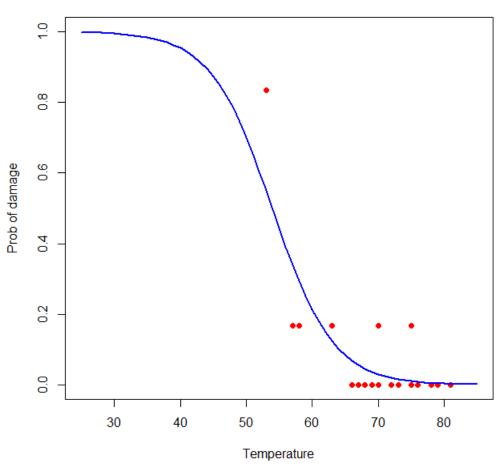
# Generalized linear modeling with

#### Challenger disaster



Source: Faraway (2006).





- 0/1 data (activity, infection, presence, sex)
- proportional data (0 100 %)
- number of successes vs. number of failures
- count data (species richness)



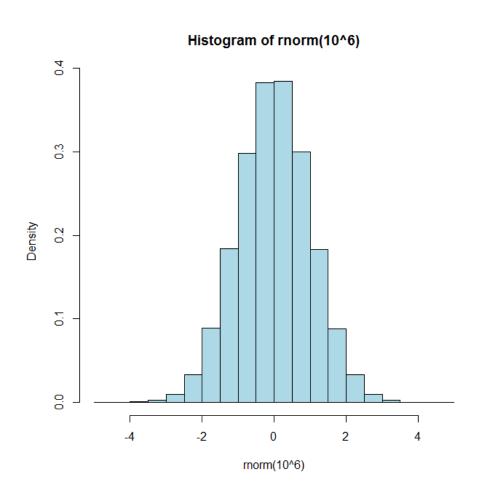


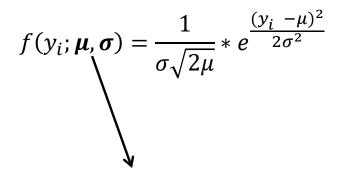
- 1. distribution of the response
- systematic part (covariates)
- 3. link-function between expected value of the response and the systematic part

## Normal distribution



seit 1558

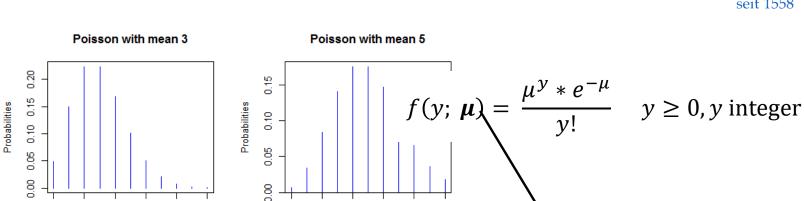


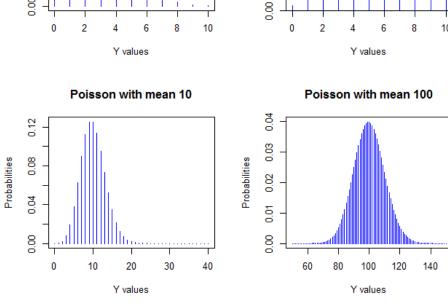


defined by mean and standard deviation

## Poisson distribution







Modified after: Zuur et al. (2009).

mean = variance

-> larger mean values have also a larger variance

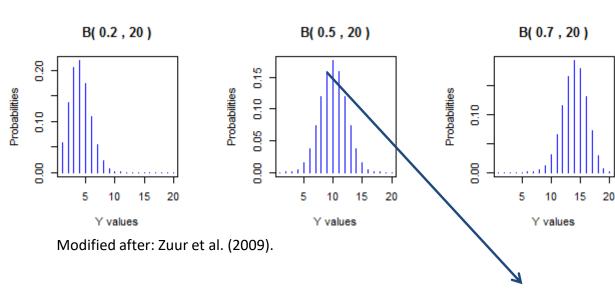
**overdispersion:** if the variance is larger than the mean





- Tossing a coin (head or tail)
- Bernoulli distribution = binomial distribution with N = 1

$$f(y; \pi) = {N \choose y} * \pi^y * (1 - \pi)^{N-y}$$



 $(20!/(9! * 11!))*0.5^9*(1-0.5)^11 = 0.16$ 

### Further common distributions



- 1. Negative binomial distribution -> quick and dirty solution for overdispersion
- **2. Gamma distribution** -> can be used for a continous response variable that has positive values (> 0)

