat{F}_t$  rather than  $X_t$

We'll talk about this more next time and compare to other high-dimensional forecasting procedures.

# Factors as Instruments – Bai & Ng (2010)

## Why Might This be Helpful?

1. Avoid many instruments bias
2. Avoid bias from irrelevant instruments
3. Allow more observed instruments  $z_{it}$  than sample size  $T$
4. Provided that  $\sqrt{T}/N \rightarrow 0$ , all of the observed instruments  $z_{it}$  can be *endogenous* as long as  $F_t$  is exogenous

# FAVARs – Bernanke, Boivin & Elias (2005)

## Two Problems with Structural VARs

1. Number of parameters is *quadratic* in the number of variables. Unrestricted VAR infeasible unless  $T$  is large relative to  $N$ .
  - ▶ You've studied one solution to this problem already this semester: Bayesian Estimation with informative priors
2. To keep estimation tractable we typically use a small number of variables, but then the VAR innovations “might not span the space of structural shocks.”

# FAVARs – Bernanke, Boivin & Elias (2005)

## Factor-Augmented VAR Model

$$\begin{bmatrix} Y_t \\ F_t \end{bmatrix} = \Phi(L) \begin{bmatrix} F_{t-1} \\ Y_{t-1} \end{bmatrix} + v_t$$

$$X_t = \Lambda^f F_t + \Lambda^y Y_t + e_t$$

$\begin{matrix} Y_t \\ (M \times 1) \end{matrix}$  = observable variables that “drive dynamics of the economy”

$\begin{matrix} F_t \\ (K \times 1) \end{matrix}$  = Small # of unobserved factors: “additional information”

$\begin{matrix} F_t \\ (N \times 1) \end{matrix}$  = Large # of observed “informational time series”

## FAVARs – Bernanke, Boivin & Elias (2005)

$$\begin{bmatrix} Y_t \\ F_t \end{bmatrix} = \Phi(L) \begin{bmatrix} F_{t-1} \\ Y_{t-1} \end{bmatrix} + v_t \quad X_t = \Lambda^f F_t + \Lambda^y Y_t + e_t$$

### Consider Two Estimation Procedures

#### 1. Two-step Procedure:

- ▶ Estimate space spanned by factors using first  $K + M$  PCs of  $X$
- ▶ Estimate VAR with  $\hat{F}_t$  in place of  $F_t$

#### 2. Full Bayes (Gibbs Sampler)

### Empirical Application

Additional information contained in FVAR is “important to properly identify the monetary transmission mechanism.”