## **Predictor function**



$$g(x_i) = \alpha + \beta_1 X_{1i} + \dots + \beta_n X_{ni}$$



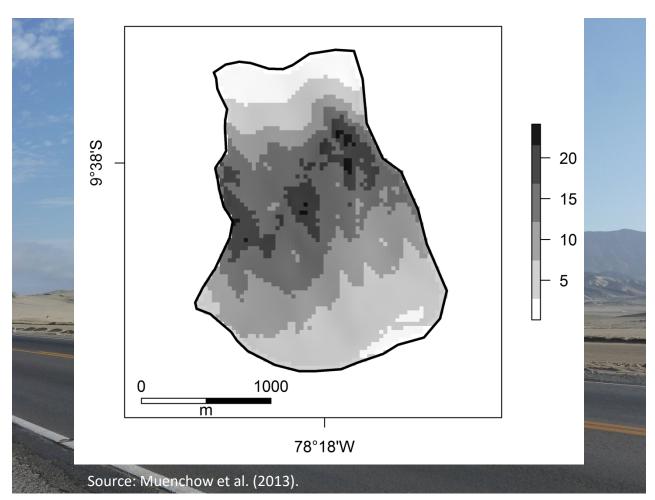


- distribution -> increase in spread
- 2. density curves avoid negative realizations
- 3. exponential link -> no negative fitted values
- 4. Maximum likelihood algorithm (see Zuur 2009: 213)

$$Y_i \sim P(\mu_i)$$
 and  $E[Y_i] = \mu_i = e^{\alpha + \beta_i X_{1i} + \dots + \beta_n X_{ni}}$  
$$\log(E[Y_i]) = \alpha + \beta_i X_{1i} + \dots + \beta_n X_{ni}$$
 
$$\log_{-\text{link}}$$







#### **Binomial GLM**



#### Absence (= 0)

- 1. Express 0 and 1 as probability P
- 2. Apply a series of transformationson P
- 3. back-transform to 0-1 intervall



I am not here, because the habitat is not good!



Here we are!

Presence (= 1)

modified after Zuur et al. (2009).

## Concept of Odds



$$O_i = \frac{\pi_i}{1 - \pi_i}$$

with  $O_i$ = Odds for the *i*th observation

 $\pi_i$  = Probability of the *i*th observation

-> Value not any longer restricted to 0 and 1!!!

# Concept of Odds



$$O_i = \frac{0.9}{(1-0.9)} = 9$$

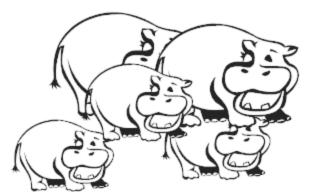
Odds of 9 -> it is **9 times** more likely to record a hippo than not to record one.

Or: In **9 from 10** plots you will find a hippo.

#### Absence (= 0)



I am not here, because the habitat is not good!



Here we are!

Presence (= 1)

modified after Zuur et al. (2009).





$$\log - \lim \left( \frac{\pi_i}{1 - \pi_i} \right) = \eta$$

with  $\eta$  = predictor function

-> Negative values are possible





$$\pi_i = \frac{e^{\eta}}{1 + e^{\eta}}$$

-> term lies always between 0 and 1 (back-transformation)!!!





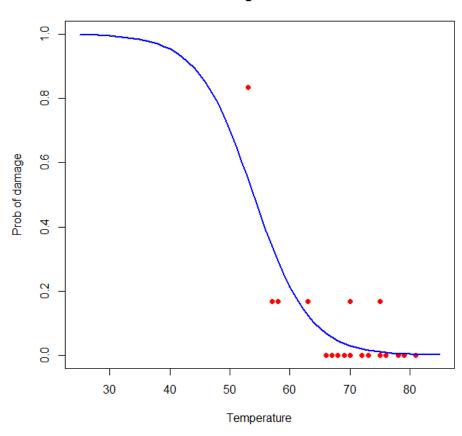
$$Y_i \sim B(1; P_i) \text{ and } E[Y_i] = P_i = \pi_i = \frac{e^{\alpha + \beta_i X_{1i} + \dots + \beta_n X_{ni}}}{1 + e^{\alpha + \beta_i X_{1i} + \dots + \beta_n X_{ni}}}$$

- appropriate distribution (Bernoulli)
- Maximum likelihood algorithm (see Zuur et al., 2007: 93)





#### Challenger disaster



Source: Faraway (2006).





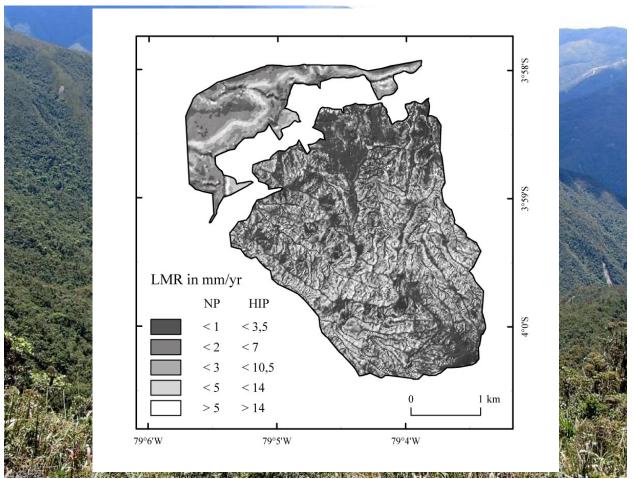


Foto: Michael Richter. Source: Muenchow et al. (2011).

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